

Computer Vision & Pattern Recognition

Spring 2025

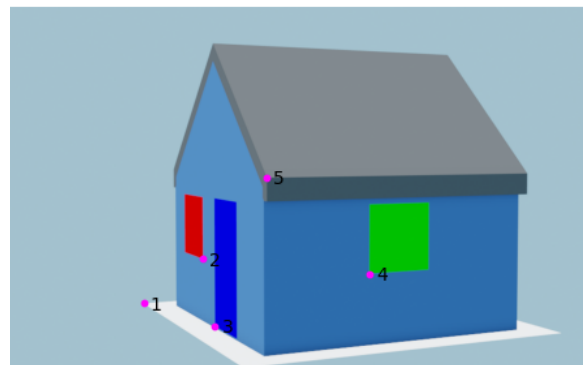
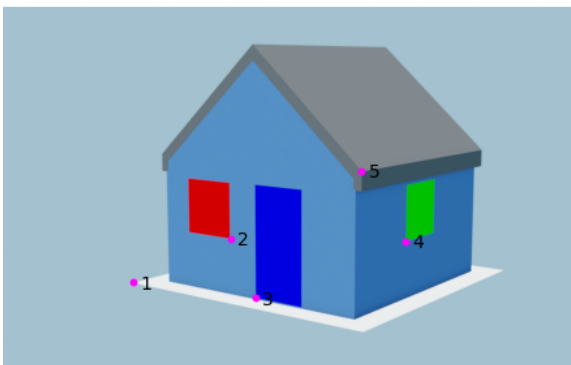
Assignment 8

May 23, 2025

Problem 1 [self-assessment]

Consider again the pixel images “house1.png” and “house2.png” (you can find them on iCorsi) and write a program for recovering the fundamental matrix that relates the two cameras which took these images, as well as the projection matrices for the two cameras. Moreover, you shall reconstruct the world coordinates of the 5 cardinal points of the house marked in the images below. In order to do so, you should attend to the following tasks:

1. Get the image coordinates x_i , $i = 1, \dots, 10$, of the points marked in the image from the previous Assignment 7 in “house1.png” and the image coordinates x'_i , $i = 1, \dots, 10$, of the same points in “house2.png” and use the *8-point algorithm* to reconstruct the *fundamental matrix* F relating the two views.
2. Using the *canonical camera pair* (\hat{P}, \hat{P}') , where $\hat{P} = [I \mid \mathbf{0}]$, $\hat{P}' = [[e']_{\times} F \mid e']$ and *triangulation*, reconstruct the 3D coordinates of the points \hat{X}_i , $i = 1, \dots, 10$, to which the image points x_i and x'_i correspond for this camera pair. To this end, implement the linear triangulation method using the DLT as described in Sec. 12.2 in the book.
3. You will notice that the coordinates \hat{X}_i differ from the world coordinates X_i in the file “coords.tex” (you can find it on iCorsi), which is to be expected, since you computed them using the canonical camera pair. By matching the \hat{X}_i with the X_i , $i = 1, \dots, 10$, recover the *3D homography* H that relates the canonical camera pair (\hat{P}, \hat{P}') to the *correct camera pair* (P, P') . Read note (i) in Sec. 4.9.2 of the book to find out how to do this using the DLT.
4. Use the correct camera pair (P, P') and triangulation to find the world coordinates Y_j , $j = 1, \dots, 5$ of the points y_j and y'_j marked in the images below, similar to how you did it in task 2 with the canonical camera pair.



For discussing the solution in the exercise class, you should have your estimates of F , X'_i ($i = 1, \dots, 10$), (\hat{P}, \hat{P}') , (P, P') , and Y_j ($j = 1, \dots, 5$) available.