## LA13 Ch5 Exercises

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## Overview

#### Ch5. The Jordan Canonical Form

- 5.2 Generalized eigenspace
- 5.3 Nilpotent operators
- 5.4 The Jordan canonical form of a matrix

$$\det \left( \begin{bmatrix} B & C \\ 0 & D \end{bmatrix} \right) = \det(B) \det(D)$$

## Step1

$$\begin{bmatrix} B & C \\ 0 & D \end{bmatrix} = \begin{bmatrix} I & 0 \\ 0 & D \end{bmatrix} \begin{bmatrix} B & C \\ 0 & I \end{bmatrix}$$

## Step2

$$\det \left( \begin{bmatrix} I & 0 \\ 0 & D \end{bmatrix} \right) = \det(D)$$

$$\det\left(\begin{bmatrix} B & C \\ 0 & I\end{bmatrix}\right) = \det(B)$$

$$A = egin{bmatrix} B_{11} & B_{12} & \cdots & B_{1t} \ 0 & B_{22} & \cdots & B_{2t} \ dots & & \ddots & dots \ 0 & \cdots & & B_{tt} \end{bmatrix}$$

#### Prove that

- 1.  $\det(A) = \det(B_{11}) \cdots \det(B_{tt})$
- 2.  $\operatorname{spec}(A) = \bigcup \operatorname{spec}(B_{ii})$  and  $\operatorname{m.geo}_A(\lambda) = \sum \operatorname{m.geo}_{B_{ii}}(\lambda), \operatorname{m.alg}_A(\lambda) = \sum \operatorname{m.alg}_{B_{ii}}(\lambda)$

$$A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

- (a)  $p_A(r)$ .
- (b) m.alg(1).
- (c) Find the smallest k such that  $\mathcal{N}((A-I)^{k+1}) = \mathcal{N}((A-I)^k)$ .
- (d) Show that  $\dim(\mathcal{N}(A-I)^k) = m$ .

LCh5. The Jordan Canonical Form └ 5.2 Generalized eigenspace

#### Ex5.2.8

Let  $\lambda$  be an e.val of A and k be any positive integer. Prove that if  $x \in \mathcal{N}((A - \lambda I)^k)$  is an e.vec of A, the corr e.val is  $\lambda$ .

## Minimal Polynomial

Since  $A \in F^{n \times n}$ , there is s such that

$$\{I, A, A^2, \cdot, A^{s-1}\}$$

is linearly independent, but

$$\{I,A,A^2,\cdot,A^s\}$$

is linearly dependent. Then there exist unique  $c_0, \dots, c_{s-1} \in F$  such that

$$c_0I + c_1A + \cdots + c_{s-1}A^{s-1} + A^s = 0$$

Then we say  $m_A(r) = c_0 + c_1 r + \cdots + c_{s-1} r^{s-1} + r^s$  is the minimal polynomial of A.

#### Theorem

Let  $m_A(r)$  be the minimal polynomial of A. If  $p(r) \in F[r]$  satisfies p(A) = 0, then there is  $q(r) \in F[r]$  such that  $p(r) = m_A(r)q(r)$ .

#### Lemma

If  $(\lambda, x)$  is an eigenpair of A and  $p(r) \in F[r]$ , then  $p(A)x = p(\lambda)x$ .

#### Theorem

The roots of  $m_A(r)$  are the eigenvalues of A.

## The Cayley-Hamilton theorem

Let *F* be a field,  $A \in F^{n \times n}$ . Then  $p_A(A) = 0$ . Thus  $m_A(r)$  divides  $p_A(r)$ .

et  $A \in \mathbb{C}^{n \times n}$  with distinct eigenvalues  $\lambda_1, \dots, \lambda_t$ . Let

$$m_A(r) = (r - \lambda_1)^{k_1} \cdots (r - \lambda_t)^{k_t}$$
  
 $p_A(r) = (r - \lambda_1)^{m_1} \cdots (r - \lambda_t)^{m_t}$ 

Then  $k_i \leq m_i$  for all  $i = 1, \dots, t$ .

Let *F* be a field and  $c_0, \dots, c_{n-1} \in F$ . Define

$$A = \begin{bmatrix} 0 & 0 & 0 & \cdot & -c_0 \\ 1 & 0 & 0 & \cdot & -c_1 \\ 0 & 1 & 0 & \cdot & -c_2 \\ \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 & -c_{n-1} \end{bmatrix}$$

Ex4.5.9 shows 
$$p_A(r) = r^n + c_{n-1}r^{n-1} + \cdots + c_1r + c_0$$
.

- 1. Prove that  $e_1$  is a cyclic vector for A.
- 2. Prove that  $m_A(r) = p_A(r)$ .

#### Ex5.3.2

Suppose  $T: X \to X$  is a nilpotent linear operator. Prove that 0 is an eigenvalue of T, and it is only eigenvalue.

Ex5.3.3

Let  $I: X \to X$  by I(x) = x. Then I + T is invertible.

Ex5.3.4

Let k be the index of T. Prove I+T is invertible by proving  $S=I-T+T^2-\cdots+(-1)^{k-1}T^{k-1}$  is the inverse of I+T.

Ex5.3.15

$$\det(I+A)=1$$

where *A* if nilpotent.

### Ex5.3.7

(a)  $A \in \mathbb{R}^{n \times n}$  and  $A_{ij} > 0$  for all i, j. Prove that A is not nilpotent.

Ch5. The Jordan Canonical Form
5.3 Nilpotent operators

#### Ex.5.3.13

Suppose *X* is a fin.v.sp over *F* and  $T: X \rightarrow X$  linear.

T/F If T is nilpotent, then T is singular.

T/F if T is singular, then T is nilpotent.

#### Ex5.4.8

In defining the Jordan canonical form, we list the vectors in an eigenvector/generalized eigenvector chain in the following order:

$$(A - \lambda_i I)^{r_j - 1} x_{i,j}, (A - \lambda_i I)^{r_j - 2} x_{i,j}, \cdots, x_{i,j}.$$

What is the form of a Jordan block if we list the vectors in the order

$$x_{i,j}, (A - \lambda_i I) x_{i,j} \cdots, (A - \lambda_i I)^{r_j - 1} x_{i,j}$$

instead?

# The End