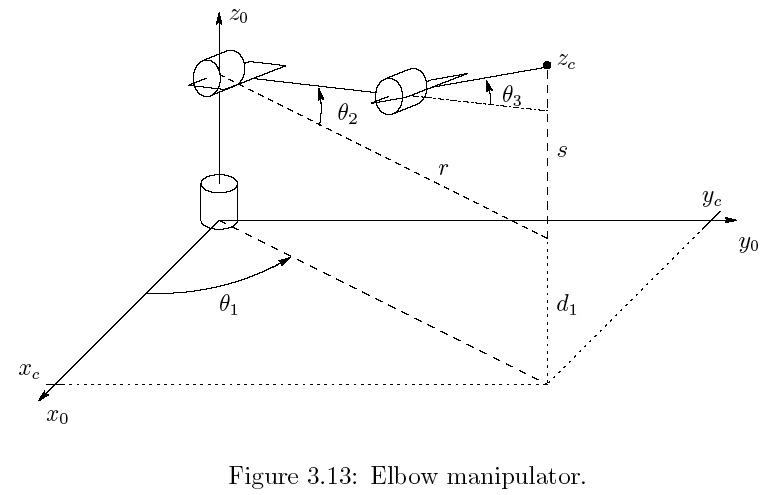


**ECE 5397/6397: Intro to Robotics**

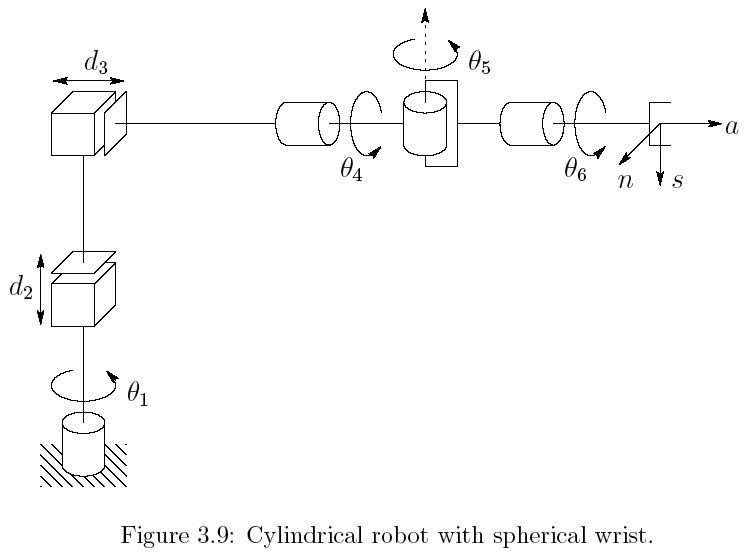
**HW 4, Due March 3** The manipulator Jacobian

1. Calculate the manipulator Jacobian of the anthropomorphic manipulator at the position *zc.*
   1. Write out the *J* matrix in terms of *zi* and *oi*.
   2. Write out the *zi* and *oi* values.
   3. Write out the *J* values. Calculate the cross products. You may use your previous calculations for the A and T matrices.



2. Calculate the manipulator Jacobian of the cylindrical robot with spherical wrist manipulator at the position *z6.*

1. Write out the J matrix in terms of zi and oi.
2. Write out the zi and oi values.
3. Calculate the cross products. You may use your previous calculations for the A and T matrices.



With non zero *d6*

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