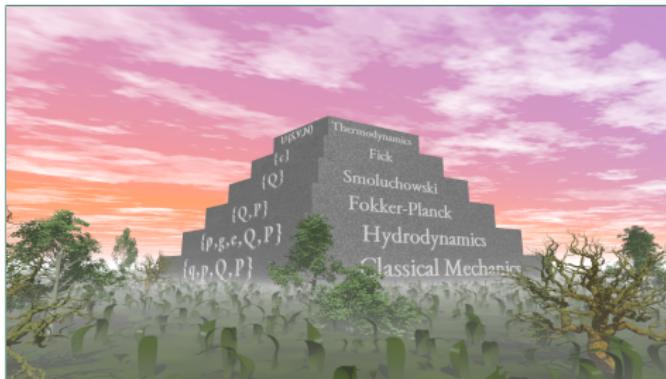


# FOLLOWING TOP-DOWN ( $\downarrow$ ) AND BOTTOM-UP ( $\uparrow$ ) APPROACHES TO DISCRETIZE NON-LINEAR STOCHASTIC DIFFUSION EQUATIONS



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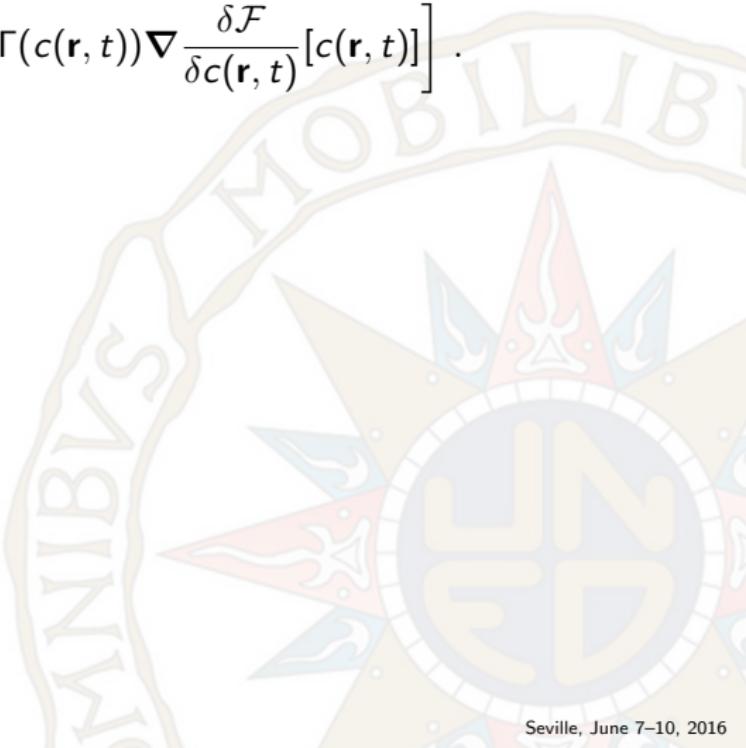


June 9<sup>th</sup>, 2016

# A Non-Linear Diffusion Equation

- ▶ Diffusion processes in softmatter are generally described by Non-Linear PDEs

$$\frac{\partial c}{\partial t}(\mathbf{r}, t) = \nabla \cdot \left[ \Gamma(c(\mathbf{r}, t)) \nabla \frac{\delta \mathcal{F}}{\delta c(\mathbf{r}, t)} [c(\mathbf{r}, t)] \right].$$



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- Landau and Lifshitz added thermal fluctuations through the divergence of a stochastic flux

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with

$$\tilde{\mathbf{J}}(\mathbf{r}, t) = \sqrt{2k_B T \Gamma[c(\mathbf{r}, t)]} \zeta(\mathbf{r}, t).$$

