

### UM++ Bridge - Accessing FEM-Models and UQ-Methods from M++

A Fully Parallelized and Budgeted MLMC Method - Acoustic Wave Propagation - Client and Server Interface to Umbridge Niklas Baumgarten, Christian Wieners, Sebastian Krumscheid, Linus Seelinger | 12.12.2023



12.12.2023



**Acoustic wave:** Search  $(\mathbf{v}, p)$ :  $\Omega \times \mathcal{D} \times [0, T] \to \mathbb{R}^{D+1}$ ,

such that 
$$\begin{cases} \rho(\omega)\partial_t \mathbf{v}(\omega) - \nabla p(\omega) &= \mathbf{f} & \mathcal{D} \times (0,T] \\ \partial_t p(\omega) - \operatorname{div} \left( \mathbf{v}(\omega) \right) &= g & \mathcal{D} \times (0,T] \\ \mathbf{v} \cdot \mathbf{n} &= 0 & \Gamma \times (0,T] \\ \mathbf{v}(0) &= \mathbf{v}_0 & \mathcal{D} \\ p(0) &= p_0 & \mathcal{D} \end{cases}$$





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$$\textbf{Determine:} \quad \mathbb{E}[\mathbb{Q}] := \int_{\Omega} \mathbb{Q}(\omega) \mathrm{d}\mathbb{P} \approx \textit{M}^{-1} \sum_{m=1}^{\textit{M}} \mathbb{Q}_{\ell}(\mathbf{y}^{(m)}) =: \widehat{\mathbb{Q}}_{\ell,\textit{M}}^{\mathsf{MC}}$$



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Goal: Find combination of methods to minimize total error

$$err_{total} = err_{input} + err_{disc} + err_{model} + err_{solve} + err_{float} + err_{bug} + \dots$$



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Constraint: Finite computational capacities (CPUs, time, memory)

⇒ Introduce budget for error minimization and utilize effective parallelization



**Assumptions:** Let  $\alpha, \beta, \gamma > 0$  and

$$\begin{split} |\mathbb{E}[\mathbf{Q}_{\ell} - \mathbf{Q}]| \lesssim h_{\ell}^{\alpha} \\ \mathbb{V}[\mathbf{Q}_{\ell} - \mathbf{Q}_{\ell-1}] \lesssim h_{\ell}^{\beta} \\ \mathbf{C}\left(\mathbf{Q}_{\ell}(\mathbf{y}^{(m)})\right) \lesssim h_{\ell}^{-\gamma} \end{split}$$



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$$\begin{split} & \text{Idea: } \text{Telescoping sum with } Y_0 \coloneqq Q_0, Y_\ell \coloneqq Q_\ell - Q_{\ell-1} \\ & \mathbb{E}[Q_L] = \mathbb{E}[Q_0] + \sum_{\ell=1}^L \mathbb{E}[Q_\ell - Q_{\ell-1}] = \sum_{\ell=0}^L \mathbb{E}[Y_\ell] \end{split}$$



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#### **Multi-level Estimator:**

$$\widehat{Q}_{\{M_{\ell}\}_{\ell=0}^{L}}^{\mathsf{MLMC}} = \sum_{\ell=0}^{L} \widehat{Y}_{\ell,M_{\ell}}^{\mathsf{MC}} = \sum_{\ell=0}^{L} M_{\ell}^{-1} \sum_{m=1}^{M_{\ell}} Y_{\ell}(\mathbf{y}^{(m)})$$





