Introduction to

# Generative Adversarial Network (GAN)

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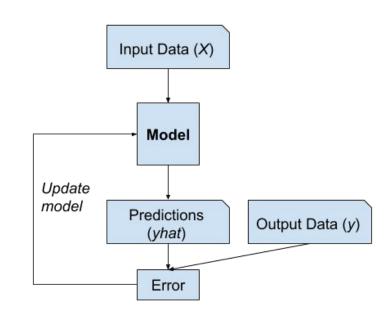
#### **Overview**

- What Are Generative Models?
- Why Generative Adversarial Networks ?
- What Are Generative Adversarial Network?

# What are Generative Model?

#### Supervised Learning

In the predictive or supervised learning approach, the goal is to learn a mapping from inputs x to outputs y, given a labeled set of input-output pairs ...



#### Supervised Learning

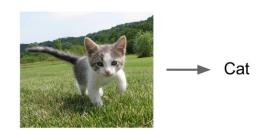
Data: (x, y)

x is data, y label

**Goal**: Learn a function to map  $x \rightarrow y$ 

**Examples**: Classification, regression, object detection, semantic segmentation, image captioning, etc.

#### Supervised Learning



classification



DOG, DOG, CAT
Object detection



segmentation

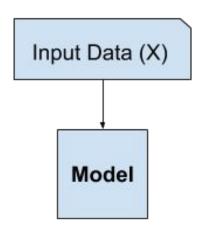


A cat sitting on a suitcase on the floor

Image captioning

#### **Unsupervised Learning**

In the descriptive or unsupervised learning we are only given inputs, and the goal is to find "interesting patterns" in the data. This is a much less well-defined problem, since we are not told what kinds of patterns to look for, and there is no obvious error metric to use (unlike supervised learning, where we can compare our prediction of y for a given x to the observed value).



#### Unsupervised Learning

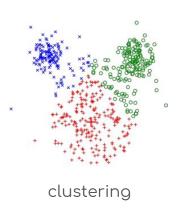
Data:x

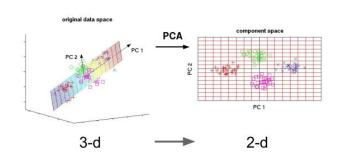
Just data, no labels!

Goal: Learn some underlying hidden structure of the data

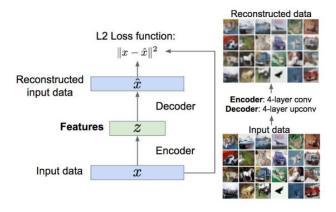
**Examples**: Clustering, Dimensionality reduction, etc.

#### **Unsupervised Learning**





PCA (Dimensionality reduction)



Autoencoder

#### Supervised Learning

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Just data, no labels!

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#### **Generative Models**

Given training data, generate new samples from same distribution.



Training data ~  $\rho$  <sub>data</sub> (x)



Generated samples ~  $\rho$  <sub>model</sub> (x)

Want to learn  $\rho_{model}$  (x) similar to  $\rho_{data}$  (x)

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Generated samples  $\sim \rho_{model}(x)$ 

Want to learn  $\rho_{\text{model}}$  (x) similar to  $\rho_{\text{data}}$  (x)

Addresses density estimation, a core problem in unsupervised learning Several flavors:

- Explicit density estimation: explicitly define and solve for  $\rho_{model}(x)$  Implicit density estimation: learn model that can sample from  $\rho_{model}(x)$  w/o explicitly defining it

### Why Generative Models?

- Realistic samples for artwork, super-resolution, colorization, etc.
- Generative models of time-series data can be used for simulation and planning
- Anomaly detection
- Etc.





