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Part 2

(Breadth First Search from start)

Goal found

Breadth first search state counter: 80

BFS result: (Location: battery Sample Extracted?: True Holding Sample?: False

Dropped Off Sample?: True

Charged? True Holding Tool? True

, 'charge')

(Depth first search from start)

Goal found

Depth first search state counter: 70

DFS result: (Location: battery

Sample Extracted?: True Holding Sample?: True Dropped Off Sample?: True

Charged? True Holding Tool? True

, 'charge')

(Depth limited search from start - limit=10)

Goal found

Depth limited search state counter: 52

DLS result: (Location: battery

Sample Extracted?: True Holding Sample?: False Dropped Off Sample?: True

Charged? True Holding Tool? True

, 'charge') Limit: 10 (BFS to sample goal)

Goal found

Breadth first search state counter: 3

Move to sample result: (Location: sample

Sample Extracted?: False Holding Sample?: False Dropped Off Sample?: False

Charged? False Holding Tool? False , 'move to sample')

(BFS to sample removed goal from sample)

Goal found

Breadth first search state counter: 23 Remove sample result: (Location: sample

Sample Extracted?: True Holding Sample?: True Dropped Off Sample?: False

Charged? False Holding Tool? True , 'pick\_up\_sample')

(BFS to battery from removed sample)

Goal found

Breadth first search state counter: 3

Return to charger result: (Location: battery

Sample Extracted?: True Holding Sample?: True Dropped Off Sample?: False

Charged? False Holding Tool? True , 'move\_to\_battery')