UNITElectronics

BMM150

Magnetometer BMM150

v1.0 2025-07-17 Rev. A

Professional electronic component

PRODUCT OVERVIEW

The BMM150 is a triaxial digital geomagnetic sensor optimized for low-power, high-precision applications. Engineered by Bosch Sensortec, it provides absolute magnetic field measurements along the X, Y, and Z axes, suitable for electronic compassing and inertial navigation tasks. The device integrates seamlessly via I²C or SPI, ensuring compatibility with a wide range of host controllers, including Arduino, ESP32, and Raspberry Pi. Its compact form factor and minimal power profile make it ideal for space- and energy-constrained systems such as wearables, mobile robotics, and UAVs. Built-in compensation algorithms correct soft-iron and hard-iron distortions, supporting reliable heading estimation in real-world environments. When used in conjunction with accelerometers and gyroscopes, the BMM150 enables robust 9DoF sensor fusion for advanced motion tracking and orientation systems.

PRODUCT VIEWS

TOP VIEW

Top View

Bottom View

Bottom View

Component placement and connectors

Underside components and connections

KEY TECHNICAL SPECIFICATIONS

POWER SUPPLY

Operating Voltage: 3.3V

Supply Current: 170µA CONNECTIVITY

Interfaces: I2C, SPI

Qwiic + Pin Headers Connector:

TECHNICAL FEATURES

Axes: 3 (X, Y, Z)

Resolution: ~0.3 µT

Interfaces: I2C and SPI

Input Voltage via VCC Pin: 3.6-6.0 V (through onboard voltage regulator)

Additional Signals:

INT (Programmable Interrupt)

Measurement Range: $\pm 1300~\mu T$

Power Consumption: Ultra-low power consumption for battery-

operated devices

Operating Voltage (VDD / VDDIO): 3.3 V (regulated internal voltage

for sensor operation)

Operating Temperature: Wide operating range suitable for various

environments

DRDY (Data Ready)

TECHNICAL SPECIFICATIONS

TYPICAL APPLICATIONS

APPLICATION	DESCRIPTION
Electronic Compass	Detects Earth's magnetic field to determine the device orientation.
Inertial Navigation (INS)	Integrates with accelerometers and gyroscopes to improve position and orientation estimation.
Augmented Reality (AR)	Dynamically adjusts AR content on smart devices based on precise orientation data.
Metal Detection / Proximity Sensing	Monitors magnetic field variations to detect metallic objects and machinery anomalies.
Mobile Robotics and Drones	Provides reliable heading information, essential for indoor navigation and autonomous operation.
Wearables and Portable Devices	Enhances personal navigation in smartwatches, fitness trackers, and other portable devices.
Indoor Geolocation	Improves indoor positioning accuracy by compensating for sensor drift and interference.

HARDWARE DOCUMENTATION

MECHANICAL DIMENSIONS



Physical dimensions and mounting specifications (measurements in millimeters)

SYSTEM TOPOLOGY



Connection topology and system integration diagram

Click image to open in full size

COMPONENT REFERENCE REF. **DESCRIPTION** IC1 BMM150 Magnetometer U1 AP2112K 3V3 Regulator L1 Power On LED SW1 Dip Switch for Mode and Address Selector QWIIC Connector (JST 1mm for I2C) J1 J2 QWIIC Connector (JST 1mm for I2C) J3 JST Connector 1mm Pitch for SPI JP1 2.54mm Castellated Holes

CIRCUIT SCHEMATIC



Complete circuit schematic showing all component connections

View Complete Schematic PDF

PIN DESCRIPTION

Detailed pin assignment and electrical specifications

SIGNAL DESCRIPTION DESCRIPTION SIGNAL VCC Power supply GND Ground SCL I²C clock SDA I2C data SDO / ADDR SPI MISO / I²C address select CS SPI chip-select (active LOW) / must be HIGH for I²C mode Protocol select (LOW=I2C, HIGH=SPI) PS DRDY Data-Ready flag (new data available) INT Programmable interrupt output (e.g. threshold, flip-over)

PIN CONFIGURATION LAYOUT

Physical connector layout and pin positioning



Pin Configuration Layout

Complete pin configuration diagram showing all connectors, pin assignments, and electrical connections for proper integration

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