

# Deep Convolutional Generative Adversarial Network

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# OVERVIEW

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# OBJECTIVES

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Propose and evaluate a set of constraints on the architectural topology of Convolutional GANs that make them stable to train in most settings. We name this class of architectures Deep Convolutional GANs (DCGAN)

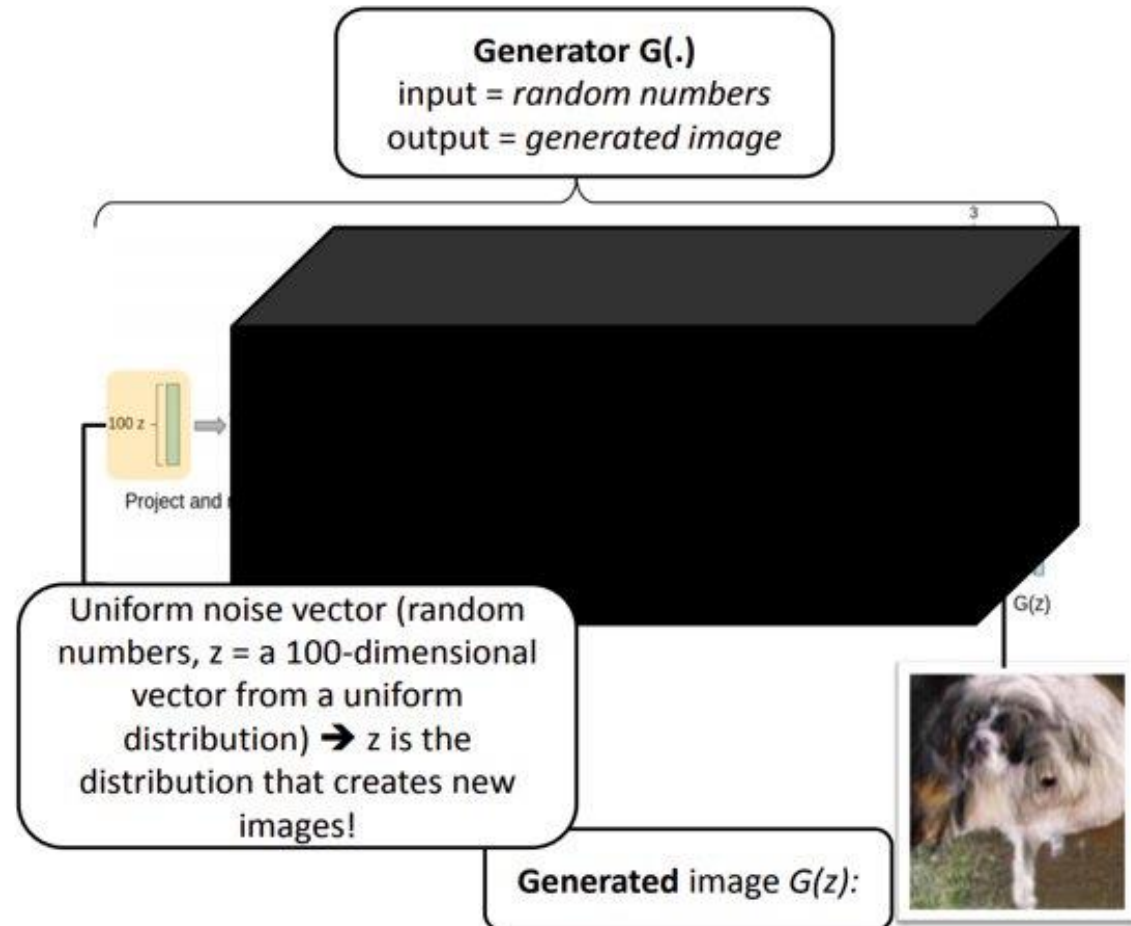
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Use the trained discriminators for image classification tasks, showing competitive performance with other unsupervised algorithms

