

Introduction to Atomistic Spin Dynamics Simulations

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- **Timetable:**

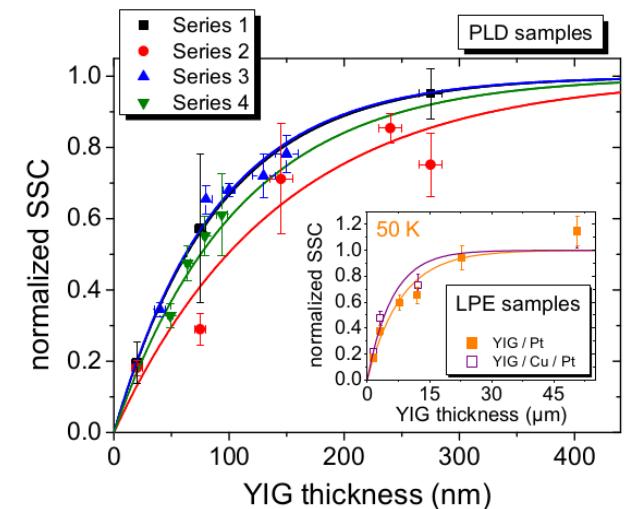
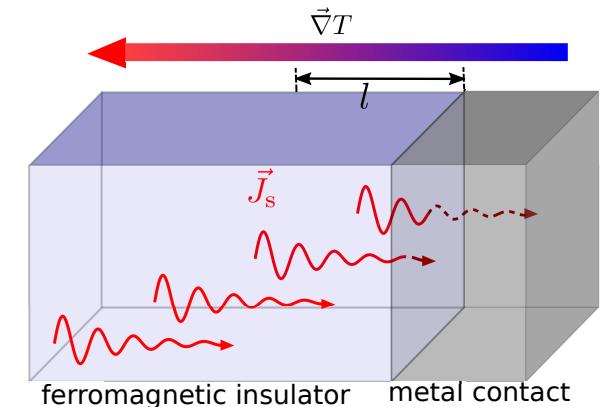
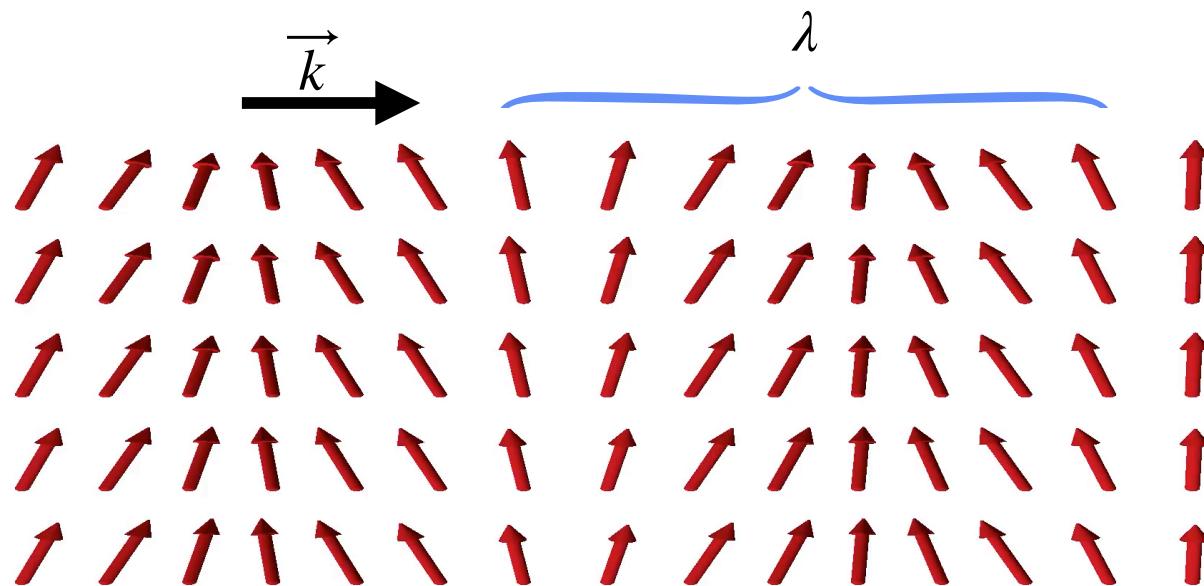
- **Today (10.00-15.00):** Introduction and compiling the code
- **Next week:** 3 different tasks you work on in teams
- **Tuesday (14.00-16.00):** Q&A
- **Friday (14.00-16.00):** Final evaluation

- **Tasks:**

- Simulate monochromatic spin waves and calculate dispersion curve
- Simulate magnetization curve
- Simulate laser-induced demagnetization
- Your ideas?

