

2024-02-19T10:00/12:30 (20 min.) @Chiyoda Campus, Hitotsubashi University Geospatial Technology for Multifaceted Crisis: Real-time Crisis Mapping and Long-term Trend Analysis

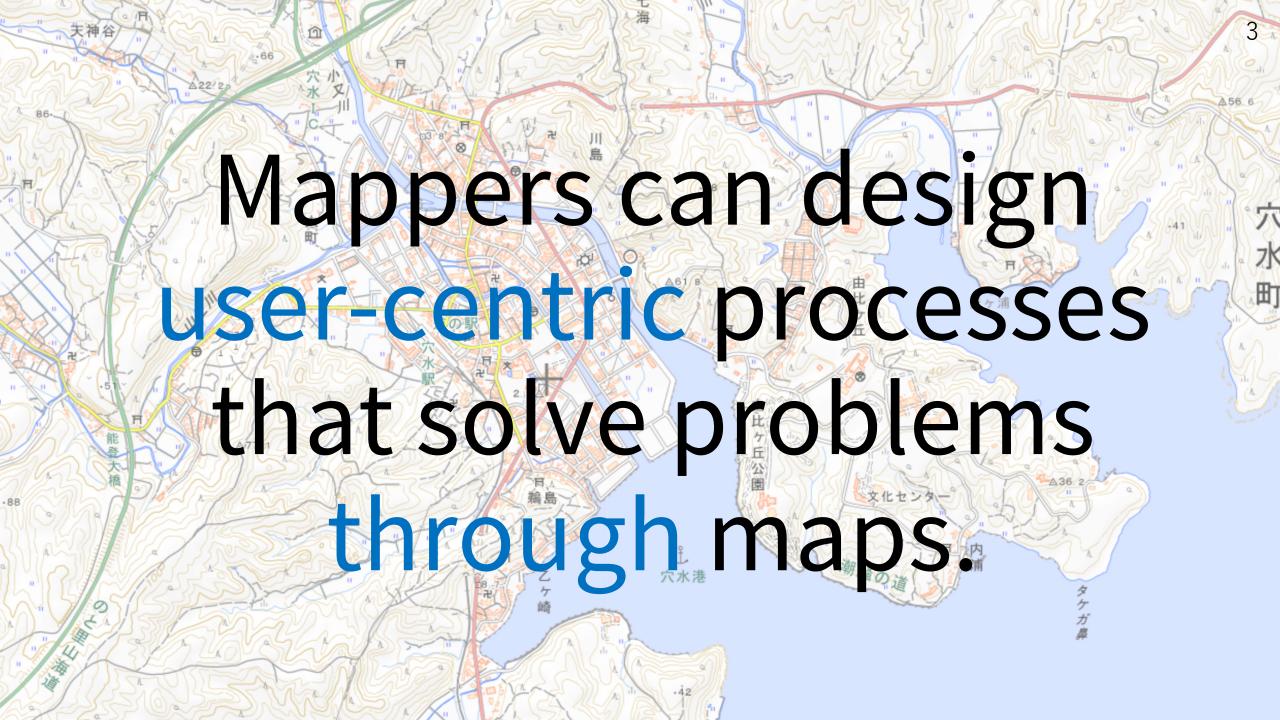
Sensemaking with Smart Maps

Hidenori Fujmura

Lead, UN Smart Maps Group, UN Open GIS Initiative

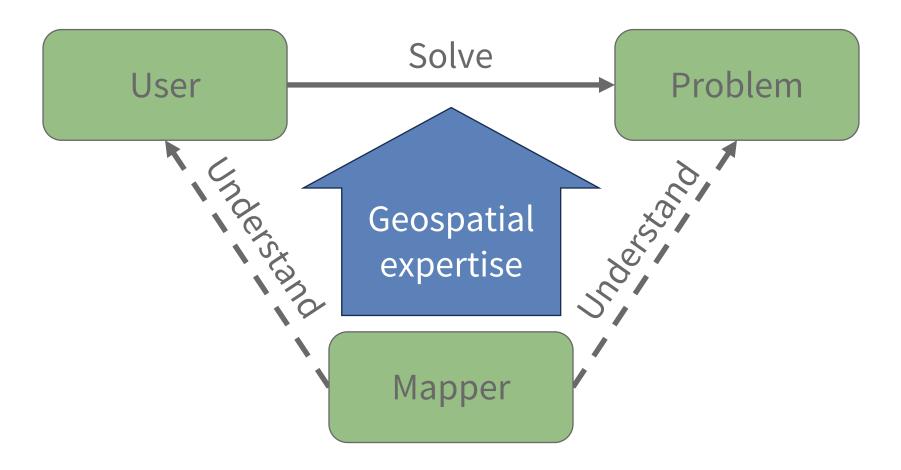
Director, Research Planning, Geography and Crustal Dynamics Research Center, Geospatial Information Authority of Japan







