NSF/NRI: INT: COLLAB: Manufacturing USA: Intelligent Human-Robot Collaboration for Smart Factory (Award I.D. #:1830383)
University of Florida Study ID: IRB201801847

or Task 1 (er	ngine par	ts): (circle y	our answe	r to each qu	uestion)				F 1	- 1
Task ½ , Metl	hod 2:							// -W-00-2		~
Question A:		safe at all, 5	is neutral	, 10 is very s	safe)					
0	1	2	3	λ	5	6	7	8	9	10
Question B:	(0 is robo	ot complete	ly prevent	ed your mot	tions, 5 is n	eutral, 10 i	s robot did	not impede	you moti	on)
0	1	2	3	4	5	X	7	8	9	10
Question C:	(0 is robo	ot motions i	made no se	ense to you,	5 is neutra	ıl, 10 is rob	ot motions	made sense	e to you)	
0	1	2	3	4	1	6	7	8	9	10
Question D:	(0 is you w	ould not wo	rk in this HR	C cell again,	5 is neutral,	10 is you en	joyed workii	ng in this cell	with the ro	obot)
0	1	2	3	λ	5	6	7	8	9	10
3				/				- market and the second		
Task 1, Met		No.						- 3		
Question A:	(0 is not	safe at all, !	5 is neutra	, 10 is very						10
0	1	2	3	4	5	6	7	*	9	10
Question B:	(0 is rob	ot complete	ely prevent	ed your mot	tions, 5 is n	eutral, 10 i	s robot did			on)
0	1	2	3	4	5	6	7	8	X	10
Question C:	(0 is rob	ot motions	made no s	ense to you,	, 5 is neutra	al, 10 is rob	ot motions	made sense	e to you)	
0	1	2	3	4	\times	6	7	8	9	10
Question D:	(0 is you w	ould not wo	rk in this Hi	RC cell again,	5 is neutral,	10 is you en	joyed workii	ng in this cell	with the ro	obot)
0	1	2	3	4	5	6	70	8	9	10
2	no-program ()									
Task 1, Met					C)					3
Question A	: (0 is not			l, 10 is very	100	V	7		9	10
0	1	2	3	. 4	5	X				
Question B	: (0 is rob	ot complete	ely prevent	ed your mo			s ropot ala			10
U	-	2			5	6	/ \	8	9	10
Question C	: (0 is rob	ot motions	made no s	ense to you						10
0	1	2	3	4	5	16	7	8	9	10
Question D:	(0 is you v	vould not wo	rk in this HI	RC cell again,	5 is neutral,	_				10
0	1	2	3	4		6	7	8	9	10
Comments	: T3	3- m	4	A_6	_ 6	5		8		5
7	-3-	M	3	4	6	B 6	,	= 7		>5