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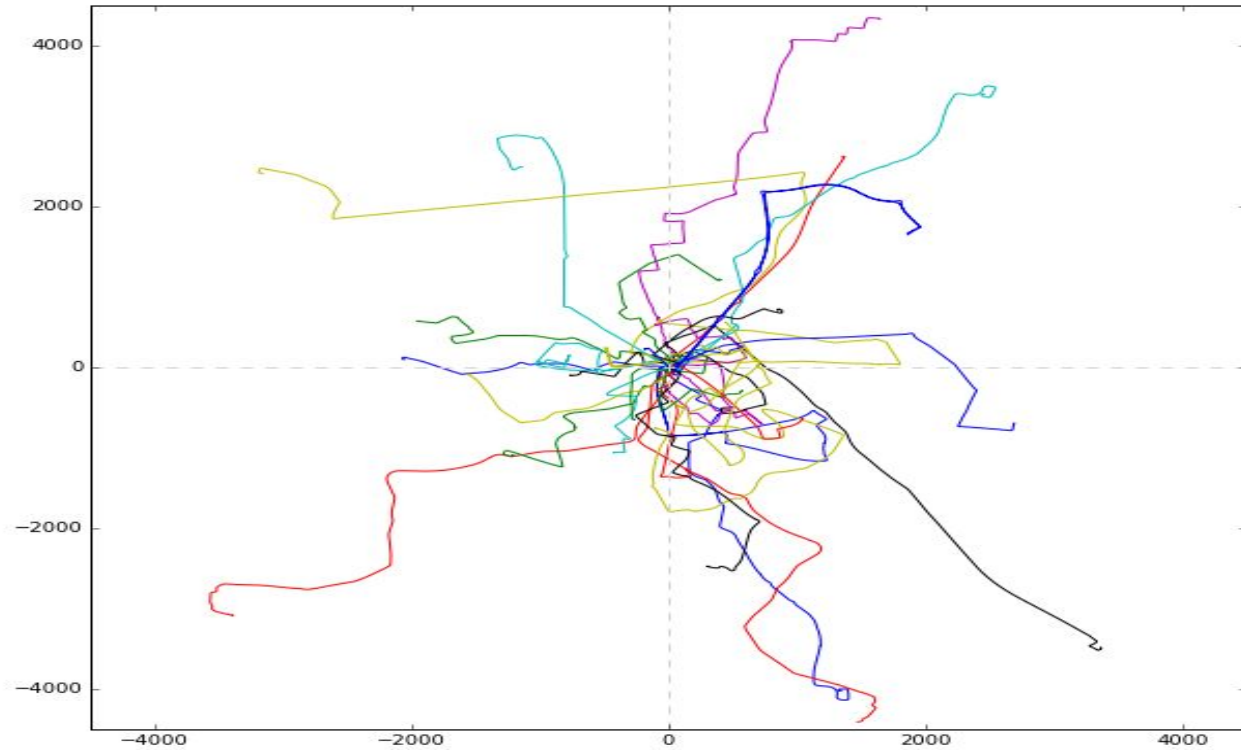
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# Identifying Drivers Signatures Through Unlabeled Telematic Data

Su-Young Hong, Mayank Kedia, Harry O'Reilly

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# Driver Trips



# The Data

- 2,736 Drivers
- 200 trips per driver (547,200 total)
- Time series of (x,y) coordinates

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# The Data

- 2,736 Drivers
  - 200 trips per driver (547,200 total)
  - Time series of (x,y) coordinates
  - False trips randomly inserted into each driver set
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# Challenge 1:

Unlabeled Data

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# Manufacture Labels

<u>Driver</u>	<u>Trip</u>	<u>Label</u>
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(Driver 1, Trip 001)	?
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(Driver 1, Trip 002)	?
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(Driver 1, Trip 003)	?
----------------------	---

(...)	
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# Manufacture Labels

<u>Driver</u>	<u>Trip</u>	<u>Label</u>
(Driver 1, Trip 001)		1
(Driver 1, Trip 002)		1
(Driver 1, Trip 003)		1
(...)		

# Manufacture Labels

<u>Driver</u>	<u>Trip</u>	<u>Label</u>
(Driver 1, Trip 001)		1
(Driver 1, Trip 002)		1
(Driver 1, Trip 003)		1
(...)		

Driver 2

Driver 54

Driver 432

...



# Manufacture Labels

<u>Driver</u>	<u>Trip</u>	<u>Label</u>	
(Driver 1, Trip 001)		1	
(Driver 1, Trip 002)		1	
(Driver 1, Trip 003)		1	
(...)			
(Driver 1, Trip 201)		0	Driver 2
(Driver 1, Trip 202)		0	Driver 54
(Driver 1, Trip 203)		0	Driver 432
(...)			...

