

Mobility Models

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Motivation

- ▶ Wireless network simulations often involve movements of entities
 - ▶ Examples
 - ▶ Users are roaming on WLAN access points that are installed in buildings (infrastructure mode)
 - ▶ Cell phone users are walking a city
 - ▶ Cars use car-to-car communication
 - ▶ Ad hoc networks in emergency situations, e.g., earthquake or fire
 - ▶ Mobility of entities plays an important role in such scenarios
 - ▶ Results may vary significantly if the mobility pattern is changed
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Categorization

- ▶ **Traces and synthetic mobility models**
 - ▶ **Traces:** Mobility patterns that are logged from real life situations
 - ▶ **Synthetic mobility models:** Generated by algorithms that specify virtual behavior of users and predict their movements
 - ▶ Entity and group mobility models
 - ▶ **Entity models:** Movement of a single individual entity, e.g., a human being or an animal.
 - ▶ **Group models:** A group of individual entities, which is moving as a whole.



Categorization

- ▶ Human, animal, and vehicle mobility models
 - ▶ **Human:** Human beings in certain scenarios.
 - ▶ **Animal:** Herds or swarms
 - ▶ **Vehicle:** Restricted to traffic rules
- ▶ Normal situation and special situation mobility models
 - ▶ **Special:** earthquake



What is Mobile Network? Why is it called Ad Hoc?

- ▶ Mobile Ad Hoc Networks (MANET) is a network consisting of mobile nodes with wireless connection (Mobile) and without central control (Ad Hoc)
 - ▶ Self-Organized Network
- ▶ Each mobile node communicates with other nodes within its transmitting range
- ▶ Transmission may be interrupted by nodal movement or signal interference



It seems that something is watching

- ▶ Sensor Network is recently a hot topic
- ▶ Specified Application in MANET
- ▶ Nodes are equipped some observation devices (GPS, Temperature, Intruder Detection and so on)
- ▶ Nodes may move spontaneously or passively
- ▶ There are **more restrictions** in Sensor Networks
 - ▶ Power
 - ▶ Transmission Range
 - ▶ Limited Computation Power
 - ▶ Moving Speed (if does)



Realistic Mobility Model is better than Proposed Mobility Models

- ▶ Although MANET and Sensor Network are being researched for a while, there do not exist many realistic implementation
- ▶ To implement a real MANET or Sensor Network environment for emulation is difficult
 - ▶ Signal Interference
 - ▶ Boundary
- ▶ We will need to evaluate MANET by simulation
- ▶ To have useful simulation results is to control factors in simulation
 - ▶ Traffic Pattern
 - ▶ Bandwidth
 - ▶ Power Consumption
 - ▶ Signal Power (Transmission Range)
 - ▶ Mobility Pattern
 - ▶ And so on



How Many Mobility Model are inspected?

- ▶ **Entity Mobility Models**

- ▶ Random Walk Mobility Model
- ▶ Random Waypoint Mobility Model
- ▶ Random Direction Mobility Model
- ▶ A Boundless Simulation Area Mobility Model
- ▶ Gauss-Markov Mobility Model
- ▶ A Probability Version of the Random Walk Mobility Model
- ▶ City Section Mobility Model



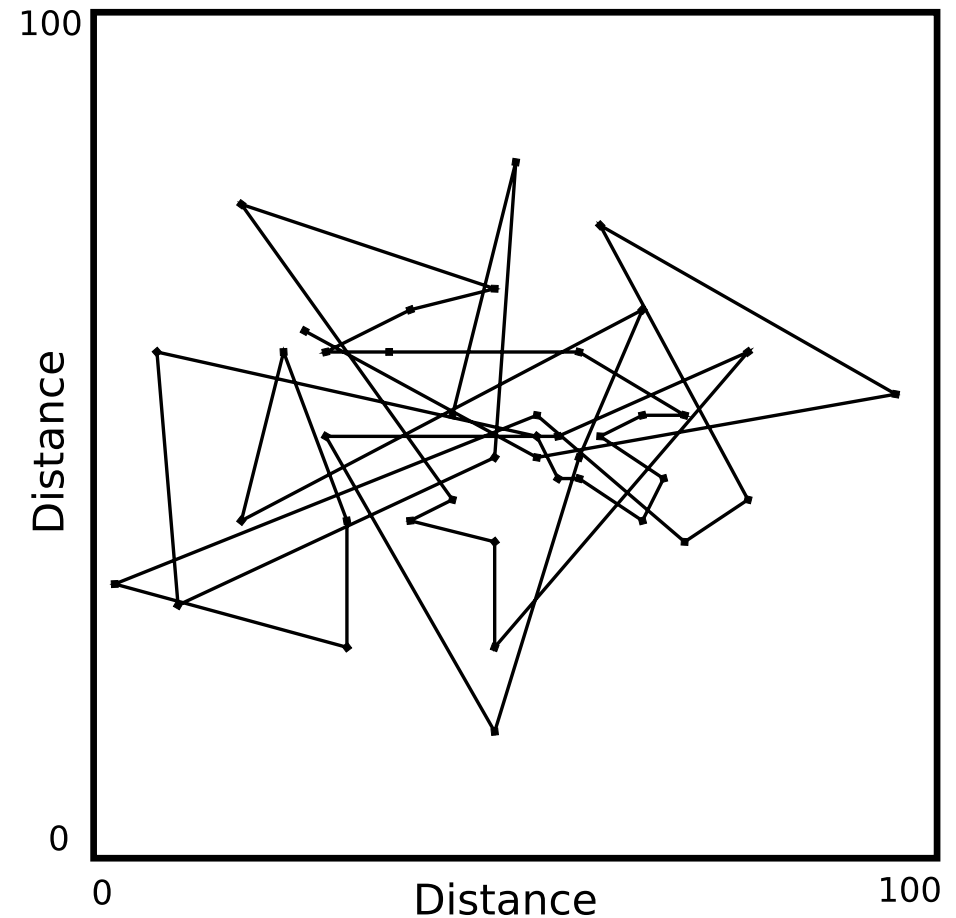
▶ Group Mobility Models

- ▶ Exponential Correlated Random Mobility Model
- ▶ Column Mobility Model
- ▶ Nomadic Community Mobility Model
- ▶ Pursue Mobility Model
- ▶ Reference Point Group Mobility Model



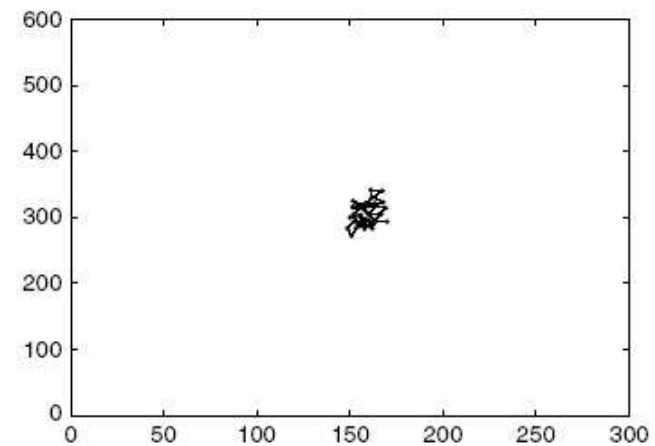
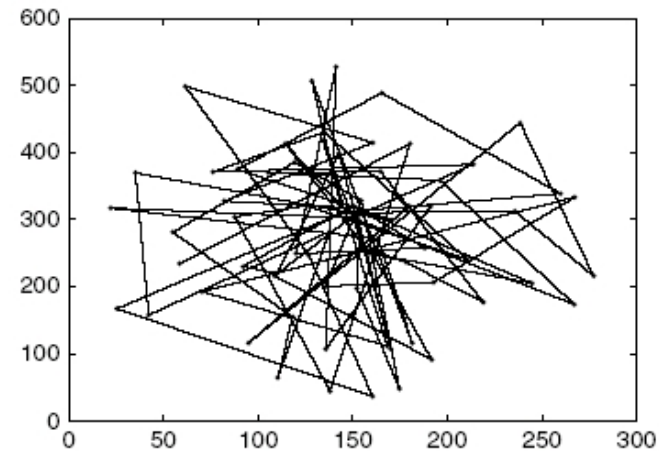
Random Walk model

