

## Logistic regression (part I)

Prof. Marco Alvarez, Computer Science  
University of Rhode Island

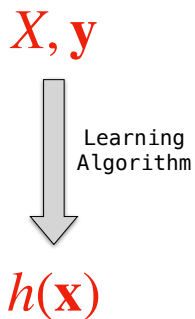
## Linear classifiers

### Binary classification

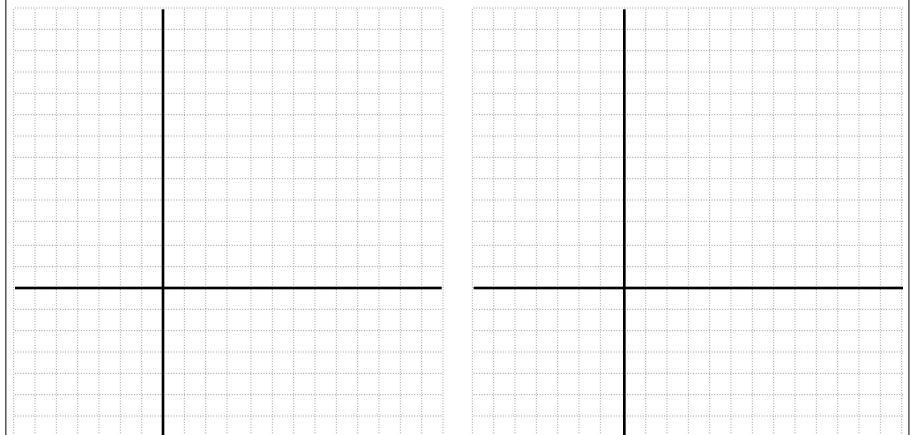
#### ► Goal

- learn a decision boundary between two classes

$x_1$	...	$x_d$	$y$
0.5	...	0.1	+1
0.3	...	0.9	-1
0.3	...	0.875	-1
0.45	...	0.15	+1
...	...	...	...

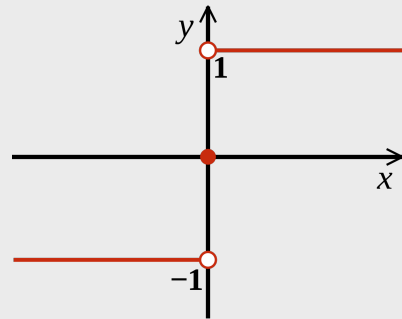


### Plots (regression x classification)



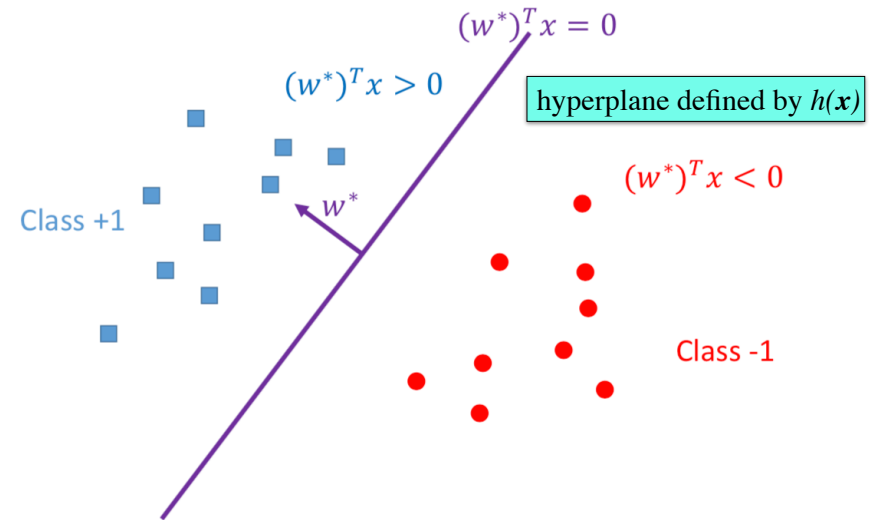
## The *sign* function

$$\text{sign}(x) = \begin{cases} -1 & \text{if } x < 0, \\ 0 & \text{if } x = 0, \\ +1 & \text{if } x > 0 \end{cases}$$



