NSF/NRI: INT: COLLAB: Manufacturing USA: Intelligent Human-Robot Collaboration for Smart Factory (Award I.D. #:1830383) University of Florida Study ID: IRB201801847

or Task 2 (Sha	arework p	arts: meta	l tabs, cyli	nders, pall	ets): (circle	your answ	er to each o	uestion)	#	- [/
Task Z, Meth	od 1:								E-	2
Question A: (0 is not sa	fe at all, 5	is neutral,	10 is very s	afe)	1000			- No. 1	40
0	1	2	3	×	5	6	7	8	9	10
Question B: (0 is robot completely prevented your motions, 5 is neutral, 10 is robot did not impede you motion)										
0	1	2	3	25	5	6	7 ,	8	9	10
Question C: (0 is robot	motions m	nade no se	nse to you,	5 is neutra	l, 10 is rob	ot motions	made sense	e to you)	
0	1	2	3	4	8	6	7	8	9	10
Question D: (0	is you wou	ıld not worl	in this HR	C cell again, !	5 is neutral,	10 is you en	joyed workir	g in this cell	with the ro	bot)
0	1	2	3	$\boldsymbol{\varkappa}$	5	6	7	8	9	10
3						- 11-				
Task 7, Meth		f+ -11 F	:	10:	f-\			7.7		
Question A: (2	8	**************************************	2		-	
0	1	2	3	. 4		6	\Rightarrow	8	9	10
Question B: (2		d your mot			s robot did	not impede		
0	1	2	3	4	5	6	7	8	8	10
Question C: (0 is robot	motions n	nade no se	nse to you,	5 is neutra	al, 10 is rob	ot motions		e to you)	
0	1	2	3	, 4	5	6	7	\$	9	10
Question D: (0) is you wo			C cell again,	5 is neutral,	10 is you en	joyed workir	ng in this cel	with the ro	bot)
0	1	2	3	4	5	6	7	85	9	10
3					20				2.27	
Task Z, Meth		ofo at all. E	ic noutral	10 is von.	sofo)					
Question A:	1					-		•	•	40
	=	2	3	4	5 	8	7	8	9	10
Question B:	-						s robot dia	A-3		•
0	1	2	3	4	5	6	*	8	9	10
Question C:								made sens	e to you)	
0	1	2	3	4	5	6	8	8	9	10
Question D: (0						1		- 7		bot)
0	1	2	3	4	5	8	7	8	9	10
Comments:	T3	5-m 4	: A	4	B_	3	<u></u>	6 1	>4	
	T3	-m5	i E A	6	B	6	C	6_	0 6	

Participant number: _____ Date: ____