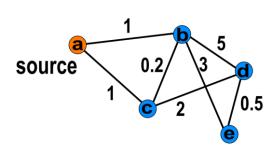
Dijekstra Algorithm



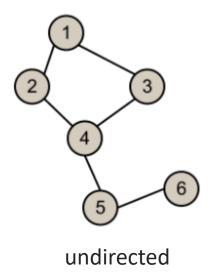
Mustafa Hajij

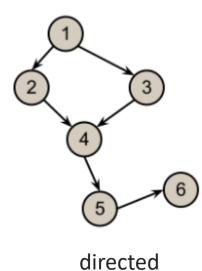


Graphs

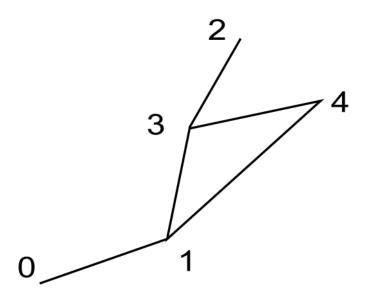
A **graph** is an ordered pair (V,E) where,

- V is the *vertex set (also node set)* whose elements are the vertices, or *nodes* of the graph.
- E is the *edge set* whose elements are the edges, or connections between vertices, of the graph. If the graph is undirected, individual edges are unordered pairs.
- If the graph is directed, edges are ordered pairs





Graphs representation: list of nodes and edges

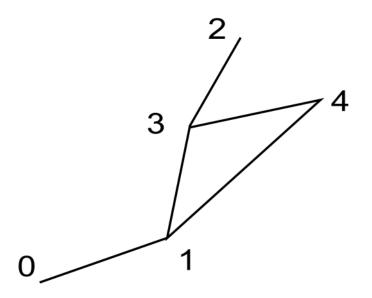


Nodes: [0,1,2,3,4]

Edges: [[0,1], [1,3],[1,4] [3,4], [3,2]]

Note that if the graph is connected, then the list of edges is enough to determine the graph completely.

Graphs representation: list of nodes and edges

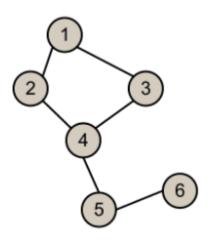


Nodes: [0,1,2,3,4]

Edges: [[0,1], [1,3],[1,4] [3,4], [3,2]]

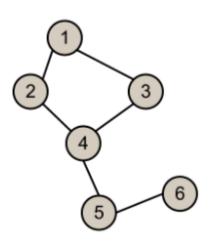
The order of the vertices is important only if the graph is directed.

Graphs representation: adjacency matrix

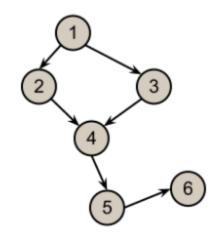


	1	2	3	4	5	6
1	0	1	1	0	0	0
2	1	0	0	1	0	0
3	1	0	0	1	0	0
4	0	1	1	0	1	0
5	0	0	0	1	0	1
6	0	0	0	0	1	0

Graphs representation: adjacency matrix



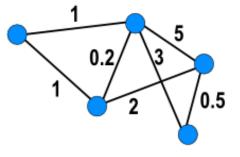
(1	2	3	4	(5)	6
1	0	1	1	0	0	0
2	1	0	0	1	0	0
3	1	0	0	1	0	0
4	0	1	1	0	1	0
(5)	0	0	0	1	0	1
6	0	0	0	0	1	0



	1	2	3	4	(5)	6
1	0	1	1	0	0	0
2	-1	0	0	1	0	0
3	-1	0	0	1	0	0
4	0	-1	-1	0	1	0
(5)	0	0	0	-1	0	1
6	0	0	0	0	-1	0

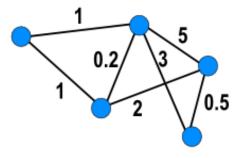
Weighted Graphs

A weighted graph is a graph in which every edge has a weight (non-negative real number)



Weighted Graphs

A weighted graph is a graph in which every edge has a weight (non-negative real number)



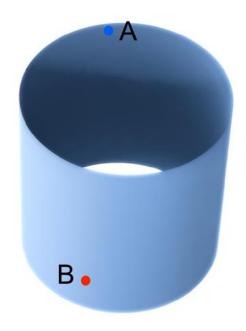
Formally speaking:

A weight function $w: E \to R^+$. In other words, the function w associates to every edge e a positive number (weight) w(e)

A weighted graph is a graph G=(V,E) with a weight function $w: E \to R^+$.