- ▶ Entities in nature move in unpredictable ways
- ▶ Entity moves from its current location to a following location by choosing randomly a new direction and speed
- ▶ Every movement is limited to a constant time interval



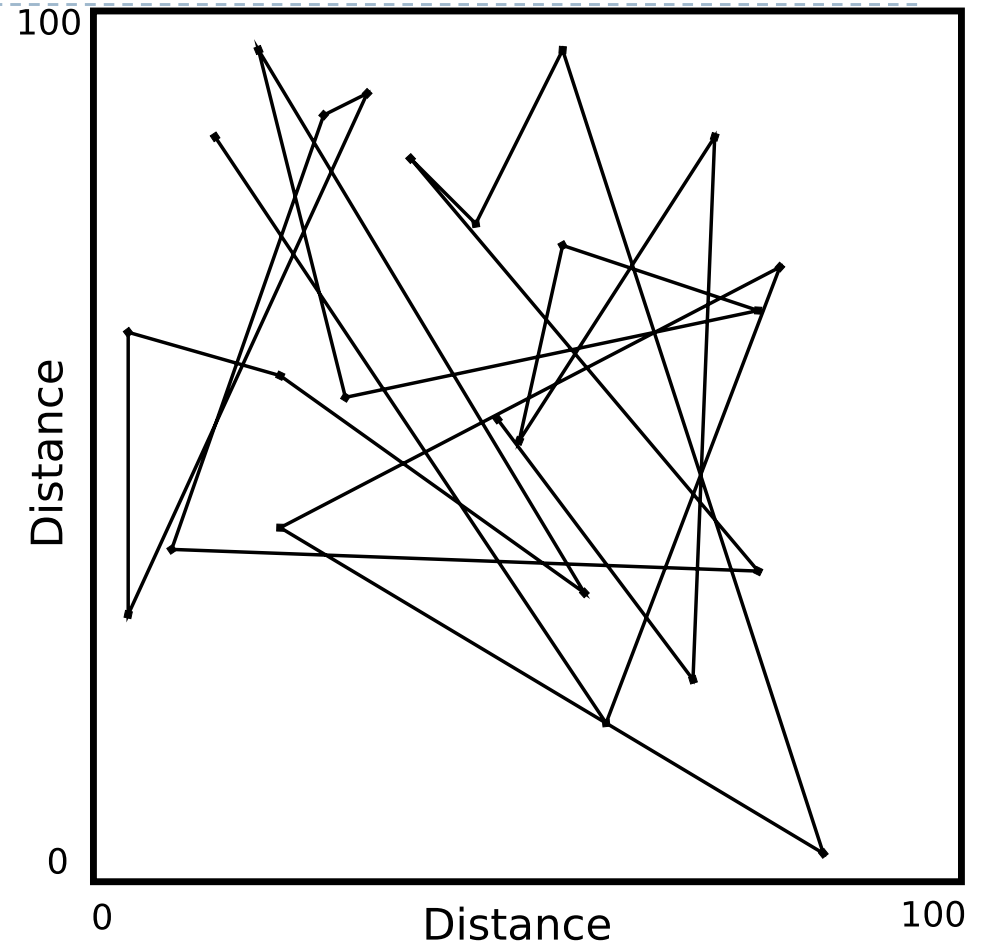
Random Walk

- ▶ **Parameters:**
 - ▶ Speed = [Speed_MIN, Speed_MAX]
 - ▶ Angle = $[0, 2\pi]$
 - ▶ Traversal Time (t) or Traversal Distance (d)



Random Waypoint Model

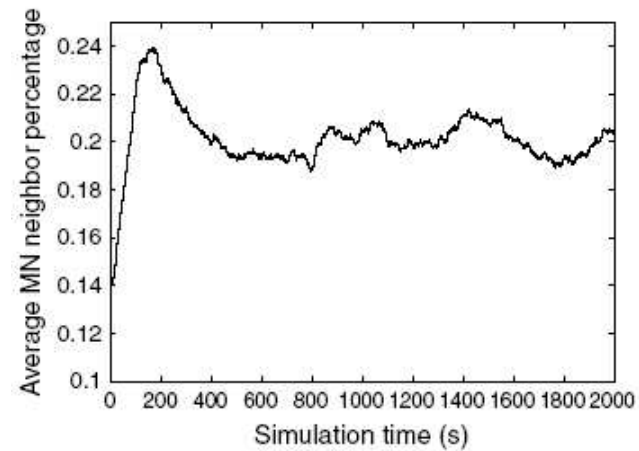
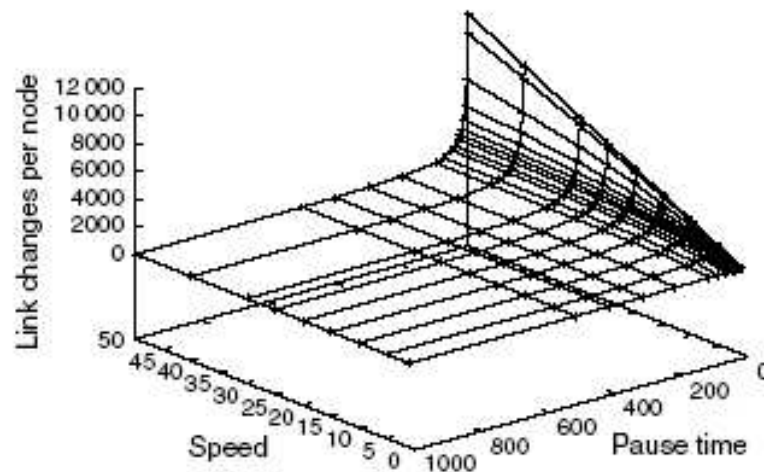
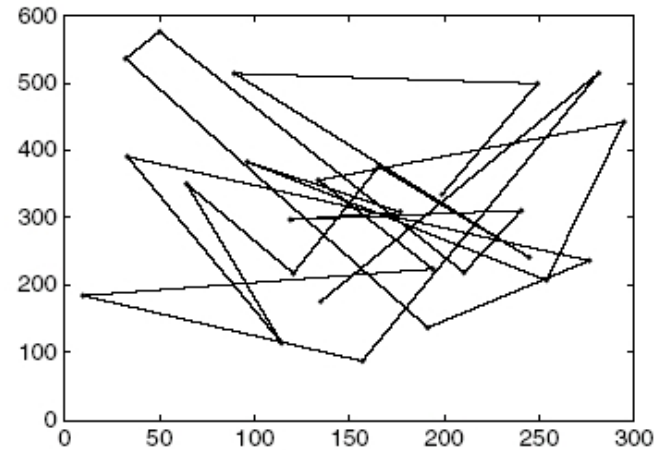
- ▶ The entity chooses a random destination coordinate
- ▶ Then it moves from its current location to the destination location
- ▶ After a pause, the new movement is calculated