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# Challenge 2:

## Feature Engineering

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## Step Level Features

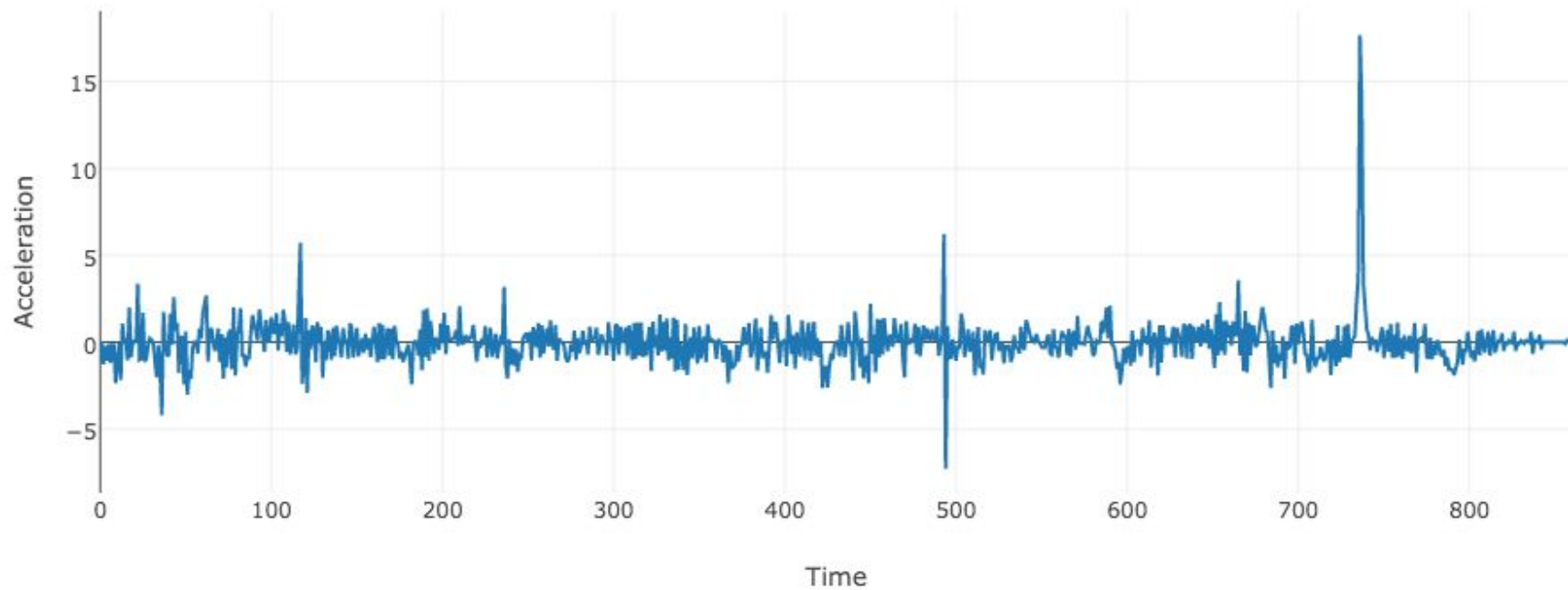
- Start with time series of Cartesian Coordinates
  - Generate velocity, acceleration, jerk
-

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## Step Level Features

- Start with time series of Cartesian Coordinates
  - Generate velocity, acceleration, jerk
  - Convert to polar, generate centripetal acceleration, angular velocity, tangential acceleration
  - Smooth
-

Acceleration: Driver 1, Trip 1



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## Step Level Features

- Start with time series of Cartesian Coordinates
- Generate velocity, acceleration, jerk
- Convert to polar, generate centripetal acceleration, angular velocity, tangential acceleration
- Smooth

## Trip Level Features

- Aggregate step level features
  - Max and min
  - Mean and Standard Deviation
  - Quantiles
-

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# Challenge 3:

## Model Building

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## Models

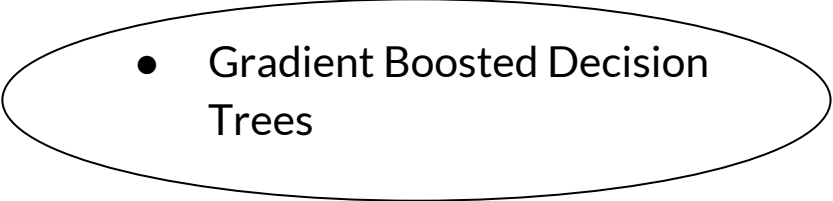
- Logistic Regression
  - Random Forest
  - Gradient Boosted Decision  
Trees
-



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## Models

- Logistic Regression
  - Random Forest
  - Gradient Boosted Decision  
Trees
- 
-