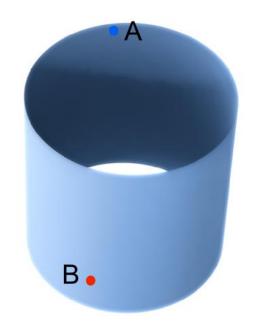
Shortest distance

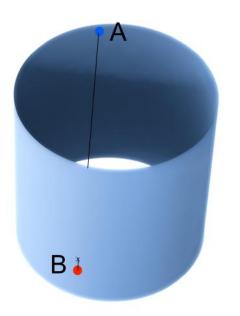
What is the shortest distance between A and B?

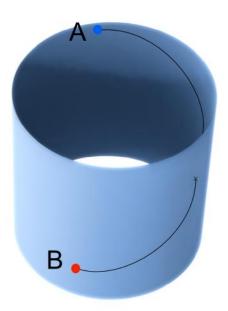


Shortest distance

What is the shortest distance between A and B?



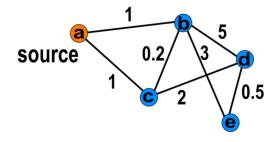




Dijkstra algorithm

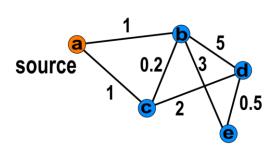
The basic Dijkstra algorithm operates on connected, undirected, weighted graph.

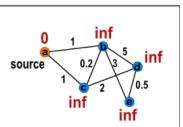
```
Dijkstra(Graph, source):
1:
2:
                     for each vertex v in Graph:
3:
                                distance[v] := infinity
                                                                // the initial distance from source to any other vertex v is infinity
4:
                                previous[v] := undefined
                     distance[source] := 0
5:
                                                                 // Distance from the source to itself is zero
                     Q := the set of all nodes in the Graph // all nodes are going in this container
6:
7:
                     while Q is not empty:
                                                                 // main loop
8:
                                u := the node in Q with smallest distance from the source (what kind of gueue you use here?)
9:
                                remove u from O
                                                        //the source will be removed first
10:
                                for each neighbor v of u: // v is still in the container Q
                                           alt := distance[u] + length(u, v)
11:
12:
                                           if alt < distance[v]
                                                                  //A shorter path from v to the source has been found
13:
                                                      distance[v] := alt
                                                      previous[v] := u
14:
15:
                     return distance[], previous[]
```



Input: weighted graph with a source vertex

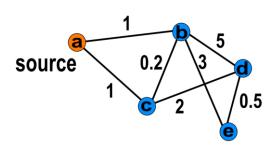


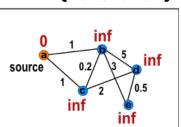




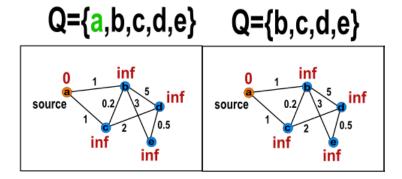
Algorithm starts by initializing the distance to every vertex other than the source to infinity. We also create a queue Q and put in it all vertices of G.

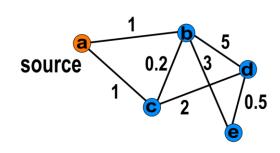




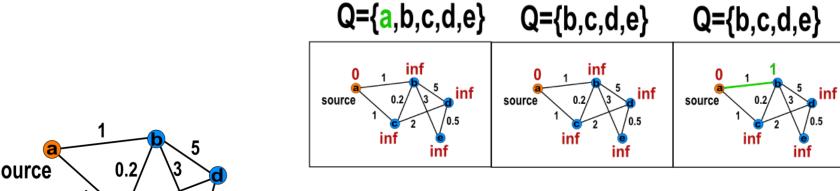


When we enter the while loop we dequeue the element in Q with shortest distance to source. In this case it is a.