Random Waypoint

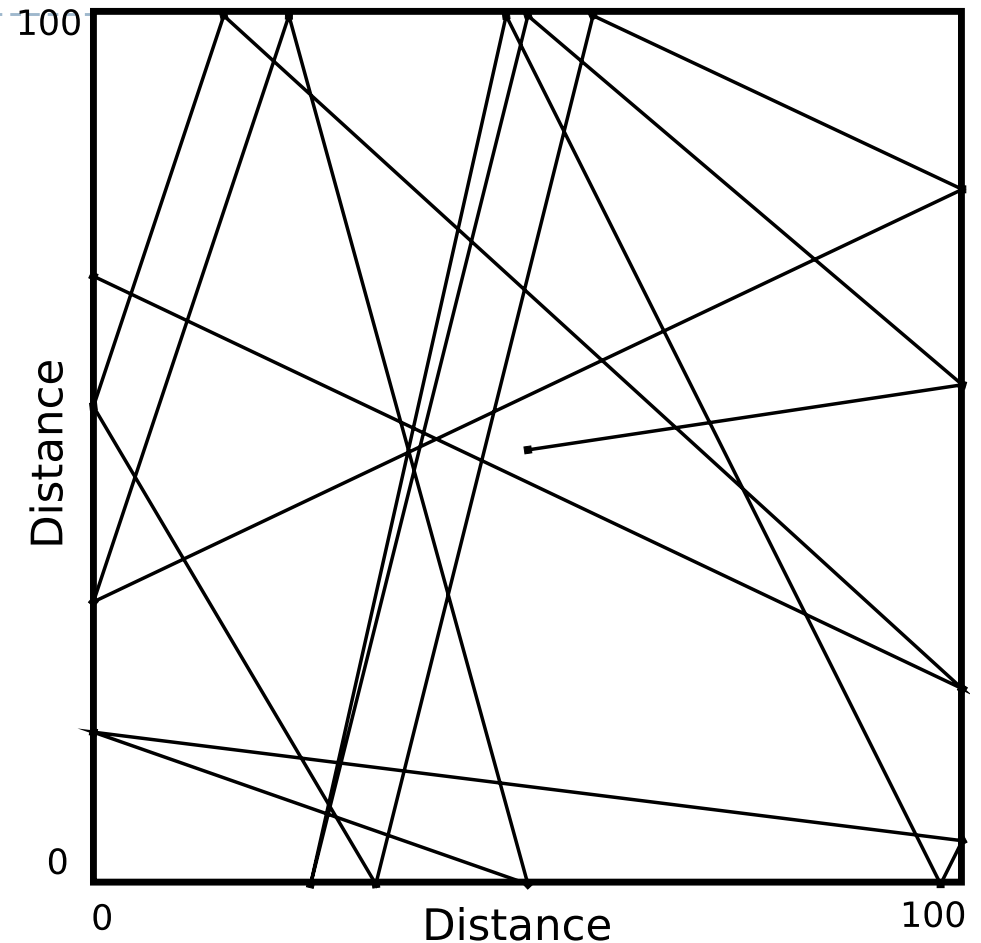
► Parameters

- Speed =
[Speed_MIN, Speed_MAX]
- Destination =
[Random_X, Random_Y]
- Pause Time ≥ 0



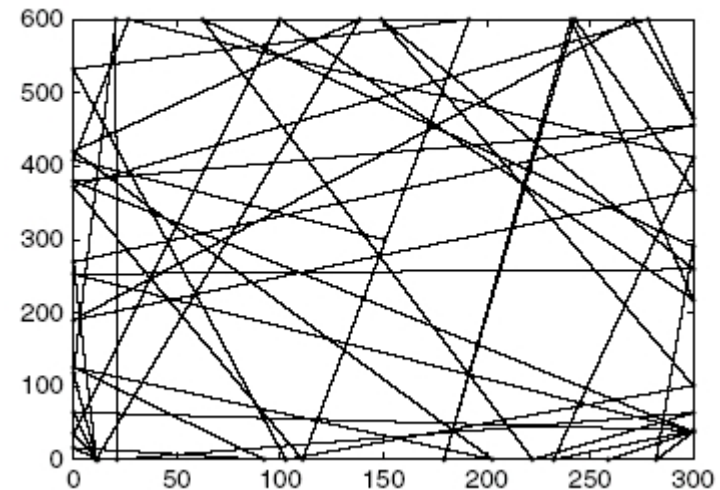
Random Direction Model

- ▶ The entity chooses a random direction and a random speed
- ▶ Entity moves towards the boundary of the simulation area
- ▶ After a pause, the new movement is calculated



Random Direction

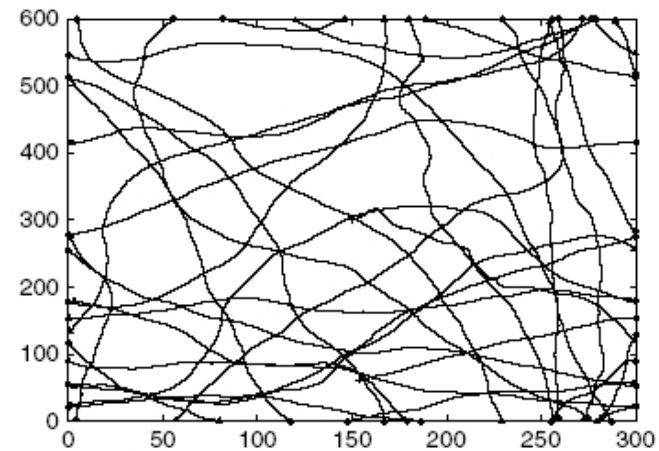
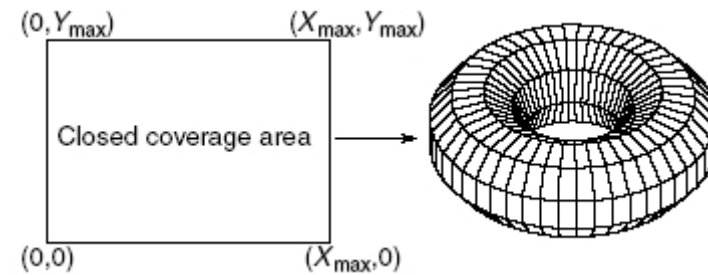
- ▶ Parameters:
 - ▶ Speed = [Speed_MIN, Speed_MAX]
 - ▶ Direction = $[0, \pi]$ (Initial $[0, 2\pi]$)
 - ▶ Pause Time
- ▶ Go straight with selected direction until bump to the boundary then pause to select another direction



