

RSS Main Conference Schedule

Tuesday, June 28: Main Conference, Day 1

Youtube broadcast link: <https://youtu.be/qI0zvRp-UnE>

9:00-9:30am <i>Arledge Aud. Lerner Hall</i>	Opening remarks Kris Hauser (Program Chair), Matei Ciocarlie (Local Arrangements Chair)
9:30-10:00am	Paper Session 1: Long talks Chair: Christoffer Heckmann (University of Colorado, Boulder)
9:30-9:45am	<i>ACID: Action-Conditional Implicit Visual Dynamics for Deformable Object Manipulation</i> Bokui Shen (Stanford University), Zhenyu Jiang (University of Texas at Austin), Christopher Choy (NVIDIA), Leonidas Guibas (Stanford University), Silvio Savarese (Stanford University), Anima Anandkumar (NVIDIA/Caltech), Yuke Zhu (University of Texas, Austin)
9:45-10:00am	<i>Resilient Multi-Sensor Exploration of Multifarious Environments with a Team of Aerial Robots</i> Graeme Best (University of Technology Sydney), Rohit Garg (CMU), John Keller (CMU), Geoff Hollinger (Oregon State University), Sebastian Scherer (CMU)
10:00-10:30am <i>N. Lobby</i>	Coffee break
10:30-11:30am <i>Arledge</i>	Paper Session 2: Short talks Chair: David Held (Carnegie Mellon University)
10:30-10:35am	<i>Equivariant Transporter Network</i> Haojie Huang, Dian Wang, Robin Walters, Robert Platt (Northeastern University)
10:35-10:40am	<i>RoboCraft: Learning to See, Simulate, and Shape Elasto-Plastic Objects with Graph Networks</i> Haochen Shi (Stanford University), Huazhe Xu (Stanford University), Zhiao Huang (University of California San Diego), Yunzhu Li (MIT), Jiajun Wu (Stanford University)
10:40-10:45am	<i>Play it by Ear: Learning Skills amidst Occlusion through Audio-Visual Imitation Learning</i> Maximilian Du, Olivia Y Lee, Suraj Nair, Chelsea Finn (Stanford University)
10:45-10:50am	<i>The Surprising Effectiveness of Representation Learning for Visual Imitation</i> Jyothish Pari, Nur Muhammad (Mahi) Shafiullah, Sridhar Pandian Arunachalam, Lerrel Pinto (NYU)
10:50-10:55am	<i>Mesh-based Dynamics with Occlusion Reasoning for Cloth Manipulation</i> Zixuan Huang, Xingyu Lin, David Held (CMU)
10:55-11:00am	Q&A
11:00-11:05am	<i>A Learning-based Iterative Control Framework for Controlling a Robot Arm with Pneumatic Artificial Muscles</i> Hao Ma, Dieter Buehler, Bernhard Schölkopf, Michael Muehlebach (Max Planck Institute for Intelligent Systems)

- 11:05-11:10am *iSDF: Real-Time Neural Signed Distance Fields for Robot Perception*
Joseph Ortiz (Imperial College London), Alexander Clegg (Facebook AI Research), Jing Dong (Facebook), Edgar A Sucar (Imperial College London), David Novotny (Facebook AI Research), Michael Zollhöfer (Facebook Reality Labs), Mustafa Mukadam (Facebook AI Research)
- 11:10-11:15am *POCD: Probabilistic Object-Level Change Detection and Volumetric Mapping in Semi-Static Scenes*
Jingxing Qian (University of Toronto), Veronica Chatrath (University of Toronto), Jun Yang (University of Toronto), James Servos (Clearpath Robotics), Angela Schoellig (University of Toronto), Steven L Waslander (University of Toronto)
- 11:15-11:20am *DICP: Doppler Iterative Closest Point Algorithm*
Bruno Hexasel, Heethesh Vhavle, Yi Chen (Aeva Inc)
- 11:20-11:30am **Q&A**
- 11:30-12:30pm **Keynote: An AI-First Approach to Building the Next Generation of Self-Driving Technology**
Raquel Urtasun (University of Toronto, Waabi.ai)
Chair: Kris Hauser
- 12:30-2:00pm **Lunch**
- 2:00-3:00pm **Paper Session 3: Long talks**
Chair: Dmitry Berenson (University of Michigan)
- 2:00-2:15pm *Iterative Residual Policy for Goal-Conditioned Dynamic Manipulation of Deformable Objects*
Cheng Chi (Columbia University), Benjamin CM Burchfiel (TRI), Eric Cousineau (TRI), Siyuan Feng (TRI), Shuran Song (Columbia University)
- 2:15-2:30pm *FlowBot3D: Learning 3D Articulation Flow to Manipulate Articulated Objects*
Benjamin Eisner (CMU), Harry Zhang (CMU), David Held (CMU)
- 2:30-2:45pm *ViKiNG: Vision-Based Kilometer-Scale Navigation with Geographic Hints*
Dhruv Shah, Sergey Levine (UC Berkeley)
- 2:45-3:00pm *DextAIRity: Deformable Manipulation Can be a Breeze*
Zhenjia Xu (Columbia University), Cheng Chi (Columbia University), Benjamin CM Burchfiel (TRI), Eric Cousineau (TRI), Siyuan Feng (TRI), Shuran Song (Columbia University)
- 3:00-3:30pm **Early Career Spotlight Talk: Henny Admoni**
Five Traps for Robots in Human Environments....And How to Avoid Them
Henny Admoni, CMU
Chair: Dylan Shell
- 3:30-4:30pm **Paper Session 4: Short talks**
Chair: Anirudah Majumdar (Princeton University)
- 3:30-3:35pm *MIRROR: Differentiable Deep Social Projection for Assistive Human-Robot Communication*
Kaiqi Chen, Jeffrey Fong, Harold Soh (NUS)
- 3:35-3:40pm *Robotic Telekinesis: Learning a Robotic Hand Imitator by Watching Humans on YouTube*
Aravind Sivakumar, Kenneth Shaw, Deepak Pathak (CMU)