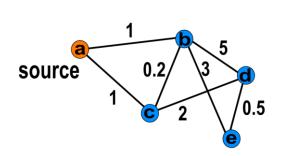
When we enter the while loop we dequeue the element in Q with shortest distance to source. In this case it is a.

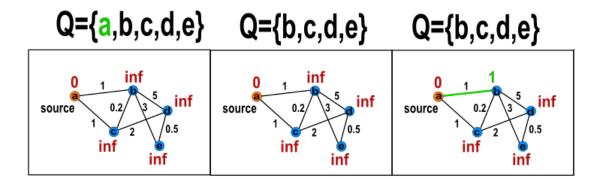


```
source
```

Now we visit all neighbors of aand update the distance to them:

```
for each neighbor v of u:
                      alt := distance[u] + length(u, v)
                      if alt < distance[v]</pre>
                                  distance[v] := alt
```



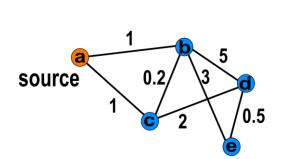


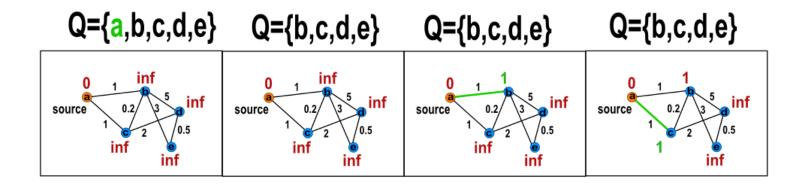
In this case we update the distance to b to 1.

Now we visit all neighbors of α and update the distance to them:

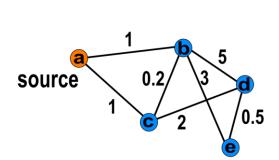
for each neighbor v of u: alt := distance[u] + length(u, v) if alt < distance[v]

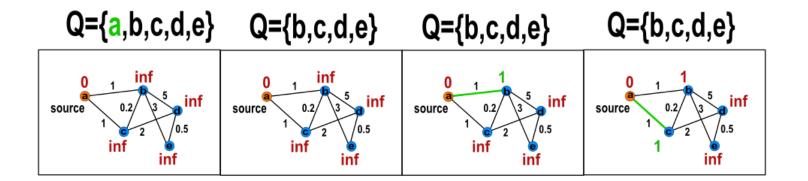
distance[v] := alt





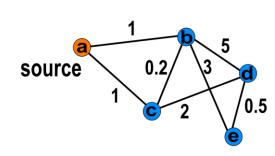
Here we update the distance to c to be 1 as well



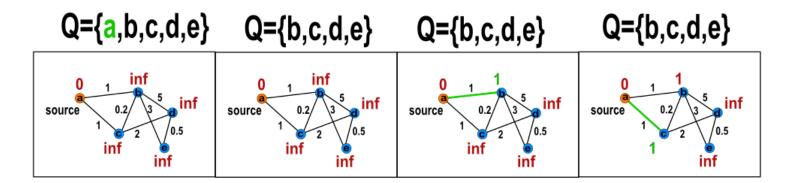


Here we update the distance to c to be 1 as well

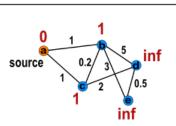
At this stage all neighbors of a have been visited so we check the queue again: if is not empty we start the process again.

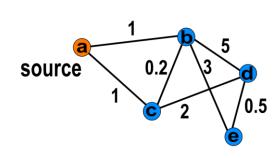


We select *b* (the closest element to a so far)





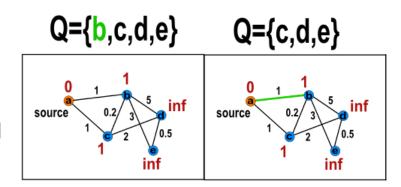


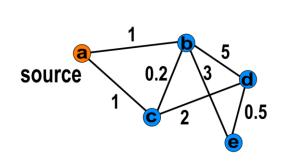


 $Q=\{a,b,c,d,e\} \qquad Q=\{b,c,d,e\} \qquad Q=\{b,c,d,e\}$

Remove b from the queue and start visiting all its neighbors and update the distance.