$$h(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x})$$

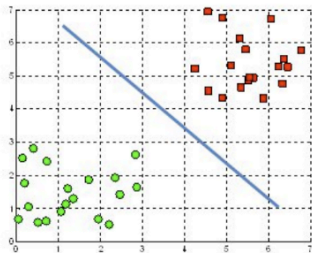
## Decision boundary



credit: yingyu liang, cos 495, princeton

## Decision boundary

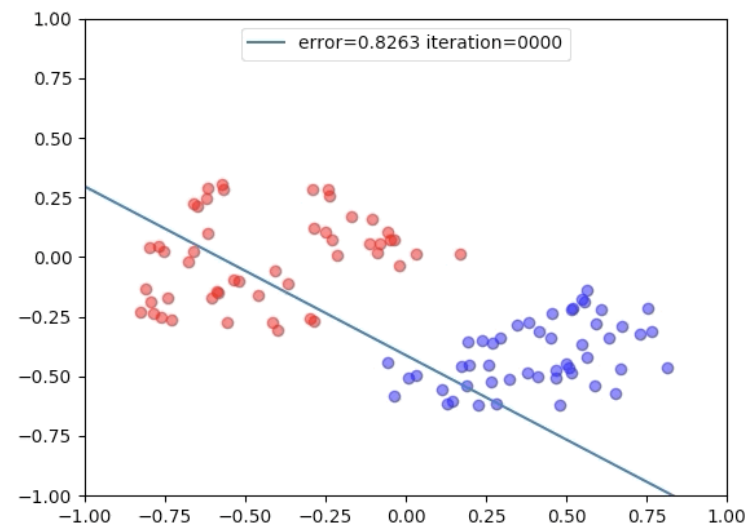
A hyperplane in  $\mathbb{R}^2$  is a line



$$0 = b + w_1 x_1 + w_2 x_2$$

Image credit: <https://mc.ai/why-activation-function-is-used-in-neural-network/>

## Learning



## Example

- Provide a solution (weight vector)

$x_0$	$x_1$	$x_2$	$y$
1	0	0	-1
1	0	1	-1
1	1	0	-1
1	1	1	+1

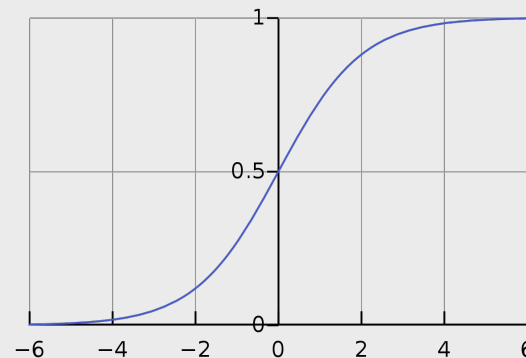
# Logistic regression

## Logistic regression

- Binary classifier
  - $\mathcal{D} = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(n)}, y^{(n)})\}$
  - $\mathbf{x}^{(i)} \in \mathbb{R}^d$ ,  $y^{(i)} \in \{-1, +1\}$
  - uses a **logistic function**
  - models **probability** of output given input
- It is considered a **linear classifier**
  - with a non-linear *activation function*

## Logistic function

$$\sigma(x) = \frac{1}{1 + e^{-x}} = \frac{e^x}{e^x + 1}$$



mapping  $\mathbb{R}$  to  $[0,1]$

continuous and  
differentiable

## Probabilistic interpretation

$$h(\mathbf{x}) = \sigma(\mathbf{w}^T \mathbf{x}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}$$

Probability of class +1  $P(y = +1 \mid \mathbf{x}) = \sigma(\mathbf{w}^T \mathbf{x})$

Probability of class -1  $P(y = -1 \mid \mathbf{x}) = 1 - P(y = +1 \mid \mathbf{x})$   
 $P(y = -1 \mid \mathbf{x}) = \sigma(-\mathbf{w}^T \mathbf{x})$  (show)

$$P(y \mid \mathbf{x}) = \frac{1}{1 + e^{-y\mathbf{w}^T \mathbf{x}}} = \sigma(y\mathbf{w}^T \mathbf{x})$$

## Another look

