
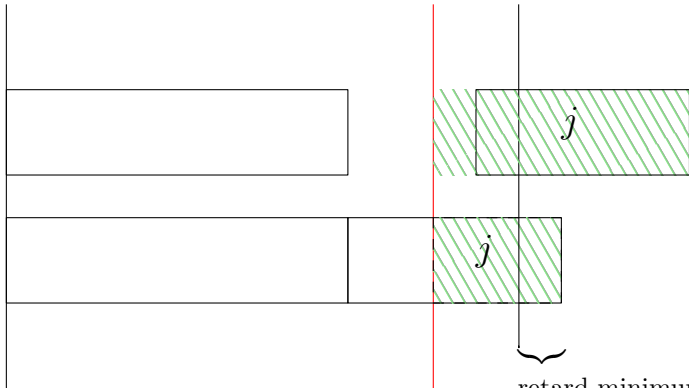


$r(S)$ d_j d_s  = retard de j 

avec “trous”
 $L_j = c_j - d_j$

sans “trous”

retard minimum
 $r(S) + p(S) - d(S)$