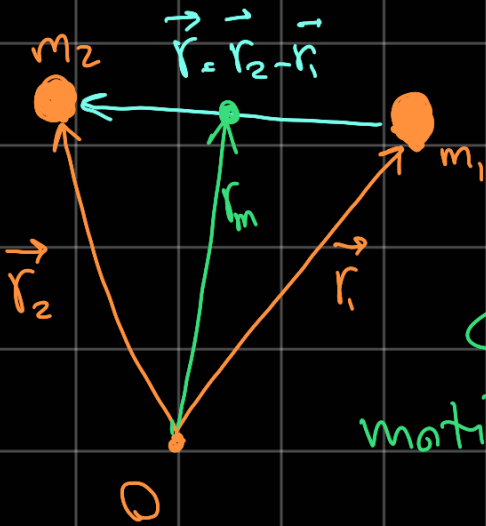


we want to derive initial conditions in which two body at gravitational interaction orbit their Center of mass in a circular motion.



let's first write the equations of motion for two particles and convert them into a single equation of motion using reduced mass.

$$m_1 \ddot{\vec{r}}_1 = \vec{F}_1 \hat{r} \quad (1); \quad m_2 \ddot{\vec{r}}_2 = -\vec{F}_2 \hat{r} \quad (2)$$

in which we have :

$$\vec{F}_i = \frac{G m_1 m_2}{r^2} \quad (4)$$

we define  $r_m$  as :

$$r_m = \frac{r_1 m_1 + r_2 m_2}{m_1 + m_2} \quad (3)$$

inserting (3) in (1), (2) results in :

$$\ddot{\vec{r}}_m = 0 \quad (5)$$

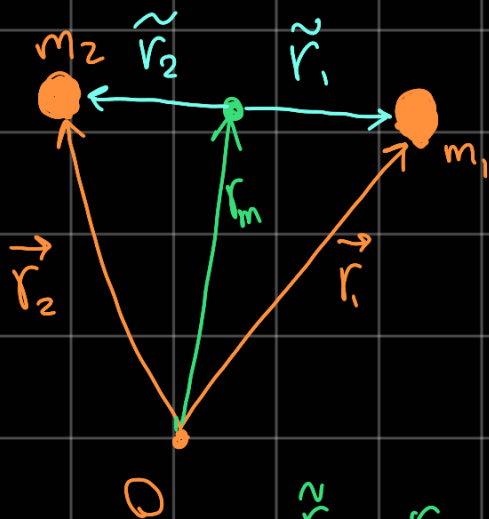
$$\begin{aligned} \rightarrow m_1 m_2 \ddot{\vec{r}} &= m_1 m_2 (\ddot{\vec{r}}_2 - \ddot{\vec{r}}_1) = m_1 (m_2 \ddot{\vec{r}}_2) - m_2 (m_1 \ddot{\vec{r}}_1) \\ &= m_1 (-\vec{F} \hat{r}) - m_2 (\vec{F} \hat{r}) \\ &= -(m_1 + m_2) \vec{F} \end{aligned}$$

⇒

$$\mu \ddot{\vec{r}} = -\frac{F}{r} \hat{r} \quad (6) ; \quad \mu = \frac{m_1 m_2}{m_1 + m_2} \quad (7)$$

So far, we reduced two equations of motion into a single one with **reduced mass**.

now let's express two original equations of motions in the **center of mass** coordinates.



$$\vec{r}_1^{\sim} = \vec{r}_1 - \vec{r}_m \quad (8) ; \quad \vec{r}_2^{\sim} = \vec{r}_2 - \vec{r}_m \quad (9)$$

inserting (3) in (8) we will have:

$$\begin{aligned} \vec{r}_1^{\sim} &= \vec{r}_1 - \vec{r}_m = \vec{r}_1 - \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{m_1 + m_2} = \frac{m_2 \vec{r}_1 - m_2 \vec{r}_2}{m} \\ &= -\frac{m_2}{m} (\vec{r}_1 - \vec{r}_2) \end{aligned}$$

$$\Rightarrow \vec{r}_1^{\sim} = -\frac{m_2}{m} \vec{r} \quad (10)$$

using same logic we can derive a similar relation for  $\vec{r}_2^{\sim}$ :

$$\vec{r}_2^{\sim} = \frac{m_1}{m} \vec{r} \quad (11)$$

now it is time to derive the initial values for velocities so that the cores maintain a circular orbit.

using (1), (4), (6) and the assumption that the cores maintain a circular motion, we can write:

$$\underbrace{\frac{m_1 m_2}{m_1 + m_2}}_A \ddot{\vec{r}} = R \hat{r} = \underbrace{\frac{G m_1 m_2}{R^2}}_B = \underbrace{\frac{m_1 v^2}{|\vec{r}_1|}}_C = \underbrace{\frac{m_2 v^2}{\vec{r}_2^2}}_D$$

$$A, B \Rightarrow \frac{G}{R^2} = \frac{1}{m_1 + m_2} = \frac{1}{m} \Rightarrow \frac{1}{m} = \frac{1}{R^2} \Rightarrow \boxed{m = R^2}$$

$$A, C \Rightarrow \frac{m_2}{m} = \frac{v^2}{|\vec{r}_1|} \Rightarrow v^2 = \frac{|\vec{r}_1| m_2}{R^2} \Rightarrow \boxed{v_1 = \frac{\sqrt{|\vec{r}_1| m_2}}{R^2}} \quad (12)$$

using same logic we can derive:

$$\boxed{v_2 = \frac{\sqrt{|\vec{r}_2| m_1}}{R^2}} \quad (13)$$

So I will use (10), (11), (12), (13) as initial values

$$\vec{r}_1 = \left( -\frac{m_2}{m} r, 0, 0 \right); \quad \vec{r}_2 = \left( \frac{m_1}{m} r, 0, 0 \right); \quad \vec{v}_1 = (0, -v_1, 0); \quad \vec{v}_2 = (0, v_2, 0)$$