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## Models

- Logistic Regression
- Random Forest
- Gradient Boosted Decision Trees

Hyper-parameter: Number of iterations

Best Feature Subset

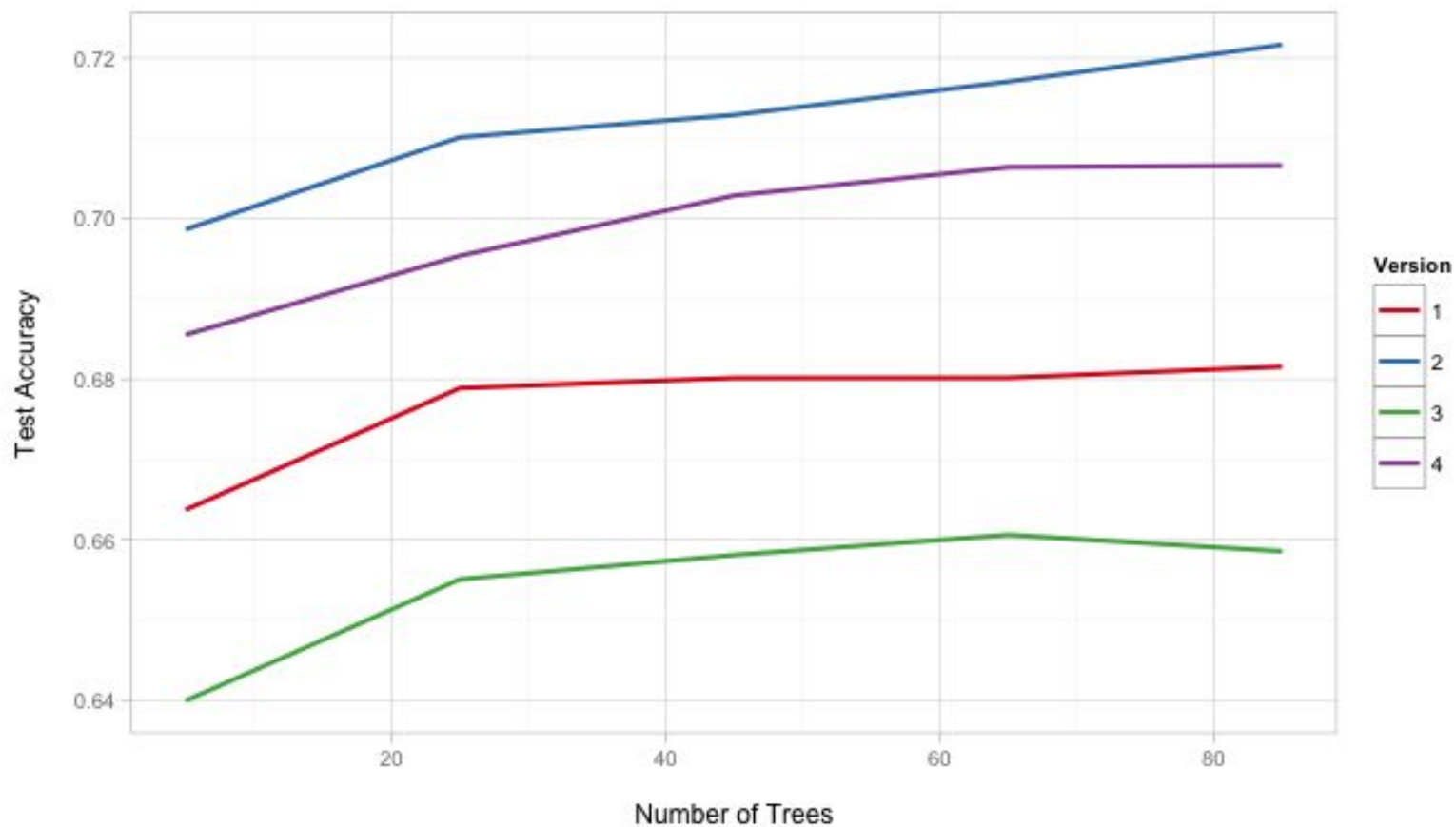
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# Results:

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# Test Accuracy: GBT With 4 Feature Sets



# GBT Version 2 Performance Metrics

Accuracy	Precision	Sensitivity	Specificity	Miss Rate
0.72	0.68	0.68	0.71	0.32

**Version 2: All features without smoothing.**

# GBT Version 2 Performance Metrics

Accuracy	Precision	Sensitivity	Specificity	Miss Rate
0.72	0.68	0.68	0.71	0.32

**Version 2: All features without smoothing.**

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# Fin

[suyoung.hong@gmail.com](mailto:suyoung.hong@gmail.com)

[horeilly2@dons.usfca.edu](mailto:horeilly2@dons.usfca.edu)

[mkkedia@dons.usfca.edu](mailto:mkkedia@dons.usfca.edu)

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