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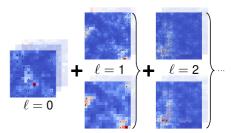
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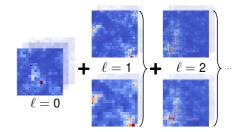
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**Epsilon-Cost Theorem:**  $\exists \{M_{\ell}\}_{\ell=0}^{L}$ , such that

$$\mathrm{err}_{\mathsf{MSE}} = \sum_{\ell=0}^L \textit{M}_{\ell}^{-1} \mathbb{V}[Y_\ell] + (\mathbb{E}[Q_L - Q])^2 < \epsilon^2$$

$$\quad \text{and} \quad T_{\epsilon} \coloneqq C_{\epsilon} \lesssim \begin{cases} \epsilon^{-2} & \beta > \gamma \\ \epsilon^{-2 - (\gamma - \beta)/\alpha} & \beta < \gamma \end{cases}$$

M. Giles. Multilevel Monte Carlo path simulation. (2008)



**Goal:** Replace accuracy  $\epsilon$  by budget  $|\mathcal{P}| \cdot T_B =: B > 0$  measured in  $[B] = \#\mathsf{CPU} \cdot \mathsf{hours}$ 



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#### **Motivation:**

- Often no a priori knowledge about  $\alpha$ ,  $\beta$  and  $\gamma$
- lacktriangledown  $\mathcal{P}$  and  $T_B$  have to be reserved for HPC
- Empirical study of algorithms



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$$\begin{aligned} & \min_{(L,\{M_\ell\}_{\ell=0}^L)} & & \operatorname{err}_{\mathsf{MSE}} = \sum_{\ell=0}^L M_\ell^{-1} \mathbb{V}[\mathbf{Y}_\ell] + (\mathbb{E}[\mathbf{Q}_L - \mathbf{Q}])^2 \\ & \text{such that} & & \sum_{\ell=0}^L \sum_{m=1}^{M_\ell} \mathbf{C}_\ell(\mathbf{y}^{(m)}) \leq \mathbf{B} \end{aligned}$$



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### Conjecture: For a feasible and parallel execution, it is

$$\begin{split} \epsilon \lesssim \underbrace{\left(1 - \lambda_p\right) \cdot T_B^{-\delta}}_{=:\epsilon_s} + \underbrace{\lambda_p(|\mathcal{P}| \cdot T_B)^{-\delta}}_{=:\epsilon_p} \end{split}$$
 with  $\delta \in \left\{\frac{1}{2}, \frac{\alpha}{(2\alpha + (\gamma - \beta))}\right\}$  and  $\lambda_p \in [0, 1]$ .

Baumgarten et al. A Fully Parallelized and Budgeted MLMC Method. arXiv Preprint (2023)

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- Decomposition in overlapping subproblems
- Solve subproblems with optimal strategy
- Reutilization of preexisting results



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⇒ Use DP for approximated knapsack problem



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#### **Approximated Knapsack Problem:**

$$\begin{aligned} & \min_{\substack{(L,\{M_\ell\}_{\ell=0}^L)}} & & \sum_{\ell=0}^L M_\ell^{-1} s_{\mathrm{Y}_\ell}^2 + \left(\widehat{\mathrm{err}}_{\mathsf{disc}}(\widehat{\mathrm{Y}}_\ell,\widehat{\alpha})\right)^2 \\ & \text{such that} & & \sum_{\ell=0}^L M_\ell \widehat{\mathrm{C}}_\ell \leq \mathrm{B} \end{aligned}$$

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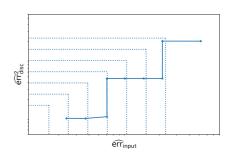
### **Dynamic Programming (DP):**

- Decomposition in overlapping subproblems
- Solve subproblems with optimal strategy
- Reutilization of preexisting results
- ⇒ Use DP for approximated knapsack problem



