# **Autoregressive Models**

### Introduction

Autoregressive model over x factor the joint distribution as the following product of conditionals:

$$p(\mathbf{x}) = p(x_1,\ldots,x_n) = \prod_{i=1}^n p(x_i|x_1,\ldots,x_{i-1})$$

The problem becomes modeling the conditional probability distribution :  $P(x_i|x_1,x_2,...,x_{i-1})$ 

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Interpretation: Given previous values  $x_1, x_2, ..., x_{i-1}$ , these models do not output a value for  $x_i$ , they output the predictive probability distribution  $P(x_i|x_1, x_2, ..., x_{i-1})$  for  $x_i$ .

# Introduction

Any autoregressive model can be run sequentially to generate a new sequence : start with your seed  $x_1, x_2, ..., x_k$  and predict  $x_{k+1}$ . Then use  $x_2, x_3, ..., x_{k+1}$  to predict  $x_{k+2}$ , and so on.

- •PixelCNN is a generative model that predicts the next pixel in an image given the previous pixels.
- •It leverages the idea of autoregressive modeling, where the image is generated pixel by pixel in a specific order.

#### Architecture Overview:

- Consists of multiple convolutional layers.
- •Each layer is designed to ensure that the generation of a pixel depends only on previously generated pixels.

•Masking Concept:Masks are used in the convolutional layers to prevent information from flowing from future pixels to the current pixel.

#### •Types of Masks:

- A-type Mask: Used in the first layer to ensure that a pixel does not depend on itself.
- B-type Mask: Used in subsequent layers, allowing the pixel to depend on itself and previous pixels.

1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	A = 0 B = 1	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0
0	0	0	0	0	0	0

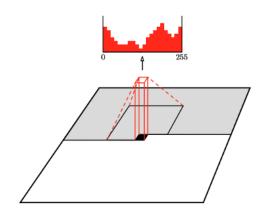
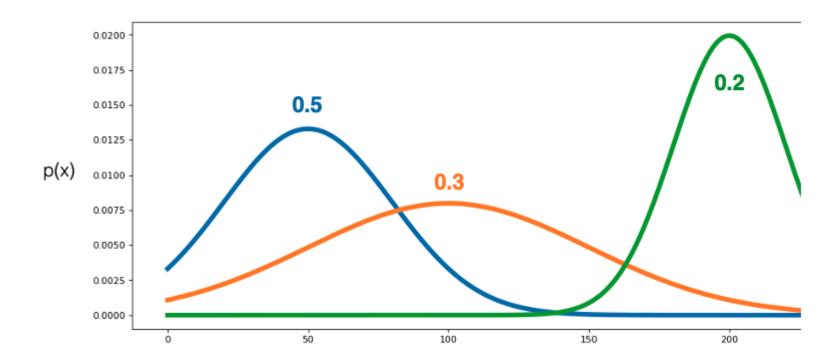


Figure 5-13. Left - a convolutional filter mask. Type A masks the central pixel and Type B does not mask the central pixel. Right - a mask applied to a set of pixels to predict the distribution of the central pixel value (source: Conditional Image Generation with PixelCNN Decoders, van den Oord et al. https://arxiv.org/pdf/1606.05328).

#### •Problems: very slow to sample, for an image of 64 by 64, we need to sample 64 by 64!

One solution is to replace the head of softmax over 256 by a mixture distribution. For instance in the following example, we have a mixture with three kernals.

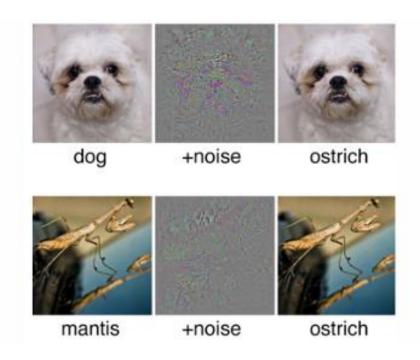


Generative Deep Learning 2nd Edition/notebooks/05 autoregressive/03 pixelcnn md/pixelcnn md.ipynb at main davidADSP/Generative Deep Learning 2nd Edition (github.com)



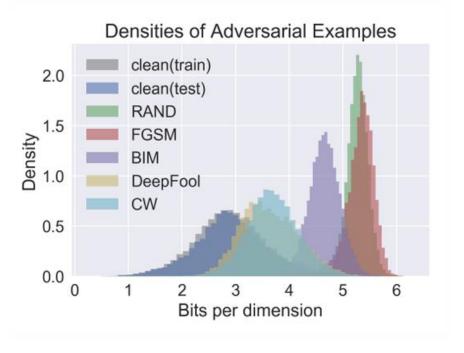
# Applications: Adversarial Attacks and Anomaly detection

Machine learning models are vulnerable to adversarial examples



Can we detect such examples?

# Applications: Adversarial Attacks and Anomaly detection



Train a generative model p(x) on clean inputs (PixelCNN)

Given a new input x`, evaluate p(x')

Adversarial examples are significantly less likely under p(x)

# Summary

- Easy to sample from
  - **1** Sample  $\overline{x}_0 \sim p(x_0)$
  - 2 Sample  $\overline{x}_1 \sim p(x_1 \mid x_0 = \overline{x}_0)$
  - **3** ...
- Easy to compute probability  $p(x = \overline{x})$ 
  - **1** Compute  $p(x_0 = \overline{x}_0)$
  - 2 Compute  $p(x_1 = \overline{x}_1 \mid x_0 = \overline{x}_0)$
  - Multiply together (sum their logarithms)
  - 4 ...
  - Ideally, can compute all these terms in parallel for fast training