CSC 411

Computer Organization (Fall 2024) Lecture 22: Basic CPU design

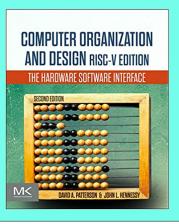
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Disclaimer

Some figures and slides are adapted from:

Computer Organization and Design (Patterson and Hennessy)

The Hardware/Software Interface



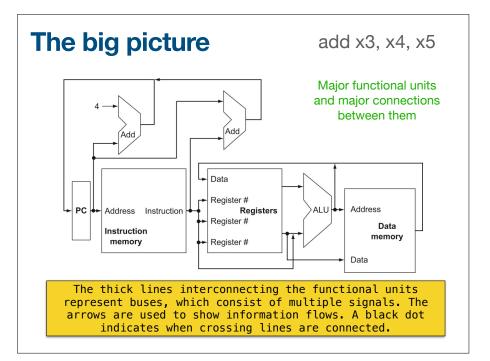
Introduction

- We will study two RISC-V implementations
 - a simplified version (single-cycle)
 - a more realistic pipelined version
- Focusing on a small instruction set (subset of an actual RISC-V implementation)
 - memory access: lw, sw
 - · arithmetic/logical: add, sub, and, or
 - control transfer: beq, j

Single-cycle CPU

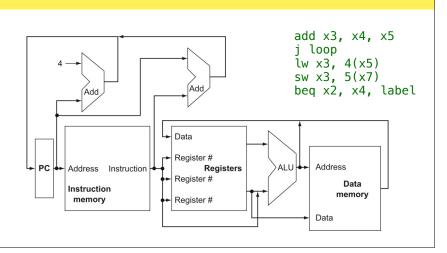
Instruction execution

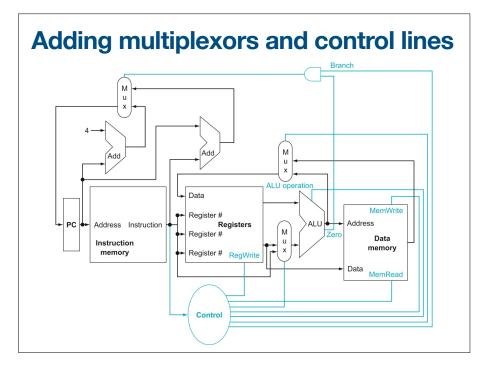
- Program counter (PC)
 - · requires access to instruction memory
 - PC determines address for instruction "fetching"
 - must be updated accordingly (PC+4 or target address)
- Register file
 - after "decoding" instruction, operands can be read from the register file
- ALU
 - depending on the type of instruction, use the ALU for "executing" the instruction
 - · may require accessing data memory for load/stores
 - · may write back to the register file
- Control logic
 - · outputs values to control lines from instruction encoding



Practice

Trace the flow of the following instructions



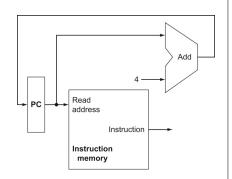


Building a datapath

- Datapath
 - · elements that process data and addresses in the CPU
 - registers, ALUs, multiplexors, memories, ...
- In the next slides, we will build a (toy) RISC-V datapath incrementally
 - leading to the "big-picture" figure from the previous slide

Instruction fetch

- State elements
 - · PC register
 - 32-bit register written at the end of every clock-cycle
 - · instruction memory
 - only read access, thus it can be treated as combinational logic
 - no control signal is needed
 - (when program is loaded, memory is written — ignored for simplicity)



Adder

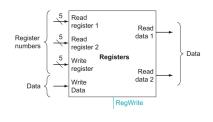
always adds two 32-bit inputs

Implementing R-type instructions

- Register file (state element)
 - always outputs the contents of the registers corresponding to the Read register inputs, no other control inputs are needed
 - a register write must be indicated to write the value to a register
 - writes are (falling) edge-triggered, therefore the design can legally read and write the same register within a clock cycle: the read gets the value written in an earlier clock cycle, while the value written will be available to a read in a subsequent clock cycle

► ALU

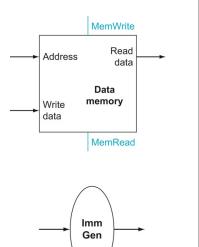
- controlled with the ALU operation signal, which will be 4 bits wide
- the Zero detection output is used to implement conditional branches





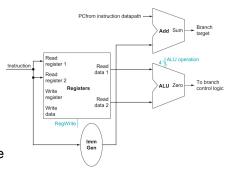
Implementing loads/stores

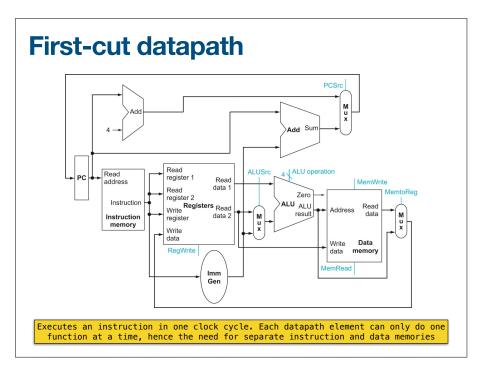
- Data memory unit (state element)
 - inputs: the memory address and the write data
 - · output: the read result
 - · edge-triggered for writes
 - separate read and write controls, although only one of these may be asserted on any given clock
 - a read signal is required, since, unlike the register file, reading the value of an invalid address can cause problems
- Immediate generation unit (ImmGen)
 - selects a 12-bit field that is signextended into a 32-bit result