Partnership through geospatial information

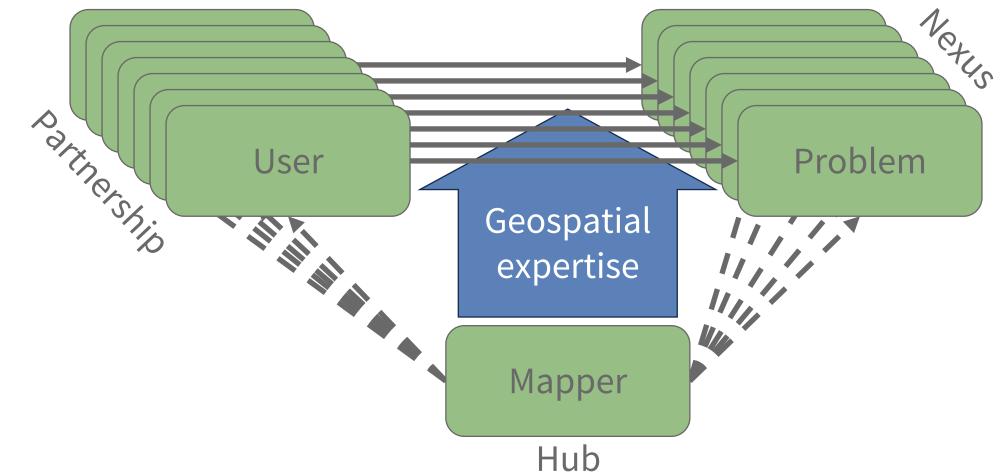


#580 of SDGs Action Plan 2023 of SDGs Promotion Headquarters, the Government of Japan (2023-03)





Mapper as a Partnership Hub



#580 of SDGs Action Plan 2023 of SDGs Promotion Headquarters, the Government of Japan (2023-03)





UN Open GIS Initiative

The UN Open GIS Initiative is an ongoing Partnership Initiative for **Technology in Peacekeeping** of United Nations Department of Operational Support. It has been running by the **United Nations Geospatial** in the Office of Information and Communications Technology (OICT), **since March 2016**.



Viable and implementable projects have been initiated since the first Partnership for Technology in Peacekeeping international symposium held in 2014 in Brindisi, - Italy. These initiatives range from quick-impact projects, which use available resources to achieve small-scale yet high-impact results, to strategic cooperation projects that look at leveraging Member States' capacities, technologies and expertise to enhance the effectiveness, efficiency, agility, and responsiveness of specific areas of field operations. Existing partnership relationships continue to thrive between the United Nations and Member States: Austria, Canada, Denmark, France, Germany, Israel, Italy, Japan, Luxembourg, Netherlands, Republic of Korea, Switzerland, the United Kingdom, and the United States of America.

UN Open GIS Initiative

UN Open GIS (Geospatial Information Systems) Initiative

Partners: Finland, Italy, Japan, Republic of Korea, United States of America

Status: Ongoing

The UN Open GIS Initiative, established in 2016, is an ongoing partnership initiative and supported by Member States, International Organizations including UN Agencies, Academia, NGOs, and the Private Sector.

The aim of UN Open GIS is the creation of an extended spatial data infrastructure by utilizing open source GIS solutions that meet the operational requirements of the United Nations (UN Secretariat including UN field missions and regional commissions). The initiative also reaches to UN agencies and operating partners, and to developing countries.

The UN Open GIS Initiative intends to provide a sustainable, hybrid GIS platform (integrating open source software GIS technology with the existing proprietary GIS platform) to effectively and efficiently support enhanced Situational Awareness and to inform decision-making. This will fulfill UN core mandates that refers to or depends on the following: geospatial information, the saving of lives and the support to emergency operations, and the enablement of cost-effective operations.

Various open source GIS solutions have been explored/assessed in the UN field operational environment, with findings of positive outcomes to move forward from the existing proprietary GIS platform toward the hybrid GIS platform. This is particularly on mobile GIS solutions (QField, KoBoToolbox, Geopaparazzi), desktop GIS solution (QGIS), OpenDroneMap, Cloud Free Satellite Imagery, and Hybrid GIS infrastructure.

To learn more, visit https://www.un.org/geospatial



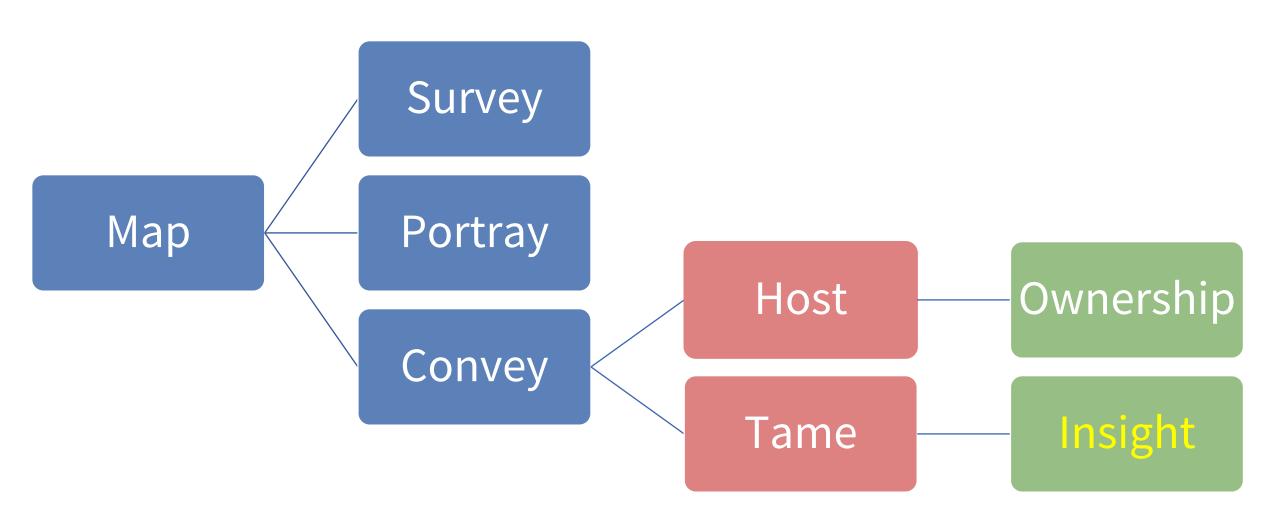
UN Smart Maps Group



- 1. Open Community of Practice. An open-source multi-sector partnership.
- 2. Vision: keep web maps open for a better world.
- 3. Mission: test new technologies for future geospatial operations.



