

Evaluator _____ Match # _____ Score _____

Team number _____ Robot name _____ Alliance _____ A or B _____

Circle one: Red Team / Blue Team

Circle three: Red / Green White / Black Blue / Yellow

Color Identification points (circle one)

3 Fixes	2 Fixes	1 Fix	0 Fixes
0	25	75	150

GPS Distances (circle one)

	Value	>45'	<= 45.0'	<= 30.0'	<= 20.0'	<= 10.0'	<= 5.0'
Near Ball		0	10	50	80	100	110
Far Ball		0	20	100	160	200	220
Robot Home		0	10	50	80	100	110

White/Black ball mission (circle one)

Failure	Success
0	60

Tiebreaker distance (optional) _____ Note, final robot score is in the top right.