

What is System?

- Systems process input signals to produce output signals
- A system is combination of elements that manipulates one or more signals to accomplish a function and produces some output.



Types of Systems

- Causal & Anticausal
- Linear & Non Linear
- Time Variant & Time-invariant
- Stable & Unstable
- Static & Dynamic
- Invertible & Inverse Systems

Causal & Anticausal Systems

- Causal system : A system is said to be *causal* if the present value of the output signal depends only on the present and/or past values of the input signal.
- Example: $y[n] = x[n] + 1/2x[n-1]$

Causal & Anticausal Systems Contd.

- Anticausal system : A system is said to be *anticausal* if the present value of the output signal depends only on the future values of the input signal.
- Example: $y[n] = x[n+1] + 1/2x[n+1]$

Linear & Non Linear Systems

- A system is said to be linear if it satisfies the principle of superposition
- For checking the linearity of the given system, firstly we check the response due to linear combination of inputs
- Then we combine the two outputs linearly in the same manner as the inputs are combined and again total response is checked
- If response in step 2 and 3 are the same, the system is linear otherwise it is non linear.

Time Invariant and Time Variant Systems

- A system is said to be *time invariant* if a time delay or time advance of the input signal leads to a identical time shift in the output signal.

Stable & Unstable Systems

- A system is said to be *bounded-input bounded-output stable* (BIBO stable) if every bounded input results in a bounded output.

Stable & Unstable Systems Contd.

Example

$$- y[n] = 1/3(x[n] + x[n-1] + x[n-2])$$

$$\begin{aligned} y[n] &= \frac{1}{3} |x[n] + x[n-1] + x[n-2]| \\ &\leq \frac{1}{3} (|x[n]| + |x[n-1]| + |x[n-2]|) \\ &\leq \frac{1}{3} (M_x + M_x + M_x) = M_x \end{aligned}$$

Stable & Unstable Systems Contd.

Example: The system represented by

$$y(t) = A x(t) \text{ is unstable ; } A > 1$$

Reason: let us assume $x(t) = u(t)$, then at every instant $u(t)$ will keep on multiplying with A and hence it will not be bounded.

Static & Dynamic Systems

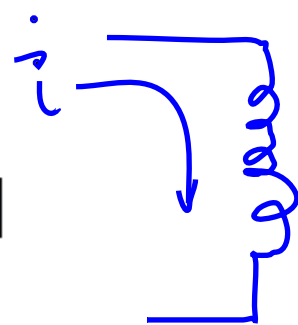
- A static system is memoryless system
 - It has no storage devices
 - its output signal depends on present values of the input signal
 - For example
- LEY DE OHM I (corriente) = V (voltaje) / R (resistencia)

$$i(t) = \frac{1}{R} v(t)$$

Sistema determinístico, sin memoria

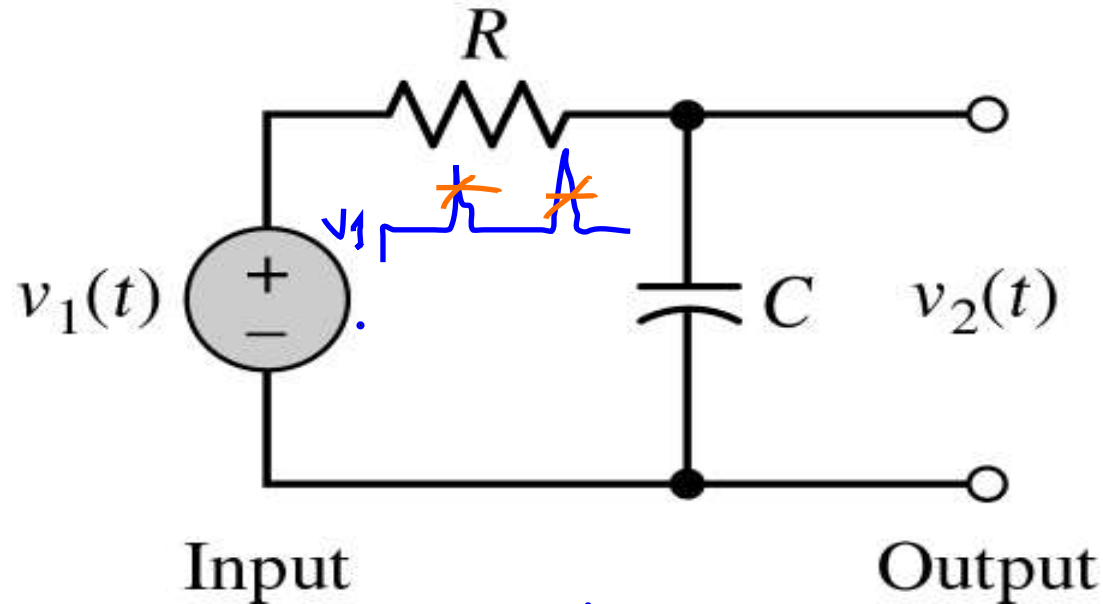
Static & Dynamic Systems Contd.

- A dynamic system possesses memory
- It has the storage devices
- A system is said to possess *memory* if its output signal depends on past values and future values of the input signal

$$i(t) = \frac{1}{L} \int_{-\infty}^t v(\tau) d\tau$$
$$y[n] = x[n] + x[n-1]$$
A hand-drawn blue circuit diagram of an inductor. It consists of a vertical coil of wire. To the left of the top of the coil, there is a horizontal line representing an input wire, and a curved arrow points from this line down into the top of the coil. To the left of the bottom of the coil, there is another horizontal line representing an output wire, connected to the bottom of the coil.

Fenómeno inductivo se opone a la variación de la corriente. Tiene memoria

Example: Static or Dynamic?



Fenómeno Capacitivo, se opone a la variación de voltaje. Tiene memoria

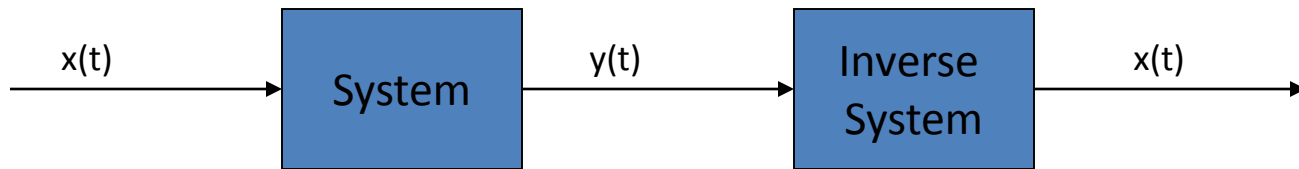
Example: Static or Dynamic?

Answer:

- The system shown above is RC circuit
- R is memoryless
- C is memory device as it stores charge because of which voltage across it can't change immediately
- Hence given system is dynamic or memory system

Invertible & Inverse Systems

- If a system is invertible it has an **Inverse System**



- Example: $y(t)=2x(t)$
 - System is invertible \rightarrow must have inverse, that is:
 - For any $x(t)$ we get a distinct output $y(t)$
 - Thus, the system must have an Inverse
 - $x(t)=1/2 y(t)=z(t)$