Implementing branch instructions

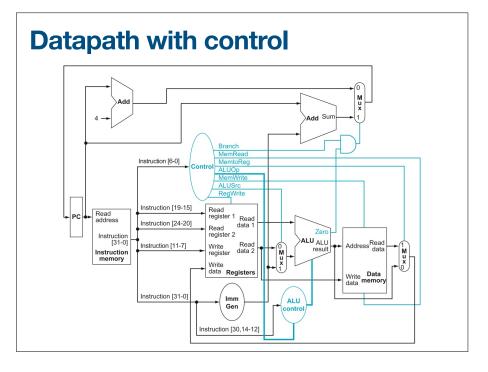
- Read and compare register operands
 - uses the ALU to evaluate the branch condition
- Calculate target address
 - uses a separate adder to compute the sum of the PC and immediate (the branch displacement)
 - control logic is used to decide whether the incremented PC or branch target should replace the PC, based on the Zero output of the ALU





Control signals are derived from instruction

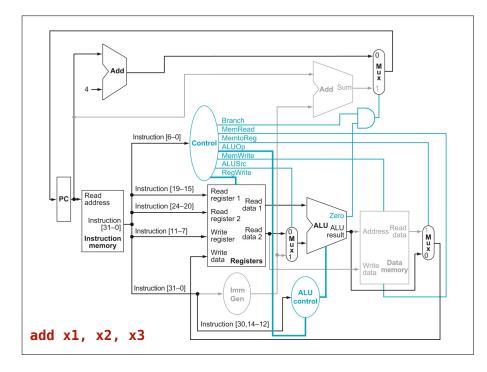
	Name	Fields Fields								
	(Bit position	31:25	24:20	19:15	14:12	11:7	6:0			
(a)	R-type	funct7	rs2	rs1	funct3	rd	opcode			
(b)	I-type	I-type immediate[11:0]		rs1	funct3	rd	opcode			
(c)	S-type	immed[11:5]	rs2	rs1	funct3	immed[4:0]	opcode			
(d)	SB-type	immed[12,10:5]	rs2	rs1	funct3	immed[4:1,11]	opcode			
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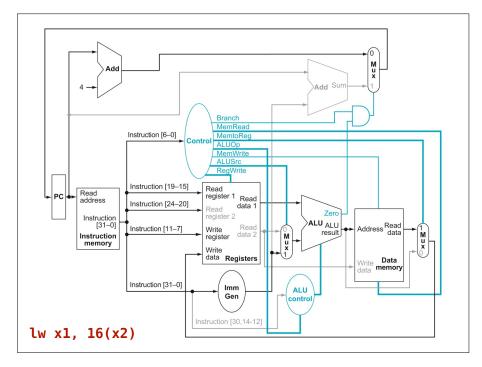


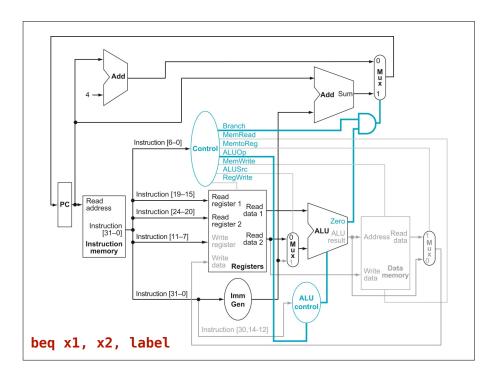
Performance issues

- Longest delay determines clock period
 - · critical path: load instruction
 - instruction memory → register file → ALU → data memory → register file
- Not feasible to vary period for different instructions
- We will improve performance by pipelining

Examples

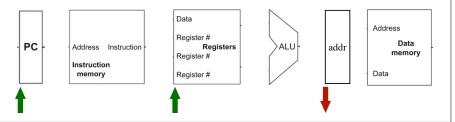






Latches and clocks in a single-cycle design

- Instruction executes in a single cycle
 - at the rising edge, a new PC is recorded
 - at the rising edge, the result of the previous cycle is recorded
 - at the falling edge, the address of LW/SW is recorded so we can access the data memory in the 2nd half of the cycle



Practice

- Consider the following instruction mix
 - R-type (20%), I-type/non-lw (24%), Load (24%), Store (12%), Branch (16%), Jump (4%)
 - · what fraction of all instructions use data memory?
 - what fraction of all instructions use the sign extend?

