IoT Hardware & Firmware

Building an loT Kit

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Agenda

- IoT Recap
- Hardware
 - Voltage / Resistance / Current
 - Breadboard and Connecting Pins
- Firmware
 - Definition
 - Platforms
- Board Setup
 - Registration
 - Circuit Building
- Coding

IoT Recap

Internet of Things

Network of physical objects or "things" that are embedded with sensors, software, and other technologies to collect and exchange data with other devices and systems over the internet.

Examples of IoT Devices

- Fitness tracking devices
- Hospital call buttons

- Smart light bulbs
- Smoke Detectors (w/ internet)

- Automatic traffic lights
- Car computers (w/ internet)





IoT Systems

Microcontrollers:

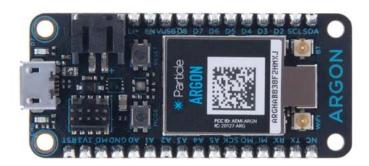
- Nordic Semiconductor nRF
- Microchip Atmega

Development Boards:

- Particle Argon
- Arduino BLE

Platforms:

- Particle IO
- Amazon Web Services
- Cisco IoT







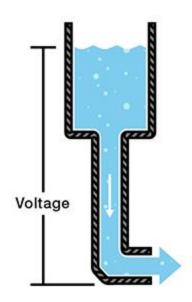
Hardware

Voltage

- Voltage is Potential Energy
- Similar to pipe water pressure
- All our hardware needs voltage

Common DC voltage levels:

- 5 V (max provided by most USB)
- 3.3 V (for lower power hardware)
- 3 V (coin cell battery)
- 1.5 V (AA & AAA battery)



Resistance

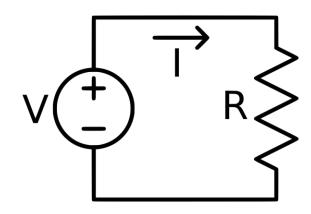
- Things we power have / need Resistance
- Similar to a garden hose faucet
- Having no resistance causes short circuit
- Your resistance will "spend" your energy

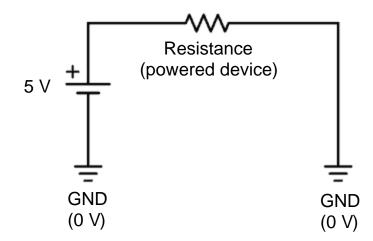
$$P = \frac{V^2}{R}$$



Current

- Current is like the water which flows in our garden hose
- The base reference that voltage relates to is called ground
- We have to "drain" our voltages to ground voltage to get current

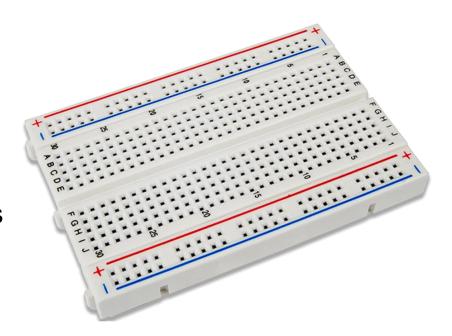




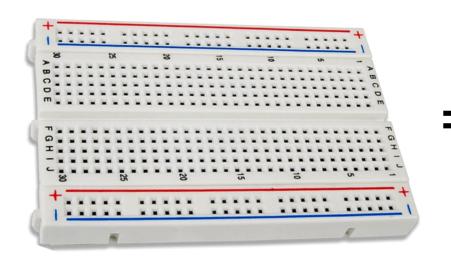
Breadboard

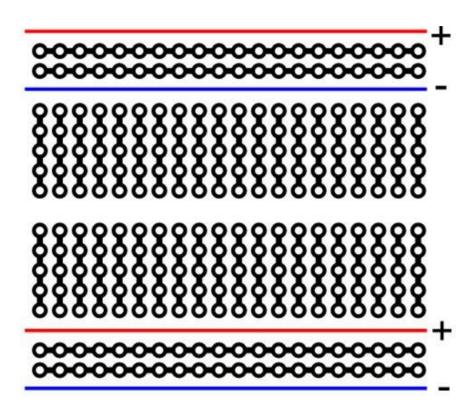
Help develop without soldering

- Easy swapping of components
- Hidden "wires" to connect parts
- Slot in pins to make a circuit