Boundless Simulation Area

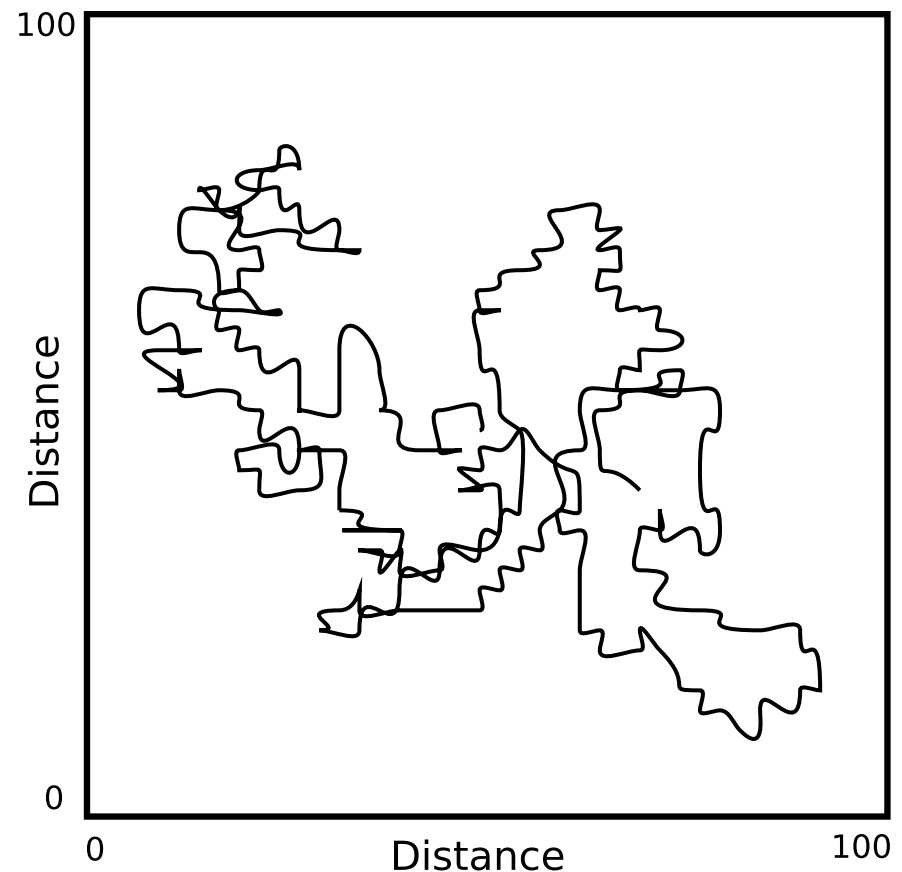
► Parameters:

- $v(t + \Delta t) = \min\{\max[v(t) + \Delta v, 0], V_{\max}\}$
- $\theta(t + \Delta t) = \theta(t) + \Delta \theta$
- $x(t + \Delta t) = x(t) + v(t) * \cos\theta(t)$
- $y(t + \Delta t) = y(t) + v(t) * \sin\theta(t)$
- $\Delta v = [-A_{\max} * \Delta t, A_{\max} * \Delta t]$
- $\Delta \theta = [-\alpha * \Delta t, \alpha * \Delta t]$



Gauss-Markov Model

- ▶ The entity gets initially assigned a speed and a direction
- ▶ At fixed intervals of time, an update of direction and speed is applied
- ▶ This model enables movements that are depending on previous movements



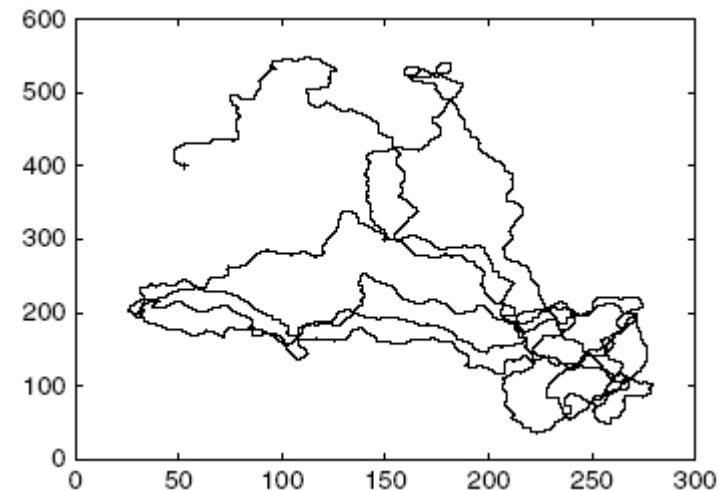
Gauss-Markov

- Parameters:

- $s_n = \alpha s_{n-1} + (1 - \alpha) \bar{s} + \sqrt{(1 - \alpha^2)} s_{n-1}$

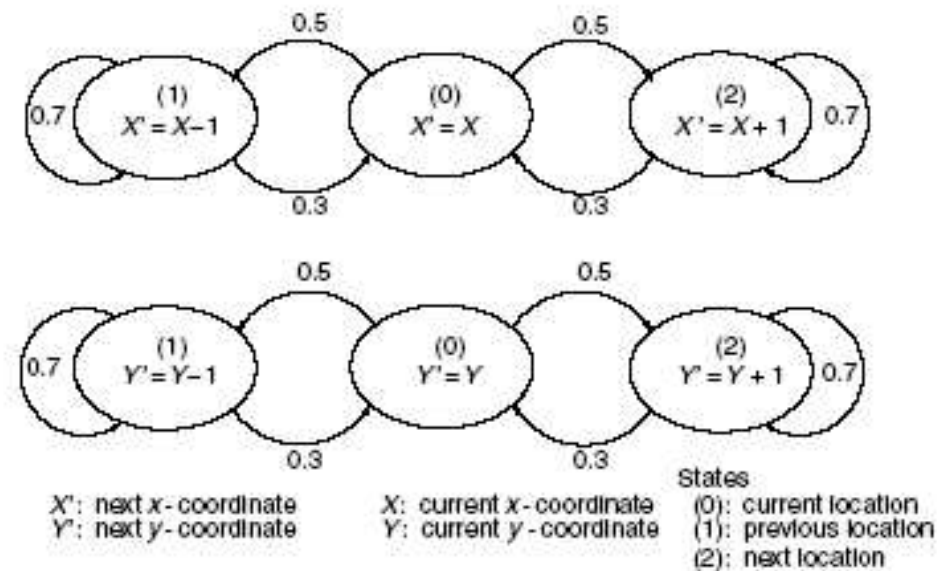
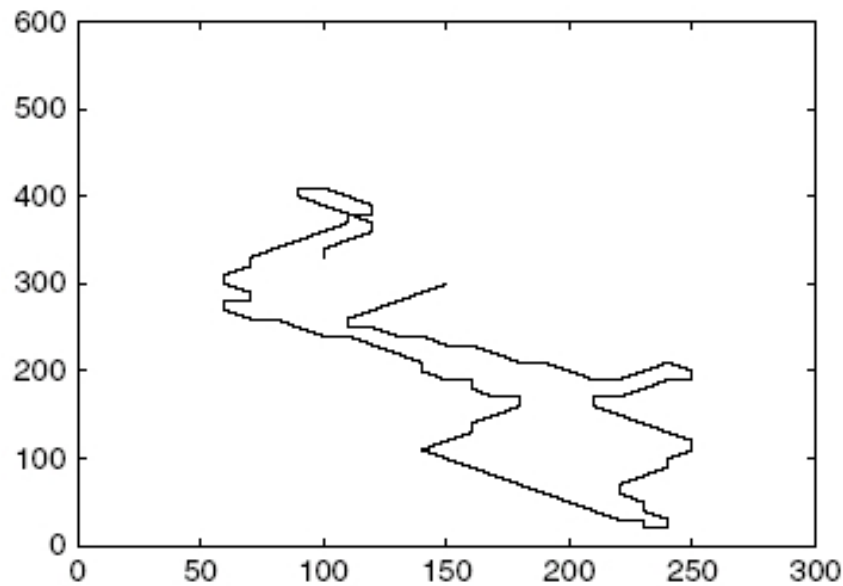
- $d_n = \alpha d_{n-1} + (1 - \alpha) \bar{d} + \sqrt{(1 - \alpha^2)} d_{n-1}$

