Assignment 5

Paolo Deidda (paolo.deidda@usi.ch) Raffaele Perri (raffaele.perri@usi.ch)

https://github.com/USI-Projects-Collection/Computer_Vision.git

Problem 1 [2 points]

In the projective plane \mathbb{P}^2 , a line is represented by a homogeneous vector $(a,b,c)^T$, defining the equation ax + by + cz = 0, where $(x,y,z)^T$ are the homogeneous coordinates of points on the line. The intersection of two lines is found using the cross product of their homogeneous vectors.

Step 1: Define the Line Equations

• For line $l = (2,4,8)^T$, the equation is:

$$2x + 4y + 8z = 0$$

• For line $m = (-2, 3, -1)^T$, the equation is:

$$-2x + 3y - z = 0$$

Step 2: Compute the Cross Product

The homogeneous coordinates of the intersection point are given by $p = l \times m$. For vectors $l = (l_1, l_2, l_3) = (2, 4, 8)$ and $m = (m_1, m_2, m_3) = (-2, 3, -1)$, the components are:

$$p_x = l_2 m_3 - l_3 m_2 = 4 \cdot (-1) - 8 \cdot 3 = -4 - 24 = -28$$

$$p_y = l_3 m_1 - l_1 m_3 = 8 \cdot (-2) - 2 \cdot (-1) = -16 - (-2) = -16 + 2 = -14$$

$$p_z = l_1 m_2 - l_2 m_1 = 2 \cdot 3 - 4 \cdot (-2) = 6 - (-8) = 6 + 8 = 14$$

Thus, the homogeneous coordinates are:

$$p = (-28, -14, 14)^T$$

Since homogeneous coordinates are defined up to scale, divide by 14:

$$p = \left(\frac{-28}{14}, \frac{-14}{14}, \frac{14}{14}\right) = (-2, -1, 1)^T$$

Step 3: Convert to Cartesian Coordinates

For a point $(x, y, z)^T$ with $z \neq 0$, the Cartesian coordinates are (x/z, y/z). Here, z = 1, so:

$$x = \frac{-2}{1} = -2$$
, $y = \frac{-1}{1} = -1$

Thus, the Cartesian coordinates are (-2, -1).

Step 4: Verification

Substitute (x, y, z) = (-2, -1, 1) into both equations:

- Line l: 2(-2) + 4(-1) + 8(1) = -4 4 + 8 = 0
- Line m: -2(-2) + 3(-1) 1 = 4 3 1 = 0

Both are satisfied, confirming the solution.

Final Answer

The Cartesian coordinates of the intersection point are:

$$(-2,-1)$$

Problem 2 [3 points]

We aim to prove:

The points
$$\mathbf{x}, \mathbf{y}, \mathbf{z}$$
 are collinear $\iff \det(M) = 0$

(\Rightarrow) Only If:

Assume the three points are collinear in projective space \mathbb{P}^2 . This means they lie on the same line. In projective geometry, three points are collinear if one of them can be expressed as a linear combination of the other two. That is, there exist scalars $\lambda, \mu \in \mathbb{R}$ such that:

$$\mathbf{z} = \lambda \mathbf{x} + \mu \mathbf{y}$$

This implies that the vectors \mathbf{x} , \mathbf{y} , \mathbf{z} are linearly dependent. By a basic result in linear algebra, if the columns of a matrix are linearly dependent, then the determinant of that matrix is zero:

$$\Rightarrow \det(M) = 0$$

(**⇐**) If:

Now assume that det(M) = 0. Then the columns of M, i.e., the vectors $\mathbf{x}, \mathbf{y}, \mathbf{z}$, are linearly dependent. Therefore, there exist scalars α, β, γ , not all zero, such that:

$$\alpha \mathbf{x} + \beta \mathbf{y} + \gamma \mathbf{z} = \mathbf{0}$$

This means one of the vectors can be written as a linear combination of the other two. For example, if $\gamma \neq 0$, then:

$$\mathbf{z} = -\frac{\alpha}{\gamma}\mathbf{x} - \frac{\beta}{\gamma}\mathbf{y}$$

Thus, the points $\mathbf{x}, \mathbf{y}, \mathbf{z}$ are collinear in projective space.

Conclusion:

$$\mathbf{x}, \mathbf{y}, \mathbf{z}$$
 are collinear $\iff \det(M) = 0$

Problem 3 [5 points]

The code is provided in the separate file **source.py**.

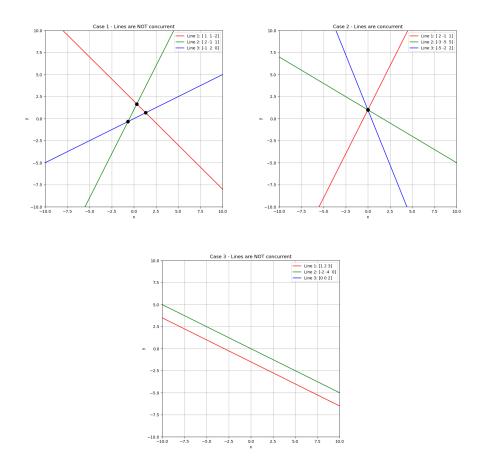


Figure 1: Intersection of lines l and m

In the third case lines 2 and 3 are parallel, so the intersection point is not defined.