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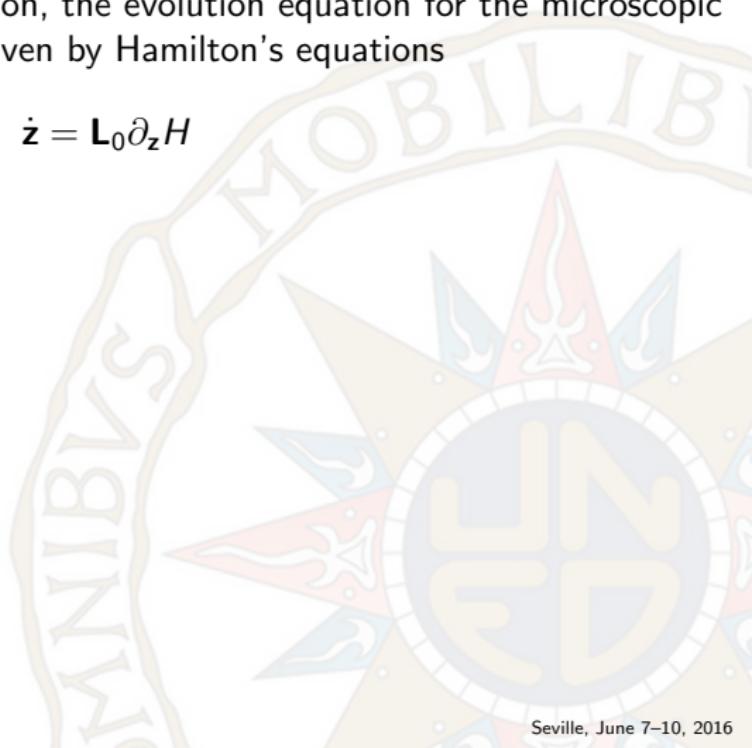
- ▶ Here,  $\delta_\mu$  is a generic smoothing kernel with support  $\mu$  that converges to a delta “function” when  $\mu \rightarrow 0$ .
- ▶ In the limit  $\mu \rightarrow 0$  (NO CG), for a dilute solution, the SPDE for  $c(\mathbf{r}, t)$  turns into

$$\frac{\partial c}{\partial t}(\mathbf{r}, t) = D\nabla^2 c + \nabla \cdot \sqrt{2Dc}\zeta(\mathbf{r}, t).$$

# Microscopic Description

- ▶ In a microscopic level of description, the evolution equation for the microscopic variables  $\mathbf{z} \equiv \{\mathbf{q}_i, \mathbf{p}_i, \mathbf{Q}_j, \mathbf{P}_j\}$  is given by Hamilton's equations

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- ▶ We define as CG variable the discrete concentration field  $\hat{\mathbf{c}}(\mathbf{z})$

$$\hat{c}_\mu(\mathbf{z}) = \sum_{i=1}^N \delta_\mu(\mathbf{r}_i)$$

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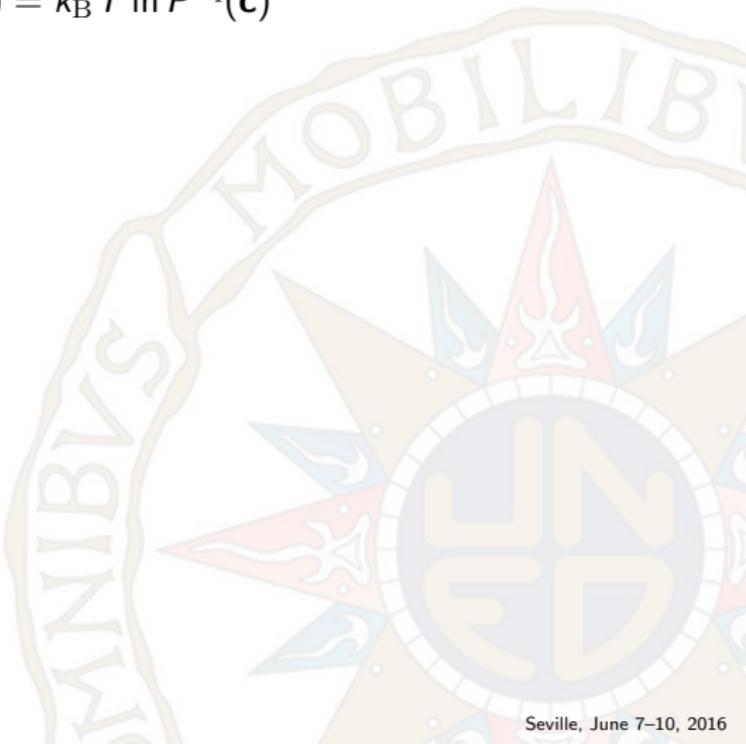
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- All the quantities involved in the SDE are defined microscopically.