Breadboard



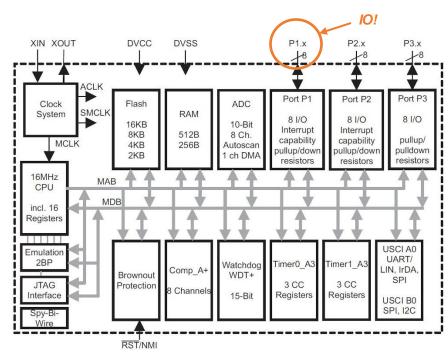


Firmware

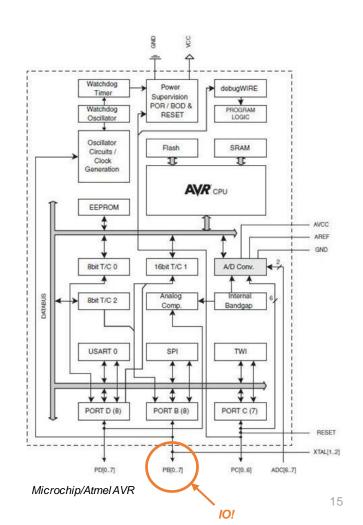
Firmware

- Code that directly controls hardware
 - Memory, interrupts, data transfer, boot process
- Most often programmed in C, but Rust use is growing
- Firmware is everywhere!
 - BIOS, SSDs, keyboards, IoT devices etc.
- To write firmware, you must first understand the hardware
- Every processor architecture requires specific firmware

Chip Architectures



Texas Instruments MSP430



Embedded C

- The same thing as C, but with compiler-specific macros
- No libraries, you must read the chip's documentation!

```
#include <avr/io.h>
     #include <msp430.h>
                                                                                       int main(void) {
     int main(void) {
                                                                                           // Set PB0 as an output pin
         // Stop the watchdog timer
                                                                                           DDRB |= (1 << DDB0);
         WDTCTL = WDTPW | WDTHOLD;
                                                                                           while (1) {
         // Set P1.0 as an output pin
                                                                                               // Set PB0 to HIGH (5V)
                                                                                  8
         P1DIR |= BIT0;
8
                                                                                               PORTB |= (1 << PORTB0);
                                                                                  9
9
                                                                                 10
10
         while (1) {
                                                                                 11
                                                                                               // Wait for a while
11
             // Set P1.0 to HIGH (3.3V)
                                                                                 12
                                                                                               _delay_ms(1000);
             P10UT |= BIT0;
12
                                                                                 13
13
                                                                                               // Set PB0 to LOW (0V)
14
             // Wait for a while
                                                                                 14
15
             __delay_cycles(1000000);
                                                                                 15
                                                                                               PORTB \&= \sim (1 << PORTB0);
                                                                                 16
             // Set P1.0 to LOW (0V)
                                                                                 17
                                                                                               // Wait for a while
18
             P10UT &= ~BIT0;
                                                                                 18
                                                                                               _delay_ms(1000);
19
                                                                                 19
20
             // Wait for a while
                                                                                 20
                                                                                           return 0:
              delay cycles(1000000);
21
                                                                                 21
22
23
         return 0;
```

Texas Instruments MSP430

Microchip/Atmel AVR

Firmware Frameworks

- Abstract the manual bitwise operations with a header file
- The Arduino framework is widely used and works with most chips

```
#include <avr/io.h>
                                                                                            const int ledPin = 8;
      int main(void) {
 3
                                                                                           void setup() {
          // Set PB0 as an output pin
                                                                                                // Set the LED pin as an output
          DDRB |= (1 << DDB0);
 5
                                                                                                pinMode(ledPin, OUTPUT);
 6
                                                                                       6
 7
          while (1) {
 8
              // Set PB0 to HIGH (5V)
                                                                                            void loop() {
              PORTB |= (1 << PORTB0);
 9
                                                                                               // Set the LED pin to HIGH (5V)
10
                                                                                      10
                                                                                                digitalWrite(ledPin, HIGH);
              // Wait for a while
11
                                                                                     11
12
              delay ms(1000);
                                                                                     12
                                                                                                // Wait for a while
13
                                                                                      13
                                                                                               delay(1000);
14
              // Set PB0 to LOW (0V)
                                                                                     14
15
              PORTB \&= \sim (1 << PORTB0);
                                                                                      15
                                                                                               // Set the LED pin to LOW (0V)
16
17
              // Wait for a while
                                                                                     16
                                                                                                digitalWrite(ledPin, LOW);
18
              delay ms(1000);
                                                                                     17
19
                                                                                     18
                                                                                                // Wait for a while
20
          return 0:
                                                                                                delay(1000);
                                                                                      19
21
                                                                                      20
Embedded C AVR
                                                                                     Arduino Framework
```

Firmware to Cloud

- When working with IoT applications you will typically use frameworks
- Particle uses the Arduino framework with added functionality, such as cloud variables and functions
 - Cloud variables and functions can be accessed from the web interface!
- NuvloT and Arduino also offer cloud specific libraries for IoT applications

Board Setup

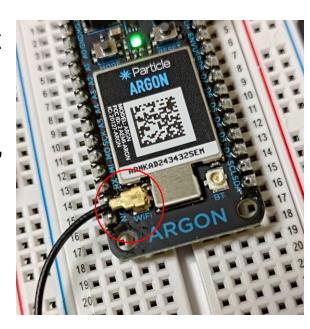
Getting Ready

- 1. docs.particle.io/quickstart/argon/
- 2. "Set up your Argon"
- 3. "Get Started"
- 4. Make Account (required)