## **Budgeted Multi-level Monte Carlo - Algorithm**

$$\begin{split} & \text{data} = \left\{ i \mapsto \left\{ \text{err}_i, \left\{ M_{i,\ell} \right\}_{\ell=0}^{L_i}, \left\{ \widehat{Q}_{i,\ell} \right\}_{\ell=0}^{L_i}, \left\{ \widehat{C}_{i,\ell} \right\}_{\ell=0}^{L_i}, \left\{ \widehat{Y}_{i,\ell} \right\}_{\ell=0}^{L_i}, \dots \right\} \right\} \\ & \text{function BMLMC}(B_0, \left\{ M_{0,\ell}^{\text{init}} \right\}_{\ell=0}^{L_0}) \colon \\ & \left\{ \text{for } \ell = L_0, \dots, 0 \colon & \Delta \text{data}_{0,\ell} \leftarrow \text{MS-FEM}(M_{0,\ell}^{\text{init}}, \mathcal{P}) \\ \text{data}_0 \leftarrow \text{Welford}(\text{data}_{-1}, \Delta \text{data}_0) & \text{return BMLMC}(B_0 - \sum_{\ell=0}^{L_0} C_\ell, \eta \cdot \text{err}_0) \right\} \\ & \text{function BMLMC}(B_i, \epsilon_i) \colon \\ & \left\{ \begin{aligned} & \text{if } B_1 & \approx 0 \colon & \text{return err}_{i-1} \\ & \text{if } \widehat{\text{err}}_{\text{disc}}(\text{data}_{i-1}) \geq \sqrt{1-\theta} \epsilon_i \colon & L_i \leftarrow L_i + 1 \\ & \text{if } \widehat{\text{err}}_{\text{input}}(\text{data}_{i-1}) \geq \theta \epsilon_i^2 \colon & \widehat{M}_{i,\ell}^{\text{opt}} \sim \left[ (\sqrt{\theta} \epsilon)^{-2} \sqrt{s_{Y_\ell}^2 / \widehat{C}_\ell} \right] \\ & \text{for } \ell = L_i, \dots, 0 \colon & \Delta M_{i,\ell} \leftarrow \max \left\{ \widehat{M}_{i,\ell}^{\text{opt}} - M_{i-1,\ell}, 0 \right\} \\ & \widehat{C}_i \leftarrow \sum_{\ell=0}^{L_1} \Delta M_{i,\ell} \widehat{C}_{i-1,\ell} \\ & \text{if } \widehat{C}_i = 0 \colon & \text{return BMLMC}(B_i, \eta \cdot \epsilon_i) \\ & \text{if } \widehat{C}_i > B_i \colon & \text{return BMLMC}(B_i, 0.5 \cdot (\epsilon_i + \epsilon_{i-1})) \\ & \text{for } \ell = L_1, \dots, 0 \colon & \Delta \text{data}_{i,\ell} \leftarrow \text{MS-FEM}(\Delta M_{i,\ell}, \mathcal{P}) \\ & \text{data}_i \leftarrow \text{Welford}(\text{data}_{i-1}, \Delta \text{data}_i) & \text{return BMLMC}(B_i - \sum_{\ell=0}^{L_i} C_\ell, \epsilon_i) \end{aligned} \end{aligned}$$



M. Giles. Multilevel Monte Carlo methods. (2015)
 Collier et al. A continuation multilevel Monte Carlo algorithm. (2015)



**Problem:** Approximate  $M_\ell$ -times a PDE on discretization level  $\ell$  on a fixed set of CPUs  $\mathcal{P}$ 

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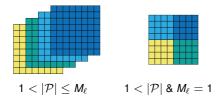


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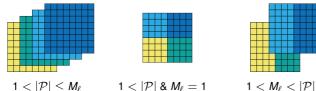


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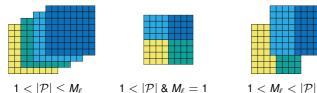


$$<|\mathcal{P}|$$
 &  $M_{\ell}=$ 

$$1 < M_{\ell} < |\mathcal{P}|$$



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$$M_{\ell}=1$$

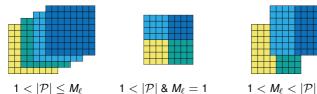
**Minimize Communication:** Search  $k \in \mathbb{N}_0$ , such that

$$2^k \leq \frac{|\mathcal{P}|}{M_\ell} < 2^{k+1} \implies \mathcal{P} = \bigsqcup_{m=1}^{M_\ell} \mathcal{P}_k^{(m)} \text{ with } \left| \mathcal{P}_k^{(m)} \right| = 2^k$$