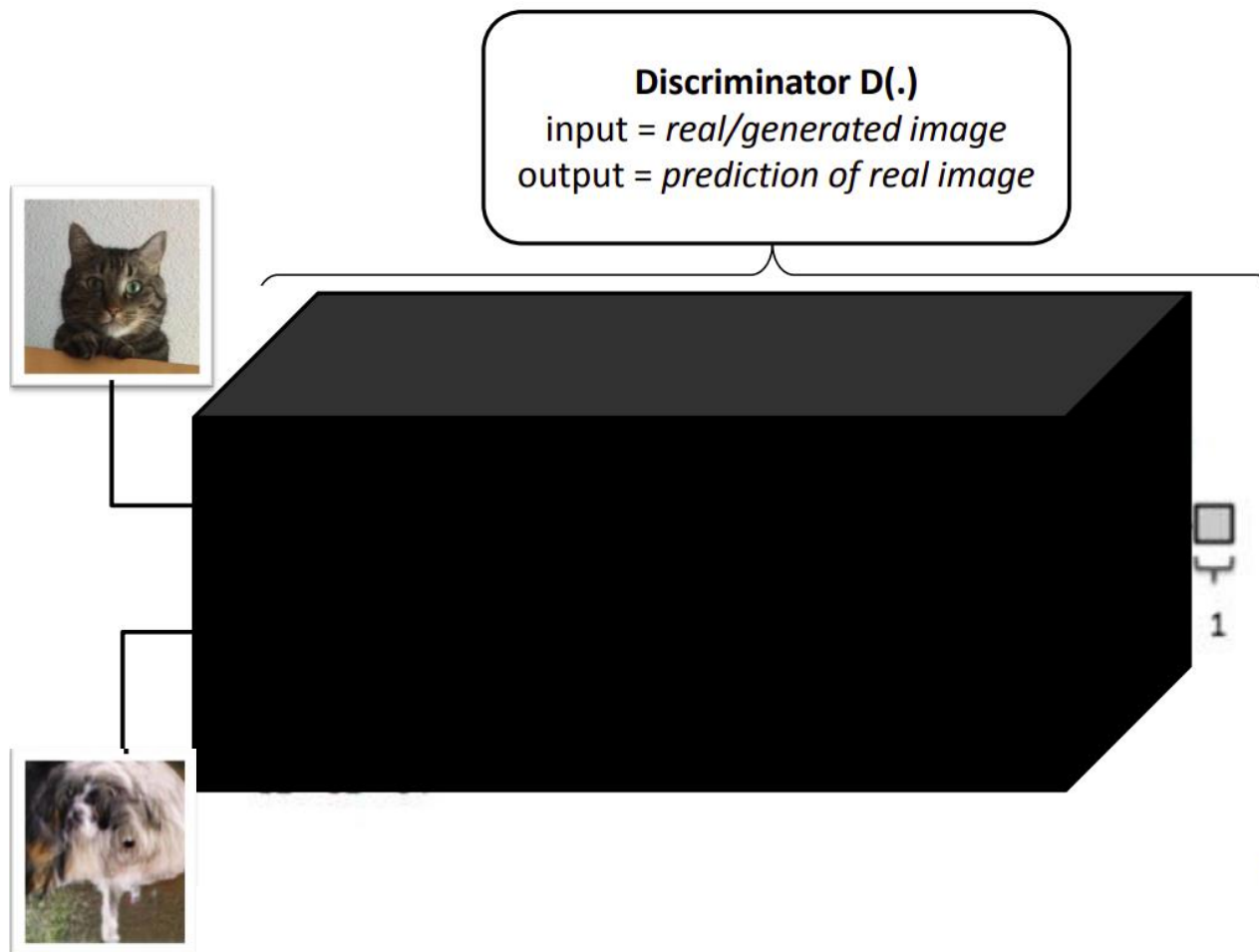
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We visualize the filters learnt by GANs and empirically show that specific filters have learned to draw specific objects

