

SensorBase::SensorBase



```
graph LR; A[SensorBase::SensorBase] --> B[Nodo::Nodo]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is filled with a dark gray color and contains the text 'SensorBase::SensorBase'. The right box is white with a black border and contains the text 'Nodo::Nodo'. A solid blue arrow points from the right side of the left box to the left side of the right box, indicating a directed relationship or flow from the left entity to the right entity.

Nodo::Nodo