

- 5.13 (1) Figure 5.41 shows two functions $x_1(t)$ and $x_2(t)$. Evaluate
- their convolution, $x_3(t)$, numerically, taking sampled values at $t = 0, 1, 2, 3, 4, 5$ s, and
 - $x_3(t)$ analytically.
- (2) Sketch the functions $x_3(t)$ and give reasons for any differences between them.

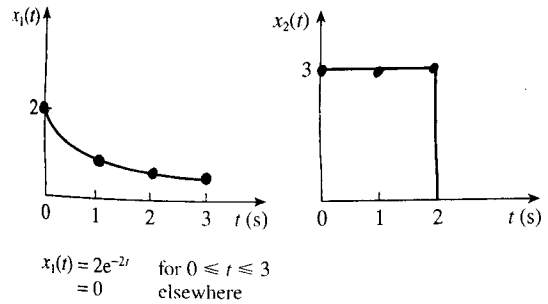


Figure 5.41 The functions $x_1(t)$ and $x_2(t)$ for Problem 5.13.

Discrete Linear convolution

$$x_1(t) \otimes x_2(t)$$

$$\{2.0 \quad 0.2707 \quad 0.0366 \quad 0.0050\} \otimes \{3 \quad 3 \quad 3\}$$

x1(t) \Rightarrow	2.0	0.2707	0.0366	0.0050	
3	3	3			$\Rightarrow x_3(0) = 6.0$
	3	3			$\Rightarrow x_3(1) = 6.8120$
		3	3		$\Rightarrow x_3(2) = 6.9219$
			3	3	$\Rightarrow x_3(3) = 0.9368$
				3	$\Rightarrow x_3(4) = 0.1248$
					$\Rightarrow x_3(5) = 0.0149$

check in Matlab

```
>> x1 = [2 2*exp(-2) 2*exp(-4) 2*exp(-6)]
```

```
x1 =
```

```
2.0000    0.2707    0.0366    0.0050
```

```
>> x2 = [3 3 3]
```

```
x2 =
```

```
3        3        3
```

```
>> y1 = conv(x1, x2)
```

```
y1 =
```

```
6.0000    6.8120    6.9219    0.9368    0.1248    0.0149
```

5.17 Determine the output of an electrical system of impulse response function $\{0, 0.899, 0.990, 0.991, 1\}$ when the input $\{0, 2.5, 5.0, 0\}$ (volts) is applied

(1) by direct convolution, and

(2) by applying the convolution theorem.

← FFT Method. See Mitra Figure 3.14 or example 3.20

You can manually crank this out yourself.

Here is a MATLAB check...

```
>> x2 = [0 0.899 0.990 0.991 1]
```

```
x2 =
```

```
0    0.8990    0.9900    0.9910    1.0000
```

```
>> x1 = [0 2.5 5.0 0]
```

```
x1 =
```

```
0    2.5000    5.0000    0
```

```
>> y1 = conv(x1, x2)
```

```
y1 =
```

```
0    0    2.2475    6.9700    7.4275    7.4550    5.0000    0
```

```
>> L = length(x1) + length(x2) - 1
```

```
L =
```

```
8
```

```
>> y2 = abs(ifft(fft(x1,L).*fft(x2,L)))
```

```
y2 =
```

```
0.0000    0.0000    2.2475    6.9700    7.4275    7.4550    5.0000    0.0000
```