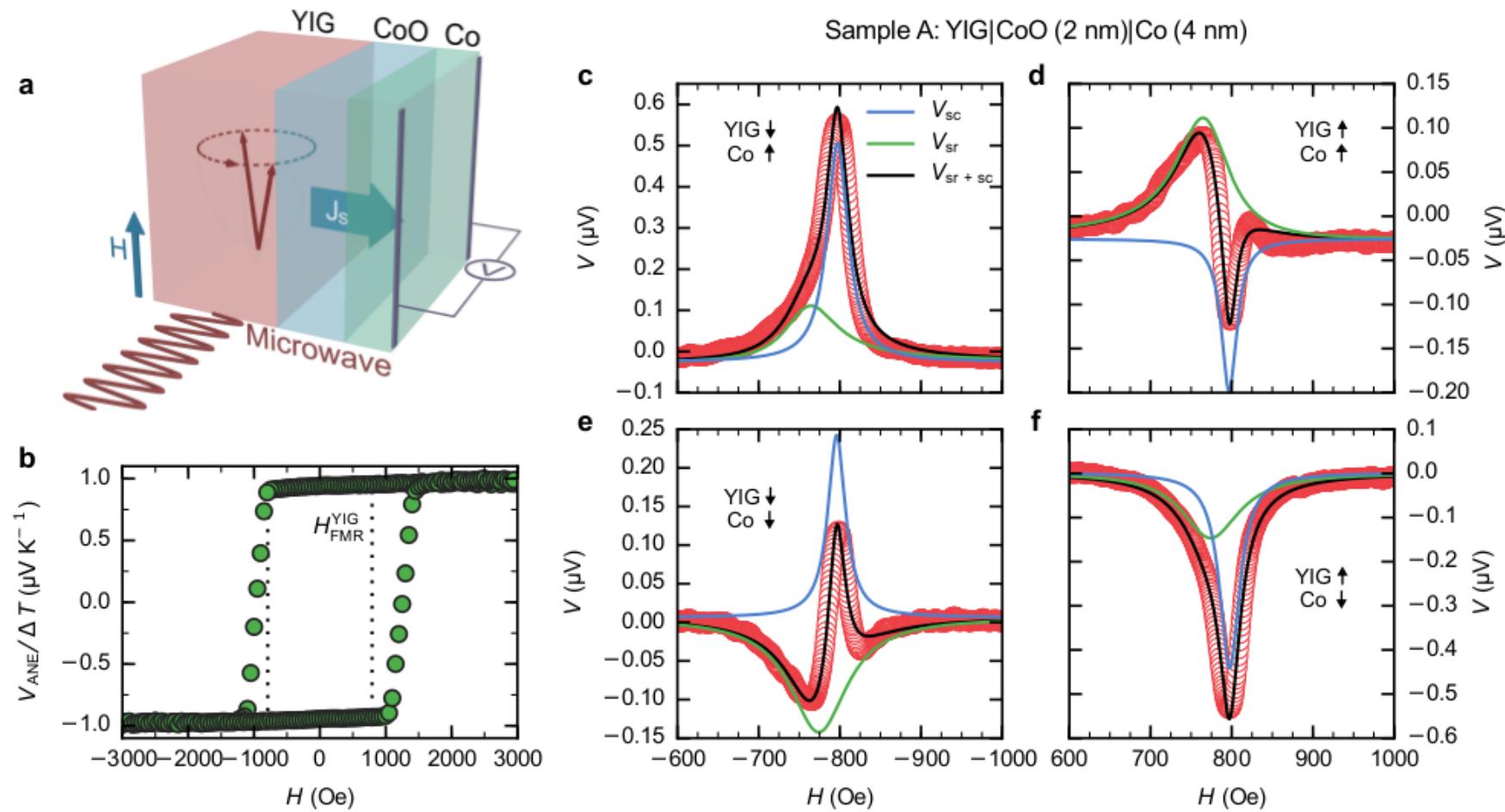
Applications

Example 1: Magnonic Spin Currents

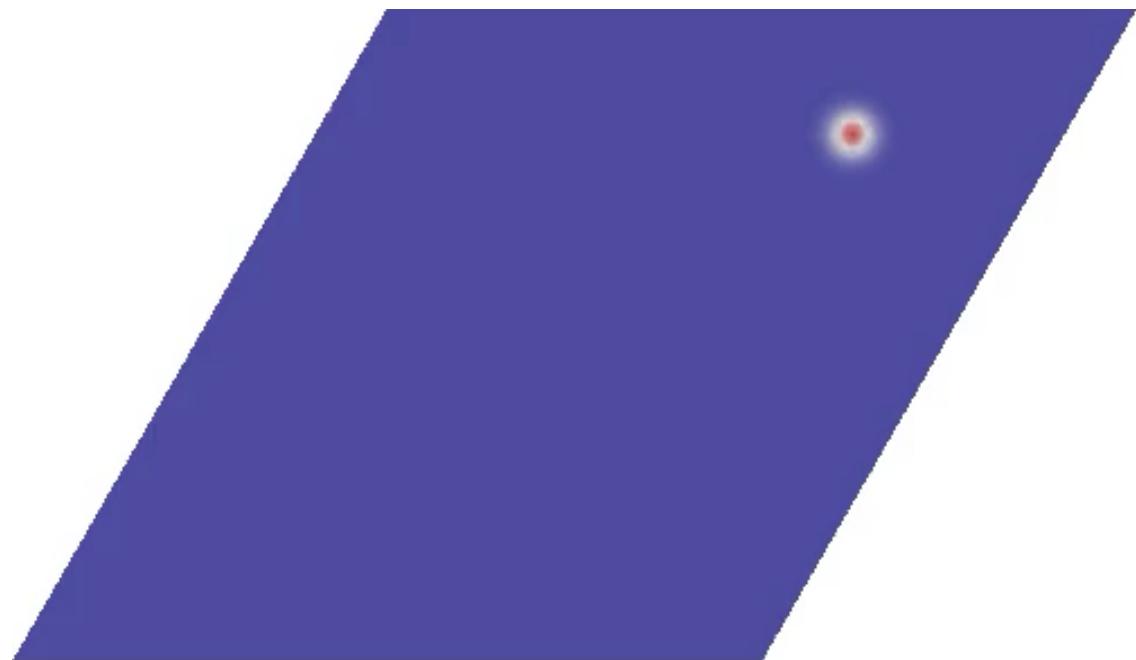
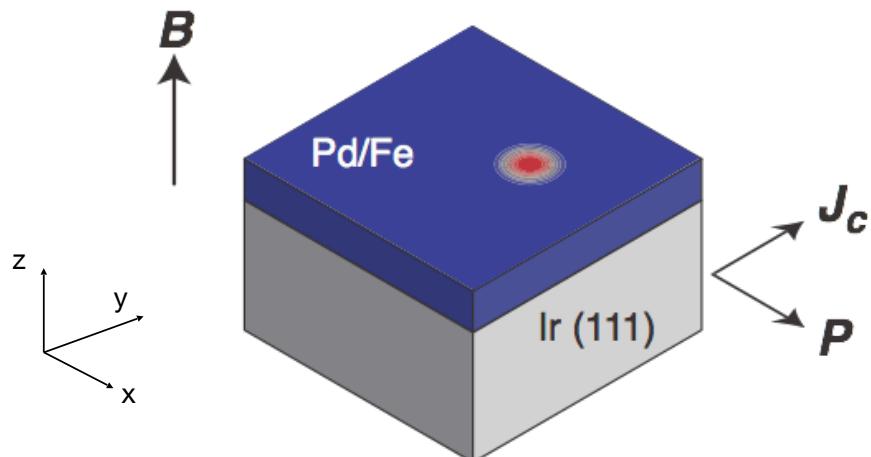


Kehlberger et al., PRL 115, 096602 (2015)

Example 1: Magnonic Spin Currents



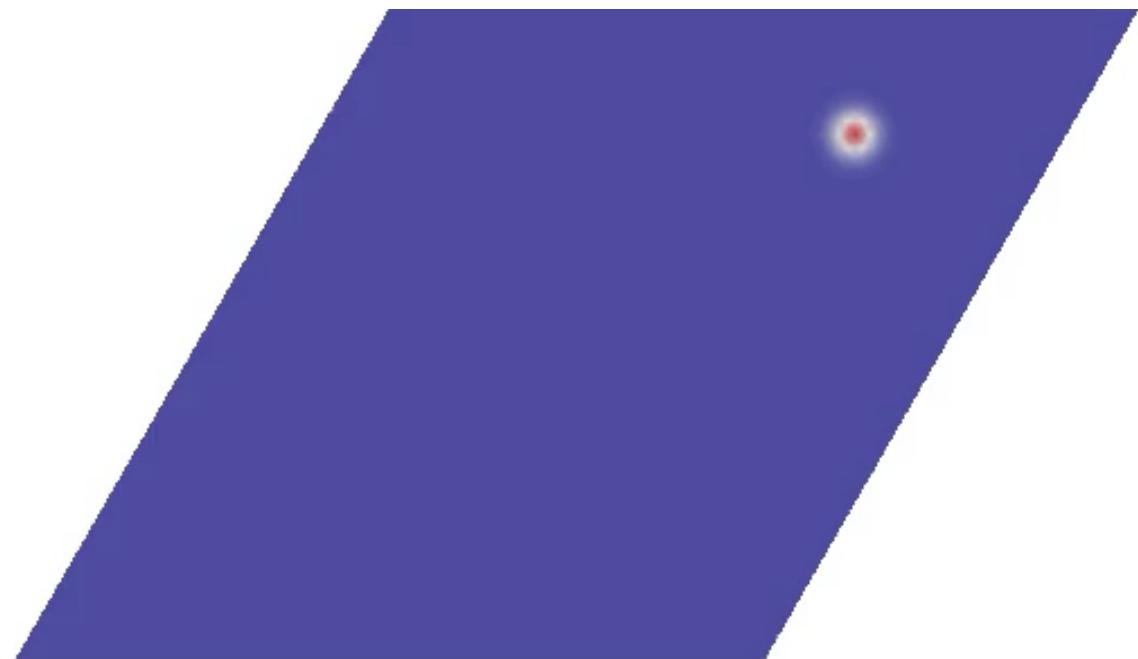
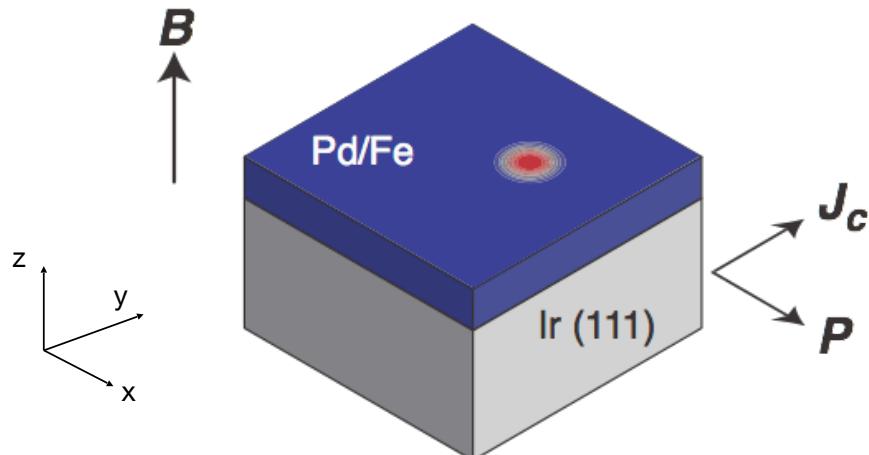
Example 2: Current driven skyrmion motion



Dynamics described by Thiele equation:

$$q \mathbf{G} \times \frac{\partial \mathbf{X}}{\partial t} + \alpha D \frac{\partial \mathbf{X}}{\partial t} = \mathbf{F}$$

Example 2: Current driven skyrmion motion



Dynamics described by Thiele equation:

$$q \mathbf{G} \times \frac{\partial \mathbf{X}}{\partial t} + \alpha D \frac{\partial \mathbf{X}}{\partial t} = \mathbf{F}$$