**Problem:** Approximate  $M_\ell$ -times a PDE on discretization level  $\ell$  on a fixed set of CPUs  $\mathcal{P}$ 







**Define:** Set of FE meshes

$$\mathcal{M}_{\mathcal{P}} \coloneqq \left\{\mathcal{M}_{\mathcal{P}_k}^{(m)}
ight\}_{m=1}^{M_\ell}$$

**Minimize Communication:** Search  $k \in \mathbb{N}_0$ , such that

$$2^k \le \frac{|\mathcal{P}|}{M_\ell} < 2^{k+1} \ \Rightarrow \ \mathcal{P} = \bigsqcup_{m=1}^{M_\ell} \mathcal{P}_k^{(m)} \text{ with } \left| \mathcal{P}_k^{(m)} \right| = 2^k$$

**MS-FEM:** Search for representation of

$$(\mathbf{u}_\ell)_{m=1}^{M_\ell} \in \prod_{m=1}^{M_\ell} V_\ell^{(m)}$$

defined on  $\mathcal{M}_{\mathcal{D}}$ 



### **Model Problem and Discretization**

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Discontinuous Galerkin (dG): Search for 
$$(\mathbf{v}, p)^{\top} =: \mathbf{u}_{\ell} \in V_{\ell, \mathbf{p}}^{\mathrm{dG}}$$

$$M_\ell \partial_t \mathbf{u}_\ell + A_\ell \mathbf{u}_\ell = \mathbf{b}_\ell$$
 and  $\mathbf{u}_\ell(\mathbf{0}) = \mathbf{u}_{\ell,\mathbf{0}}$ 

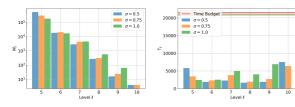
**Implicit midpoint-rule (IMPR):** Solve for 
$$t_n = n\tau_\ell$$
 with  $\tau_\ell = T/N_\ell^\tau$ 

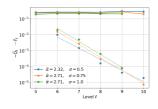
$$\left(\mathrm{M}_{\ell} + \frac{\tau_{\ell}}{2}\mathrm{A}_{\ell}\right)\mathbf{u}_{\ell}(\mathit{t}_{n}) = \left(\mathrm{M}_{\ell} - \frac{\tau_{\ell}}{2}\mathrm{A}_{\ell}\right)\mathbf{u}_{\ell}(\mathit{t}_{n-1}) + \tau_{\ell}\mathbf{b}_{\ell}(\mathit{t}_{n-1/2})$$

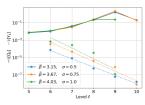
Circulant Embedding: Sample from log-normally distributed material density  $\rho$ 

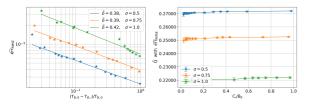
# Numerical Experiments - Covariance Function











#### **Covariance Function:**

$$\mathsf{Cov}(\mathbf{x}_1, \mathbf{x}_2) = \sigma^2 \exp\left(-\left\|\left(\frac{\mathbf{x}_1 - \mathbf{x}_2}{\lambda}\right)\right\|_2^{\nu}\right)$$

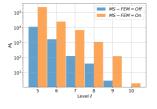
with  $\lambda =$  0.15,  $\nu =$  1.8 and  $\sigma \in \{$ 0.5, 0.75, 1.0 $\}$ 

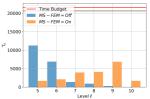
# Numerical Experiments - Parallelization



### 1st Experiment:

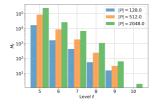
■ Solver parallelization vs. MS-FEM with fixed B = 2048 · 6h