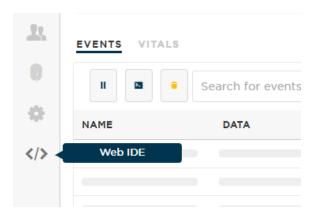
Updating

- 1. Attach antenna to Argon board "Wi-Fi" port
- 2. "Start setting up my device"
- 3. Attach board with USB cable to laptop
- 4. "Select Device," pick device, and "connect"
- 5. "Continue," pick device, and "connect"
- 6. "Continue" and "Update Device"



Registering

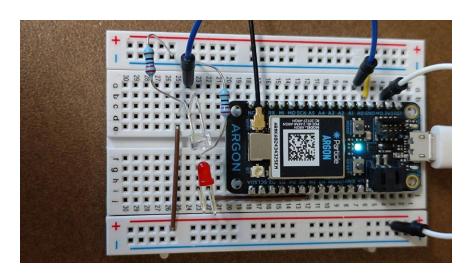
- 1. "Or create a new product" and give a name
- 2. "Add to product" and gave a device name
- 3. "Name Device"
- 4. Choose Wi-Fi network (Not school Wi-Fi, try phone hotspot)
- Activate Device
- 6. "Go to Console"
- 7. Open Web IDE

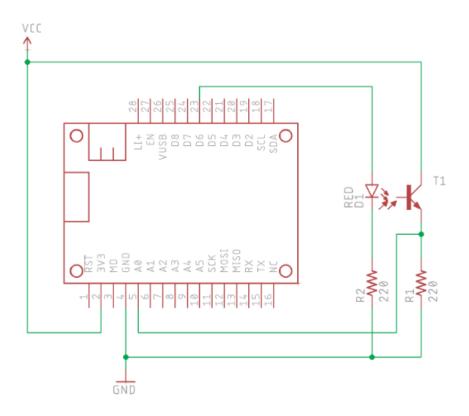


Circuit Assembly

3v3 voltage goes to:

- Long leg of LED
- Short leg of phototransistor





Coding

Code – Beginning

```
// The following line is optional, but recommended in most firmware.
    // It allows your code to run before the cloud is connected.
    SYSTEM THREAD(ENABLED);
    // This uses the USB serial port for debugging logs.
    SerialLogHandler logHandler;
    // This is where your LED is plugged in. The other side goes to a resistor
    // connected to GND.
    const pin_t LED_PIN = D6;
10
11
12
13
    const pin t SENSOR PIN = A0;
14
15
    // Here we are declaring the integer variable analogyalue, which we will
16
17
    int analogvalue;
    int ledToggle(String command); // Forward declaration
19
```

Code - Setup

```
void setup()
21
22 - {
        // First, declare all of our pins. This lets our device know which ones
23
24
        // will be used for outputting voltage, and which ones will read
25
        // incoming voltage.
26
         pinMode(LED PIN, OUTPUT); // Our LED pin is output (lighting up the LED)
27
        digitalWrite(LED PIN, HIGH);
28
29
        // We are going to declare a Particle.variable() here so that we can
        // access the value of the photosensor from the cloud.
30
         Particle.variable("analogvalue", analogvalue);
31
32
33
        // We are also going to declare a Particle.function so that we can turn
34
        // the LED on and off from the cloud.
        Particle.function("led", ledToggle);
35
36
37
```

Code - Loop

```
void loop()
38
39 -
        // Check to see what the value of the photoresistor or phototransistor is
40
41
        // and store it in the int variable analogyalue
         analogvalue = analogRead(SENSOR PIN);
42
43
44
        // This prints the value to the USB debugging serial port (for optional
45
        // debugging purposes)
        Log.info("analogvalue=%d", analogvalue);
46
47
48
        // This delay is just to prevent overflowing the serial buffer, plus we
49
        // really don't need to read the sensor more than
         // 10 times per second (100 millisecond delay)
50
51
        delay(100ms);
52
53
```

Code – LED Toggle Function

```
This function is called when the Particle.function is called
     int ledToggle(String command) {
         if (command.equals("on")) {
57 -
             digitalWrite(LED PIN, HIGH);
58
59
             return 1;
60
         else if (command.equals("off")) {
61 -
             digitalWrite(LED PIN, LOW);
62
63
             return 0;
64
         else {
65 -
             // Unknown option
66
67
             return -1;
68
69
```

Code – Dashboard Interface

You can now:

- Turn the LED on and off
- See how much light is detected Also possible:
- Creating events to register things happening and send notifications
- Using a mobile app to access the dashboard and notifications remotely

Full original tutorial and code are available at https://docs.particle.io/getting-started/hardware-tutorials/hardware-examples/







Questions?





Next Events

Conclusion