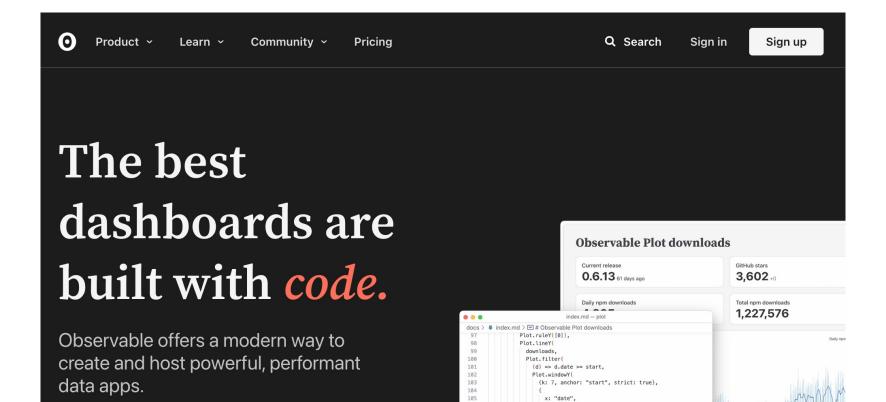
Anatomy of Mapping





Tame the data for insight.

- The purpose of visualization is **insight**, not a picture. (Ben Shneiderman)
- Someone must establish tie with (= tame) the data to create insight.
- We use interactive visualization and large language models (LLMs).





What if Smart Maps is applied to...

UCDP Georeferenced Event Dataset (GED) Global version 23.1

This dataset is UCDP's most disaggregated dataset, covering individual events of organized violence (phenomena of lethal violence occurring at a given time and place). These events are sufficiently fine-grained to be geo-coded down to the level of individual villages, with temporal durations disaggregated to single, individual days.

Available as:



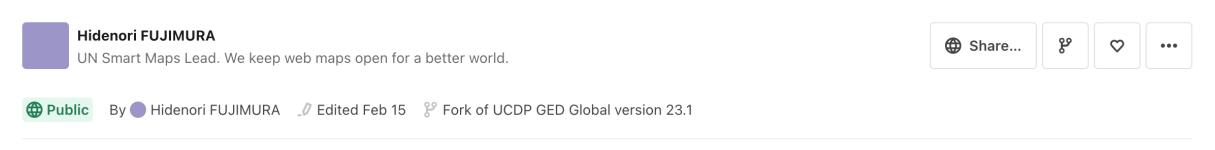
Please cite:

- Davies, Shawn, Therese Pettersson & Magnus Öberg (2023). Organized violence 1989-2022 and the return of conflicts between states?. Journal of Peace Research 60(4).
- Sundberg, Ralph and Erik Melander (2013) Introducing the UCDP Georeferenced Event Dataset. Journal of Peace Research 50(4).



