

view_frames Result

Recorded at time: 1612366011.609

map

Broadcaster: /slam_gmapping
Average rate: 20.204 Hz
Most recent transform: 1612366011.613 (-0.004 sec old)
Buffer length: 4.900 sec

odom

Broadcaster: /ekf_localization
Average rate: 50.237 Hz
Most recent transform: 1612366011.602 (0.007 sec old)
Buffer length: 4.956 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

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Buffer length: 0.000 sec

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Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /link1_broadcaster
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 1612366011.602 (0.007 sec old)
Buffer length: 4.896 sec

Broadcaster: /robot_state_publisher
Average rate: 10.213 Hz
Most recent transform: 1612366011.602 (0.007 sec old)
Buffer length: 4.896 sec

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Average rate: 10.213 Hz
Most recent transform: 1612366011.602 (0.007 sec old)
Buffer length: 4.896 sec

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Average rate: 10.213 Hz
Most recent transform: 1612366011.602 (0.007 sec old)
Buffer length: 4.896 sec

base_footprint

front_bumper_link

imu_link

inertial_link

rear_bumper_link

top_chassis_link

top_plate_link

user_rail_link

D455_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

top_plate_front_link

top_plate_rear_link

D455_depth_frame

D455_color_frame

D455_depth_optical_frame

D455_color_optical_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /D455/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

Broadcaster: /D455/realsense2_camera_manager
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz
Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec

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Most recent transform: 0.000 (1612366011.609 sec old)
Buffer length: 0.000 sec