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- The dissipative matrix  $\hat{\mathbf{D}}(\mathbf{c})$ , for a **infinitely diluted suspension** with a **separation of scales between positions and velocities**, is given by

$$\hat{D}_{\mu\nu} = \frac{D}{k_B T} \int d\mathbf{r} \nabla \delta_{\nu}(\mathbf{r}) \nabla \delta_{\mu}(\mathbf{r}) \langle \hat{c}_{\mathbf{r}} \rangle^{\mathbf{c}}$$

where

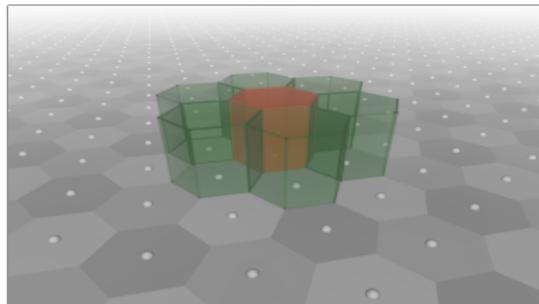
$$D = \int_0^{\infty} dt \langle \mathbf{v}_i \mathbf{v}_i(t) \rangle^{\mathbf{c}} \quad \text{and} \quad \langle \hat{c}_{\mathbf{r}} \rangle^{\mathbf{c}} = \left\langle \sum_i \delta(\mathbf{r} - \mathbf{r}_i) \right\rangle^{\mathbf{c}}$$

# Finite Elements

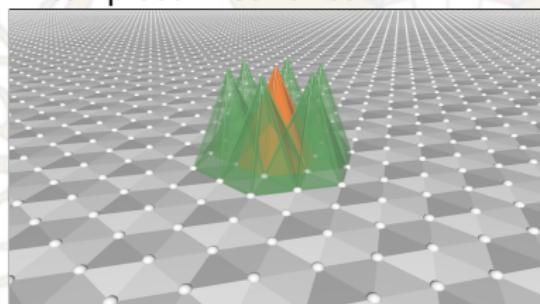
- ▶ The dissipative matrix  $\hat{\mathbf{D}}(\mathbf{c})$  shows that choosing a good definition for the finite element  $\delta_\mu(\mathbf{r})$  is a sensitive issue [P. Español & I. Zúñiga, JCP 131(16), 2009].

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- ▶ A finite element based on the Voronoi construction assigns a particle to the nearest node.



- ▶ A finite element based on the Delaunay triangulation assigns a particle to a node following a linear piece-wise function.

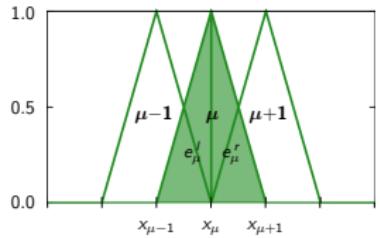


# Finite Elements

- ▶ A finite element based on the Delaunay triangulation (which is well behaved) define the discrete concentration field as

$$\hat{c}_\mu(\mathbf{r}) = \sum_{i=1}^N \delta_\mu(\mathbf{r}_i) \quad \left( \delta_\mu(\mathbf{r}) \rightarrow \frac{\psi_\mu(\mathbf{r})}{V_\mu} \right)$$