3:40-3:45pm	<i>Underwater Robot-To-Human Communication Via Motion: Implementation and Full-Loop Human Interface Evaluation</i> Michael S Fulton, Muntaqim Mehtaz, Owen Queeglay, Junaed Sattar (University of Minnesota)
3:45-3:50pm	<i>Gaze Complements Control Input for Goal Prediction During Assisted Teleoperation</i> Reuben M Aronson, Henny Admoni (CMU)
3:50-3:55pm	<i>Negative Result for Learning from Demonstration: Challenges for End-Users Teaching Robots with Task And Motion Planning Abstractions</i> Nakul Gopalan, Nina M Moorman, Manisha Natarajan, Matthew Gombolay (Georgia Tech)
3:55-4:00pm	Q&A
4:00-4:05pm	<i>Human Motion Control of Quadrupedal Robots using Deep Reinforcement Learning</i> Sunwoo Kim (Seoul National University), Maks Sorokin (Georgia Tech), Jehee Lee (Seoul National University), Sehoon Ha (Georgia Tech)
4:05-4:10pm	<i>Rapid Locomotion via Reinforcement Learning</i> Gabriel B Margolis (MIT), Ge Yang (University of Chicago), Kartik Paigwar (ASU), Tao Chen (MIT), Pulkit Agrawal (MIT)
4:10-4:15pm	<i>Human-to-Robot Imitation in the Wild</i> Shikhar Bahl (CMU), Abhinav Gupta (CMU/FAIR), Deepak Pathak (CMU)
4:15-4:20pm	<i>Variational Inference MPC using Normalizing Flows and Out-of-Distribution Projection</i> Thomas J Power, Dmitry Berenson (University of Michigan)
4:20-4:30am	Q&A
4:30-6:00pm <i>Arledge</i>	Poster session Coffee served in North Lobby
6:00-7:30pm <i>Low Rotunda</i>	Welcome reception <i>Drinks and hors d'oeuvres will be served</i>