- When approach the edge, d value will change to prevent the node stocking at the edge



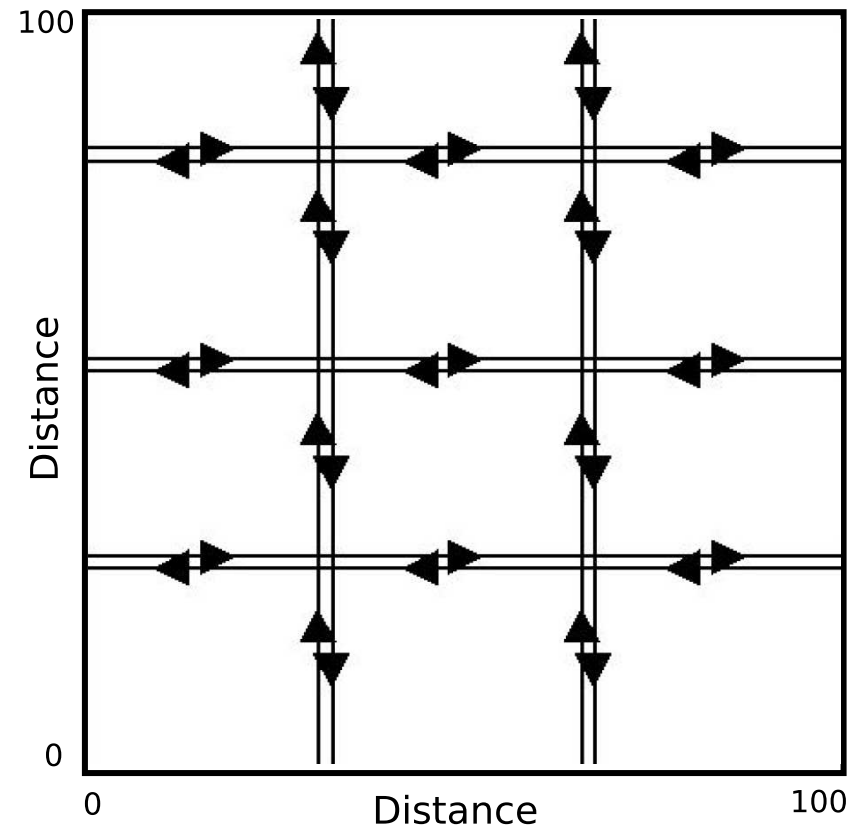
Probability Version of Random Walk

$$P = \begin{bmatrix} P(0, 0) & P(0, 1) & P(0, 2) \\ P(1, 0) & P(1, 1) & P(1, 2) \\ P(2, 0) & P(2, 1) & P(2, 2) \end{bmatrix}$$

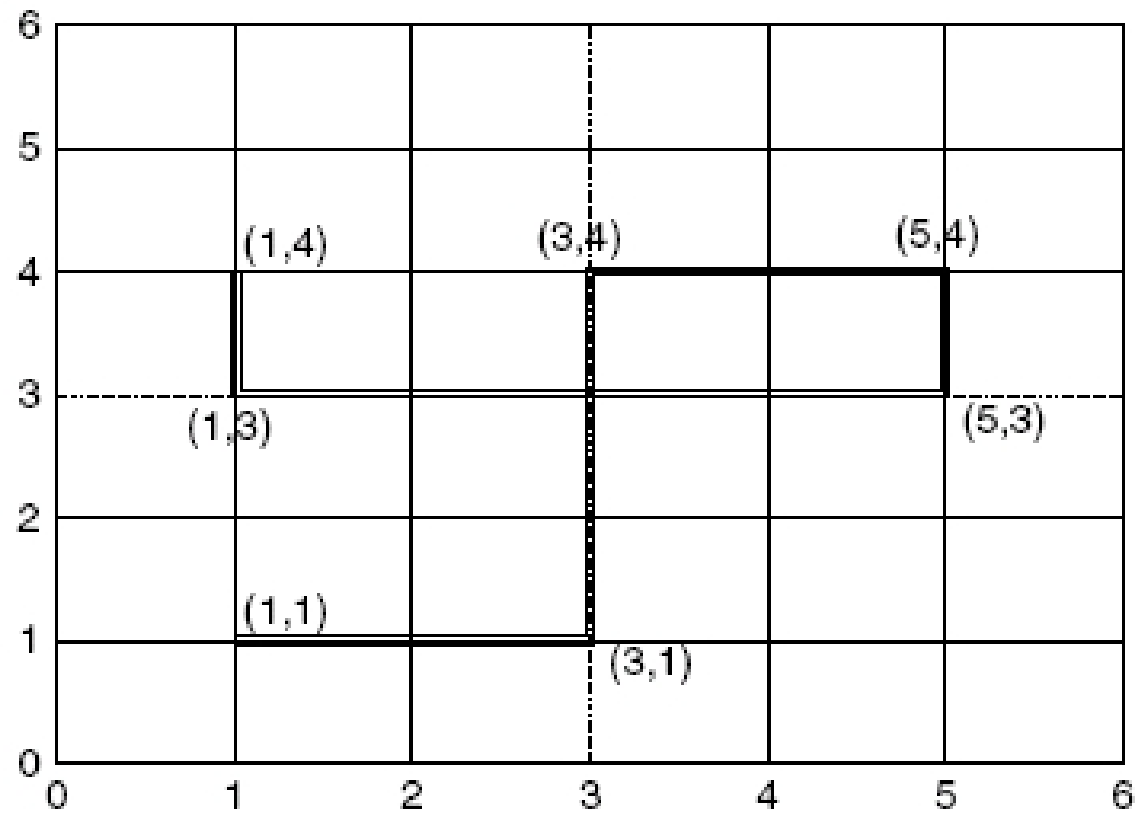


Manhattan Model

- ▶ Entities are bound to streets or highways
- ▶ Map with streets and crossings is defined
- ▶ Safety distance between entities
- ▶ Street changes at crossings happen according to a probability



City Section



Group Mobility

- ▶ Exponential Correlated Random Mobility Model



$$b(t+1) = b(t)e^{-\frac{1}{\tau}} + \left(\sigma \sqrt{1 - \left(e^{-\frac{1}{\tau}} \right)^2} \right) r$$

- ▶ Column Mobility Model

- ▶ Given a reference grid, each node has a reference point on the reference grid
 - ▶ Each node can move freely around its reference point (Ex: Random Walk)

- ▶ Nomadic Community Mobility Model

- ▶ Similar to Column Mobility Model, but all nodes of a group share a reference point