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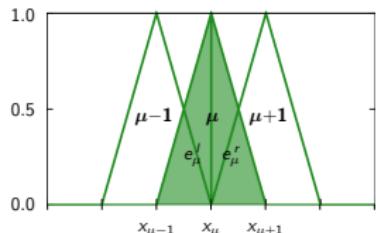
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- ▶ By using the finite element with support on the Delaunay triangulation, the SDE is explicitly written as [J. A. de la Torre & P. Español, JCP 135(11), 2011].

$$\begin{aligned}
 dc_\mu(t) = & -\frac{D}{k_B T} \sum_{\nu} \sum_{e \in \mu \nu} \mathbf{b}_{e \rightarrow \mu} \cdot \mathbf{b}_{e \rightarrow \nu} \frac{V_e}{V_\mu V_\nu} c_e \frac{\partial \hat{F}}{\partial c_\nu} dt \\
 & + D \sum_{\nu} \sum_{e \in \mu \nu} \mathbf{b}_{e \rightarrow \mu} \cdot \mathbf{b}_{e \rightarrow \nu} \frac{V_e}{V_\mu V_\nu} \frac{\partial c_e}{\partial c_\nu} dt \\
 & + \sum_{e \in \mu} \sqrt{2Dc_e V_e} \frac{1}{V_\mu} \mathbf{b}_{e \rightarrow \mu} \cdot d\mathcal{W}_e
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$$\frac{dc_\mu}{dt}(t) = - \int d\mathbf{r} \nabla \delta_\mu(\mathbf{r}) \Gamma(\bar{c}(\mathbf{r}, t)) \nabla \delta_\nu(\mathbf{r}) \frac{\partial \hat{F}}{\partial c_\nu}$$

# Thermodynamic Limit

- In the limit of **large cells**, the SDE turns into an ODE

$$\begin{aligned} dc_\mu(t) &= -\frac{D}{k_B T} \sum_{\nu} \sum_{e \in \mu\nu} \mathbf{b}_{e \rightarrow \mu} \cdot \mathbf{b}_{e \rightarrow \nu} \frac{V_e}{V_\mu V_\nu} c_e \frac{\partial \hat{F}}{\partial c_\nu} dt \\ &= - \sum_{\nu} \hat{D}_{\mu\nu} \frac{\partial \hat{F}}{\partial c_\nu} dt \end{aligned}$$

- If we define a discrete concentration field, and an interpolated concentration field (namely, a (Petrov) Galerkin discretization method)

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# Thermodynamic Limit

- The discrete evolution equations (without fluctuations)

$$\frac{dc_\mu}{dt}(t) = - \sum_\nu D_{\mu\nu} \frac{\partial F}{\partial c_\nu}$$

obtained from microscopic principles by using the ToCG, can be understood as a discrete version of the continuum equation

$$\frac{\partial c}{\partial t}(\mathbf{r}, t) = \nabla \cdot \left[ \Gamma(c(\mathbf{r}, t)) \nabla \frac{\delta \mathcal{F}}{\delta c(\mathbf{r}, t)} [c(\mathbf{r}, t)] \right].$$

