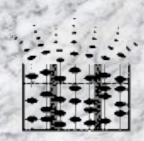
CIS 631 Parallel Processing

Lecture 5: Parallel Programming

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Acknowledgements

- □ Portions of the lectures slides were adopted from:
 - O I. Foster, "Designing and Building Parallel Programs," 1995.
 - O John Mellor-Crummey, COMP 422, "Parallel Computing," Rice University, Spring 2010.

Term Project

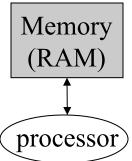
- □ Work on a code for parallel particle advection
 - Contribute by Prof. Hank Childs
 - O Start by reading "GPU Acceleration of Particle Advection Workloads in a Parallel, Distributed Memory Setting"
 - O Skype with Prof. Childs on Wednesday during class meeting to discuss
 - O Verbal agreement needed to keep confidential the paper, the code, the ideas contained in each
- □ Work with David Ozog's Framework for Parallel Task Operation (FRAMPTON)
 - Extend how FRAMPTON can process task DAGs
 - O Develop new tasks adaptors

Outline

- □ Quick look at parallel models
- □ Parallelism
 - Where can you find parallelism in a computation?
 - Dependencies
- □ Different types of parallelism
 - o data parallelism
 - o task parallelism
- □ Parallel programming
 - Creating parallel programs
- □ Standard models of parallelism and parallel programs

Parallel Models 101

- □ Sequential models
 - O von Neumann (RAM) model
- □ Parallel model
 - A parallel computer is simple a collection of *processors interconnected* in some manner to *coordinate* activities and *exchange data*
 - O Models that can be used as general frameworks for describing and analyzing parallel algorithms
 - > Simplicity: description, analysis, architecture independence
 - > Implementability: able to be realized, reflect performance
- ☐ Three common parallel models
 - O Directed acyclic graphs, shared-memory, network



Directed Acyclic Graphs (DAG)

- □ Captures data flow parallelism
- □ Nodes represent operations to be performed
 - Inputs are nodes with no incoming arcs
 - Output are nodes with no outgoing arcs
 - Think of nodes as tasks
- ☐ Arcs are paths for flow of data results
- □ DAG represents the operations of the algorithm and implies precedent constraints on their order

$$a[i] = a[i-1] + 100;$$

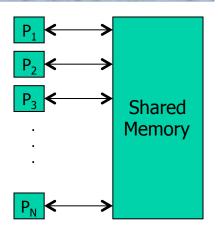


Shared Memory Model

- ☐ Parallel extension of RAM model (PRAM)
 - Memory size is infinite
 - Number of processors in unbounded
 - Processors communicate via the memory



- Synchronous
 - > All processors execute same algorithm synchronously
 - READ phase
 - COMPUTE phase
 - WRITE phase
 - > Some subset of the processors can stay idle
- Asynchronous



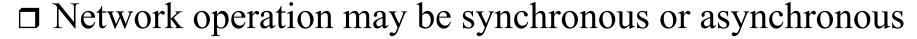
Memory Access in PRAM

- □ Exclusive Read (ER): p processors can simultaneously read the content of p distinct memory locations
- □ Concurrent Read (CR): p processors can simultaneously read the content of p' memory locations, where p' < p
- □ Exclusive Write (EW): p processors can simultaneously write the content of p distinct memory locations
- \Box Concurrent Write (CW): p processors can simultaneously write the content of p' memory locations, where p' < p
- □ EREW and ERCW (weird)
- □ CREW and CRCW

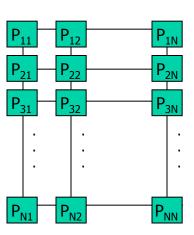
Network Model

$$\Box$$
 G = (N,E)

- O N are processing nodes
- E are bidirectional communication links
- ☐ Each processor has its own memory
- □ No shared memory is available



- □ Requires communication primitives
 - O Send (X, i)
 - O Receive (Y, j)
- □ Captures message passing model for algorithm design



Parallelism

- ☐ Ability to execute different parts of a computation concurrently on different machines
- ☐ Why do you want parallelism?
 - Shorter running time or handling more work
- □ What is being parallelized?
 - O Task: instruction, statement, procedure, ...
 - O Data: data flow, size, replication
 - Parallelism granularity
 - > Coarse-grain versus fine-grainded
- ☐ Thinking about parallelism
- □ Evaluation

Why is parallel programming important today?

- □ Parallel programming has matured
 - Standard programming models
 - Common machine architectures
 - O Programmer can focus on computation and use suitable programming model for implementation
- ☐ Increasing portability between models and architectures
- ☐ Reasonable hope of portability across platforms
- □ Problem
 - O Performance optimization is still platform-dependent
 - Performance portability is a problem
 - O Parallel programming methods are still evolving

Parallel Algorithm

- □ Recipe to solve a problem "in parallel" on multiple processing elements
- ☐ Standard steps for constructing a parallel algorithm
 - Identify work that can be performed concurrently
 - Partition the concurrent work on separate processors
 - O Properly manage input, output, and intermediate data
 - O Coordinate data accesses and work to satisfy dependencies
- □ Which are hard to do?