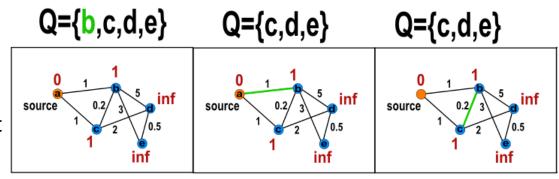
In this case the distance does not update—why?

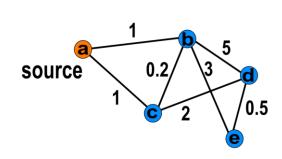




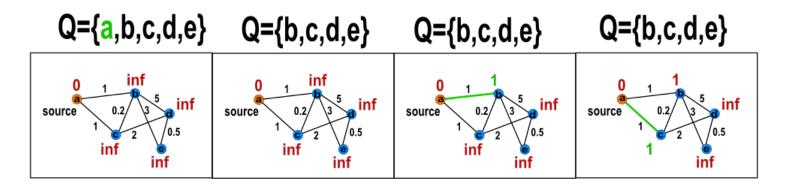
Q={a,b,c,d,e} Q={b,c,d,e} Q={b,c,d,e} Q={b,c,d,e} Q={b,c,d,e}

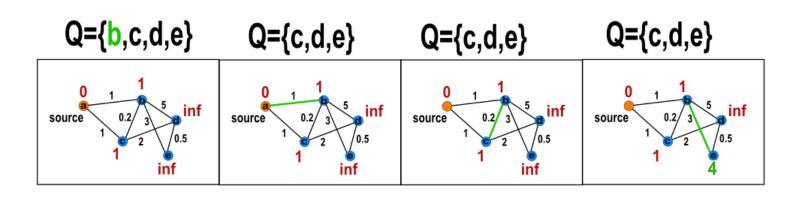
The distance here also does not update

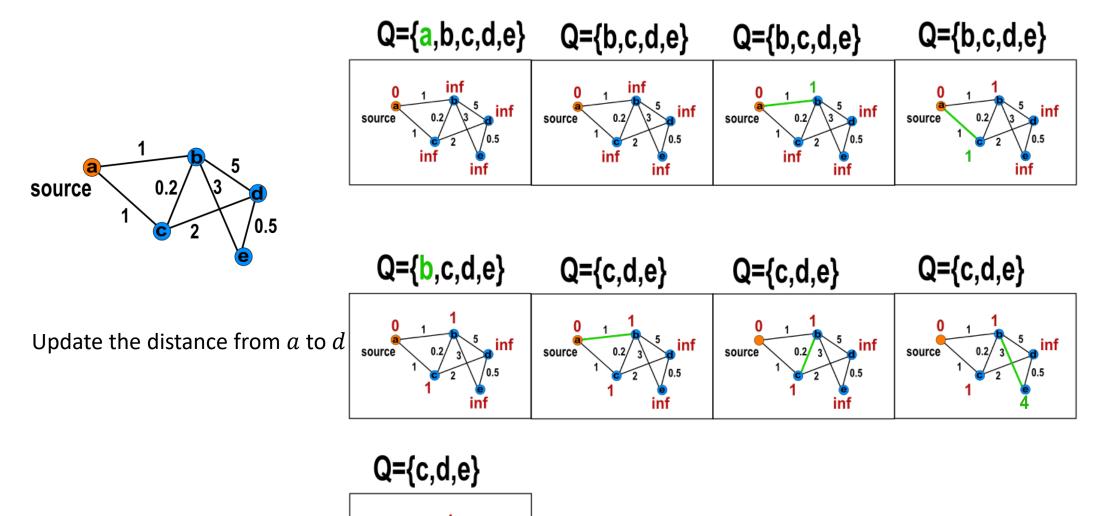


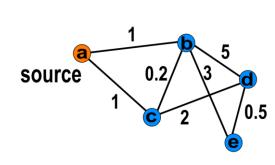