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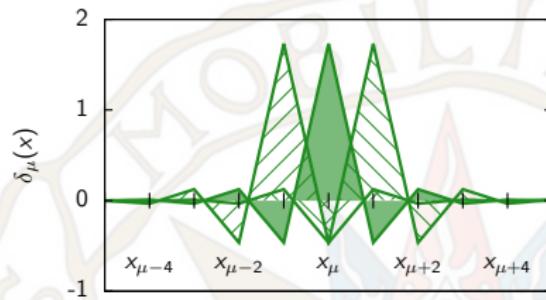
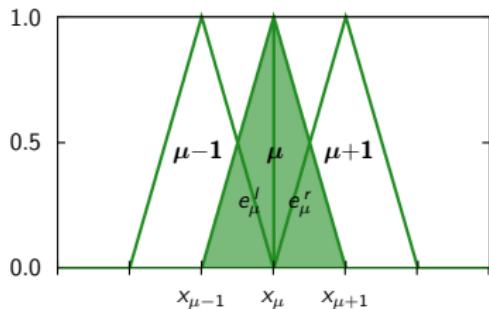
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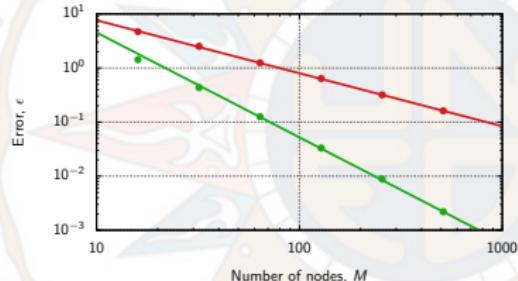
- Reciprocally, the continuum PDE can be obtained from Hamilton's equations, by using the ToCG. This is the Bottom-Up ( $\uparrow$ ) Approach [P. Español & H. Löwen, JCP 131(24), 2009].

# Conjugate Finite Elements

- Consider now  $\delta_\mu(\mathbf{r}) \rightarrow \sum_\nu M_{\mu\nu}^\delta \psi_\nu(\mathbf{r})$ , which is different from the previous definition  $\delta_\mu(\mathbf{r}) \rightarrow \psi_\mu(\mathbf{r})/V_\mu$ . [J. A. de la Torre, P. Español, & A. Donev, JCP 142(9), 2015].



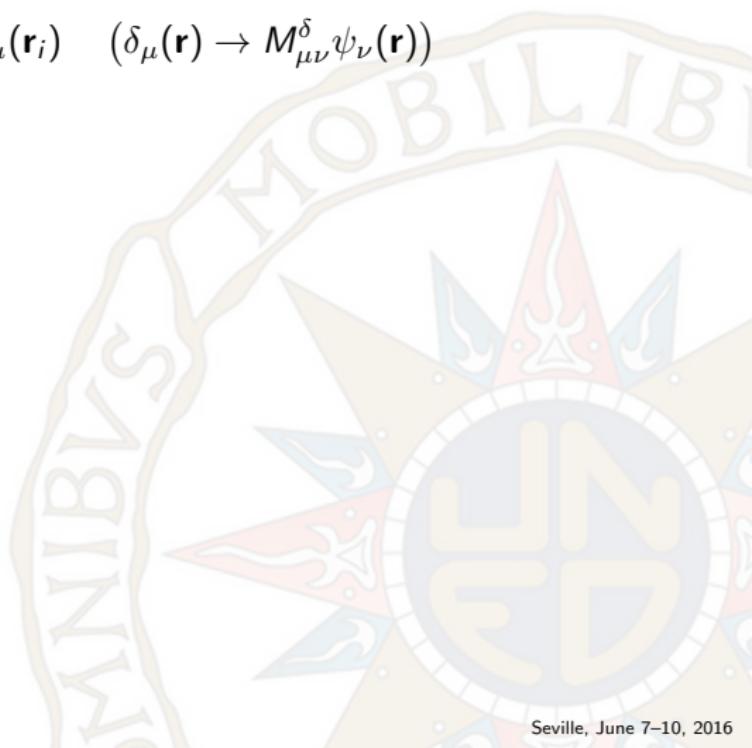
- The discretization method gives a **discrete Laplacian**  $\Delta = \mathbf{M}^\delta \mathbf{L}^\psi$ , where  $\mathbf{M}^\delta = (\delta, \delta) = (\mathbf{M}^\psi)^{-1}$  and  $\mathbf{L}^\psi = (\nabla \psi, \nabla \psi)$ .
- This discrete Laplacian gives a **second order accuracy scheme** for linearly consistent basis functions.