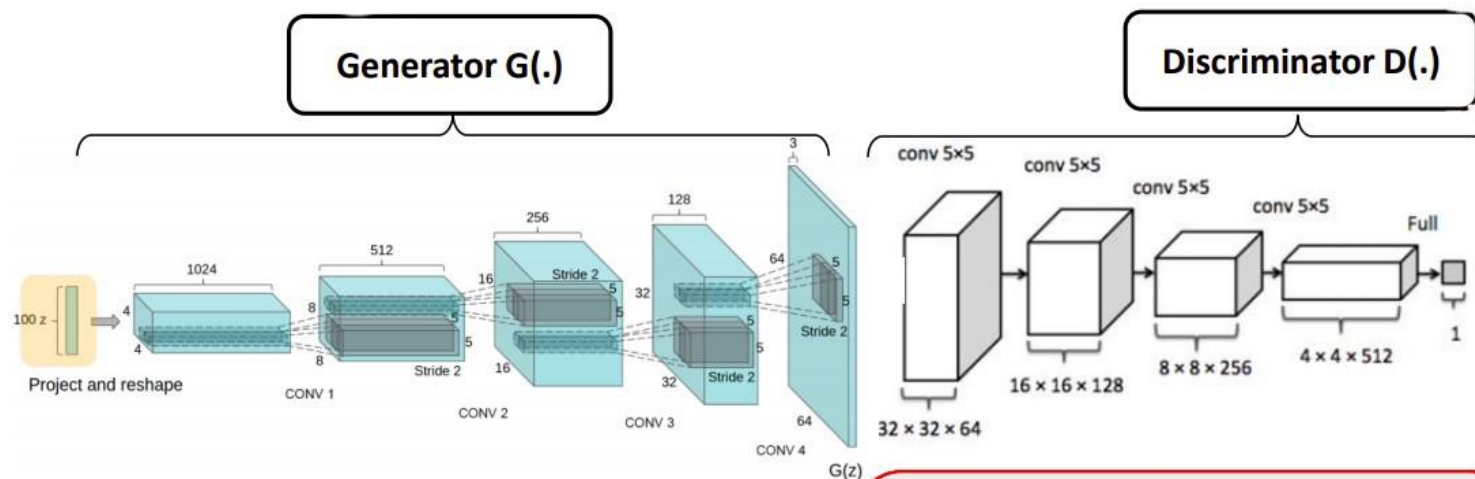
# ARCHITECTURE



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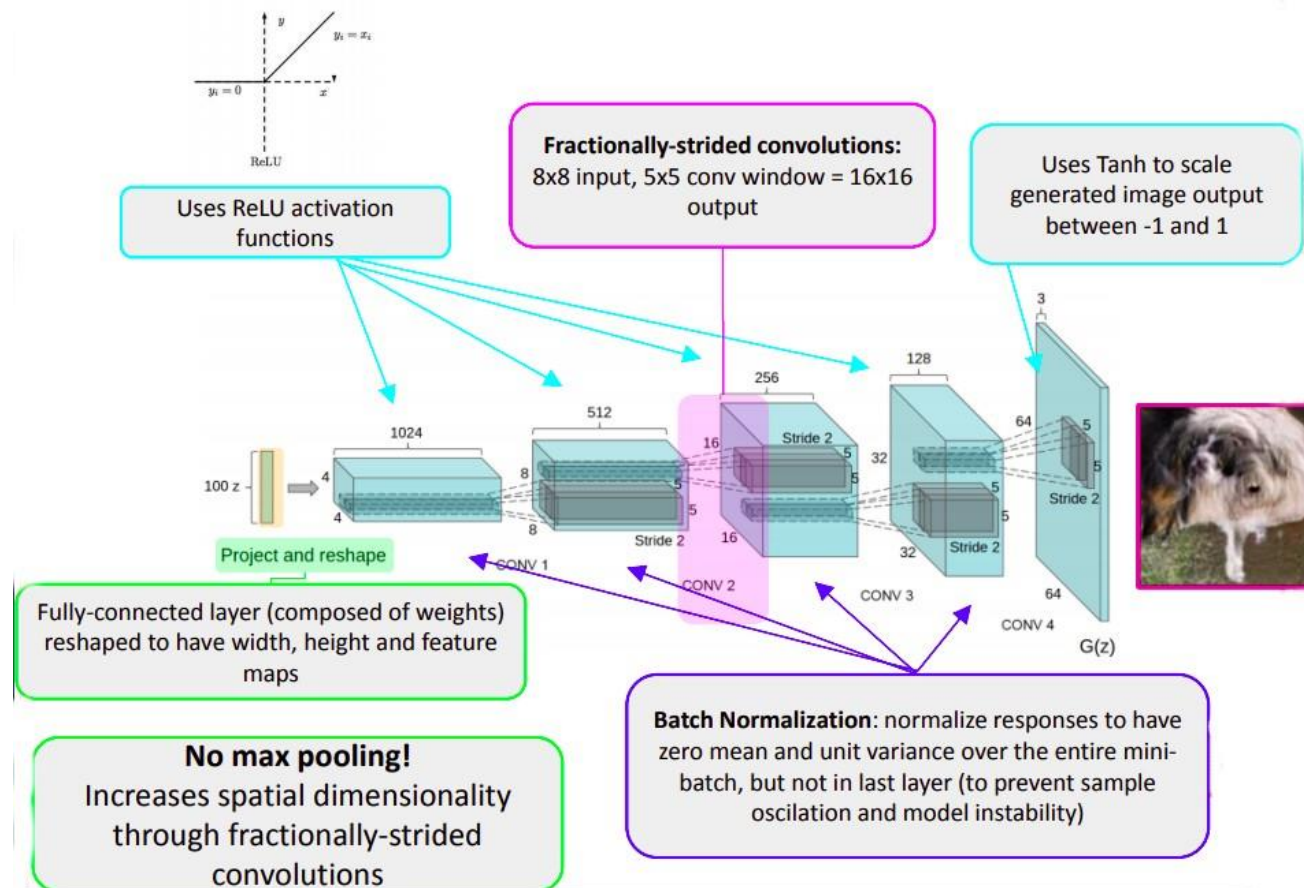
**Generator Goal:** Fool  $D(G(z))$   
i.e., generate an image  $G(z)$  such that  
 $D(G(z))$  is wrong, i.e.,  $D(G(z)) = 1$

**Discriminator Goal:** discriminate  
between **real** and **generated** images  
i.e.,  $D(x)=1$ , where  $x$  is a **real** image  
 $D(G(z))=0$ , where  $G(z)$  is a **generated**  
image.

- **Conflicting goals.**
- Both goals are **unsupervised**.
- Optimal when  $D(\cdot)=0.5$  (i.e., cannot tell the difference between real and generated images) and  $G(z)$  learns the training images distribution.