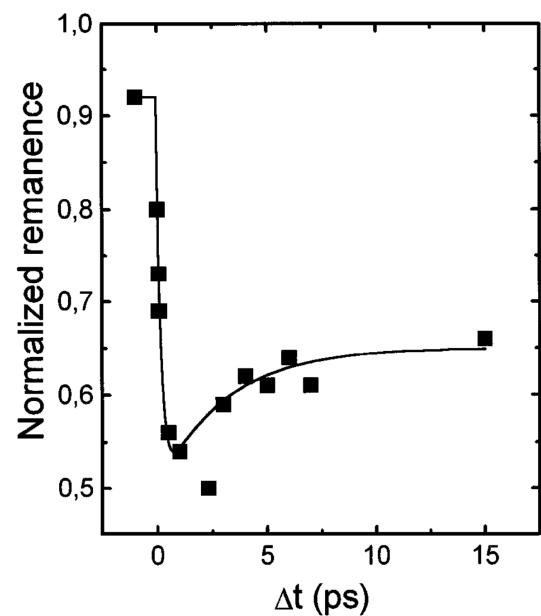
Time-dependent forces by helicity dynamics:

$$D_\psi \frac{\partial \psi}{\partial t} = \sigma_\psi \hbar \beta_{DL} \eta \cos(\phi_p - \phi_t) - \frac{\partial U}{\partial \psi}$$

U. Ritzmann et al., Nat. Electron. 1, 451 (2018)

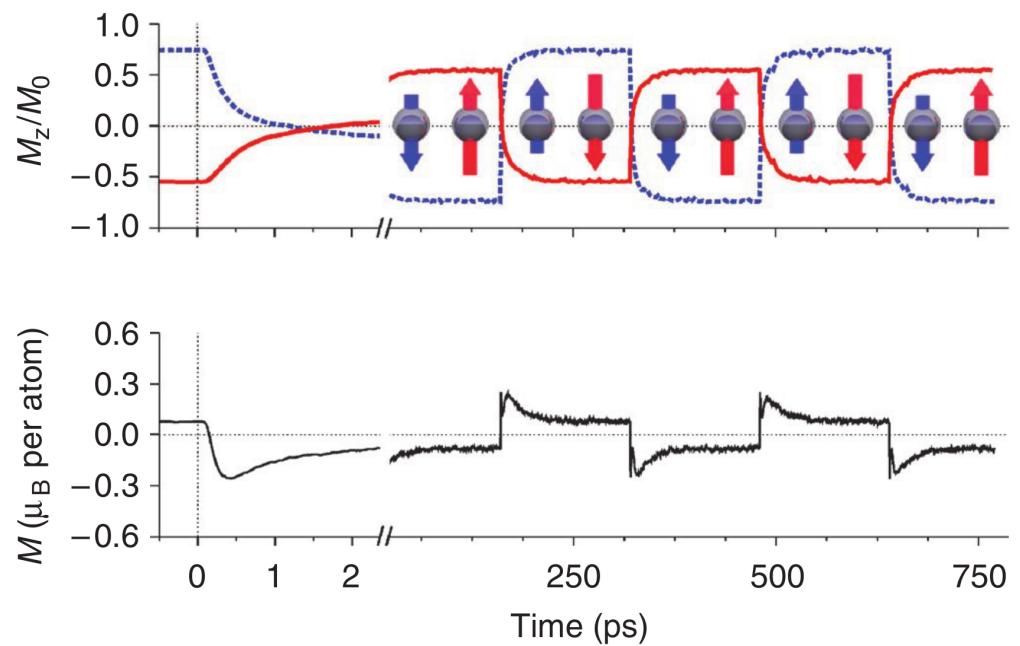
Example 3: Ultrafast Demagnetization and Switching

Laser-induced demagnetization in nickel:



Beaurepaire et al., PRL 76, 4250 (1996)

Deterministic switching in GdFeCo:



Ostler et al., Nat. Commun. 3, 666 (2012)

Basics

Numerical integration of stochastic Landau-Lifshitz-Gilbert equation:

$$\frac{d\mathbf{m}_i}{dt} = -\frac{\gamma}{\mu_s(1+\alpha^2)} \times \left(-\frac{\partial \mathcal{H}}{\partial \mathbf{m}_i} + \zeta_i \right) - \frac{\alpha\gamma}{\mu_s(1+\alpha^2)} \mathbf{m}_i \times \left(\mathbf{m}_i \times \left(-\frac{\partial \mathcal{H}}{\partial \mathbf{m}_i} + \zeta_i \right) \right)$$

Hamiltonian:

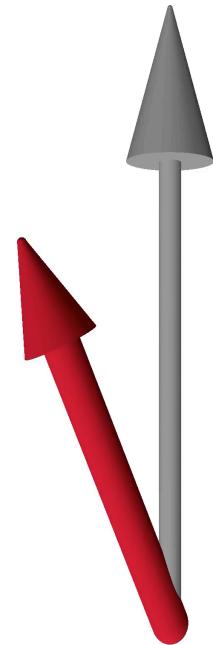
Key features:

$$\mathcal{H} = -\sum_{ij} J_{ij} \mathbf{m}_i \cdot \mathbf{m}_j - \sum_{ij} \mathbf{D}_{ij} \cdot (\mathbf{m}_i \times \mathbf{m}_j) - \sum_i d (\mathbf{m}_i^x)^2 - \sum_i \mathbf{B} \cdot \mathbf{m}_i$$

- Atomic resolution
- Exchange interaction
- Complex magnetic structures and interactions
- Ultrafast dynamics and non-equilibrium effects

Thermal noise: $\langle \zeta_i(t) \rangle = 0 \quad \zeta_{i\eta}(0)\zeta_{j\theta}(t) = \delta_{ij}\delta_{\eta\theta}\delta(t)2\alpha k_B T \mu_s / \gamma$

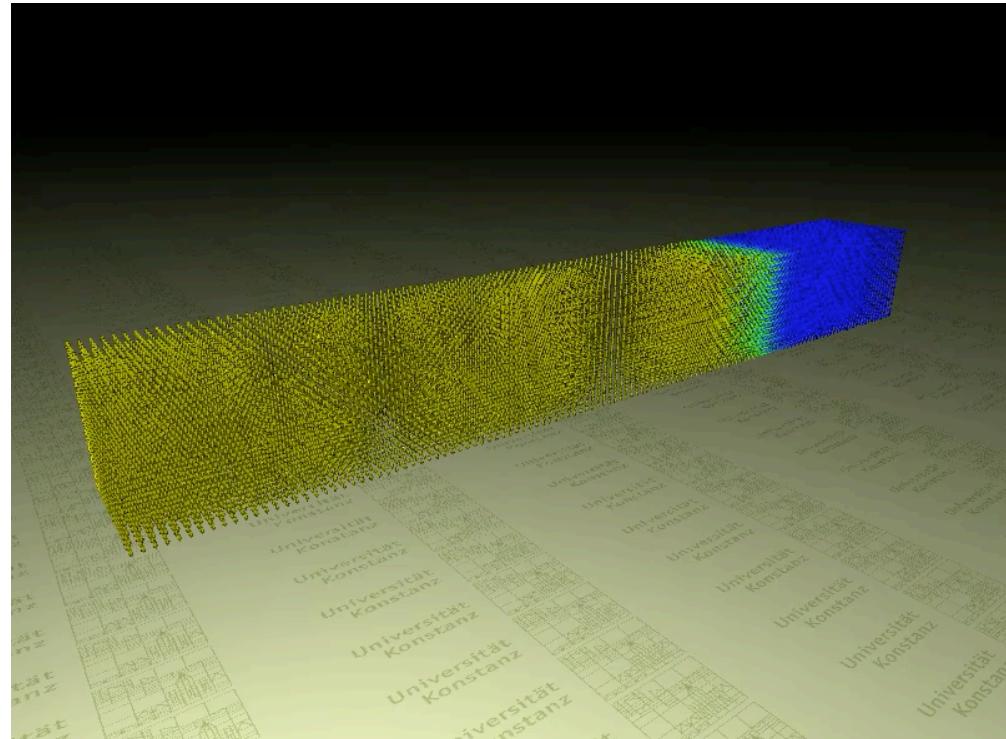
and further dissipative contributions as **STT**, **SOT** ...