Parallelism Views

- □ Where can we find parallelism?
- □ Program (task) view
 - Statement level
 - > Between program statements
 - > Which statements can be executed at the same time?
 - O Block level / Loop level / Routine level / Process level
 - > Larger-grained program statements
- □ Data view
 - How is data operated on?
 - Where does data reside?
- □ Resource view

Parallelism, Correctness, and Dependence

- □ Parallel execution, from any point of view, will be constrained by the sequence of operations needed to be performed for a correct result
- □ Parallel execution must address control, data, and system dependences
- □ A *dependency* arises when one operation depends on an earlier operation to complete and produce a result before this later operation can be performed
- ☐ We extend this notion of dependency to resources since some operations may depend on certain resources
 - For example, due to where data is located

Executing Two Statements in Parallel

- ☐ Want to execute two statements in parallel
- ☐ On one processor:

Statement 1;

Statement 2;

☐ On two processors:

Processor 1: Processor 2:

Statement 1; Statement 2;

- ☐ Fundamental (*concurrent*) execution assumption
 - O Processors execute independent of each other
 - O No assumptions made about speed of processor execution

Sequential Consistency in Parallel Execution

□ Case 1: Processor 2: Processor 1: time statement 1; statement 2; □ Case 2: Processor 1: Processor 2: time statement 2; statement 1;

- □ Sequential consistency
 - O Statements execution does not interfere with each other
 - Computation results are the same (independent of order)

Independent versus Dependent

☐ In other words the execution of statement1; statement2; must be equivalent to statement2; statement1;

- ☐ Their order of execution must not matter!
- ☐ If true, the statements are *independent* of each other
- ☐ Two statements are *dependent* when the order of their execution affects the computation outcome

Examples

□ Example 1

S1: a=1;

S2: b=1;

☐ Example 2

S1: a=1;

S2: b=a;

□ Example 3

S1: a=f(x);

S2: a=b;

□ Example 4

S1: a=b;

S2: b=1;

□ Statements are independent

□ Dependent (*true (flow) dependence*)

• Second is dependent on first

• Can you remove dependency?

□ Dependent (*output dependence*)

• Second is dependent on first

• Can you remove dependency? How?

□ Dependent (*anti-dependence*)

• First is dependent on second

• Can you remove dependency? How?

True Dependence and Anti-Dependence

- ☐ Given statements S1 and S2,
 - S1;
 - S2;
- □ S2 has a *true (flow) dependence* on S1 if and only if
 - S2 reads a value written by S1
- ☐ S2 has a *anti-dependence* on S1 if and only if
 S2 writes a value read by S1

$$X = \bigcup_{i \in X} \delta$$

$$= X \longrightarrow \delta^{-1}$$

$$\vdots \qquad \delta^{-1}$$

$$X =$$

Output Dependence

- ☐ Given statements S1 and S2,
 - S1;
 - S2;
- ☐ S2 has an *output dependence* on S1 if and only if
 - S2 writes a variable written by S1

$$X = \bigcup_{i \in \mathcal{X}} \delta^{0}$$

$$X = \bigcup_{i \in \mathcal{X}} \delta^{0}$$

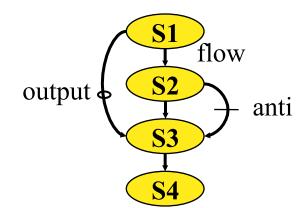
- □ Anti- and output dependences are "name" dependencies
 - Are they "true" dependences?
- ☐ How can you get rid of output dependences?
 - Are there cases where you can not?

Statement Dependency Graphs

- □ Can use graphs to show dependence relationships
- □ Example

$$S1: a=1;$$

S3:
$$a=b+1$$
;



- \square S₂ δ S₃ : S₃ is flow-dependent on S₂
- \square S₁ δ^0 S₃ : S₃ is output-dependent on S₁
- \square S₂ δ^{-1} S₃ : S₃ is anti-dependent on S₂

When can two statements execute in parallel?

- ☐ Statements S1 and S2 can execute in parallel if and only if there are *no dependences* between S1 and S2
 - True dependences
 - Anti-dependences
 - Output dependences
- □ Some dependences can be remove by modifying the program
 - Rearranging statements
 - Eliminating statements

How do you compute dependence?