Interactive Mapping of UCDP GED

https://observablehq.com/d/8c1b592ba7abe90d

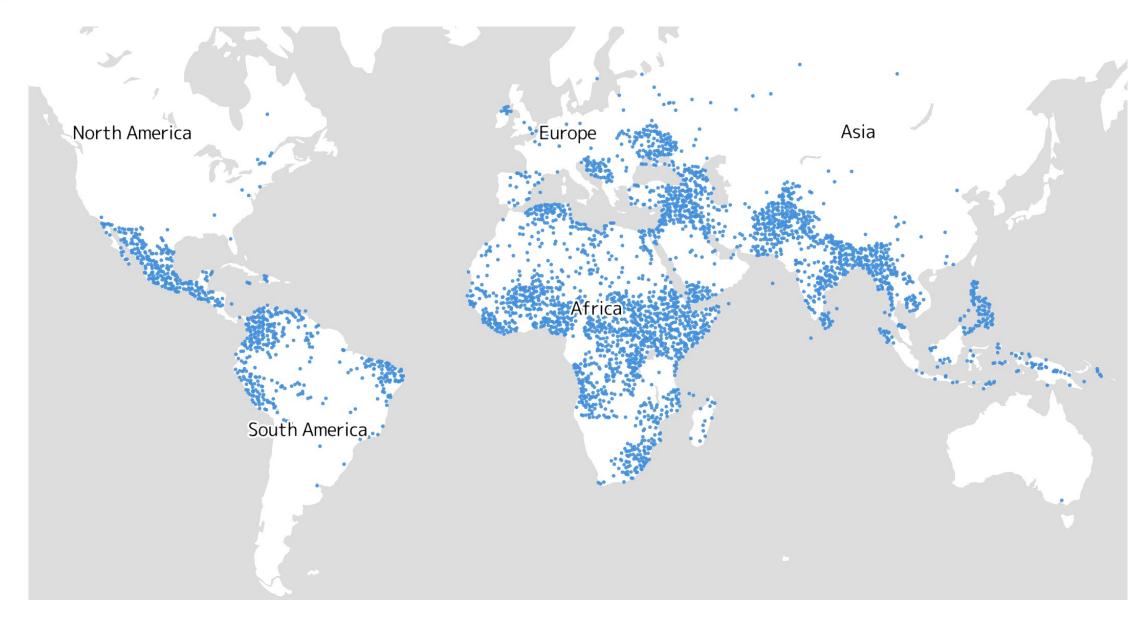


(cf-ipfs) UCDP GED Global version 23.1

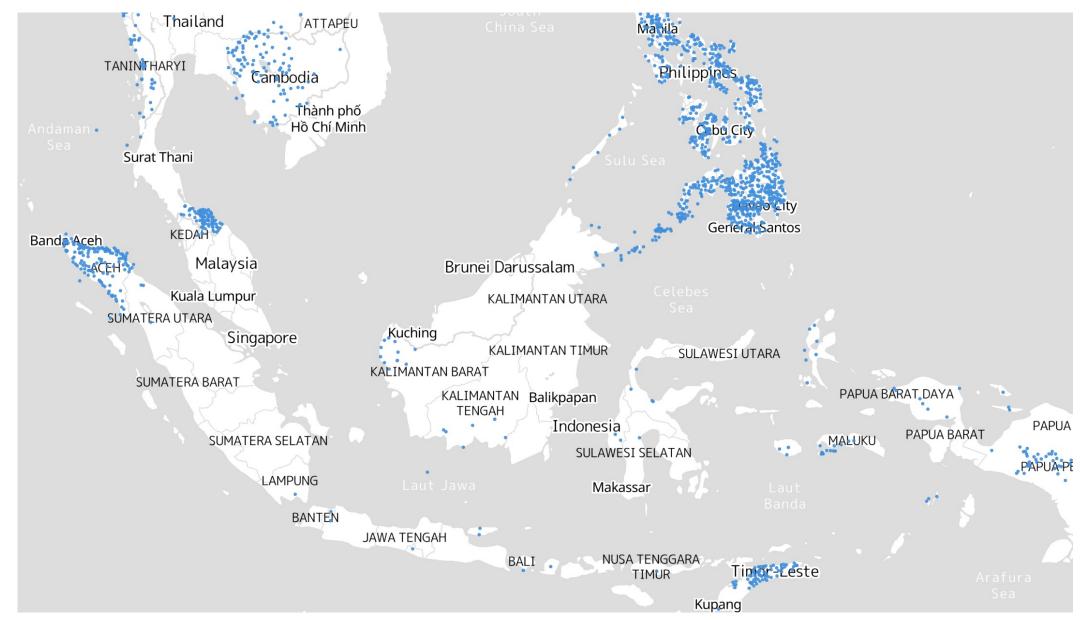
• uppsala-conflict

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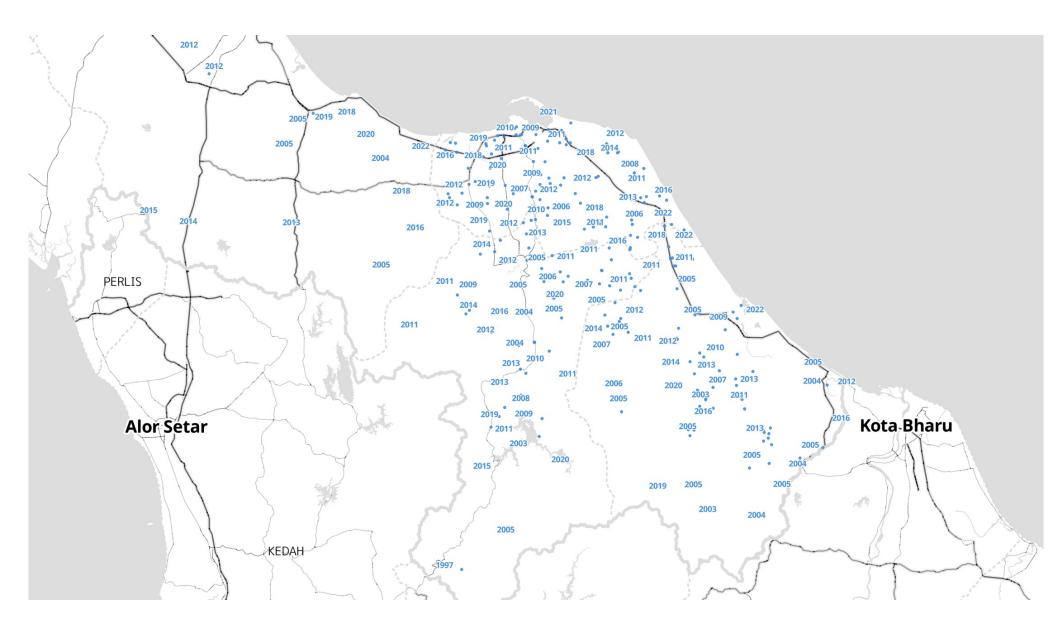