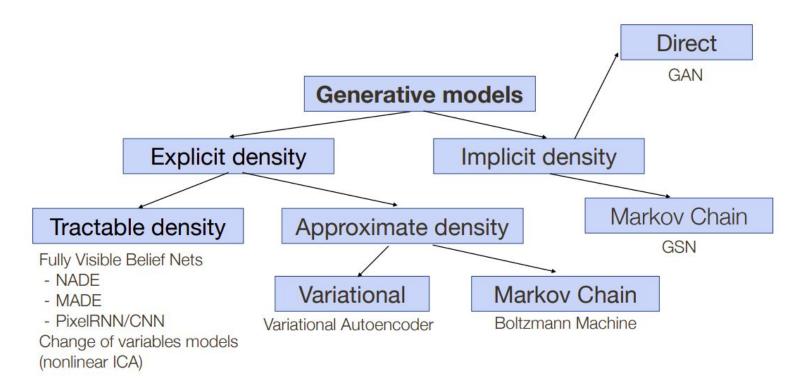


# Why Generative Models?



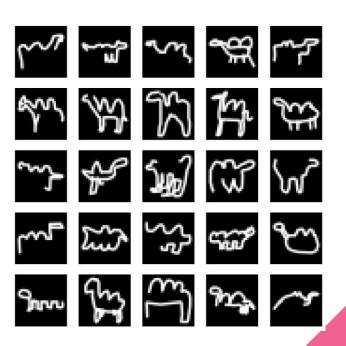
CycleGAN

# Taxonomy of Generative Models



What Are Generative Adversarial Network

- Photographer
- Painter









A generative adversarial network (GAN) has two parts:

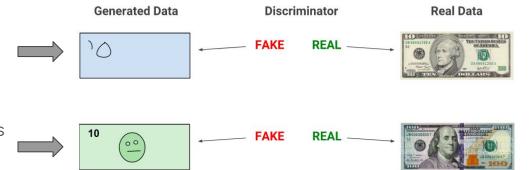
- The **generator** learns to generate plausible data. The generated instances become negative training examples for the discriminator.
- The **discriminator** learns to distinguish the generator's fake data from real data. The discriminator penalizes the generator for producing implausible results.

When training begins, the generator produces obviously fake data, and the discriminator quickly learns to tell that it's fake

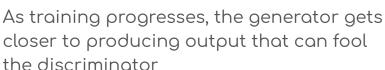


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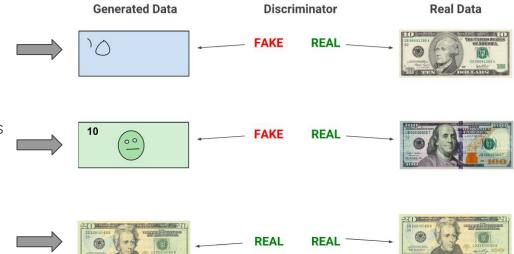
As training progresses, the generator gets closer to producing output that can fool the discriminator



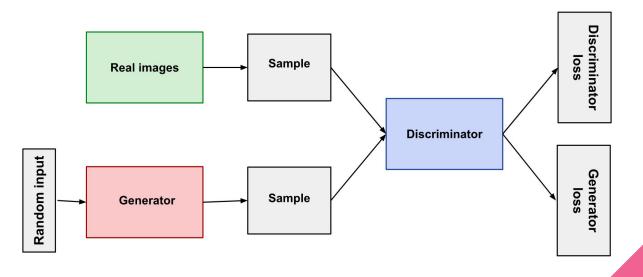
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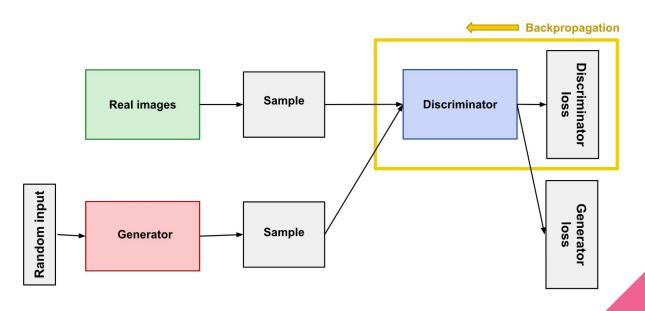
Finally, if generator training goes well, the discriminator gets worse at telling the difference between real and fake. It starts to classify fake data as real, and its accuracy decreases.



Both the generator and the discriminator are neural networks. The generator output is connected directly to the discriminator input. Through backpropagation, the discriminator's classification provides a signal that the generator uses to update its weights.



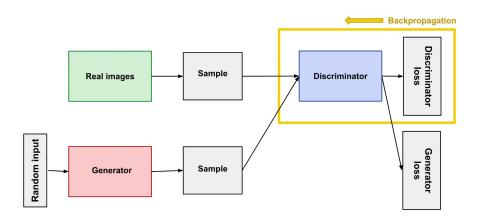
The discriminator in a GAN is simply a classifier. It tries to distinguish real data from the data created by the generator. It could use any network architecture appropriate to the type of data it's classifying.