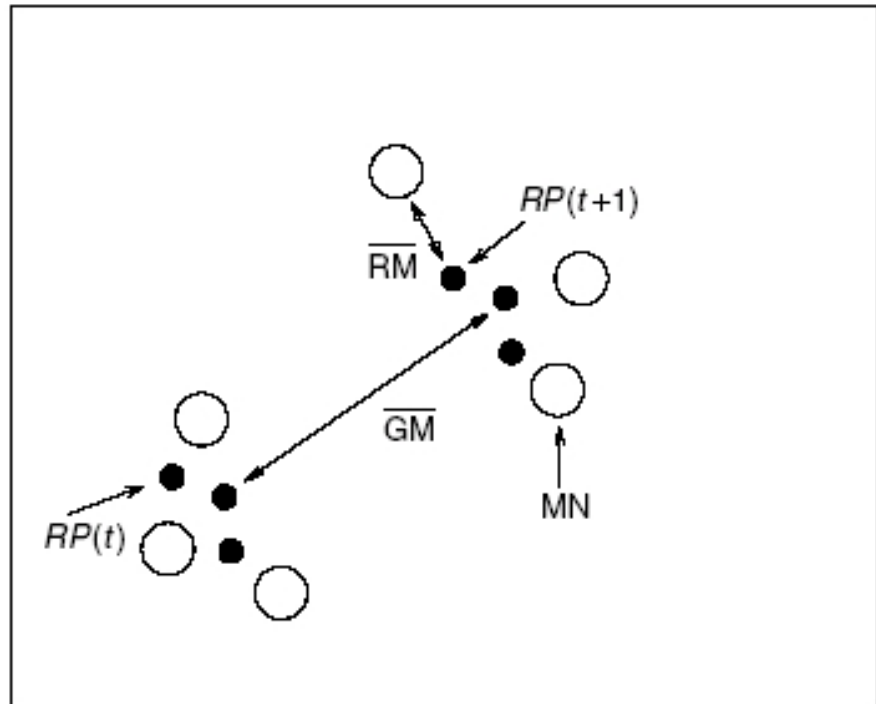
- ▶ Pursue Mobility Model

- ▶ $\text{new_pos} = \text{old_pos} + \text{acceleration}(\text{target} - \text{old_pos}) + \text{random_vector}$



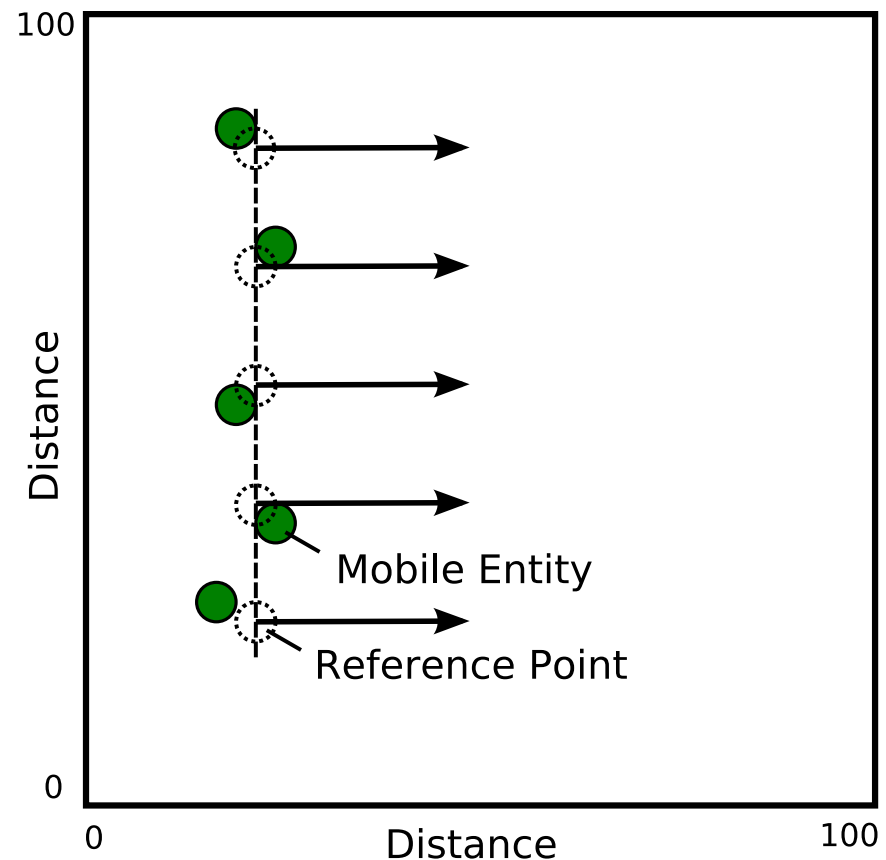
- ▶ Reference Point Group Mobility Model

- ▶ Group movements are based on the path traveled by a logical center for the group
- ▶ GM: Group Motion Vector
- ▶ RM: Random Motion Vector
- ▶ Random motion of individual node is implemented by Random Waypoint without Pause



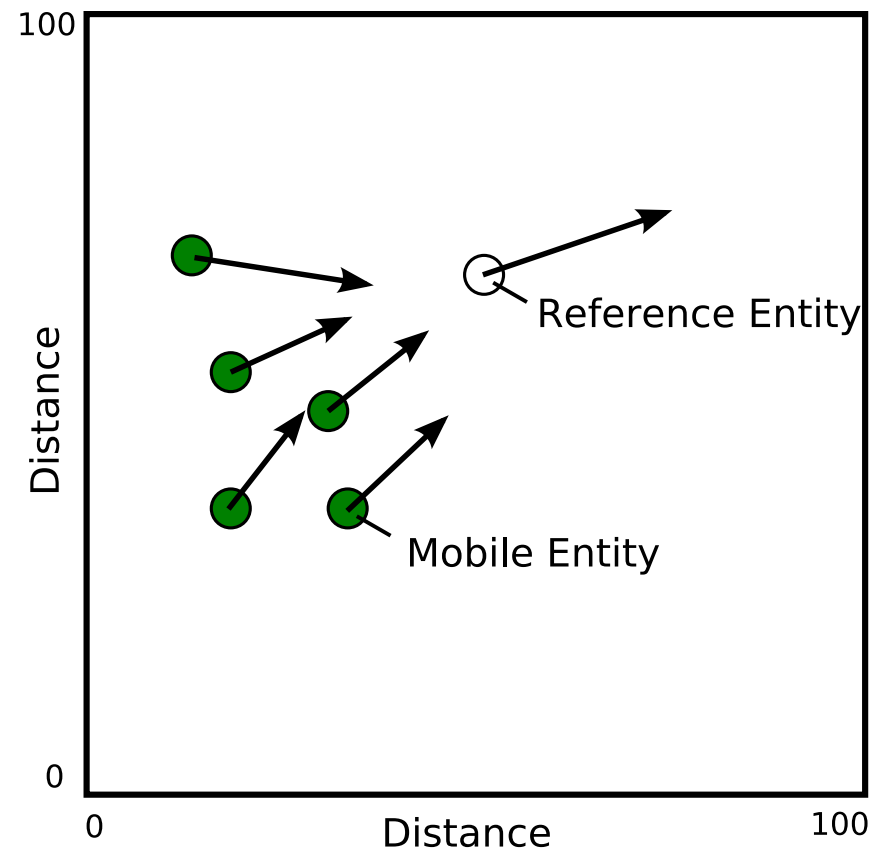
Column Model

- ▶ Group mobility model in which each entity follows a *reference point*
- ▶ Reference points are arranged in a line
- ▶ The line is moving
- ▶ Entities are choosing random point near the reference point to move to
- ▶ Example: tanks