Atomistic spin dynamics simulations



- Lattice in simulations corresponds to real magnetic lattice structure (in contrast to micromagnetics)
- Simulations with up to **10 000 000 lattice points** and **timesteps of 0.1-1 fs**
- Input parameters can be obtained by *ab initio* calculations or can be fitted from experiments



source: Uli Nowak, Konstanz

Advantages:

- **Includes lattice effects**
- Correct dispersion curve
- Exchange interaction beyond NN
- **Complex magnetic structures**
- Antiferromagnets, ferrimagnets
- Non-collinear states and magnetic textures
- **Non-equilibrium effects**

Disadvantages:

- Limited to small system sizes and short timescales
- Thermal noise and phenomenological damping
- is a pure phenomenological model
- Classical spin model

Stochastic equation of motion:

$$\dot{x}_i(t) = f(x_i(t), t) + g(x(t), t)\zeta(t)$$

Heun-method:

Predictor-step (Euler):

$$\bar{x}_{n+1} = x_n + f(x_n, t_n) \Delta t + g(x_n, t_n) \zeta(t_n)$$

Heun-step:

$$\begin{aligned} x_{n+1} &= x_n + \frac{1}{2} (f(x_n, t_n) + f(\bar{x}_{n+1}, t_{n+1})) \Delta t \\ &\quad + \frac{1}{2} (g(x_n, t_n) + g(\bar{x}_{n+1}, t_{n+1})) \zeta(t_n) \end{aligned}$$

Random numbers:

Gaussian distribution: $p(\zeta) \propto \exp\left(-\frac{\zeta^2}{2\sigma^2}\right)$

Variance: $\sigma^2 = 2\alpha k_B T \frac{\mu_s}{\gamma} \Delta t$

I use a Ziggurat algorithm provided by gsl-library: [*gsl_ran_gaussian_ziggurat*](#)

Why are we using Heun-method?

Euler algorithm: $\bar{x}_{n+1} = x_n + f(x_n, t_n) \Delta t + g(x_n, t_n) \zeta(t_n)$

Converges towards wrong solution with stochastic noise: **Itô-Stratonovich dilemma**

→ Heun-method is lowest possible order (2nd order)

Higher-order Runge-Kutta are used (typically for simulations without temperature):

- advantages: adaptive step sizes possible, better stability enabling larger step size

Semi-implicit solver:

- possible larger timesteps

Mentink et al., J. Phys.: Condens. Matter **22**, 176001 (2010)

Simple examples



Examples that you can explore with more details:

- Magnon dispersion
- Magnetization curve
- Demagnetization of a ferromagnet

Spin wave dispersion in ferromagnets

Linear spin wave theory:

- Linear LLG equation:

$$\frac{\partial S_i^x}{\partial t} = -\frac{\gamma}{\mu_s} \left(2d_z S_i^y + J \sum_j (S_i^y - S_j^y) \right)$$

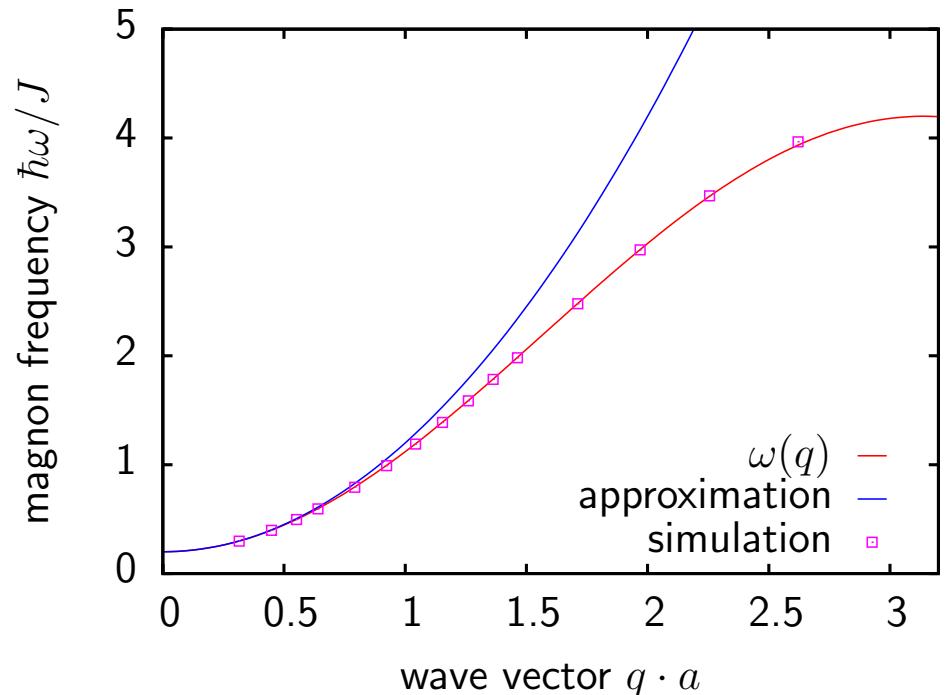
$$\frac{\partial S_i^y}{\partial t} = \frac{\gamma}{\mu_s} \left(2d_z S_i^x + J \sum_j (S_i^x - S_j^x) \right)$$

$$\frac{\partial S_i^z}{\partial t} = 0$$

- Dispersion relation:

$$\hbar\omega_{\mathbf{q}} = 2d_z + J \sum_{\theta} (1 - \cos(q_{\theta}a))$$

- Lifetime of a magnon: $\tau = \frac{1}{\alpha\omega_{\mathbf{q}}}$



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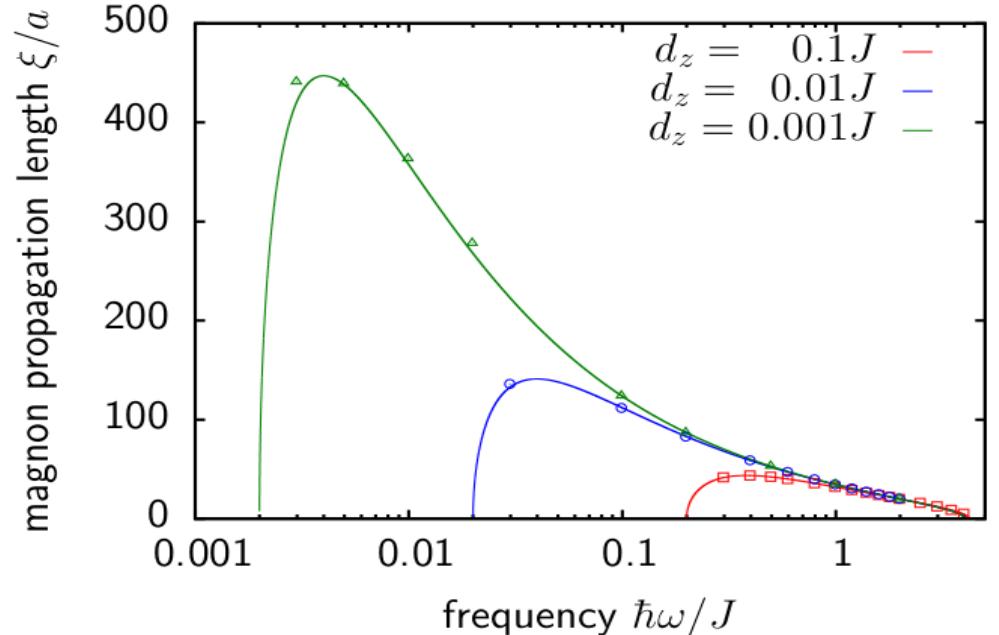
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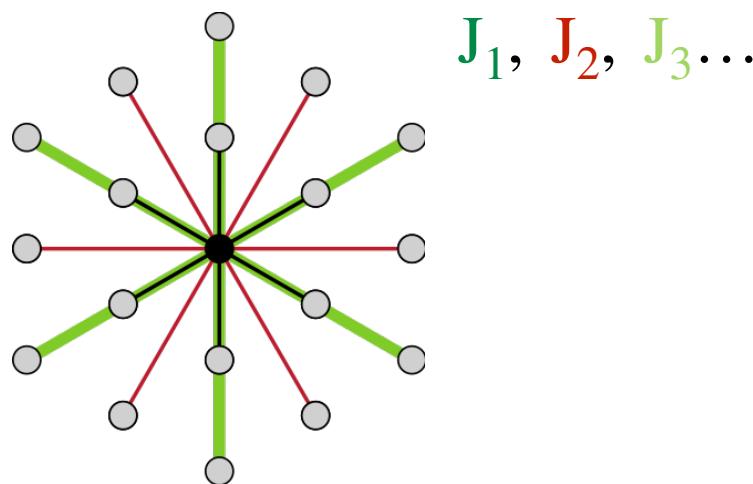
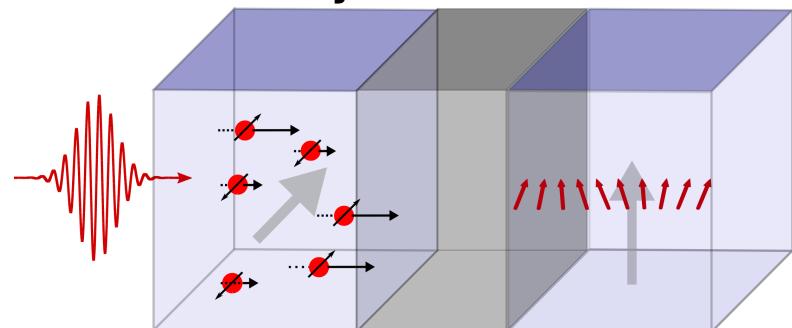