# Conjugate Finite Elements

- ▶ Define a **new** (conjugate) CG variable

$$\hat{c}_\mu(\mathbf{z}) = \sum_{i=1}^N \delta_\mu(\mathbf{r}_i) \quad (\delta_\mu(\mathbf{r}) \rightarrow M_{\mu\nu}^\delta \psi_\nu(\mathbf{r}))$$



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- ▶ The Bottom-Up ( $\uparrow$ ) Approach gives the SDE that governs the evolution of the CG variable

$$dc_\mu(t) = -\hat{D}_{\mu\nu}(\mathbf{c}) \frac{\partial \hat{F}}{\partial c_\nu}(\mathbf{c}) dt + k_B T \frac{\partial \hat{D}_{\mu\nu}}{\partial c_\nu}(\mathbf{c}) dt + d\tilde{c}_\mu(t)$$

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- ▶ The free energy is obtained from microscopic principles.
- ▶ The dissipative matrix is

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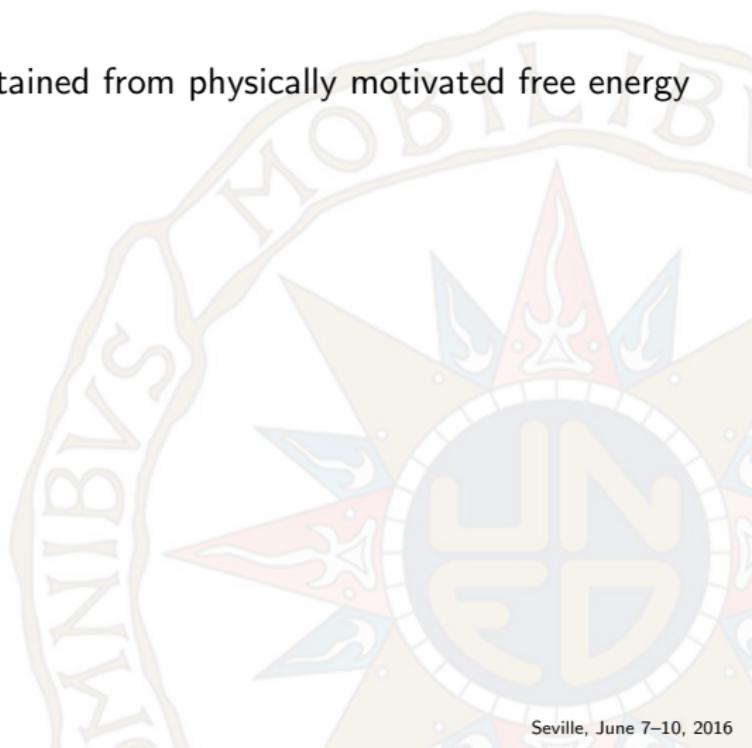
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- ▶ The dissipative matrix coincides with the one obtained in the Top-Down ( $\downarrow$ ) Approach.