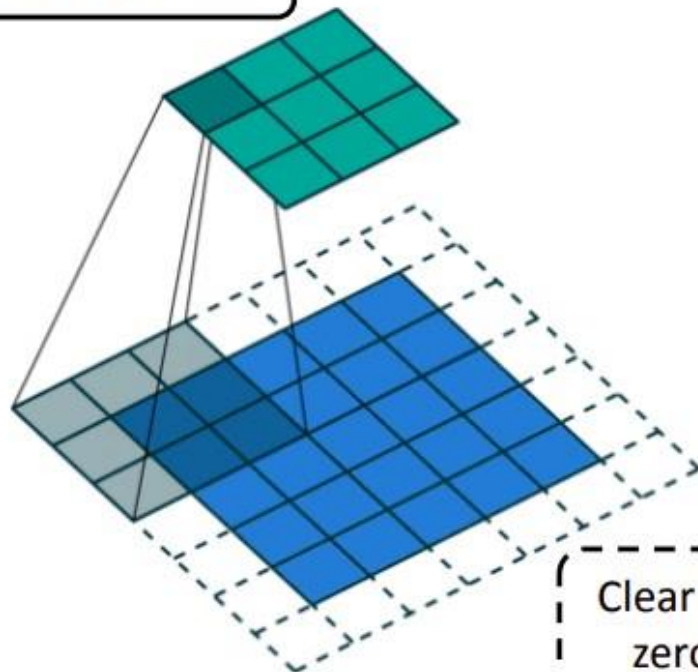
# ARCHITECTURE

## Generator



## Regular convolution

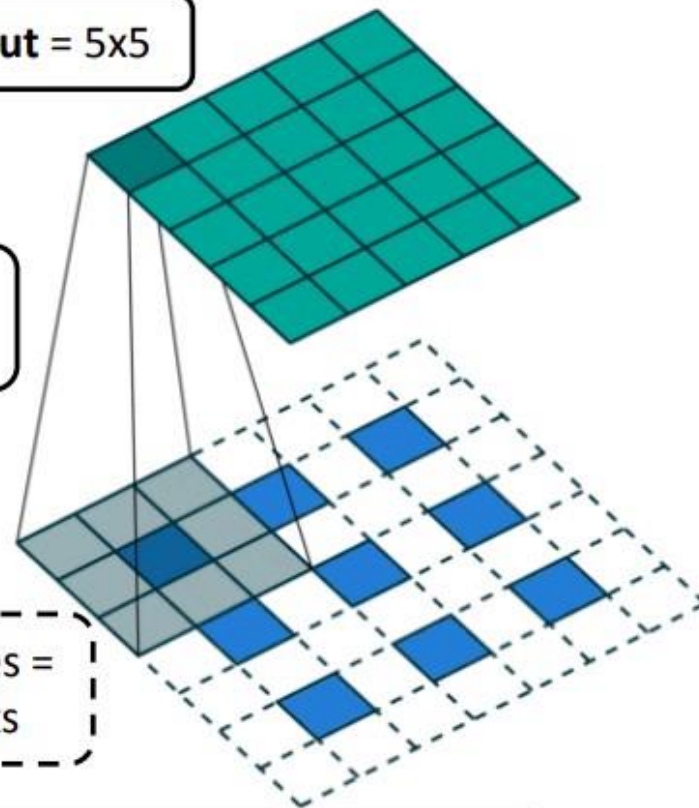
Output = 3x3



**Input** = 5x5  
with zero-padding at  
border = 6x6  
(stride=2)

Output = 5x5

**Filter**  
size=3x3



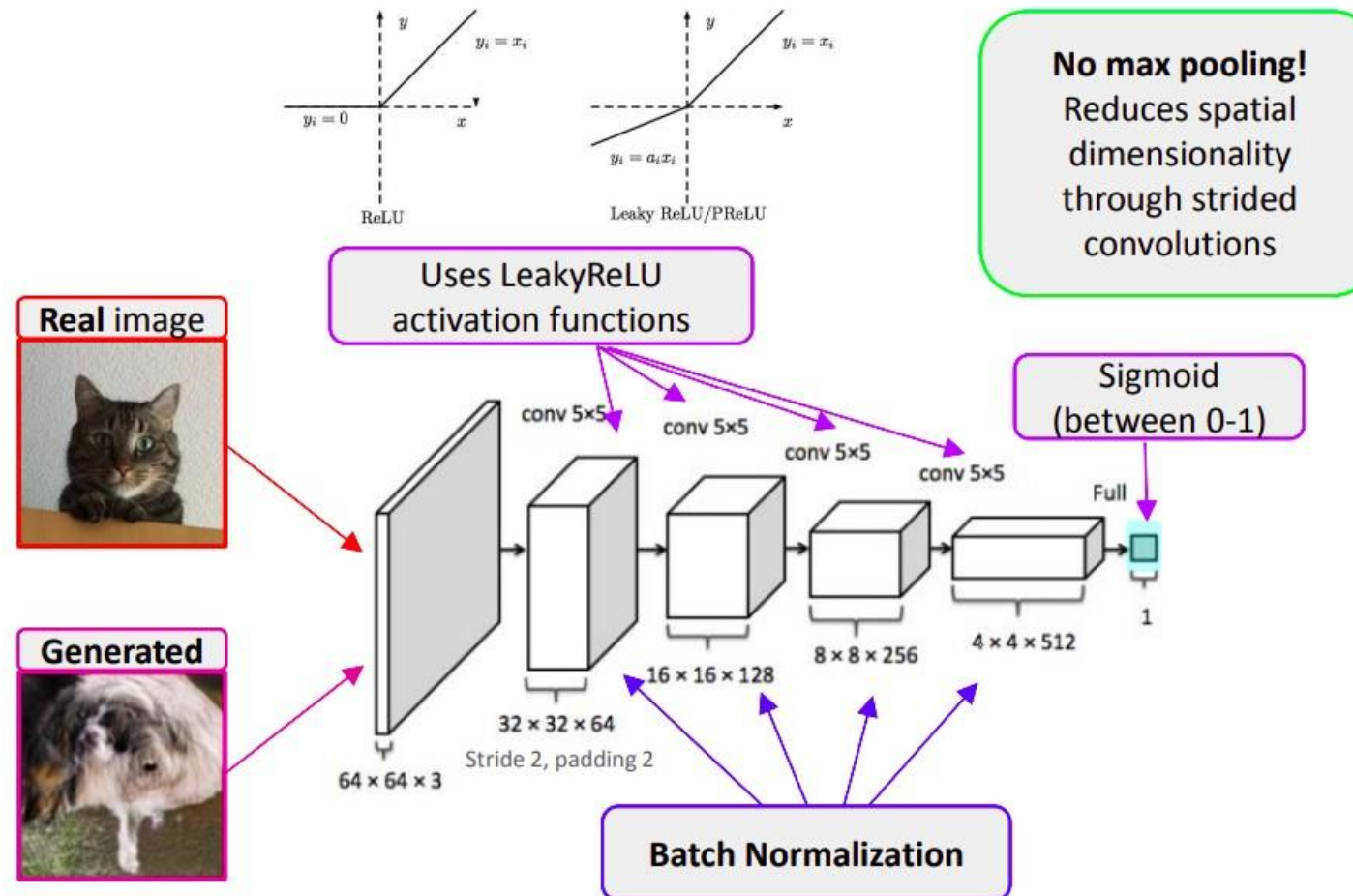
**Input** = 3x3  
Interlace zero-padding with  
inputs = 7x7  
(stride=1)

Clear dashed squares =  
zero-padded inputs



# ARCHITECTURE

## Discriminator



# ARCHITECTURE GUIDELINES FOR STABLE DEEP CONVOLUTIONAL GANS

- Replace any pooling layers with strided convolutions (discriminator) and fractional-strided convolutions (generator).
- Use batchnorm in both the generator and the discriminator.
- Use ReLU activation in generator
- Use LeakyReLU activation in the discriminator.

# Datasets

- Large-scale Scene Understanding (LSUN)
- Faces
- ImageNet-1K

# TRAINING

- Pre-processing: scale images between -1 and 1 (tanh range).
- Minibatch SGD ( $m = 128$ ).
- Weight init.: zero-centered normal distribution (std. dev. = 0.02).
- Leaky ReLU slope = 0.2.
- Adam optimizer with tuned hyperparameters to accelerate training.
- Learning rate = 0.0002.
- Momentum term  $\beta_1 = 0.5$  to stabilize training