- □ Data dependence relations can be found by comparing the IN and OUT sets of each node
- ☐ The IN and OUT sets of a statement S are defined as:
 - IN(S): set of memory locations (variables) that may be used in S
 - OUT(S): set of memory locations (variables) that may be modified by S
- □ Note that these sets include all memory locations that may be fetched or modified
- ☐ As such, the sets can be conservatively large

IN and OUT Sets and Computing Dependence

☐ Assuming that there is a path from S1 to S2, the following shows how to intersect the IN and OUT sets to test for data dependence

$$out(S_1) \cap in(S_2) \neq \emptyset$$
 $S_1 \delta S_2$ flow dependence $in(S_1) \cap out(S_2) \neq \emptyset$ $S_1 \delta^{-1} S_2$ anti-dependence $out(S_1) \cap out(S_2) \neq \emptyset$ $S_1 \delta^0 S_2$ output dependence

Loop-Level Parallelism

□ Significant parallelism can be identified within loops

```
for (i=0; i<100; i++) for (i=0; i<100; i++) {
S1: a[i] = i;
S2: b[i] = 2*i;
}
```

- \square Dependencies? What about *i*, the loop index?
- □ DOALL loop
 - All iterations are independent of each other
 - All statements be executed in parallel at the same timeIs this really true?

Iteration Space

- ☐ Unroll loop into separate statements / iterations
- ☐ Show dependences between iterations

for (i=0; i<100; i++) for (i=0; i<100; i++) {
S1: a[i] = i;
S2: b[i] =
$$2*i$$
;
}

S10 S11 ... S199 S10 S11 ... S199 S299

Multi-Loop Parallelism

☐ Significant parallelism can be identified <u>between</u> loops

for
$$(i=0; i<100; i++) a[i] = i;$$

- for (i=0; i<100; i++) b[i] = i;
- □ Dependencies?
- ☐ How much parallelism is available?
- ☐ Given 4 processors, how much parallelism is possible?
- □ What parallelism is achievable with 50 processors?

Loops with Dependencies

Case 1:

$$a[i] = a[i-1] + 100;$$



- □ Dependencies?
 - What type?
- ☐ Is the Case 1 loop parallelizable?
- ☐ Is the Case 2 loop parallelizable?

Case 2:

$$a[i-5] = a[i] + 100;$$

- a[0] a[5] a[10] ...
- $\begin{bmatrix} a[1] \end{bmatrix}$ $\begin{bmatrix} a[6] \end{bmatrix}$ $\begin{bmatrix} a[11] \end{bmatrix}$...
- a[2] a[7] a[12] ...
- $\begin{array}{c|c} a[3] & a[8] & a[13] & \cdots \end{array}$
- a[4] a[9] a[14] ···

Another Loop Example

for (i=1; i<100; i++)

$$a[i] = f(a[i-1]);$$

- □ Dependencies?
 - O What type?
- □ Loop iterations are not parallelizable
 - Why not?

Loop Dependencies

- □ A *loop-carried* dependence is a dependence that is present only if the statements are part of the execution of a loop (i.e., between two statements instances in two different iterations of a loop)
- □ Otherwise, it is *loop-independent*, including between two statements instances in the same loop iteration
- □ Loop-carried dependences can prevent loop iteration parallelization
- ☐ The dependence is *lexically forward* if the source comes before the target or *lexically backward* otherwise
 - O Unroll the loop to see

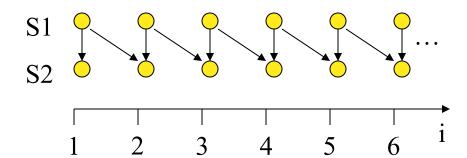
Loop Dependence Example

for (i=0; i<100; i++)

$$a[i+10] = f(a[i]);$$

- □ Dependencies?
 - Between a[10], a[20], ...
 - Between a[11], a[21], ...
- ☐ Some parallel execution is possible
 - O How much?

Iteration Dependence and Pipelining



- □ Dependencies?
 - O Between a[i] and a[i-1]
- ☐ Is parallelism possible?
 - O Statements can be executed in pipelined parallel

Another Loop Dependence Example

- □ Dependencies?
 - O Loop-independent dependence on i
 - O Loop-carried dependence on j
- □ Which loop can be parallelized?
 - Outer loop parallelizable
 - Inner loop cannot be parallelized

Still Another Loop Dependence Example

- □ Dependencies?
 - O Loop-independent dependence on i
 - O Loop-carried dependence on j
- □ Which loop can be parallelized?
 - O Inner loop parallelizable
 - Outer loop cannot be parallelized
 - O Less desirable (why?)