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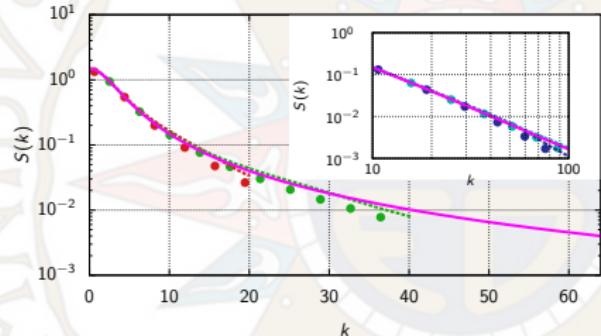
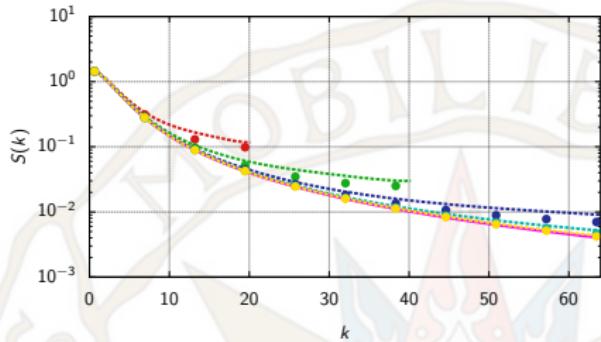
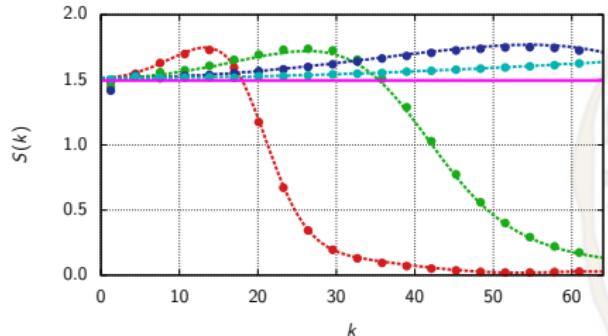
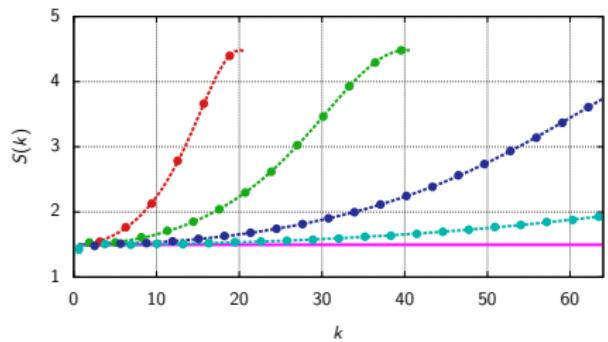
- ▶ Free energy **functions** can be obtained from physically motivated free energy **functionals**
  - ▶ Ideal Gas free energy functional → Gaussian free energy function.
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- ▶ The dissipative matrix takes the form, by assuming a constant mobility  $\Gamma(\mathbf{c})$

$$\mathbf{D} = \frac{Dc_0}{k_B T} \mathbf{L}^\delta$$

where  $L_{\mu\nu}^\delta = (\nabla \delta_\mu, \nabla \delta_\nu)$ .

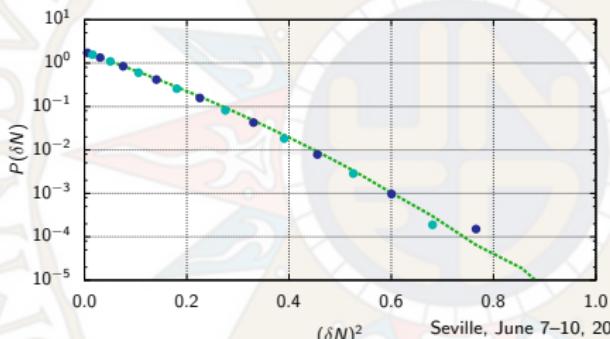
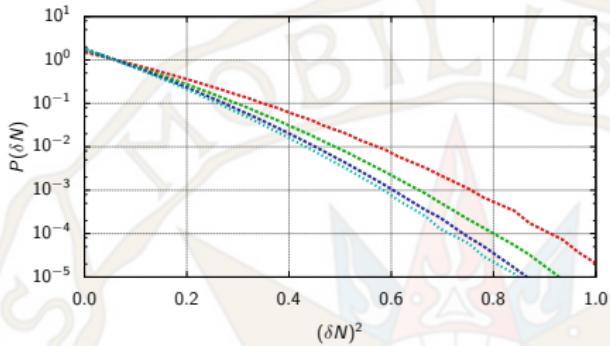
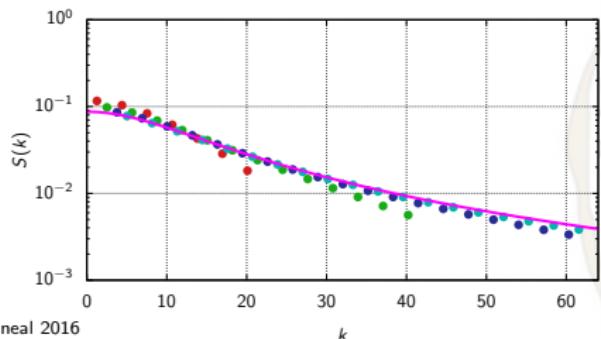
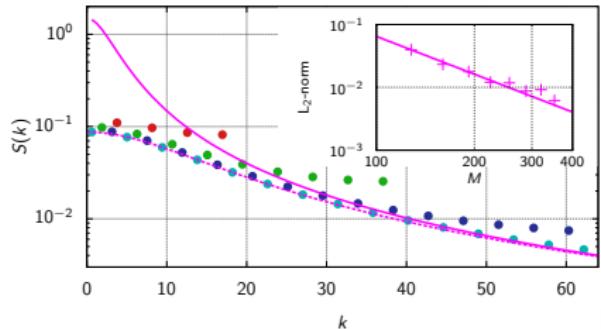
# Results – 1D