- Magnon propagation length:

$$\xi_{\mathbf{q}} = (\mathbf{v}_{\mathbf{q}} \mathbf{e}_z) \cdot \tau(\omega) = \frac{\partial \omega_{\mathbf{q}}}{\partial q_z} \cdot \frac{1}{\alpha\omega}$$

Magnon dispersion beyond nearest neighbors

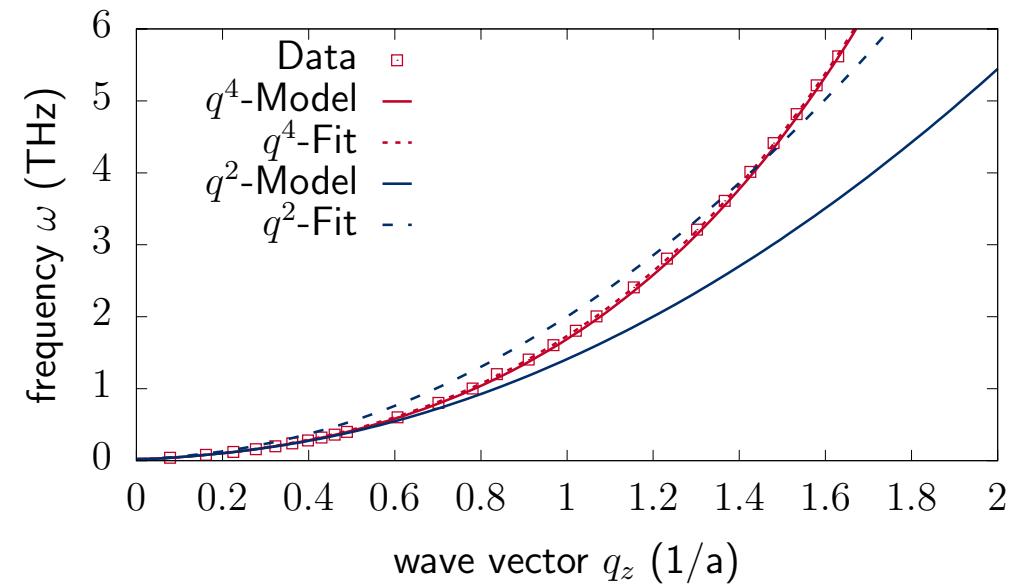
FeICuFe layer:



- Exchange interactions up to 6th neighbor:

$$\hbar\omega = \sqrt{(2k_x + J_{\text{eff}}(\mathbf{q})) \cdot (2k_x - 2k_z + J_{\text{eff}}(\mathbf{q}))}$$

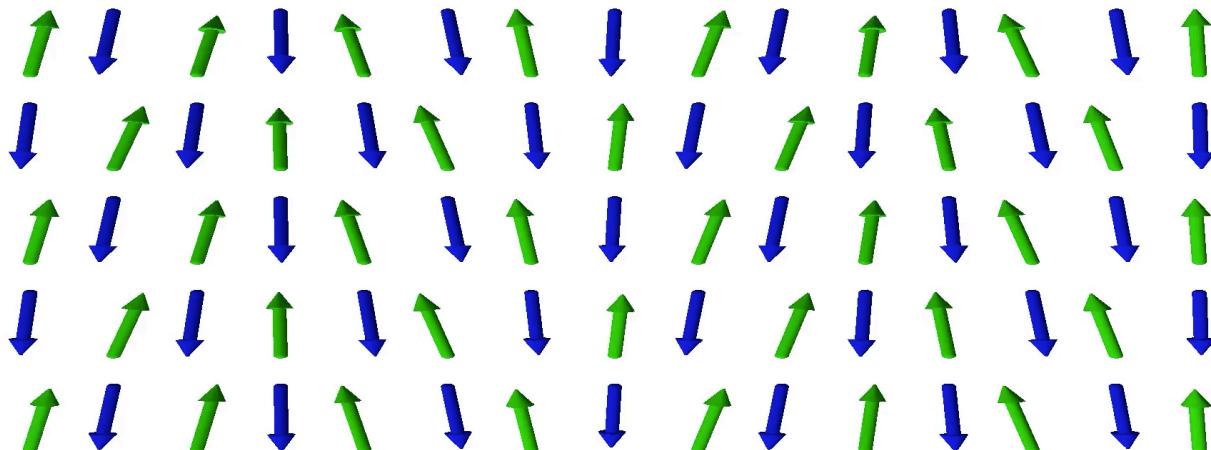
$$J_{\text{eff}}(\mathbf{q}) = \sum_{k=1}^6 J_k \cdot \left(N_k - \sum_{\theta_k} 2 \cdot \cos(\mathbf{q} \cdot \boldsymbol{\theta}_k) \right)$$



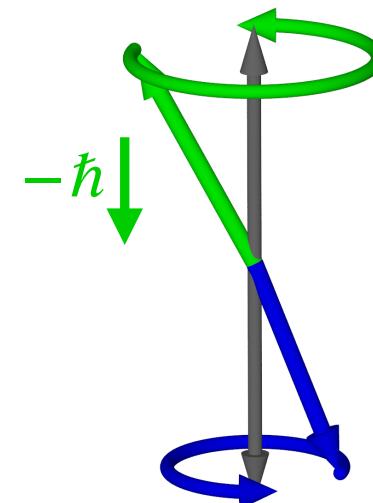
Spin waves in antiferromagnets

Dispersion relation:

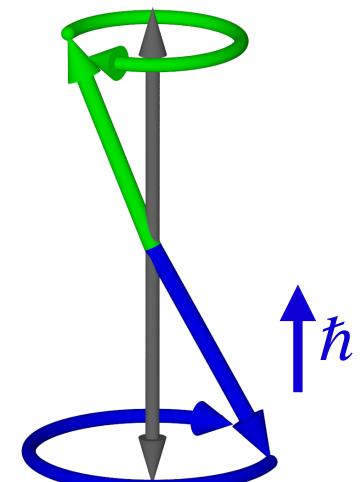
$$\omega = \pm \left(\frac{\gamma}{\mu_s} \right) \sqrt{ \left((2d_z + 6|J|)^2 - 4J^2 \left(\sum_{\theta} \cos(qa) \right)^2 \right)}$$