Indirect Indexing and Dependences

- □ Dependencies?
 - O Cannot tell for sure
- □ Parallelization depends on knowledge of index values
 - O User may know
 - O Compiler does not know
 - User could inform the compiler

Hidden Dependencies – Printing

```
printf("a");
printf("b");
```

- ☐ Statements have a hidden output dependence
 - Due to the serial output stream

Hidden Dependences – Functions

$$a = f(x);$$
$$b = g(x);$$

☐ Statements could have hidden dependence if f() and g() update the same variable through side effects

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Parallelizing Compilers

- □ Parallelizing compilers analyze program dependences to decide parallelization
- □ In parallelization by hand, user does the same analysis.
- □ Compiler more convenient and more correct
- ☐ User more knowledgable
 - O Can analyze more patterns

Key Ideas for Dependency Analysis

- ☐ To execute in parallel:
 - O Statement order must not matter
 - O Statements must not have dependences
- ☐ Some dependences can be removed
- ☐ Some dependences may not be obvious

Dependencies and Synchronization

- ☐ How is parallelism achieved when have dependencies?
 - Think about concurrency
 - Some parts of the execution are independent
 - Some parts of the execution are dependent
- ☐ Must control ordering of events on different processors
 - O Dependencies pose constraints on parallel event ordering
 - Partial ordering of execution action
- ☐ Use synchronization mechanisms
 - Need for concurrent execution too
 - Maintains partial order

Synchronization Primitives

- \square Suppose we had a set of primitives, signal(x) and wait(x)
- \square wait(x) blocks unless a signal(x) has occurred.
- □ signal(x) does not block, but causes a wait(x) to unblock, or causes a future wait(x) not to block

```
f() {
    a=1; b=2; c=3;
    }
    g() {
    d=4; e=5; a=6;
    }
    main() { f(); g(); }
    f() {
    a=1; signal(e_a); b=2; c=3;
    }
    g() {
    d=4; e=5; wait(e_a); a=6;
    }
    main() { f(); g(); }
```

Synchronization in Loops

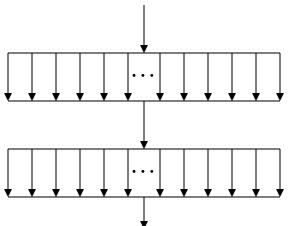
```
for (i=0; i<100; i++) {
    a[i] = ...;
    a[i] = ...;
```

- ☐ Loop cannot be parallelized unless have synchronization!
- □ Does it matters which processors get which iterations?
- ☐ This is called a *DOACROSS* loop
- ☐ How could you parallelize this without synchronization?

Fork-Join Parallelism

$$x = g(a);$$

for(i=0; i<100; i++) a[i] = f(i);
 $y = h(a);$
for(i=0; i<100; i++) b[i] = x + h(a[i]);



- ☐ First loop is a DOALL loop
- ☐ Middle statement is sequential
- □ Second loop is a DOALL loop
- ☐ Execution moves between sequential and parallel phases
- □ Call this *fork-join* parallelism
- ☐ Fork-join, loop-level parallelism is basis for OpenMP

Fork-Join and Barrier Synchronization

- □ fork() causes a number of processes to be created and to be run in parallel
- □ join() causes all these processes to wait until all of them have executed a join() (barrier synchronization)

```
fork();
for( i=0; i<100; i++ ) a[i] = f(i);
join();
y = h(a);
fork();
for( i=0; i<100; i++ ) b[i] = x + h(a[i]);
join();</pre>
```

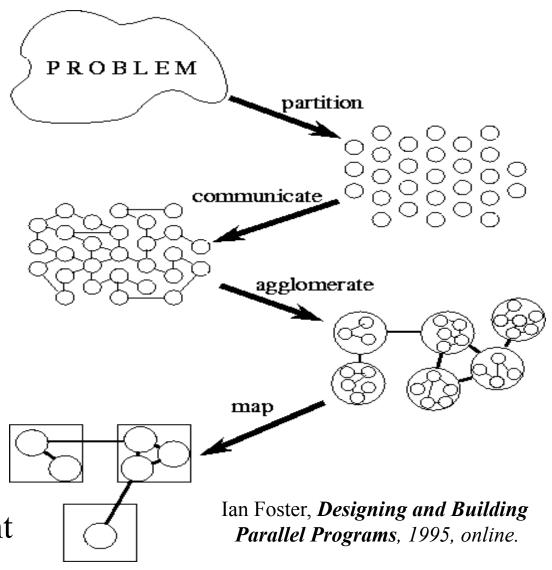
Synchronization Issues

- ☐ Synchronization is necessary to make some programs execute correctly in parallel
- ☐ Dependences have to be "covered" by appropriate synchronization operations
- □ Different sychronization constructs exist in different parallel programming models
- ☐ However, synchronization is expensive
- □ To reduce synchronization
 - May need to limit parallelization
 - Look for opportunities to increase parallelism granularity

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Methodological Design

- □ Partition:
 - Task/data decomposition
- □ Communication
 - Task execution coordination
- □ Agglomeration
 - Evaluation of the structure
- □ Mapping
 - Resource assignment



Next Class

- □ Parallel programming models
- □ Introduction to HPC Linux and LiveDVD