- Structure factors (discrete Fourier Transform of the matrix of covariances) in Gaussian models for **regular** (top) and **irregular** (bottom) grids



# Results – 1D

- Structure factors and probability of finding a given number of particle in a finite region, in Ginzburg-Landau models for **regular** (top) and **irregular** (bottom) grids



# Conclusions

- ▶ In 1D, Gaussian models have a continuum limit.
- ▶ In 1D, Ginzburg-Landau model also has a continuum limit.
- ▶ For  $D > 1$ , Gaussian fields are extremely rough, and should be understood as distributions (*à la* Schwartz).

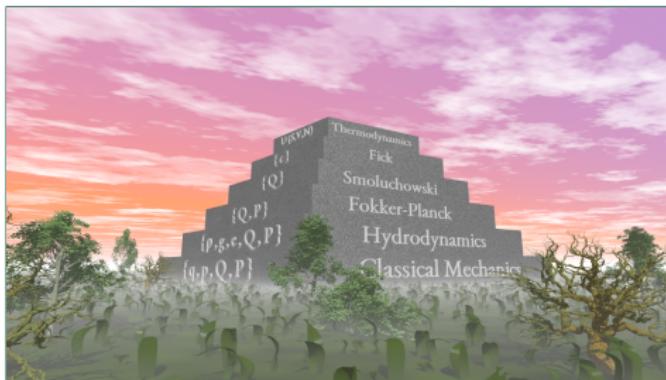
$$\langle \delta c(\mathbf{r})\delta c(\mathbf{r}') \rangle = \begin{cases} 1D & \rightarrow \frac{c_0^2 k_0}{2r_0} e^{-k_0|r-r'|} \\ 2D & \rightarrow \frac{c_0^2 k_0^2}{4\pi r_0} K_0(k_0|\mathbf{r}-\mathbf{r}'|) \\ 3D & \rightarrow \frac{c_0^2 k_0^2}{4\pi r_0} \frac{e^{-k_0|r-r'|}}{|\mathbf{r}-\mathbf{r}'|} \end{cases}$$

- ▶ Non-linear equations are not well defined.
- ▶ SPDEs can be constructed, but they do not have a physical meaning.
- ▶ In the GL model, an observable like **the fluctuations of the number of particles in a finite region depends on the resolution of the grid.**

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# FOLLOWING TOP-DOWN ( $\downarrow$ ) AND BOTTOM-UP ( $\uparrow$ ) APPROACHES TO DISCRETIZE NON-LINEAR STOCHASTIC DIFFUSION EQUATIONS



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