Here we update the distance from a to e to be 4

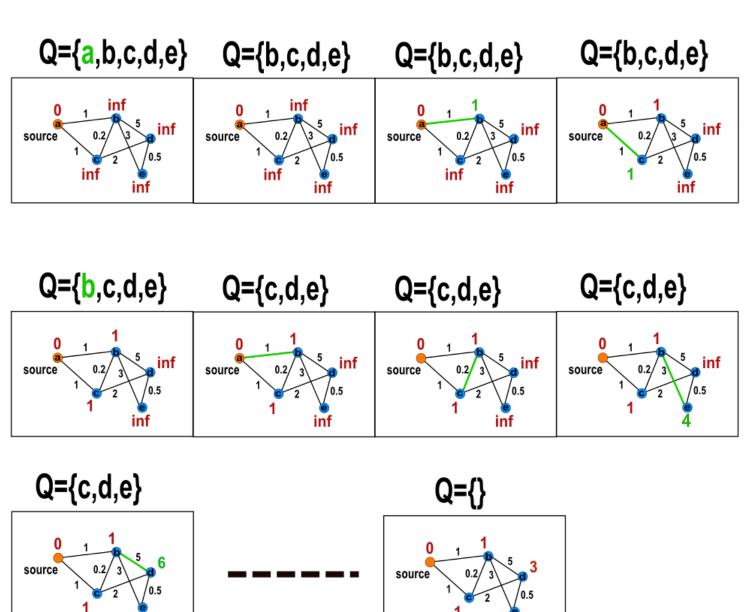




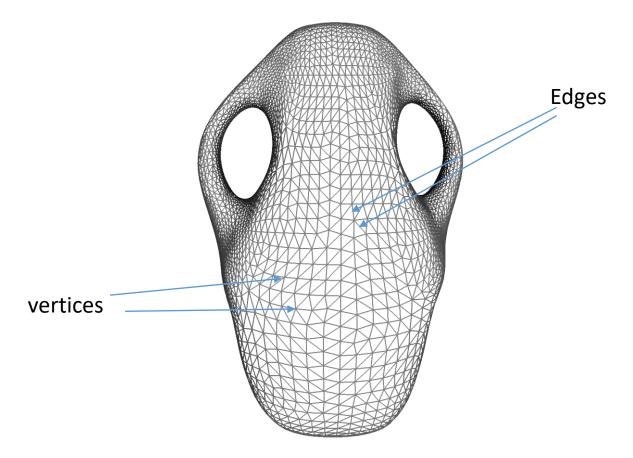




And so on

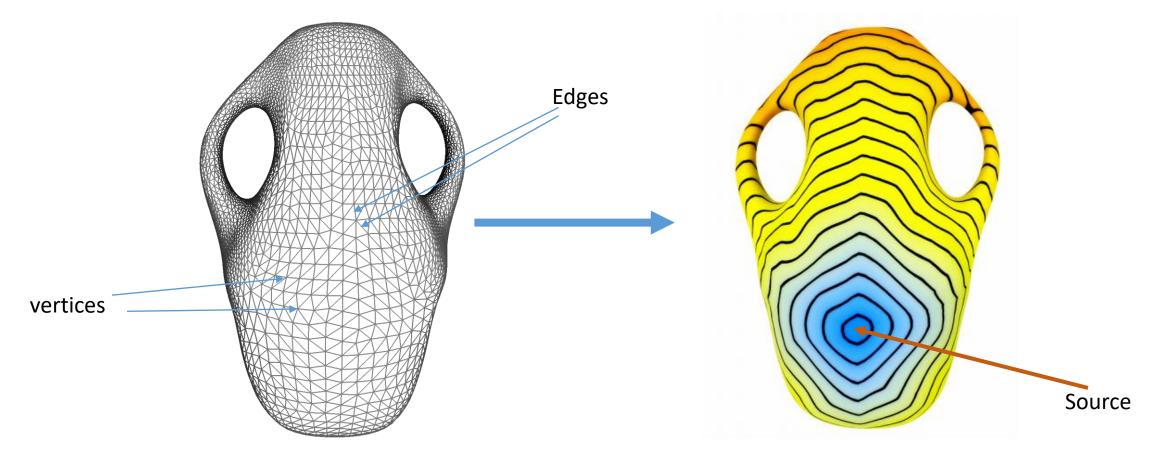


Example



We can view a mesh as a graph and apply Dijkstra algorithm on it.

Example



We can view a mesh as a graph and apply Dijkstra algorithm on it.

Blue indicates the regions closest to the source