

# Analysis - PMA 17 -

KYB

Thrn, it's a Fact

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# Overview

Funtions of Several Variables

- The Contraction Principle

- The Inverse Function Theorem

- The Implicit Function Theorem

- The Rank Theorem

- Exercises

# The Contraction Principle

## Definition (9.22)

Let  $X$  be a metric space, with metric  $d$ . If  $\varphi$  maps  $X$  into  $X$  and if there is a number  $c < 1$  such that

$$d(\varphi(x), \varphi(y)) \leq cd(x, y)$$

for all  $x, y \in X$ , then  $\varphi$  is said to be a *contraction* of  $X$  into  $X$ .

## Theorem (9.23)

*If  $X$  is a complete metric space, and if  $\varphi$  is a contraction of  $X$  into  $X$ , then there exists one and only one  $x \in X$  such that  $\varphi(x) = x$ .*

# The Inverse Function Theorem

## Theorem (9.24)

Suppose  $\mathbf{f}$  is a  $\mathcal{C}^1$ -mapping of an open set  $E \subset \mathbb{R}^n$  into  $\mathbb{R}^n$ ,  $\mathbf{f}'(\mathbf{a})$  is invertible for some  $\mathbf{a} \in E$ , and  $\mathbf{b} = \mathbf{f}(\mathbf{a})$ . Then

(a) there exist open sets  $U$  and  $V$  in  $\mathbb{R}^n$  such that  $\mathbf{a} \in U$ ,  $\mathbf{b} \in V$ ,  $\mathbf{f}$  is one-to-one on  $U$ , and  $\mathbf{f}(U) = V$ ;

(b) if  $\mathbf{g}$  is the inverse of  $\mathbf{f}$ , defined in  $V$  by

$$\mathbf{g}(\mathbf{f}(\mathbf{x})) = \mathbf{x},$$

then  $\mathbf{g} \in \mathcal{C}^1(V)$ .

# The Inverse Function Theorem

## Theorem (9.25)

*If  $\mathbf{f}$  is a  $\mathcal{C}^1$ -mapping of an open set  $E \subset \mathbb{R}^n$  into  $\mathbb{R}^n$  and if  $\mathbf{f}'(\mathbf{x})$  is invertible for every  $\mathbf{x} \in E$ , then  $\mathbf{f}(W)$  is an open subset of  $\mathbb{R}^n$  for every open set  $W \subset E$ . In other words,  $\mathbf{f}$  is an open mapping of  $E$  into  $\mathbb{R}^n$ .*

# The Implicit Function Theorem

## Notation(9.26)

- If  $\mathbf{x} = (x_1, \dots, x_n) \in \mathbb{R}^n$  and  $\mathbf{y} = (y_1, \dots, y_m) \in \mathbb{R}^m$ , let us write  $(\mathbf{x}, \mathbf{y})$  for the point

$$(x_1, \dots, x_n, y_1, \dots, y_m) \in \mathbb{R}^{n+m}.$$

- Every  $A \in L(\mathbb{R}^{n+m}, \mathbb{R}^n)$  can be split into two linear transformations  $A_x$  and  $A_y$  by

$$A_x \mathbf{h} = A(\mathbf{h}, \mathbf{0}), \quad A_y \mathbf{k} = A(\mathbf{0}, \mathbf{k})$$

for  $\mathbf{h} \in \mathbb{R}^n$ ,  $\mathbf{k} \in \mathbb{R}^m$ . Then  $A_x \in L(\mathbb{R}^n, \mathbb{R}^n)$ ,  $A_y \in L(\mathbb{R}^m, \mathbb{R}^n)$ , and

$$A(\mathbf{h}, \mathbf{k}) = A_x \mathbf{h} + A_y \mathbf{k}.$$

# The Implicit Function Theorem

## Theorem (9.27)

If  $A \in L(\mathbb{R}^{n+m}, \mathbb{R}^n)$  and if  $A_x$  is invertible, then there corresponds to every  $\mathbf{k} \in \mathbb{R}^m$  a unique  $\mathbf{h} \in \mathbb{R}^n$  such that  $A(\mathbf{h}, \mathbf{k}) = \mathbf{0}$ .

# The Implicit Function Theorem

## Theorem (9.28)

Let  $\mathbf{f}$  be a  $\mathcal{C}^1$ -mapping of an open set  $E \subset \mathbb{R}^{n+m}$  into  $\mathbb{R}^n$ , such that  $\mathbf{f}(\mathbf{a}, \mathbf{b}) = \mathbf{0}$  for some point  $(\mathbf{a}, \mathbf{b}) \in E$ .

Put  $A = \mathbf{f}'(\mathbf{a}, \mathbf{b})$  and assume that  $A_x$  is invertible.