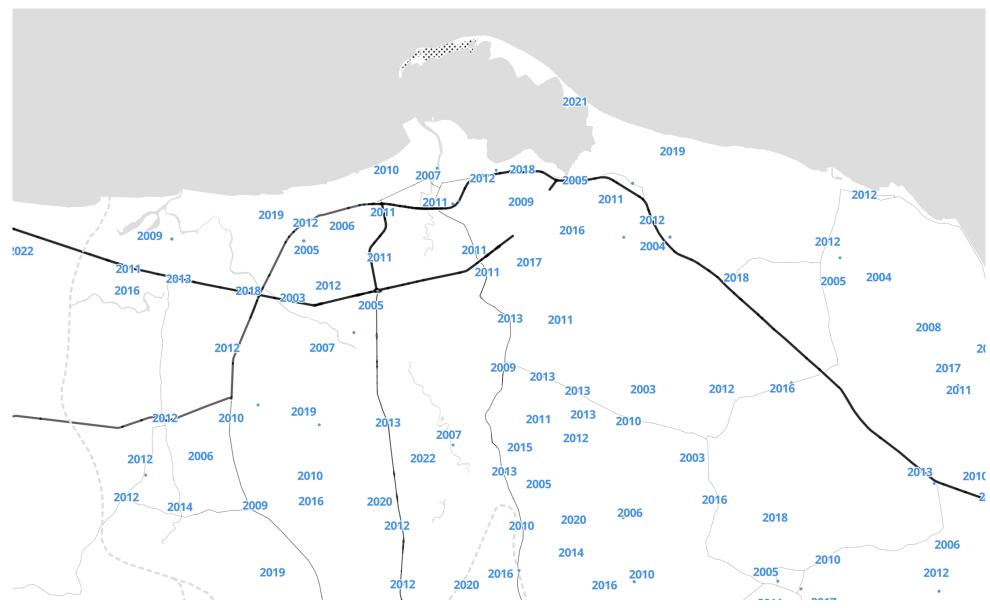




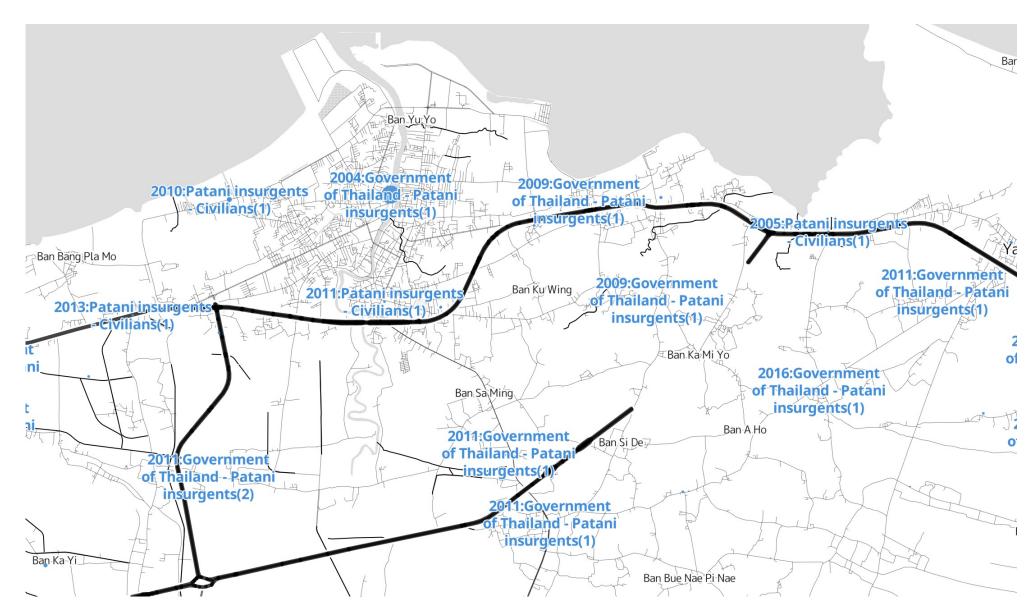










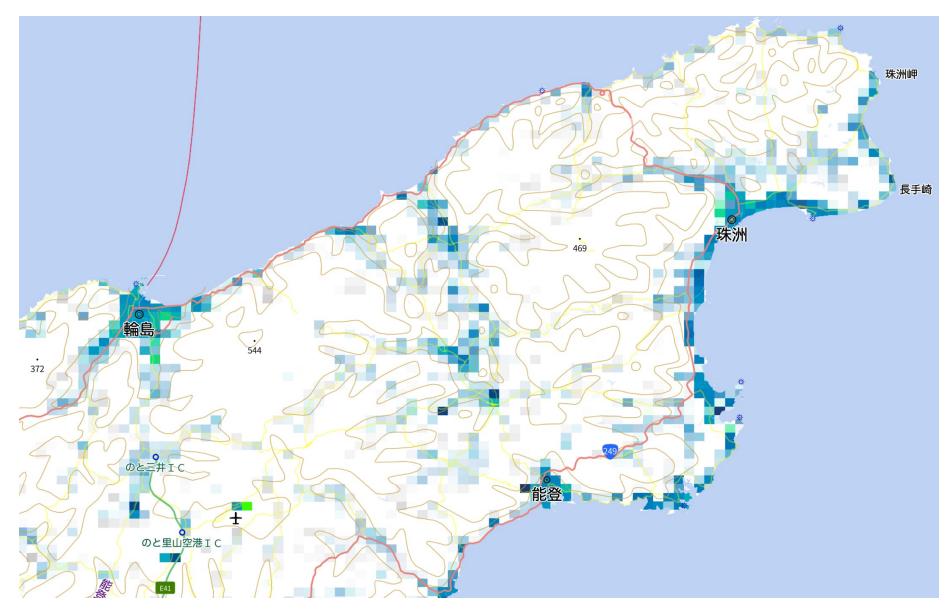








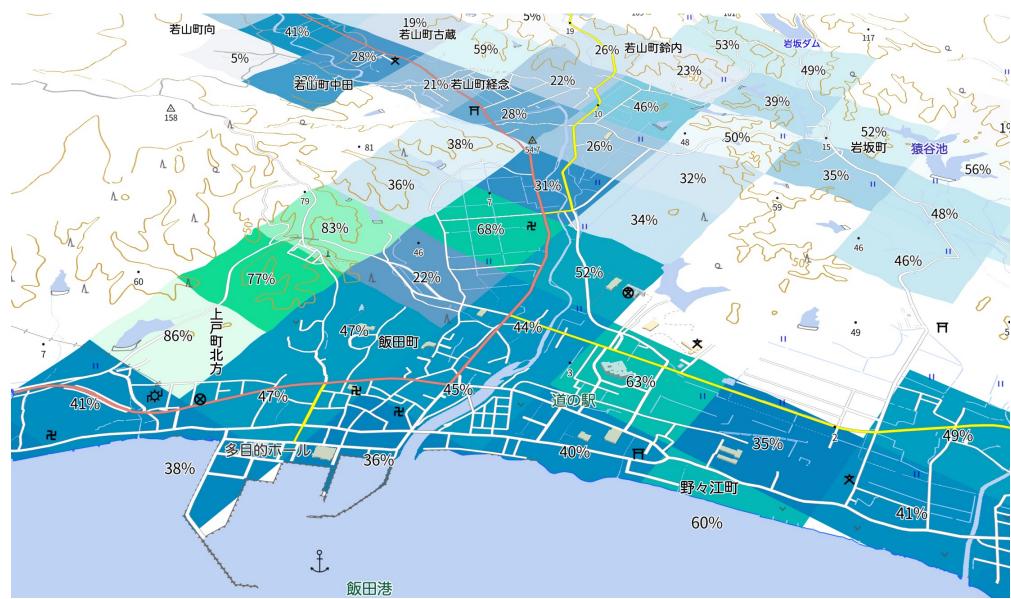
Interactive mapping of population est.







