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Predictive analytics in quality assurance for assembly processes: lessons learned from a case study at an industry 4.0 demonstration cell

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Abstract

Quality assurance (QA) is an important task in manufacturing to assess whether products meet their specifications. However, QA might be expensive, time-consuming, incomplete, or delayed. This paper presents a solution for predictive analytics in QA based on machine sensor values during production while employing machine-learning models based on logistic regression in a controlled environment. Furthermore, we present lessons learned while implementing this model, which helps to reduce complexity in further industrial applications. The paper's outcome proves that the developed model was able to predict product quality, as well as to identify the correlation between machine-status and faulty product occurrence.

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Keywords: Machine-Learning; Predictive Quality; Production; Quality Assurance; Logistic Regression

1. Introduction

(AP:

- Products' quality must always be guaranteed.
- In certain cases (especially in series assembly production) there is a delay between quality inspection and end of the production process high potential for producing scrap
- By doing quality inspection based on samples, there is still a risk of sending NOK parts to customers
- The cost of quality checks might be expensive
- Quality assurance is normally done at the end of production (for assembly processes)
- Early prediction of the production's quality would help to decrease the amount of scrap and the risk of sending NOK parts to customers
- Variable predictions by using machine learning models is currently widely used in diverse fields due to its

accurate predictions with the data collected from the machines, prediction models can be implemented for specific predicted values

2. Related Works

2.1. Quality check in production

The quality control of production processes and products is one part of the general quality management and contains the measures and activities needed to fulfill the quality requirements [6]. According to Illés, currently there are three established tools and methods of quality control [6]: The Statistical Process Control (SPC), Auditing, and Total Quality Control (TQC). The SPC is used for checking the quality of the products with statistical techniques and contains methods like acceptance sampling or quality control charts [12]. It can take place before and after a manufacturing process as off-line SPC or implemented in the manufacturing process as in-line SPC.

With SPC, large batches can be checked, but it is only possible, if the variance of the product quality is small enough, to ensure process capability [7]. Auditing, in this case especially product and process auditing, is the most fundamental quality control technique. Product and process auditing is the independent examination of product and process quality to provide information. This is executed by an independent auditor, based on sampling, or checking records. But the auditor is just reporting incorrect processes or products. The required adapting is done by others [5]. This is associated with higher costs compared to a quality control based on a machine learning model. The concept of TQC is to extend the scope of quality control to the whole company and product life cycle, by involving all departments of the organization [6]. The quality characteristics of a product can be classified as variables or attributes. Variables are measurable characteristics, which are shown as numbers. On the contrary, attributes are not measurable and can only take the value go or no-go [10]. The advantage of variable measurements is that in the event of a defective intermediate or end product, precise measured values are available, which enable precise adjustment of the process parameters. This allows the desired quality to be restored. With that in mind, a predictive quality control is a promising solution.

(AP:

- **How quality check is done in production**
- **Concepts and sampling plan**
- **Attributive vs Variable measurements [VM has higher measurement accuracy, reason why it's better to use regression model]**

)

2.2. Predictive analytics in production

Predictive analytics discover according to Delen and Damirkan explanatory and predictive patterns which represents the inherent relationships between data inputs and outputs, using data and mathematical techniques [4]. This offers a wide range of applications. In the context of industrial or production environments, this includes in the areas of Processes, Products and Machines and Assets for example predictive maintenance, product design or optimization of routing and scheduling [8]. Predictive analytics combined with quality control can be a powerful tool because it is an improvement compared with the mentioned earlier currently established quality control methods, in terms of speed, accuracy and time delay. So far, only in exceptional cases in the literature is a combination of predictive analytics and quality control found [1, 11]. With regard to general approaches to the use of predictive analytics, for example in the form of machine learning in quality prediction, there is a lack in the literature. Related work, e.g from Krauß focused on automated machine learning for predictive quality in production [9] and a product quality prediction in a process chain [8]. The few existing approaches are extended by this paper in that a demonstrator executes an industry-unspecific production/assembly process, the collection and processing of the

data from the process parameters in continuous and a few different ML algorithms are used for prediction, in order to determine, which algorithms are most advantageous for predicting the quality of an outcoming product. In addition, it is described in detail how the collected data was collected, prepared and processed.

(AP: Predictive analytics as concepts. Implementation in production

- **Predictive Maintenance**
- **Scheduling**
- **Other**

If happens to be something with P.A. Quality Check

- **Predictive analytics in production focusing in QA**
- **Existing approaches and methods**

Note: Ideal is to find a gap in the literature, that proves why do we do it and why it is important)

(AP: - Research Question and research hypotesis)

3. The case industry 4.0 demonstration cell

In our work we applied a case-based research approach [13] to answer the research question. One central motivation for a case-based research approach is to gain insights for real needs, rather than to develop theories without practical relevance [3]. In addition case-based research approaches have already been successfully applied in the area of quality prediction based on process parameters (see, for example,). **(AP: - To answer the question, we apply a case base research. Then explain)**

Our case of study is an abstraction of an assembly process at the industry. The industry 4.0 demonstration cell is composed by three independent conveyor belts, a robotic assembly arm, a laser scanner used for quality control as well as a wide range of sensors, all orchestrated by a SIEMENS PLC S7-1200. The assembly process done at this demonstration cell consist on stacking two disks of different size on the top of each other. The quality of the pseudo products is later evaluated by the laser scanner by evaluating the concentricity of both disks. If the disk's concentricity is within a tolerance of 1.5mm, the piece is classified as OK, if not, it shall be classified as NOK. By considering that malfunctions can occurs during real production processes at industries, our demonstration cell is able to simulate failures in diverse areas, such as:

- Assemble errors due to the robotic arm
- Bearing damage on the conveyor belt
- Resistance on the conveyor belt
- Leakage in the compressed air system
- Productivity limit reached
- Missing material

Those simulated failures have a real impact in the data collected by the sensors. Anomalies can be observed at the vibra-

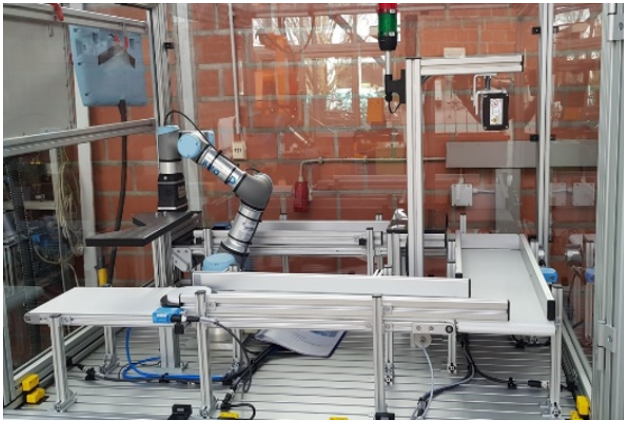


Fig. 1. The industry 4.0 demonstration cell at the University of Siegen

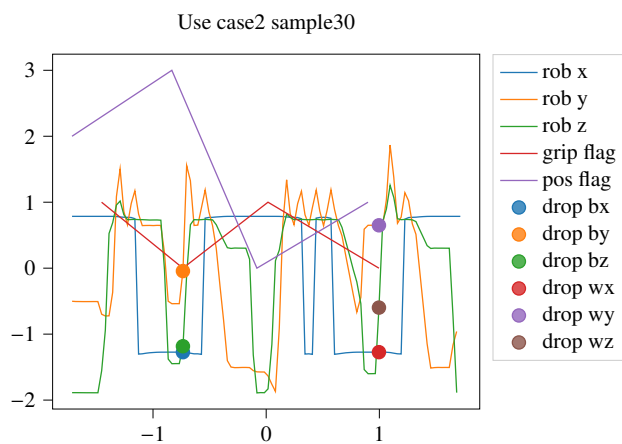


Fig. 2. Robot arm movement patterns. We show the movement of the cell's robot arm, its grippers, and the encoding of the overall position in the system. The changes in the grip flag are triggered, when the gripper opens or closes. Zero indicates an open, while one indicates a closed gripper. The position flags marks the state of the cell's arm. 0 means the black disk is in store, one that the black disk is at the gate, two that the white disk is in store and three that the white disk is located at the gate.

tion sensors, temperature rise, fluctuations in the air pressure system, noticeable shifting on pieces' position as well as the stop of the process.

The continuous data collection and the clear correlation between the machine parameter is the ideal play-ground to implement a sandbox for machine learning implementations. With this in mind, our goal is to predict the quality of the product (concentricity of the assembled parts), prior to the actual quality check done by the laser scanner. The findings gained with the demonstration cell can be transferred to various real assembly processes and use cases, due to its manageable size and the high degree of scalability. This would be a step forwards for future implementations at the industry, where the quality predictions might determine early enough, the next steps for the assembled pieces.

(AP: @Moritz: Why is figure 2 within the area of the Demozelle section?)

| | |
|------------------------|-------|
| Support Vector Machine | 95.% |
| Multilinear Perceptron | 95.% |
| Random Forest | 100.% |

Table 1. Method comparison for our anomaly detection task using the industry demo data test set.

4. Methods

Data is collected from the demonstration cell and analyzed.

4.1. Measurement

(DSt: - what is this section about?)

4.2. Machine Learning

We compare Support Vector Machines (SVM), Multilinear Perceptrons [2] as well as Random forests in the task of quality prediction.

5. Experiments

5.1. Recording the data

(DSt: - could we include collection via OPCUA server? or manually?)

(AP: - AUExpert manually/ automated)

5.2. Classifier optimization and testing

The robot's position at disc drop is marked in Figure 2. The quality prediction problem is framed as a classification task. The input vectors which we feed into our classifiers consists of the arm positions at the disc drops for both discs in three dimensions, as well as the largest recorded belt speed of all three belts. The interpretation of the quality measurement is used as the training target. It can be good or bad which we encode as zero and one.

We work with a total of 132 measurements. Each containing arm and belt data logs of individual cell runs. 20 samples are set aside at random for testing purposes, leaving 112 training samples. The random number generator seed is set to one in order to ensure the train and test set splits are identical for all experiments.

We compare a total of three different classifier architectures on the data. A Support Vector Machine (SVM), a multilinear perceptron and a Random Forest structure. All three methods are trained using standard hyperparameters.¹ Results are shown in table 1. For 55 of the total 132 samples quality measurements indicate a problem. This sets the baseline over the entire data set, that would be obtained by simply labeling all samples as good. Over the entire data set, we require to classify more than

¹ In order to allow exact reproduction of these results source code is available at <https://github.com/manubrain/Demo-Cell-Classification>

58.3% of the data correctly. The test set contains eight incorrect samples. We would therefore expect any naive classifier to produce a 60% accuracy, which we have to beat. In Table 1, we observe that this is indeed the case for all three approaches evaluated here. The random forest performed best in this case.

6. Conclusion

6.1. Lesson Learned

(AP: explain experiences by doing the research
 - Connection problem between devices - Network connection - Device restriction: SIM4000, SIEMENS. - Server Timestamp syncr. - Missing data tags: modifying PLC and robot code to have tags - Interpretation of data: preprocessing - What data is relevant? - Data sample size - ML implementation @Moritz
)

7. Conclusion

Acknowledgments

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