Then there exist open sets  $U \subset \mathbb{R}^{n+m}$  and  $W \subset \mathbb{R}^m$ , with  $(\mathbf{a}, \mathbf{b}) \in U$  and  $\mathbf{b} \in W$ , having the following property: To every  $\mathbf{y} \in W$  corresponds a unique  $\mathbf{x}$  such that

$$(\mathbf{x}, \mathbf{y}) \in U \quad \text{and} \quad \mathbf{f}(\mathbf{x}, \mathbf{y}) = \mathbf{0}.$$

If this  $\mathbf{x}$  is defined to be  $\mathbf{g}(\mathbf{y})$ , then  $\mathbf{g}$  is a  $\mathcal{C}^1$ -mapping of  $W$  into  $\mathbb{R}^n$ ,  $\mathbf{g}(\mathbf{b}) = \mathbf{a}$ ,

$$\mathbf{f}(\mathbf{g}(\mathbf{y}), \mathbf{y}) = \mathbf{0} \quad \mathbf{y} \in W,$$

and

$$\mathbf{g}'(\mathbf{b}) = -(A_x)^{-1}A_y.$$



# The Implicit Function Theorem

## Example (9.29)

Take  $n = 2$ ,  $m = 3$ , and  $\mathbf{f} = (f_1, f_2)$  given by

$$f_1(x_1, x_2, y_1, y_2, y_3) = 2e^{x_1} + x_2 y_1 - 4y_2 + 3$$

$$f_2(x_1, x_2, y_1, y_2, y_3) = x_2 \cos x_1 - 6x_1 + 2y_1 - y_3.$$

If  $\mathbf{a} = (0, 1)$  and  $\mathbf{b} = (3, 2, 7)$ , then  $\mathbf{f}(\mathbf{a}, \mathbf{b}) = \mathbf{0}$ .

$$[A] = \begin{bmatrix} 2 & 3 & 1 & -4 & 0 \\ -6 & 1 & 2 & 0 & -1 \end{bmatrix} \implies [A_x] = \begin{bmatrix} 2 & 3 \\ -6 & 1 \end{bmatrix}, [A_y] = \begin{bmatrix} 1 & -4 & 0 \\ 2 & 0 & -1 \end{bmatrix}$$

and

$$[(A_x)^{-1}] = \frac{1}{20} \begin{bmatrix} 1 & -3 \\ 6 & 2 \end{bmatrix}$$

gives

$$[\mathbf{g}'(3, 2, 7)] = -\frac{1}{20} \begin{bmatrix} 1 & -3 \\ 6 & 2 \end{bmatrix} \begin{bmatrix} 1 & -4 & 0 \\ 2 & 0 & -1 \end{bmatrix} = \begin{bmatrix} \frac{1}{4} & \frac{1}{5} & -\frac{3}{20} \\ -\frac{1}{2} & \frac{1}{5} & \frac{1}{10} \end{bmatrix}$$

# The Rank Theorem

## Definition (9.30)

Suppose  $X$  and  $Y$  are vector spaces, and  $A \in L(X, Y)$ .

- ▶ The *null space* of  $A$ ,  $\mathcal{N}(A) = \{\mathbf{x} \in X : A\mathbf{x} = \mathbf{0}\}$ .
- ▶ The *range* of  $A$ ,  $\mathcal{R}(A) = \{A\mathbf{x} : \mathbf{x} \in X\}$ .
- ▶ The *rank* of  $A$  is defined to be the dimension of  $\mathcal{R}(A)$ .

# The Rank Theorem

## Projections(9.31)

Let  $X$  be a vector space. An operator  $P \in L(X)$  is said to be a *projection* in  $X$  if  $P^2 = P$ .

(a) If  $P$  is a projection in  $X$ , then every  $\mathbf{x} \in X$  has a unique representation of the form

$$\mathbf{x} = \mathbf{x}_1 + \mathbf{x}_2$$

where  $\mathbf{x}_1 \in \mathcal{R}(P)$ ,  $\mathbf{x}_2 \in \mathcal{N}(P)$ .

(b) If  $X$  is a finite-dimensional vector space and if  $X_1$  is a vector space in  $X$ , then there is a projection  $P$  in  $X$  with  $\mathcal{R}(P) = X_1$ .

# The Rank Theorem

## Theorem (9.32)

Suppose  $m, n, r$  are nonnegative integers,  $m \geq r$ ,  $n \geq r$ ,  $\mathbf{F}$  is a  $\mathcal{C}^1$ -mapping of an open set  $E \subset \mathbb{R}^n$  into  $\mathbb{R}^m$ , and  $\mathbf{F}'(\mathbf{x})$  has rank  $r$  for every  $\mathbf{x} \in E$ .

Fix  $\mathbf{a} \in E$ , put  $A = \mathbf{F}'(\mathbf{a})$ , let  $Y_1$  be the range of  $A$ , and let  $P$  be a projection in  $\mathbb{R}^m$  whose range is  $Y_1$ . Let  $Y_2$  be the null space of  $P$ .