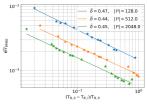




### 2<sup>nd</sup> Experiment:

■ Weak scaling measurement with  $T_B = 6h$  on  $|\mathcal{P}| \in \{128, 512, 2048\}$ 







### **Recall of Algorithm & Umbridge Client Interface**

```
\mathsf{data} = \left\{ \mathtt{i} \mapsto \left\{ \mathsf{err}_{\mathtt{i}}, \{ \textit{M}_{\mathtt{i},\ell} \}_{\ell=0}^{\mathit{L}_{\mathtt{i}}}, \{ \widehat{\mathsf{Q}}_{\mathtt{i},\ell} \}_{\ell=0}^{\mathit{L}_{\mathtt{i}}}, \{ \widehat{\mathsf{C}}_{\mathtt{i},\ell} \}_{\ell=0}^{\mathit{L}_{\mathtt{i}}}, \{ \widehat{\mathsf{Y}}_{\mathtt{i},\ell} \}_{\ell=0}^{\mathit{L}_{\mathtt{i}}}, \ldots \right\} \right\}
  function BMLMC(B<sub>0</sub>, \{M_{0,\ell}^{\text{init}}\}_{\ell=0}^{L_0}):
                  \begin{cases} \text{for } \ell = L_0, \dots, 0: & \Delta \text{data}_{0,\ell} \leftarrow \text{MS-FEM}(M_0^{\text{init}}, \mathcal{P}) \\ \text{data}_0 \leftarrow \text{Welford}(\text{data}_{-1}, \Delta \text{data}_0) & \text{return BMLMC}(B_0 - \sum_{\ell=0}^{L_0} C_\ell, \eta \cdot \text{erro}) \end{cases} 
  function BMLMC(B_i, \epsilon_i):
                \begin{cases} \text{if } B_i \approx 0: & \text{return } \text{err}_{i-1} \\ \text{if } \widehat{\text{err}}_{\text{disc}}(\text{data}_{i-1}) \geq \sqrt{1-\theta} \epsilon_i: & L_i \leftarrow L_i + 1 \\ \text{if } \widehat{\text{err}}_{\text{input}}(\text{data}_{i-1}) \geq \theta \epsilon_i^2: & \widehat{M}_{i,\ell}^{\text{opt}} \sim \left[ (\sqrt{\theta} \epsilon)^{-2} \sqrt{s_{i_\ell}^2/\widehat{C}_\ell} \right] \\ \text{for } \ell = L_i, \ldots, 0: & \Delta M_{i,\ell} \leftarrow \max \left\{ \widehat{M}_{i,\ell}^{\text{opt}} - M_{i-1,\ell}, 0 \right\} \end{cases} \\ \widehat{C}_i \leftarrow \sum_{\ell=0}^{L_i} \Delta M_{i,\ell} \widehat{C}_{i-1,\ell} \\ \text{if } \widehat{C}_i = 0: & \text{return } \text{BMLMC}(B_1, \eta \cdot \epsilon_i) \end{cases} \\ \text{if } \widehat{C}_i > B_i: & \text{return } \text{BMLMC}(B_1, 0.5 \cdot (\epsilon_i + \epsilon_{i-1})) \end{cases} \\ \text{for } \ell = L_i, \ldots, 0: & \Delta \text{data}_{i,\ell} \leftarrow \text{MS-FEM}(\Delta M_{i,\ell}, \mathcal{P}) \end{cases} 
                                                                                                                                                                                                                                                           return BMLMC(B<sub>i</sub> - \sum_{\ell=0}^{L_i} C_{\ell}, \epsilon_i)
```

```
#ifdef UMBRIDGE CLIENT
     umbridge::HTTPModel client(
         "http://localhost:4242", "forward"
     );
 #else
   std::unique_ptr<PDESolver> pdeSolver =
     CreatePDESolverUnique(slEstmConf.pdeSolvConf.
           WithCommSplit(commSplit)):
 #endif
 // Only code snippet, more stuff happening here
 #ifdef UMBRIDGE CLIENT
     fineSolution.Q = client.Evaluate(input);
 if (!slEstmConf.onlvFine)
         coarseSolution.0 = client.Evaluate(input):
#else
     // Solves PDE for several samples in parallel
     fineSolution = pdeSolver->Run(input);
    if (!slEstmConf.onlyFine)
         coarseSolution = pdeSolver->Run(input):
 #endif
 // Only code snippet, more stuff happening here
```