#### Discriminator Training Data

The discriminator's training data comes from two sources:

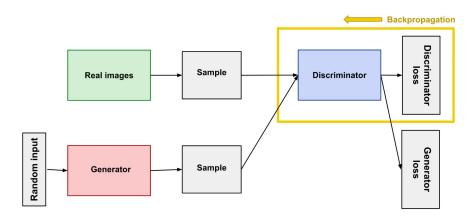
- Real data instances, such as real pictures of people. The discriminator uses these instances as positive examples during training.
- Fake data instances created by the generator. The discriminator uses these instances as negative examples during training.



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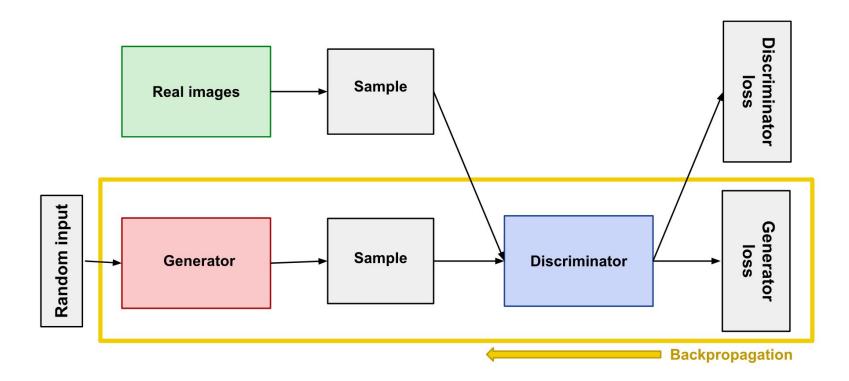
During discriminator training the generator does not train. Its weights remain constant while it produces examples for the discriminator to train on.

#### Training the Discriminator

The discriminator connects to two loss functions. During discriminator training, the discriminator ignores the generator loss and just uses the discriminator loss. We use the generator loss during generator training.

- 1. The discriminator classifies both real data and fake data from the generator.
- 2. The discriminator loss penalizes the discriminator for misclassifying a real instance as fake or a fake instance as real.
- 3. The discriminator updates its weights through backpropagation from the discriminator loss through the discriminator network.

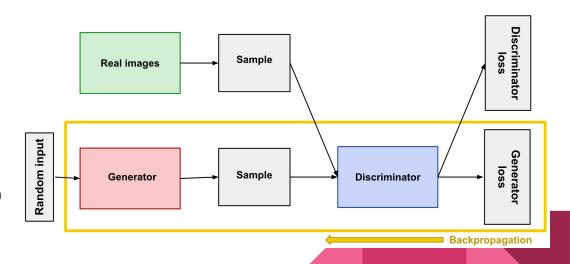
#### **The Generator**



#### The Generator

The generator part of a GAN learns to create fake data by incorporating feedback from the discriminator. It learns to make the discriminator classify its output as real.

- 1. Sample random noise
- 2. Produce generator output from sampled random noise.
- Get discriminator "Real" or "Fake" classification for generator output.
- 4. Calculate loss from discriminator classification.
- Backpropagate through both the discriminator and generator to obtain gradients.
- Use gradients to change only the generator weights.



### **GAN Training**

- The discriminator trains for one or more epochs
- The generator trains for one or more epochs
- Repeats steps 1 and 2 to continue to train the generator and discriminator networks.

#### Convergence

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- This progression poses a problem for convergence of the GAN as a whole
- The discriminator is giving completely random feedback
- Convergence is often a fleeting, rather than stable state

$$\min_{G} \max_{D} V(D, G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{z}}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z})))]$$

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- G(z) is the generatore's output when given noise z.
- D(G(z)) is the discriminator's estimate of the probability that a fake instance is real
- Ez is the expected value over all random inputs to the generator (in effect, the expected value over all generated fake instance G(z))

## Review

$$h_{\theta}(x^{i}) = \theta_{0}x_{0} + \theta_{1}x_{1} + \dots + \theta_{j}x_{j}$$

$$x_0 = 1$$
,  $j = the number of features$ 

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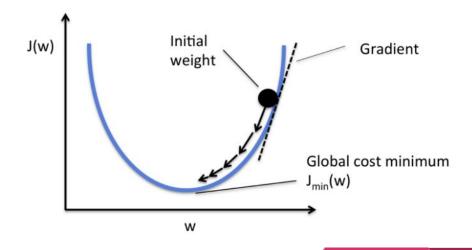
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Least Squared Error = 
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Cost Function = 
$$J(\theta) = \frac{1}{2m} \sum_{i=1}^{m} (h_{\theta}(x^{i}) - y^{i})^{2}$$
,  $m = number of data$ 