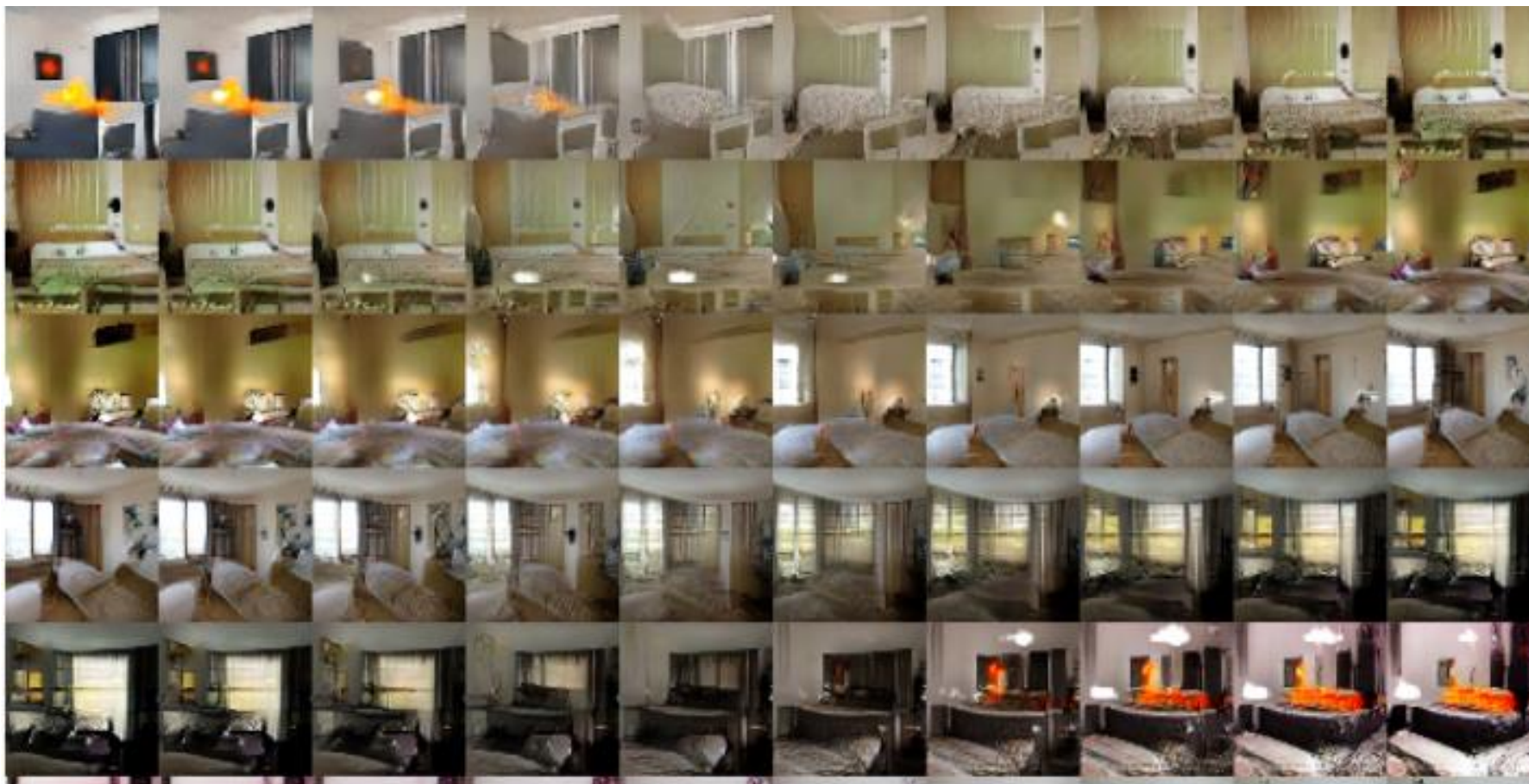
# Results



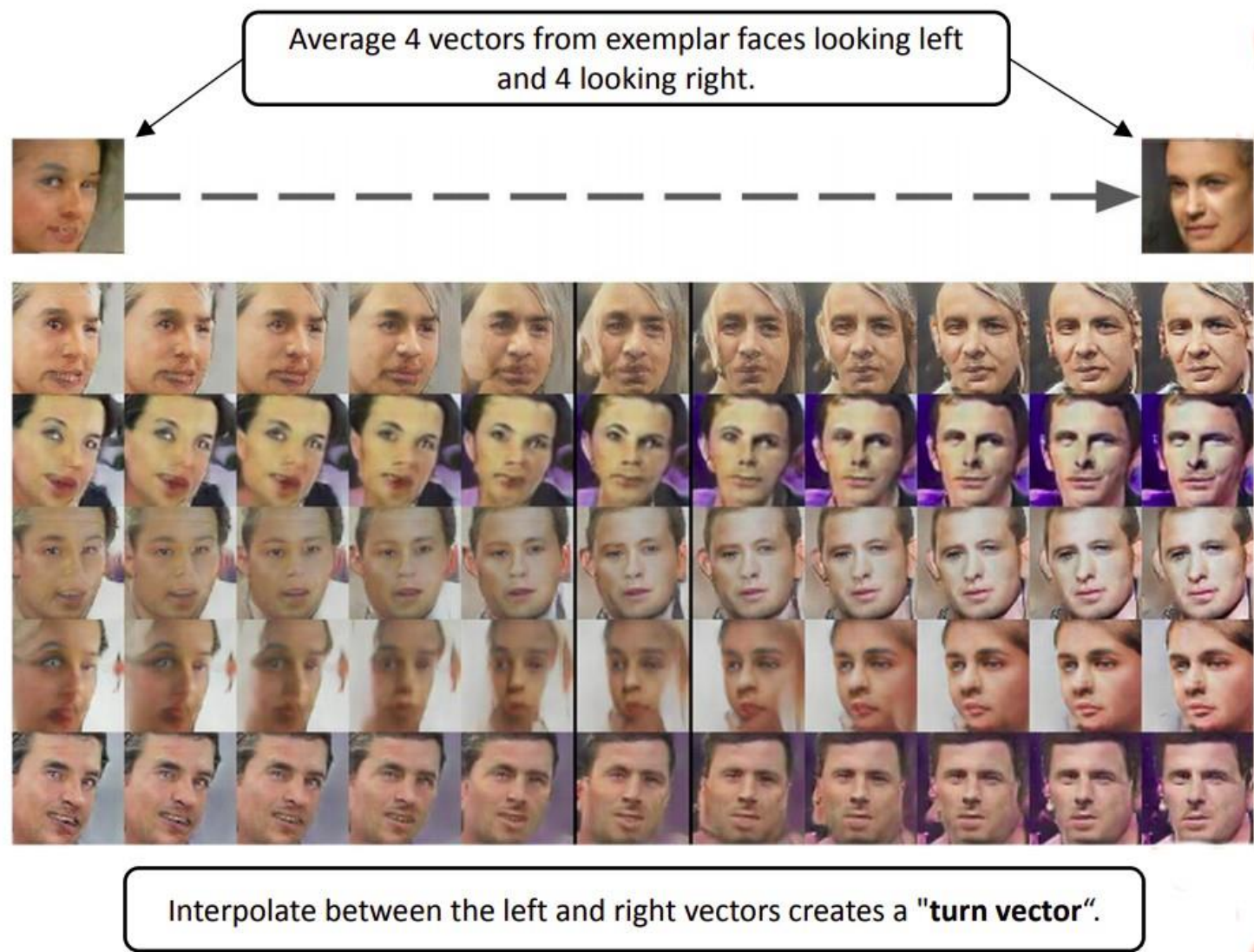


# Results

INTERPOLATION BETWEEN A SERIES OF RANDOM POINTS IN  $\mathcal{Z}$



# Results





# Results



(Bottom) Samples generated after dropping out "window" concept.  
Some windows are removed or transformed.  
The overall scene stays the same, indicating the generator has separated objects  
(windows) from the scene.



# Results