### Umbridge Server Interface & M++

```
#include "AcousticPDESolver"
#include "umbridge.h"
class AcousticPDESolver4Umbridge: public AcousticPDESolver, public umbridge::Model {
public:
  explicit AcousticPDESolver4Umbridge(const PDESolverConfig &conf)
      : AcousticPDESolver(conf), umbridge::Model("forward") {}
  std::vector<std::size_t> GetInputSizes(const json &confiq_json) const override {
    return {static_cast<unsigned long>(GetProblem().StochasticDimension())}:
  std::vector<std::size_t> GetOutputSizes(const_ison &config_ison) const_override {
    return {1}; // Always one since only a QoI is returned
  std::vector<std::vector<double>> Evaluate(const std::vector<std::vector<double>> &
        inputs, json json_config) override {
    PPM->Broadcast(inputs): // WIP
    GetProblem().SetSample(inputs);
    return {{Run(),0}}:
};
```



https://gitlab.kit.edu/kit/mpp/mpp

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15 16

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### **Conclusion and Outlook**

#### Conclusion:

Budgeted Multi-level Monte Carlo (BMLMC)





### **Conclusion and Outlook**

#### Conclusion:

Budgeted Multi-level Monte Carlo (BMLMC)



Multi-Sample Finite Element Method (MS-FEM)

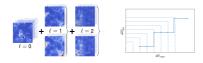




### **Conclusion and Outlook**

#### Conclusion:

Budgeted Multi-level Monte Carlo (BMLMC)



■ Multi-Sample Finite Element Method (MS-FEM)



Acoustic Wave Simulations in Random Media

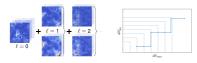


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### **Conclusion and Outlook**

#### Conclusion:

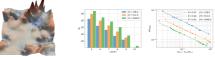
Budgeted Multi-level Monte Carlo (BMLMC)



Multi-Sample Finite Element Method (MS-FEM)



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#### **Further Work:**

- Other PDEs with various FE&UQ methods
  - N. Baumgarten. A Fully Parallelized and Budgeted Multi-level Monte Carlo Framework for Partial Differential Equations: From Mathematical Theory to Automated Large-Scale Computations. (2023) Baumgarten, Wieners. The parallel finite element system M++ with integrated multilevel preconditioning and multilevel Monte Carlo methods. (2021)
- FEM-Software M++ & Main Source of Talk
  Wieners. Corallo. Schneiderhan. Stengel. Lindner. Rheinbay Baumgarten. Mpg 3.2.0. (2023)

Baumgarten et al. A Fully Parallelized and Budgeted Multi-level Monte Carlo Method and the Application to Acoustic Waves. arXiv Preprint (2023)

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#### Conclusion:

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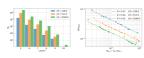


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  Baumgarten et al. A Fully Parallelized and Budgeted Multi-level Monte Carlo Method and the Application to Acoustic Waves. arXiv Preprint (2023)

#### In Progress / Outlook / Interests:

- Interface to Umbridge
- (B)MLSC, (B)MLQMC, (B)MIMC
- Implementation of û<sub>L</sub> in Mpp 3.2.1
- SGD/ADAM for Optimal Control
- Bayesian Inverse UQ via SMC