Then there are open sets  $U$  and  $V$  in  $\mathbb{R}^n$ , with  $\mathbf{a} \in U \subset E$ , and there is a  $1-1$   $\mathcal{C}^1$ -mapping  $\mathbf{H}$  of  $V$  onto  $U$  such that

$$\mathbf{F}(\mathbf{H}(\mathbf{x})) = A\mathbf{x} + \varphi(A\mathbf{x})$$

where  $\varphi$  is a  $\mathcal{C}^1$ -mapping of the open set  $A(V) \subset Y_1$  into  $Y_2$ .

# Exercises

## Ex 9.17

Let  $\mathbf{f} = (f_1, f_2)$  be the mapping of  $\mathbb{R}^2$  into  $\mathbb{R}^2$  given by

$$f_1(x, y) = e^x \cos y, \quad f_2(x, y) = e^x \sin y.$$

- (a) What is the range of  $f$ ?
- (b) Show that the Jacobian of  $f$  is not zero at any point of  $\mathbb{R}^2$ . Thus every point of  $\mathbb{R}^2$  has a neighborhood in which  $f$  is one-to-one. Nevertheless,  $f$  is not one-to-one on  $\mathbb{R}^2$ .
- (c) Put  $\mathbf{a} = (0, \pi/3)$ ,  $\mathbf{b} = f(\mathbf{a})$ , let  $\mathbf{g}$  be the continuous inverse of  $\mathbf{f}$ , defined in a neighborhood of  $\mathbf{b}$ , such that  $\mathbf{g}(\mathbf{b}) = \mathbf{a}$ . Find an explicit formula for  $\mathbf{g}$ , compute  $\mathbf{f}'(\mathbf{a})$  and  $\mathbf{g}'(\mathbf{b})$ , and verify the  $\mathbf{g}'(\mathbf{b}) = \{\mathbf{f}'(\mathbf{g}(\mathbf{b}))\}^{-1}$ .

# Exercises

## Ex 9.19

Show that the system of equations

$$3x + y - z + u^2 = 0$$

$$x - y + 2z + u = 0$$

$$2x + 2y - 3z + 2u = 0$$

can be solved for  $x, y, u$  in terms of  $z$ ; for  $x, z, u$  in terms of  $y$ ; for  $y, z, u$  in terms of  $x$ ; but not for  $x, y, z$  in terms of  $u$ .

# Exercises

## Ex 9.21

Define  $f$  in  $\mathbb{R}^2$  by

$$f(x, y) = 2x^3 - 3x^2 + 2y^3 + 3y^2.$$

- (a) Find the four points in  $\mathbb{R}^2$  at which the gradient of  $f$  is zero. Show that  $f$  has exactly one local maximum and one local minimum in  $\mathbb{R}^2$ .
- (b) Let  $S$  be the set of all  $(x, y) \in \mathbb{R}^2$  at which  $f(x, y) = 0$ . Find those points of  $S$  have no neighborhoods in which the equation  $f(x, y) = 0$  can be solved for  $y$  in terms of  $x$ .

# Exercises

## Ex 9.23

Define  $f$  in  $\mathbb{R}^3$  by

$$f(x, y_1, y_2) = x^2 y_1 + e^x + y_2.$$

Show that  $f(0, 1, -1) = 0$  and  $(D_1 f)(0, 1, -1) \neq 0$ , and that there exists therefore differential function  $g$  in some neighborhood of  $(1, -1)$  in  $\mathbb{R}^2$ , such that  $g(1, -1) = 0$  and

$$f(g(y_1, y_2), y_1, y_2) = 0.$$

Find  $(D_1 g)(1, -1)$  and  $(D_2 g)(1, -1)$ .



## Exercises

### Ex 9.24

For  $(x, y) \neq (0, 0)$ , define  $\mathbf{f} = (f_1, f_2)$  by

$$f_1(x, y) = \frac{x^2 - y^2}{x^2 + y^2}, \quad f_2(x, y) = \frac{xy}{x^2 + y^2}.$$

Compute the rank of  $\mathbf{f}'(x, y)$ , and find the range of  $\mathbf{f}$ .

## Exercises

### Ex 9.25

Suppose  $A \in L(\mathbb{R}^n, \mathbb{R}^m)$ , let  $r$  be the rank of  $A$ .

- (a) Define  $S$  as in the proof of Theorem 9.32. Show that  $SA$  is a projection in  $\mathbb{R}^n$  whose null space is  $\mathcal{N}(A)$  and whose range is  $\mathcal{R}(S)$ .
- (b) Use (a) to show that

$$\dim \mathcal{N}(A) + \dim \mathcal{R}(A) = n.$$

# The End