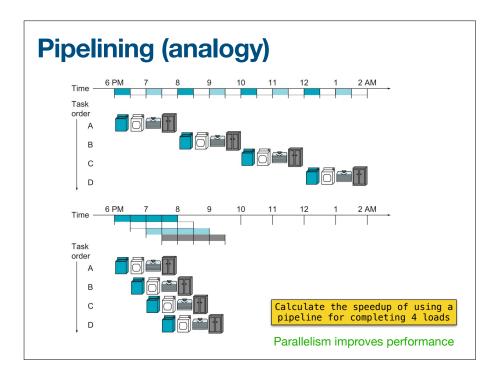
Practice

► If the *MemToReg* wire is always set to 0, which instructions fail to operate correctly?

Practice

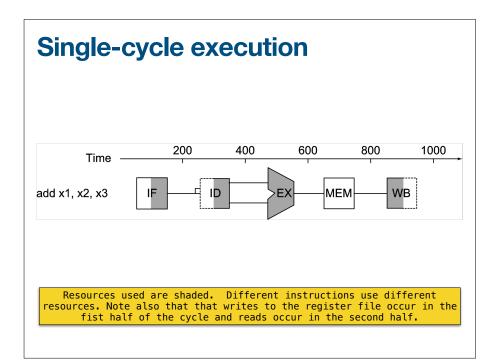
► If the *ALUSrc* wire is always set to 0, which instructions fail to operate correctly?

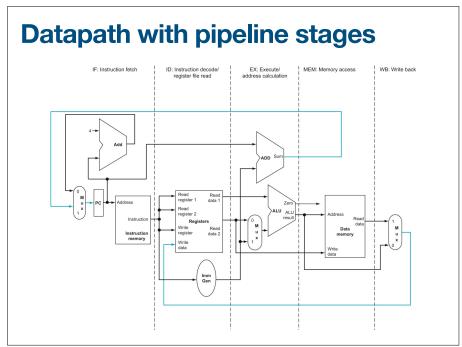
Pipeline execution

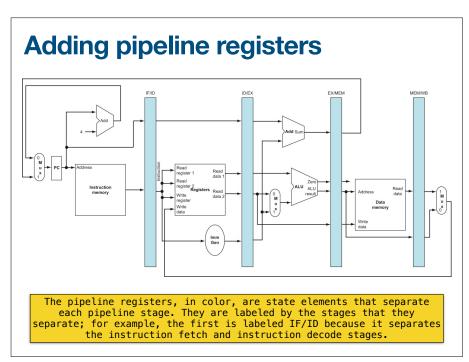


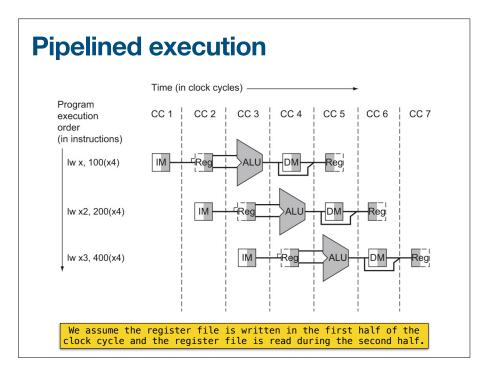
RISC-V pipeline

- Consider 5 stages (steps)
 - IF: instruction fetch from memory
 - ID: instruction decode & register read
 - EX: execute operation or calculate address
 - MEM: access memory operand
 - WB: write result back to register









Pipeline performance

- Assume time per stage is according to the table below
 - 100ps for register read or write
 - 200ps for all other stages

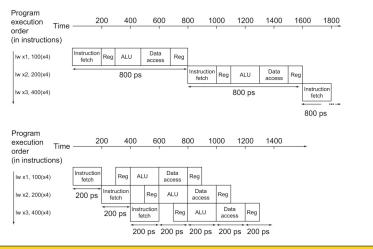
Instruction class	Instruction fetch	Register read	ALU operation	Data access	Register write	Total time
Load word (lw)	200 ps	100 ps	200 ps	200 ps	100 ps	800 ps
Store word (sw)	200 ps	100 ps	200 ps	200 ps		700 ps
R-format (add, sub, and, or)	200 ps	100 ps	200 ps		100 ps	600 ps
Branch (beq)	200 ps	100 ps	200 ps			500 ps

Note this calculation ignores the delays from multiplexers, PC access, control unit, and sign extension

Pipeline performance

- If all stages take the same time
 - time between pipelined instructions is the time between non-pipelined instructions divided by the number of stages
 - if stage times are not balanced, speedup is less
- Speedup due to increased throughput
 - · latency (time for each instruction) does not decrease
 - it may go up, due to the need for latches at each stage
- Instructions take more cycles to finish
 - although clock speed goes high

Pipeline performance



Using the same hardware components we see a fourfold speed-up on average time between instructions, from 800 ps down to 200 ps. Stage times of a computer are limited by the slowest resource, either the ALU operation or the memory access. We assume the write to the register file occurs in the first half of the clock cycle and the read from the register file occurs in the second half.

Practice

 Add NOP instructions to the code below so that it will run "correctly" on a pipeline