Counter-Clockwise



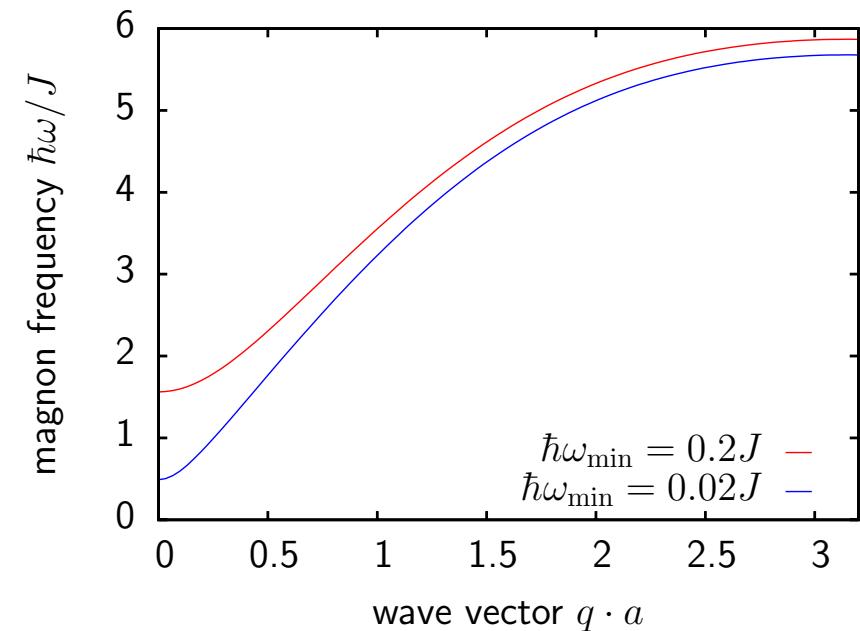
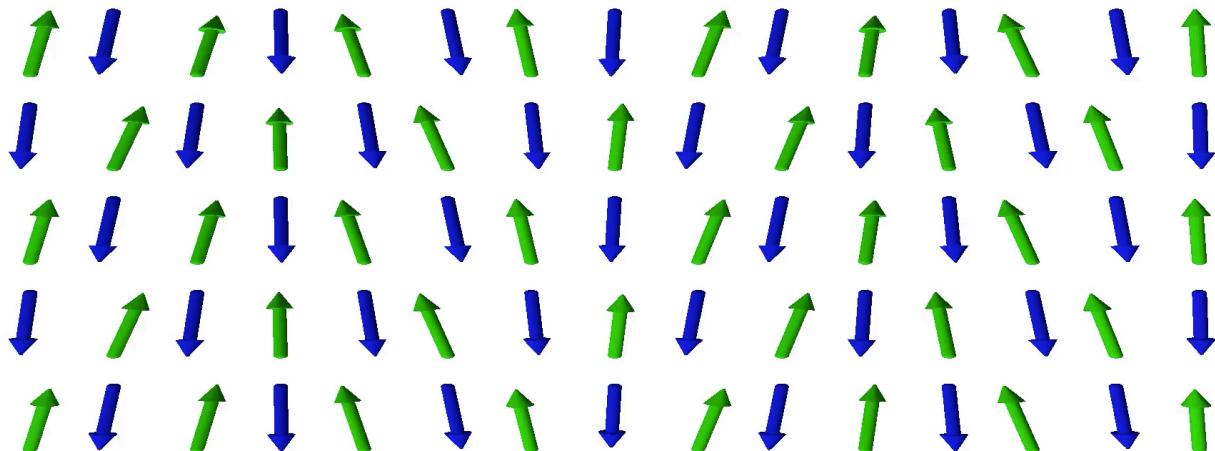
Clockwise



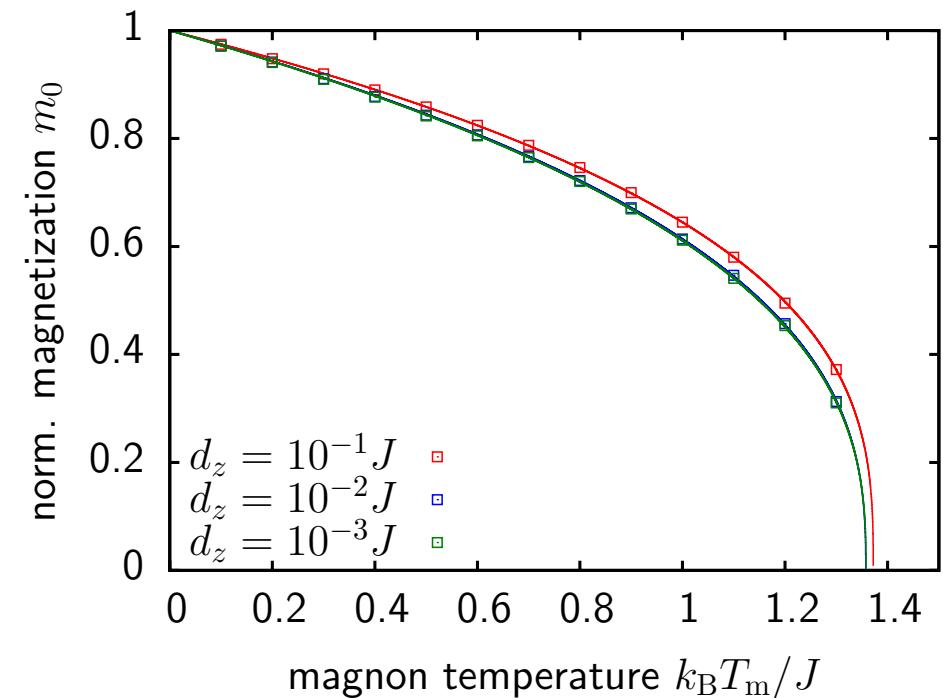
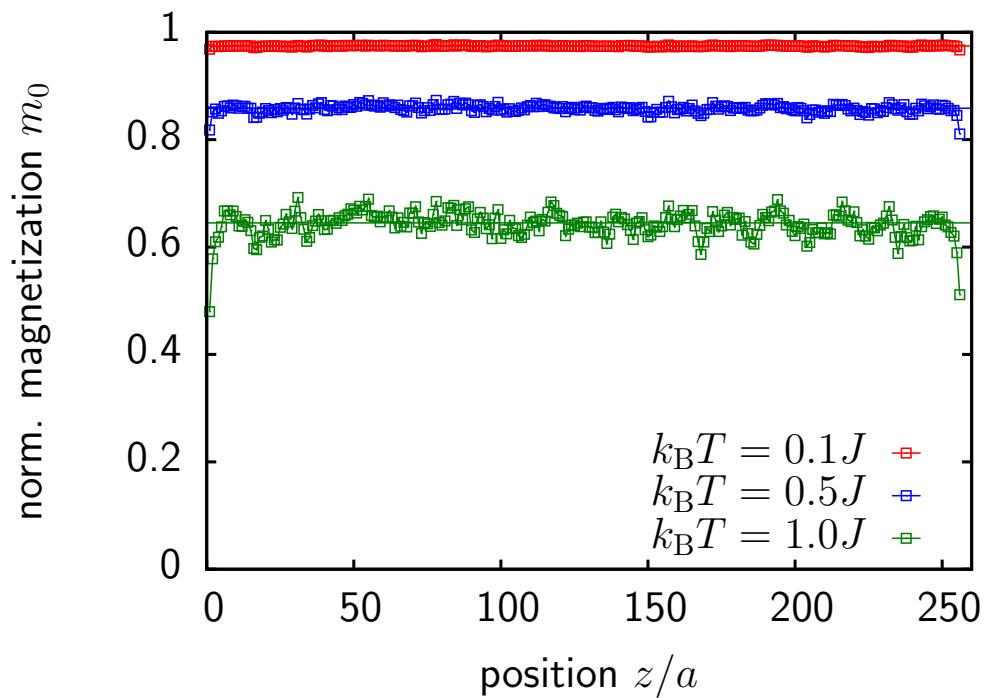
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Magnetization curve

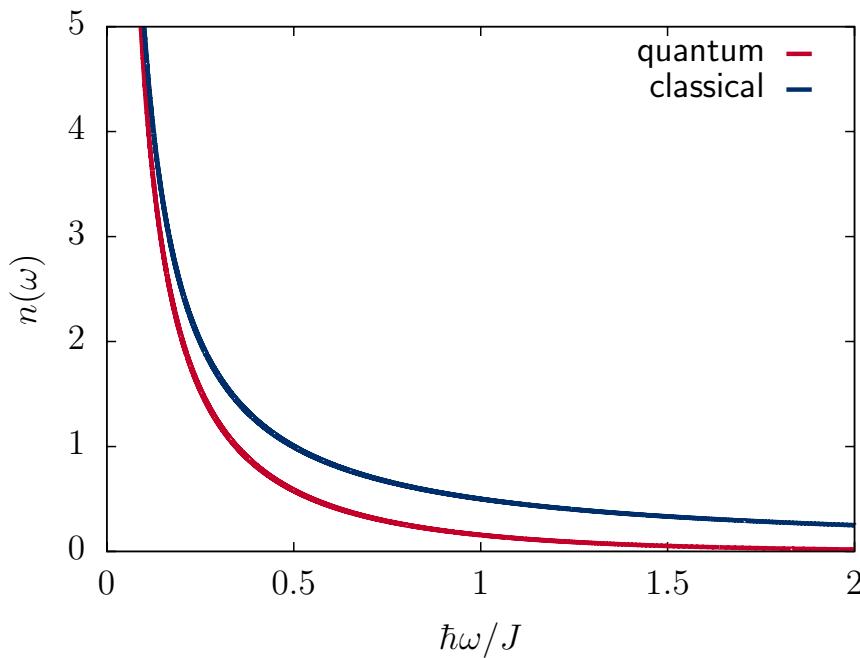


- Classical magnetization curve: linear scaling at low temperatures
- Increasing fluctuations with increasing temperature; finite size effects