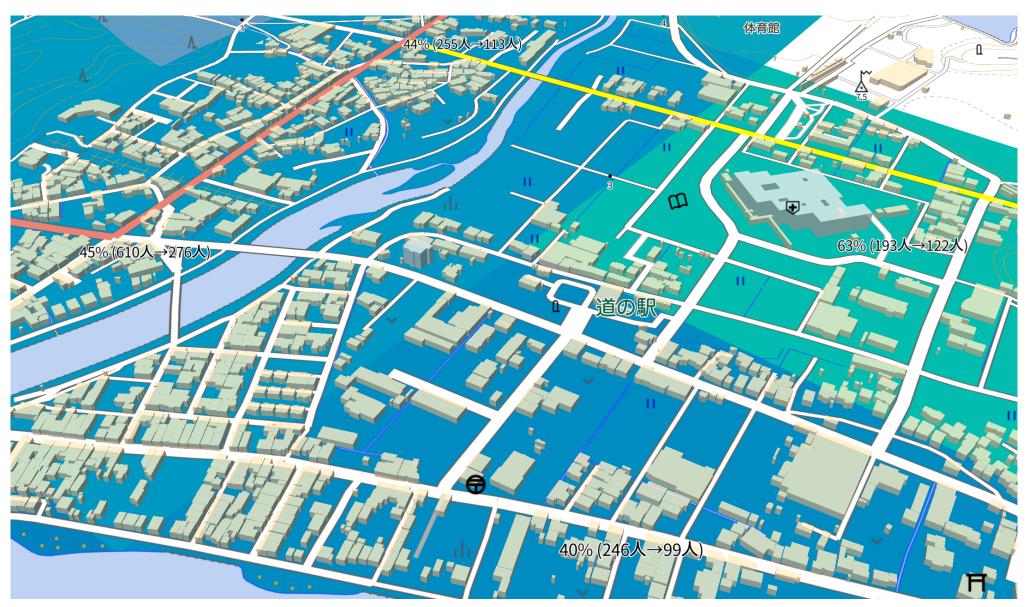




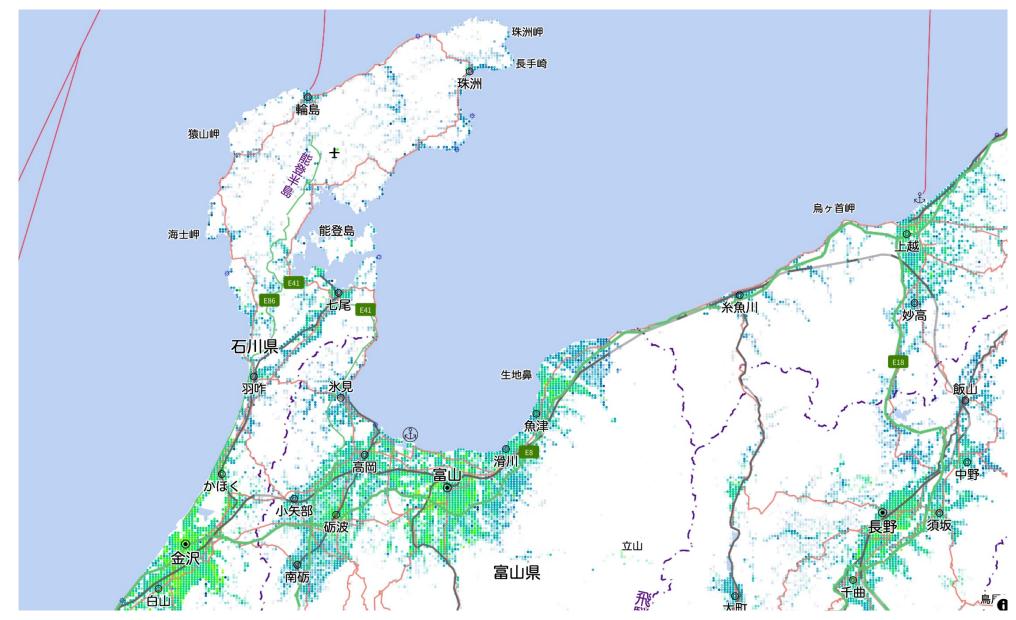




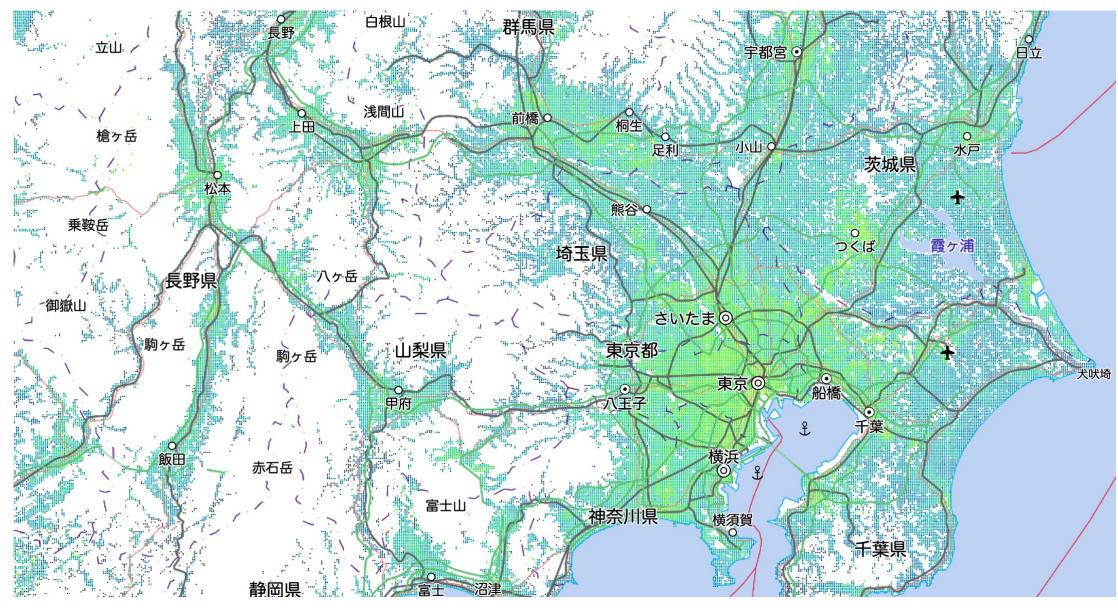




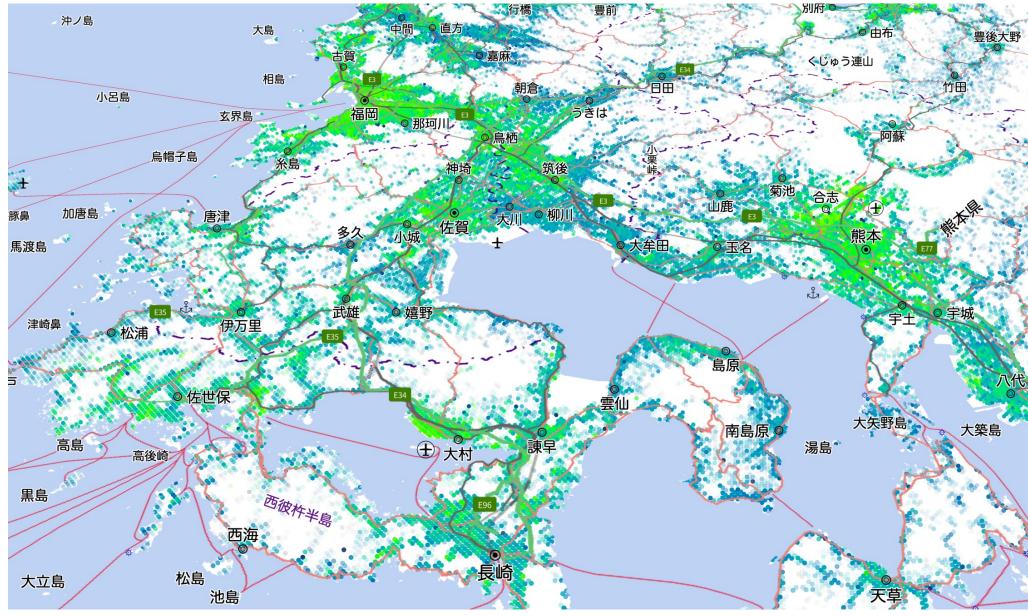


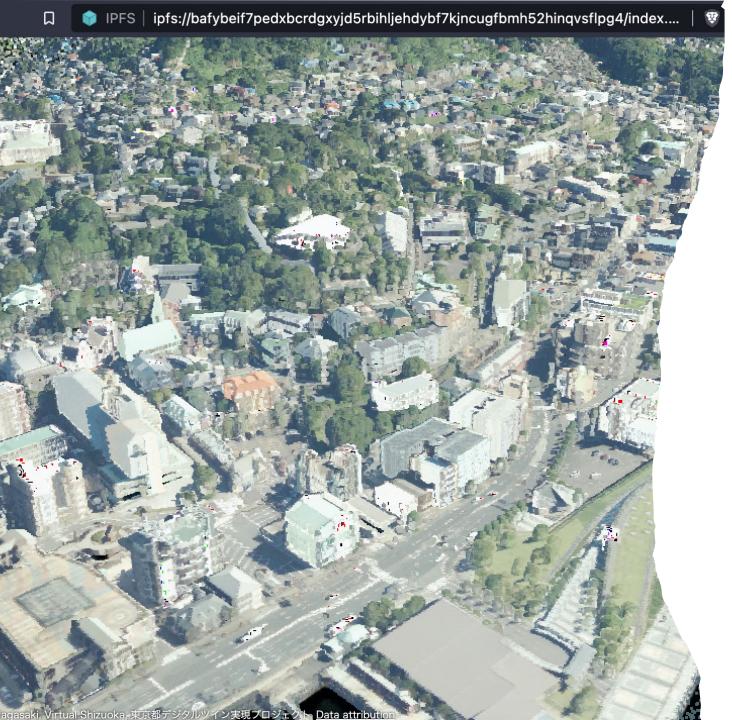






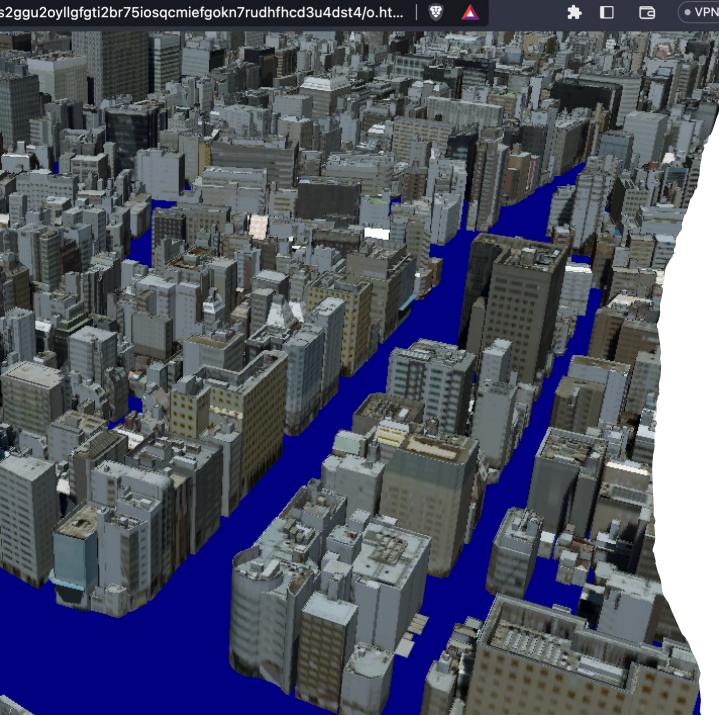






Point Cloud

• Open Data from Nagasaki prefecture.



City Model

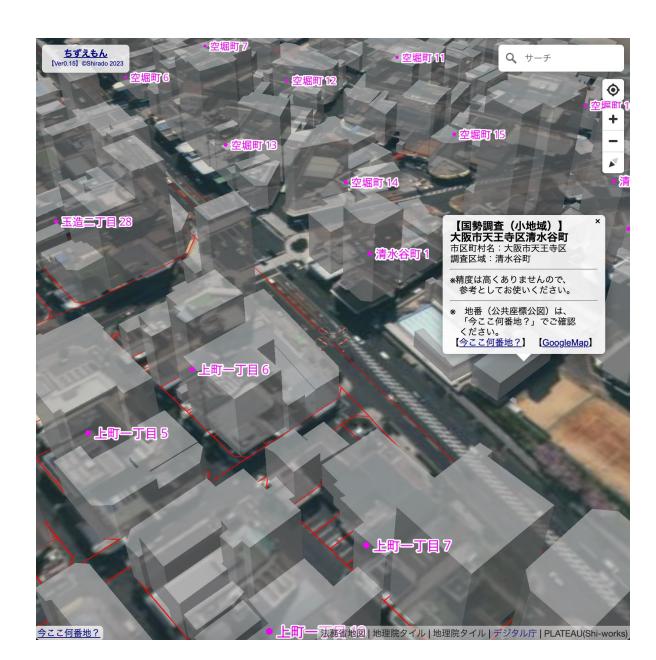
• 3D Tiles released by a Government Ministry (Project PLATEAU by MLIT)



Chizuemon

Combined open cloud-native data in a simple web map.

Detailed city data from 2 ministries, 1 agency and 1 authority.







Open Community supports Secured Data

Secured Data

Open Community

Open Data

We transfer technology and respect secured data.

We test new open-source technologies with open data.



Thank you!

UN Smart Maps

Keep web maps open for a better world

Join UN Smart Maps

See upcoming events



Open License

UN Smart Maps is committed to sharing Open Source Software and Open Data.



Open Practice

UN Smart Maps is a Community of Practice.

We share best practices and lessons

learned.



Open Community

Anyone can join UN Smart Maps. We welcome contributions from anyone.