### Review

$$\frac{\partial J(\theta)}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$$



#### Review

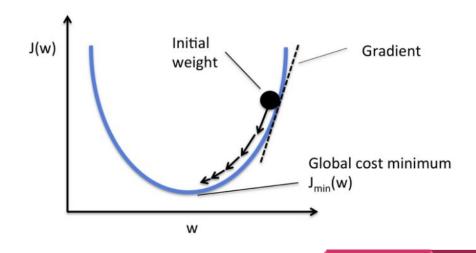
$$\nabla_{\theta_j} J(\theta) = \frac{1}{m} \sum_{i=1}^m \left( h_{\theta} (x^i) - y^i \right) x_j^i$$

$$\widehat{\theta}_0 = \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^i) - y^i) x_0^i$$

$$\widehat{\theta}_1 = \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^i) - y^i) x_1^i$$

..

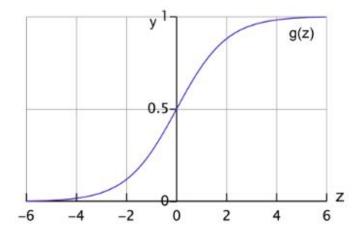
$$\widehat{\theta}_j = \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^i) - y^i) x_j^i$$



$$h_{\theta}(x^{i}) = \theta_{0}x_{0} + \theta_{1}x_{1} + \dots + \theta_{j}x_{j} = \theta^{T}x$$

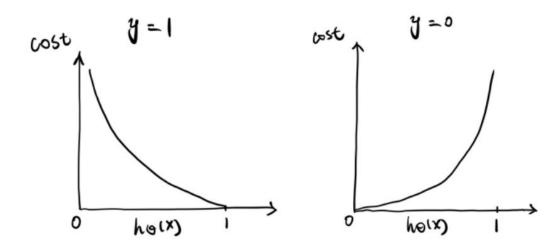
Sigmoid Function: 
$$g(z) = \frac{1}{1 + e^{(-z)}}$$

Hypothesis: 
$$h_{\theta}(x) = \frac{1}{1 + e^{(-\theta^T x)}}$$

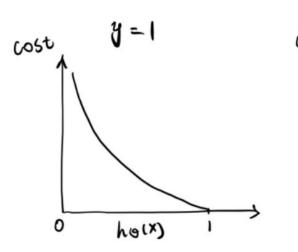


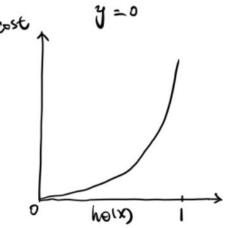
$$Cost(h_{\theta}(x), y) = \begin{cases} -log(h_{\theta}(x)) & \text{if } y = 1\\ -log(1 - h_{\theta}(x)) & \text{if } y = 0 \end{cases}$$

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$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} Cost(h_{\theta}(x^{(i)}), y^{(i)})$$

$$J(\theta) = \frac{1}{m} \left[ \sum_{i=1}^{m} -y^{(i)} log(h_{\theta}(x^{(i)})) + (1 - y^{(i)}) log(1 - h_{\theta}(x^{(i)})) \right]$$

$$m = number of samples$$

$$L_D = -\sum_{i=1}^m y^i \log(D(x_i)) - \sum_{i=1}^m (1 - y^i) \log(1 - D(x_i))$$

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$$x \sim \begin{cases} p_{data} & \text{if, } y_1 = 1, \text{ with prob } 0.5 \\ p_g & \text{if, } y_1 = 0 \text{ otherwise} \end{cases}$$

$$L_D = -\left[\sum_{i=1}^{\frac{m}{2}} y^i \log(D(x_i)) + \sum_{i=\frac{m}{2}}^{m} (1 - y^i) \log(1 - D(x_i))\right]$$

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## Discriminator's loss function(cost func)

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The discriminator's goal, through training, is to minimize its loss LD

$$\max_{D}[-L_{D}] = \max_{D} \left[ \frac{1}{2} \mathbb{E}_{x \sim p_{data}} y \log(D(x)) + \frac{1}{2} \mathbb{E}_{z \sim p_{z}} (1 - y) \log(1 - D(G(z))) \right]$$

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• The generator however, wants to maximize the discriminator's uncertainty (LD), or equivalently minimize -LD

$$L_G = -L_D$$

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