- Magnons are bosons following Bose-Einstein statistics:

$$n(\omega) = \frac{1}{\exp\left(\frac{\hbar\omega}{k_B T}\right) - 1}$$

- Classical spin models lead to Rayleigh-Jeans distributions: $n(\omega) = \frac{k_B T}{\hbar\omega}$

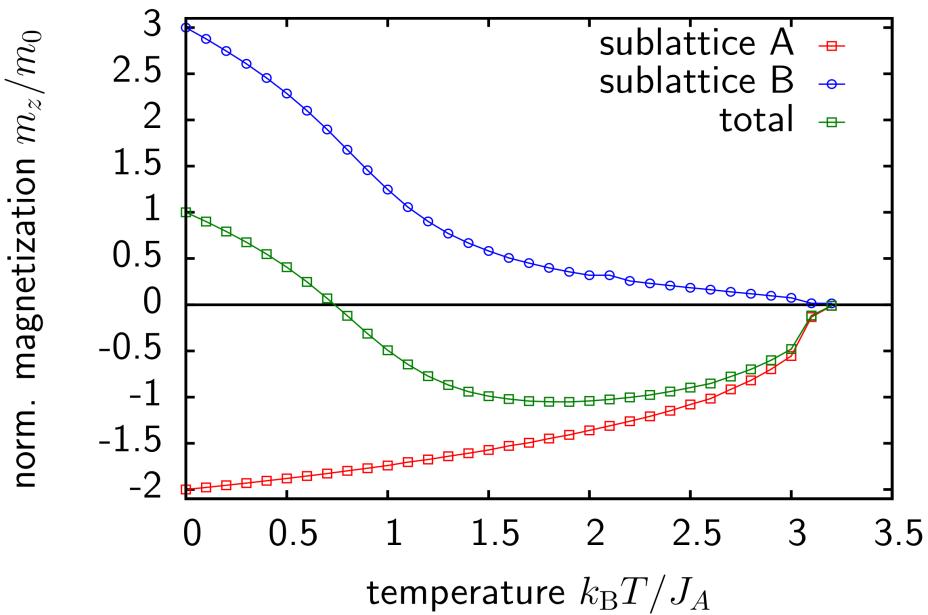


- numerical simulations include classical spin wave distributions
- High frequency with larger populations than in BE-statistics
- Different temperature-dependence of the magnetisation at low temperature

Magnetization curves in ferrimagnets

- Simulations in two-sublattice ferrimagnets
- Hamiltonian including next-nearest neighbor interaction

$$\mathcal{H} = \sum_{NN} J_{AB} \mathbf{S}_i \mathbf{S}_j + \sum_{NNN} (J_A \mathbf{S}_{i_A} \mathbf{S}_{j_A} + J_B \mathbf{S}_{i_B} \mathbf{S}_{j_B}) + \sum_i d_z S_{i,z}^2$$

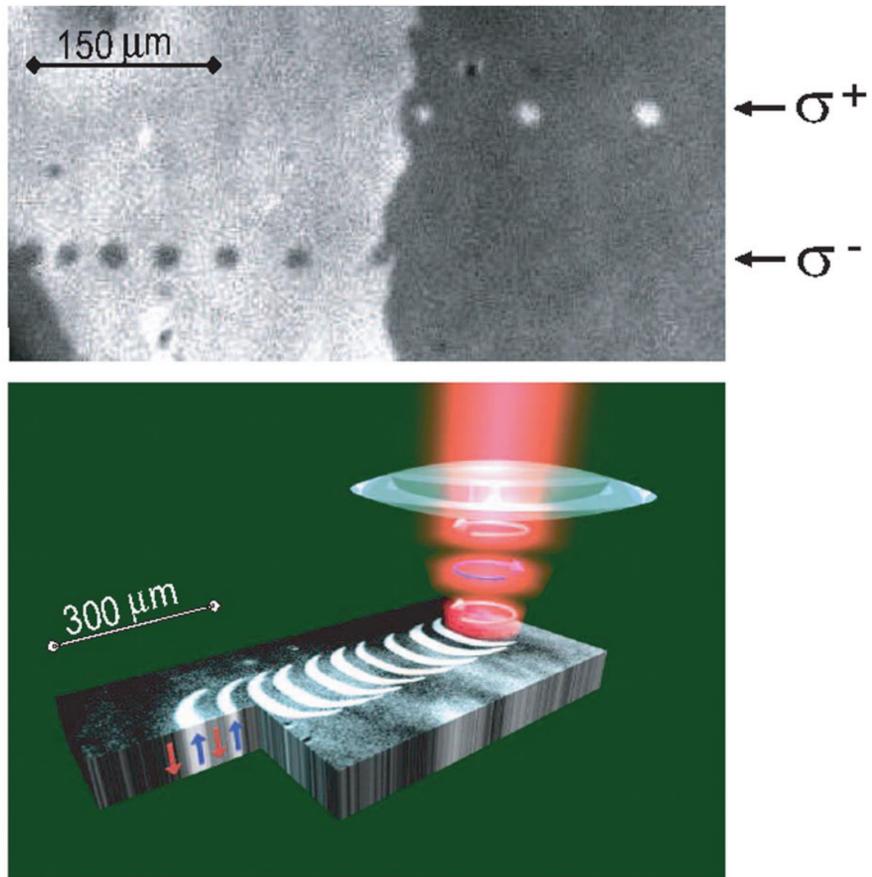


$$J_B = 0.2 J_A; \quad J = -0.1 J_A \quad \mu_B = 1.5 \mu_A$$

- sublattice B has higher magnetic moment, but demagnetizes at lower temperatures
- **Compensation point around:**

$$k_B T_{\text{comp}} \approx 0.7 J_A$$

Laser-induced Demagnetization and Switching



Simulations:

- laser-induced electron-phonon dynamics calculated by the two-temperature model:

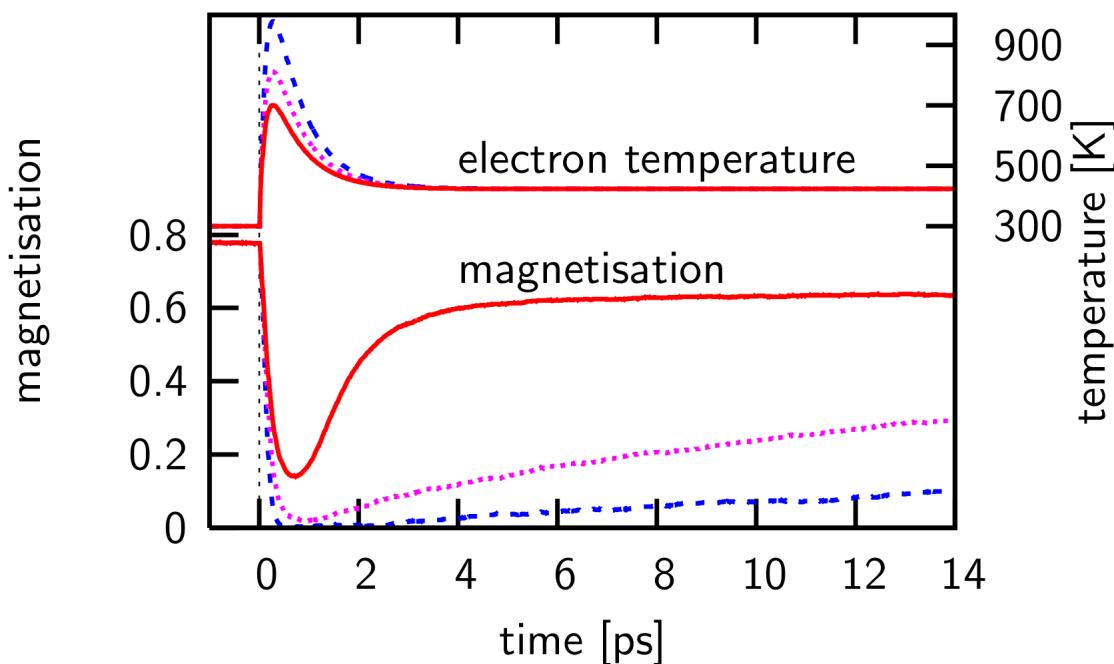
$$C_e \frac{\partial T_e}{\partial t} = G_{ep}(T_p - T_e) + P(z, t) + \frac{\partial}{\partial z} \kappa \frac{\partial T_e}{\partial z} - \frac{\partial(E_d + 0.5E_{int})}{\partial t},$$
$$C_p \frac{\partial T_p}{\partial t} = G_{ep}(T_e - T_p) - 0.5 \frac{\partial E_{int}}{\partial t}.$$