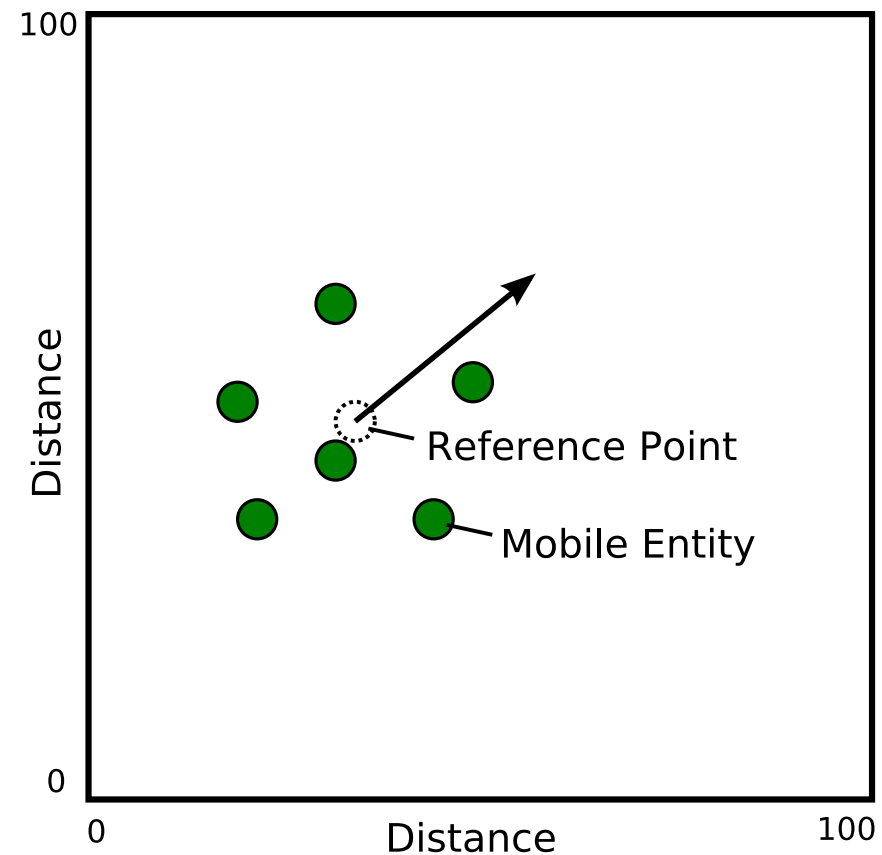
Persue Model

- ▶ Group of mobile entities are pursuing single *reference entity*
- ▶ The reference entity is using an entity mobility model
- ▶ Group entities are pursuing the reference entity while adding small deviations
- ▶ Example: Tourists following guide



Nomadic Community Model

- ▶ Group of entities are following a single *reference point*
- ▶ All entities are sharing the same reference point
- ▶ Each entity is randomly moving around the reference point
- ▶ Example: Nomads moving from one place to another



Selection of Models

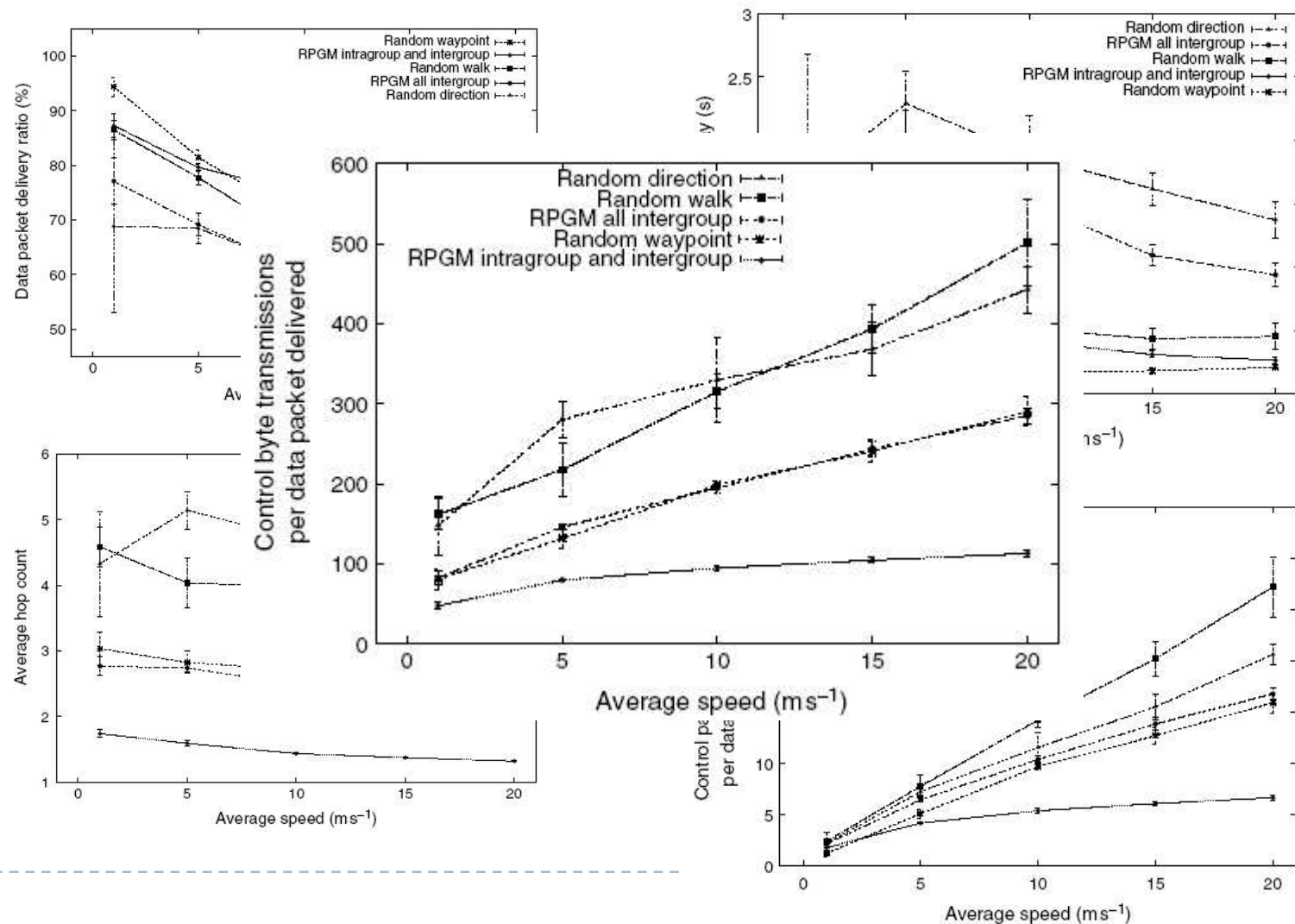
- ▶ Trade-off between accuracy and costs of the model
 - ▶ Detailed models fit into real-life scenarios
 - ▶ Realistic models impose high complexity
 - ▶ Implementation efforts
 - ▶ Performance of calculation
 - ▶ Simple models are easy to implement and can be calculated fast
 - ▶ Finding the right model
 - ▶ Review available models of the area
 - ▶ Start with a simple model that fits best
 - ▶ Improve it to the specified scenario
 - ▶ Alternatively: Use the same model as it is used in related research → comparable results
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Simulation Parameters

- ▶ Simulation Package: ns-2
- ▶ 50 Mobile Nodes
- ▶ 100m Transmission Range
- ▶ Simulation Time from 0s ~ 2010s
 - ▶ Results is collected from 1010s
- ▶ Routing Protocol: Dynamic Source Routing (DSR)
- ▶ Each mobility model has 10 different runs and show with 95% confidence interval
- ▶ Simulated Model
 - ▶ Random Walk
 - ▶ Random Waypoint
 - ▶ Random Direction
 - ▶ RPGM
 - ▶ 100% Intergroup communication
 - ▶ 50% Intergroup communication, 50% Intragroup communication



What results do different mobility models bring?



Observation of Different Mobility Models

- ▶ The performance of an ad hoc network protocol can vary significantly with different mobility models
- ▶ The performance of an ad hoc network protocol can vary significantly when the same mobility model is used with different parameters
- ▶ Data traffic pattern will affect the simulation results
- ▶ Selecting the most suitable mobility model fitting to the proposed protocol



Considerations when Applying Each Mobility Model

- ▶ **Random Walk**
 - ▶ Small input parameter: Stable and static networks
 - ▶ Large input parameter: Similar to Random Waypoint
 - ▶ **Random Waypoint**
 - ▶ Scenarios such as conference or museum
 - ▶ **Random Direction**
 - ▶ Unrealistic model
 - ▶ Pause time before reaching the edge → Similar to Random Walk
 - ▶ **Boundless Simulation**
 - ▶ Although moving without boundary, the radio propagation and neighboring condition are unrealistic
 - ▶ **Gauss-Markov**
 - ▶ Most realistic mobility model
 - ▶ **Probabilistic Random Walk**
 - ▶ Choosing appropriate parameters to fit real world is difficult
 - ▶ **City Section**
 - ▶ For some protocol designed for city walk
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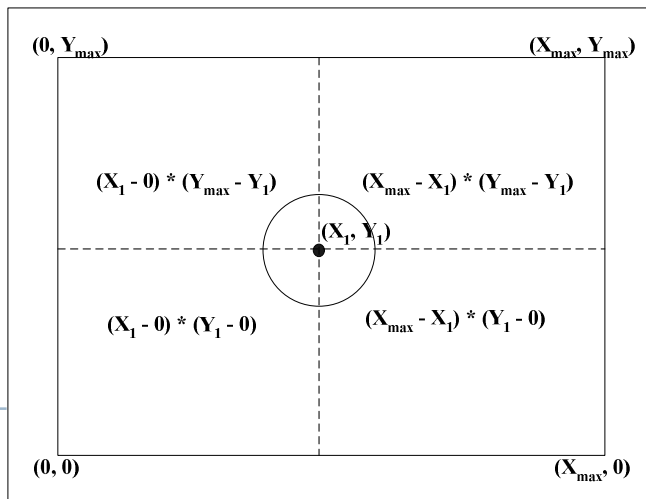


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- ▶ **Exponential Correlated Random Mobility Model**
 - ▶ Theoretically describe all other mobility models, but selecting appropriate parameter is impossible
 - ▶ **Column, Nomadic Community, Pursue Mobility Models**
 - ▶ Above three mobility models can be modeled by RPGM with different parameters
 - ▶ **RPGM Model**
 - ▶ Generic method for group mobility
 - ▶ Assigned an entity mobility model to handle groups and individual node
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Random Waypoint Considered Harmful

- ▶ Yoon has published a paper indicating that network average speed of RWVP will decay to zero in simulation
 - ▶ Setting the minimum speed larger than zero
- ▶ Besides speed decaying, the nodes with RWVP tend to cross the center of the area



$$\textit{First} : \frac{(X_{\max} - X_1) \cdot (Y_{\max} - Y_1)}{X_{\max} \cdot Y_{\max}}$$

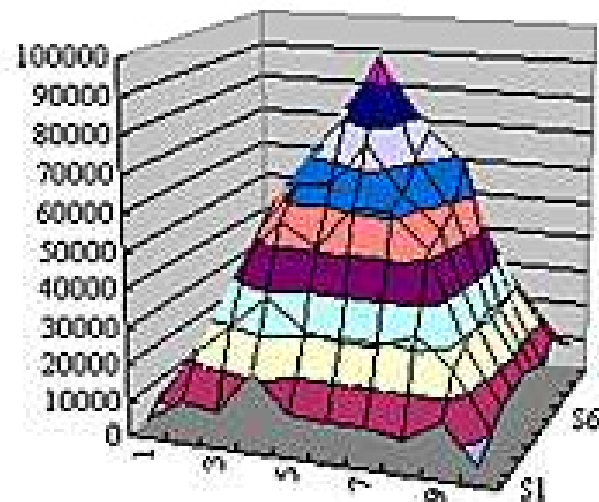
$$\textit{Second} : \frac{(X_1 - 0) \cdot (Y_{\max} - Y_1)}{X_{\max} \cdot Y_{\max}}$$

$$\textit{Third} : \frac{(X_1 - 0) \cdot (Y_1 - 0)}{X_{\max} \cdot Y_{\max}}$$

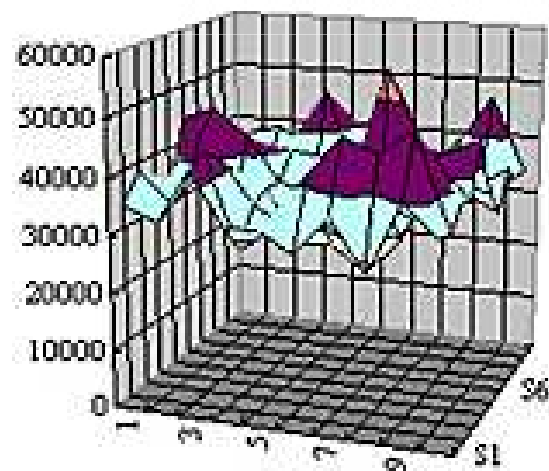
$$\textit{Fourth} : \frac{(X_{\max} - X_1) \cdot (Y_1 - 0)}{X_{\max} \cdot Y_{\max}}$$

Spatial Distribution Comparisons

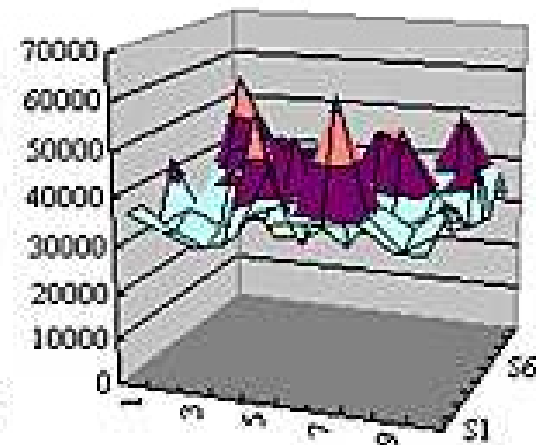
- Cumulate the nodal appearance in the square of 100m x 100m (Moving area is 1000m x 1000m)



Random Waypoint



RMM(0,0)



RMM(2,200)

Conclusions

- ▶ The defects in RWP are explored by some research and solutions are also proposed
 - ▶ Decaying Average Speed
 - ▶ Unfair Moving Pattern
- ▶ Most proposed solutions target to one of the defects but not both
- ▶ To generate different moving pattern within the same speed range is a reasonable requirement but it has not been brought up



Reference

- ▶ Tracy Camp, Jeff Boleng, and Vanessa Davies, “A Survey of Mobility Models for Ad Hoc Network Research”, Wireless Communication and Mobile Computing (WCMC) 2002
- ▶ Guolong Lin, Guevara Noubir, and Rajmohan Raharaman, “Mobility Models for Ad Hoc Network Simulation”, INFOCOM 2004