- Spin-system coupled to the electron-phonon system

Frietsch et al., Nat. Commun. 6, 9262 (2015)

Stanciu et al., PRL 99, 047601 (2007)

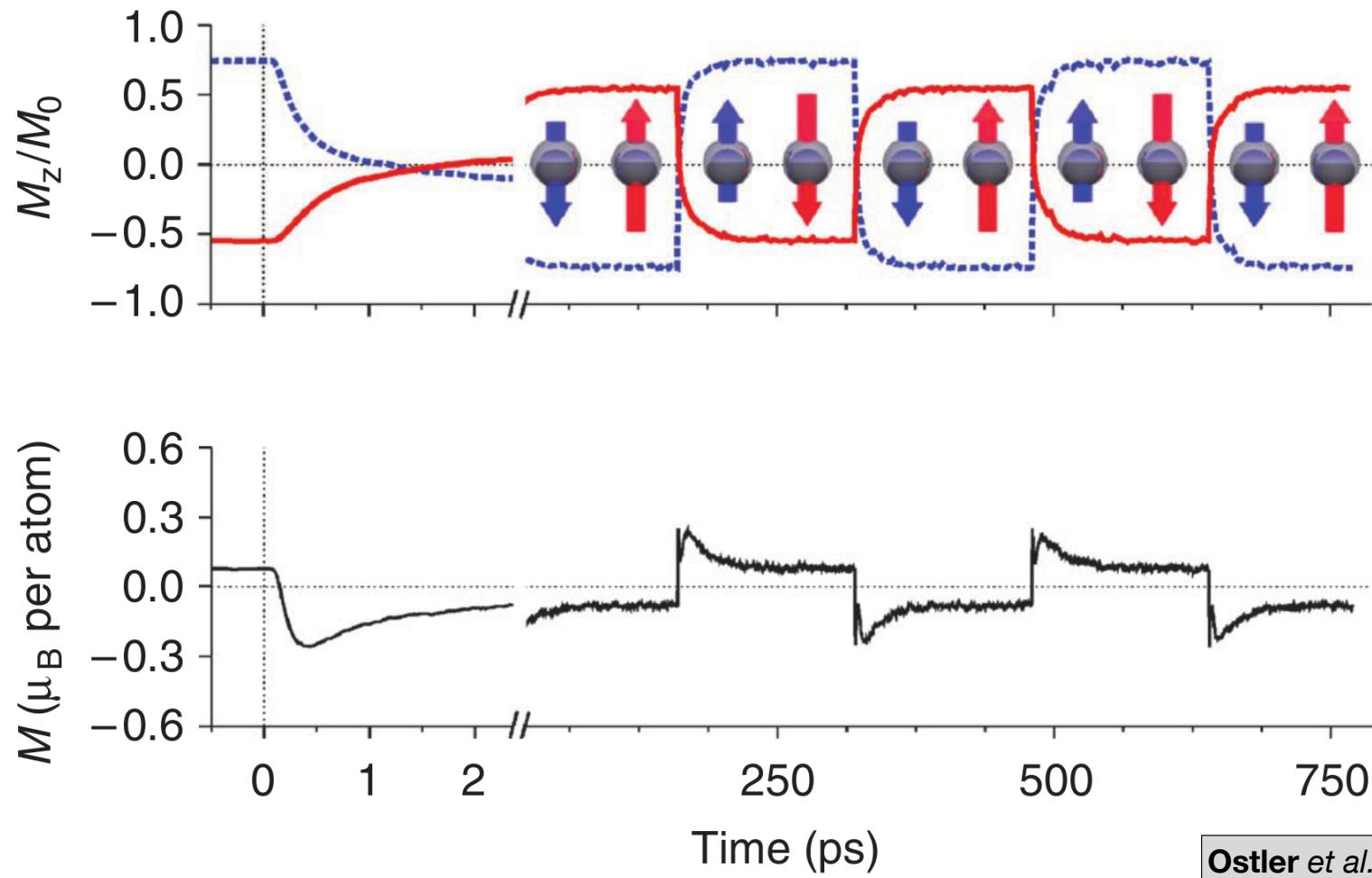
Demagnetization in FePt:



- Ultrafast demagnetization within a few ps
- Slow remagnetization times (formation of several domains)
- Final Magnetization direction not defined
- Further effects: induced moments via IFE

Kazantseva et al., PRB 77, 184428 (2008)

Laser-induced Demagnetization and Switching



Ostler et al., Nat. Commun. 3, 666 (2012)

Introduction to the code



- System Size:

- LX, LY, LZ - number of lattice positions
- $RAND_PLUS$ - number of extra lattice positions at the boundaries

- Flags for structure and boundary conditions:

- $KUBUS_SC$ - to initialize sc ferromagnet
- PBC_X, PBC_Y - periodic boundary conditions in x, y direction (if not set: open boundaries)
- $MONO_Z$ - to initialise monochromatic spin wave excitation at 0-th layer in z-direction

- Simulation parameters:

- $DT, NMAX$ - timestep and number of timesteps
- HX, DX, \dots - external magnetic field and anisotropy (in units of J_1)
- $TEMP$ - constant temperature
- $ALPH$ - damping constant
- $OMEGA, AMP$ - frequency and amplitude of the oscillating boundary conditions

Most relevant functions of the code

- *Kubus(sx, sy, sz, find_index)* - initialize magnetic moments
- *gsl_ran_gaussian_ziggurat(rng, temp)* - random number generator
- *heun(spin, n, find_index, sx,sy,sz, ceta_x, ceta_y, ceta_z)* - integration of 1 timestep
- *ex_sc(sx, i,j,k)* - calculate exchange interaction
- *fx(sx[i][j][k], sy[i][j][k], sz[i][j][k],hx[], hy[], hz[])* - calculate deterministic part of equation of motion
- *cx(sx[i][j][k], sy[i][j][k], sz[i][j][k],hx[], hy[], hz[])* - calculate stochastic part of equation of motion

Suggested tasks of the ATM

- **Simulation of a monochromatic wave in a (sc) ferromagnet:**
 - Excitation via oscillating boundary conditions in z-direction
 - Choose correct boundary conditions and excitation parameter (OMEGA, AMP)
 - Use 256x1x1 magnetic moments, ALPH=0.05, TEMP=0, D_X=0.01J, NMAX=10^6
 - Plot spatial magnetization profile and calculate wave vector and propagation length:

$$m_y = A \cdot \cos(q \cdot z + \phi) \cdot \exp(-z/\xi)$$

- **Questions:**
 - How is the dispersion curve defined?
 - What is the frequency range? What are the minimum and maximum value?
 - How is the rescaled frequency defined in the parameter set?
 - What is the order of the timestep?



- **Simulation of a monochromatic wave in a ferromagnet:**
 - Choose correct boundary conditions and vary the temperature
 - Use 32x32x32 magnetic moments, ALPH=1, D_X=0.01J, NMAX=10^5, DT=1.76x10^(-3)
 - Plot total magnetization as function of time and determine the equilibrium magnetization as function of the temperature.
- **Questions:**
 - What is the unit of the temperature? What is the critical temperature?
 - What are errors in the current fitting? How can it be improved?
 - How does magnetization and temperature scale for low temperatures? What scaling would you expect in reality?
 - Why are we using ALPH=1.0? What is the influence of the size?



- **Simulation of demagnetization of a ferromagnet:**

- Implement the temperature profile: TEMP=2.0 for $10^5 < n < 1.15 \cdot 10^5$, TEMP=0.5 else
- Use 32x32x32 magnetic moments, ALPH=1, D_X=0.01J, NMAX=5*10^5
- Plot total magnetization as function of time and vary the maximum temperature and the seed of the random number generator (example: change to 572235)

- **Questions:**

- For which parameter do you obtain total demagnetization?
- Why can't you realize deterministic switching? What is the probability to obtain switching?