Wednesday, June 27: Main Conference, Day 2

Youtube broadcast link: <https://youtu.be/A6rRCVtB2sM>

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|---|---|
| 9:00-10:00am
<i>Arledge Aud.
Lerner Hall</i> | Paper Session 5: Hybrid short / long talks
Chair: Kostas Bekris (Rutgers University) |
| 9:00-9:05am | <i>Embodied Multi-Agent Task Planning from Ambiguous Instruction</i>
Xinzhu Liu, Xinghang Li, Di Guo, Sinan Tan, Huaping Liu, Sun Fuchun (Tsinghua University) |
| 9:05-9:10am | <i>Data Augmentation for Manipulation</i>
Peter Mitrano, Dmitry Berenson (University of Michigan) |
| 9:10-9:15am | <i>Bridging Model-based Safety and Model-free Reinforcement Learning through System Identification of Low Dimensional Linear Models</i>
Zhongyu Li, Jun Zeng, Akshay Thirugnanam, Koushil Sreenath (UC Berkeley) |
| 9:15-9:20am | <i>A Local Optimization Framework for Multi-Objective Ergodic Search</i>
Zhongqiang Ren (Carnegie Mellon University), Akshaya Kesarimangalam Srinivasan (Carnegie Mellon University), Howard Coffin (Carnegie Mellon University), Ian Abraham (Yale University), Howie Choset (Carnegie Mellon University) |
| 9:20-9:25am | <i>Aerial Layouting: Design and Control of a Compliant and Actuated End-Effector for Precise In-flight Marking on Ceilings</i>
Christian Lanegger, Marco Tognon, Lionel Ott (ETH Zurich) |
| 9:25-9:30am | Q&A |
| 9:30-9:45am | <i>Multi-Robot Adversarial Resilience using Control Barrier Functions</i>
Matthew Cavorsi (Harvard University), Beatrice Capelli (University of Modena and Reggio Emilia), Lorenzo Sabattini (University of Modena and Reggio Emilia), Stephanie Gil (Harvard University) |
| 9:45-10:00am | <i>Autonomously Untangling Long Cables</i>
Kaushik Shivakumar, Vainavi Viswanath, Justin Kerr, Brijen Thananjeyan, Ellen Novoseller, Jeffrey Ichnowski, Ken Goldberg, Joseph Gonzalez, Michael Laskey, Alejandro Escontrela (UC Berkeley) |
| 10:00-10:30am
<i>N. Lobby</i> | Coffee break |
| 10:30-11:30am
<i>Arledge</i> | Paper Session 6: Short talks
Chair: TBD |
| 10:30-10:35am | <i>Proxima: An Approach for Time or Accuracy Budgeted Collision Proximity Queries</i>
Daniel Rakita, Bilge Mutlu, Michael Gleicher (University of Wisconsin-Madison) |
| 10:35-10:40am | <i>PROX-QP: Yet another Quadratic Programming Solver for Robotics and Beyond</i>
Antoine Bambade (INRIA), Sarah El Kazdadi (INRIA), Adrien B Taylor (INRIA/ENS), Justin Carpentier (INRIA) |
| 10:40-10:45am | <i>SymForce: Symbolic Computation and Code Generation for Robotics</i>
Hayk Martiros, Aaron Miller (Skydio, Inc.) |
| 10:45-10:50am | <i>Failure Prediction with Statistical Guarantees for Vision-Based Robot Control</i>
Alec Farid, David Snyder, Allen Z. Ren, Anirudha Majumdar (Princeton University) |

10:50-10:55am	<p><i>Factory: Fast Contact for Robotic Assembly</i></p> <p>Yashraj S Narang, Kier Storey, Iretiayo A Akinola, Miles Macklin, Philipp Reist, Lukasz Wawrzyniak, Yunrong Guo, Adam Moravanszky, Gavriel State, Michelle Lu, Ankur Handa, Dieter Fox (NVIDIA)</p>
10:55-11:00am	Q&A
11:00-11:05am	<p><i>Collision Detection Accelerated: An Optimization Perspective</i></p> <p>Louis Montaut (INRIA/CNRS), Quentin Le Lidec (INRIA), Vladimír Petrík (Czech Technical University), Josef Sivic (Czech Technical University), Justin Carpentier (INRIA)</p>
11:05-11:10am	<p><i>Fundamental Performance Limits for Sensor-Based Robot Control and Policy Learning</i></p> <p>Anirudha Majumdar, Vincent Pacelli (Princeton University)</p>
11:10-11:15am	<p><i>Certifiable Robot Design Optimization using Differentiable Programming</i></p> <p>Charles B Dawson, Chuchu Fan (MIT)</p>
11:15-11:20am	<p><i>Collocation Methods for Second Order Systems</i></p> <p>Siro Moreno (Consejo Superior de Investigaciones Científicas), Lluís Ros (Institut de Robòtica i Informàtica Industrial, CSIC-UPC), Enric Celaya (Consejo Superior de Investigaciones Científicas)</p>
11:20-11:30am	Q&A
11:30-12:30pm	<p>Keynote: Wireless Skin-Conformal Devices for Health Monitoring and Haptic Interactions</p> <p>John Rogers (Northwestern University)</p> <p>Chair: Kris Hauser</p>
12:30-2:00pm	Lunch
2:00-3:00pm	<p>Paper Session 7: Long talks</p> <p>Chair: Henny Admoni (CMU)</p>
2:00-2:15pm	<p><i>You Only Demonstrate Once: Category-Level Manipulation from Single Visual Demonstration</i></p> <p>Bowen Wen (Rutgers University), Wenzhao Lian (Intrinsic), Kostas Bekris (Rutgers University), Stefan Schaal (University of S. California)</p>
2:15-2:30pm	<p><i>DiPCAN: Distilling Privileged Information for Crowd-Aware Navigation</i></p> <p>Gianluca Monaci, Michel Aractingi, Tomi Silander (NAVER LABS Europe)</p>
2:30-2:45pm	<p><i>Parameterized Differential Dynamic Programming</i></p> <p>Alex Oshin (Georgia Tech), Matthew D Houghton (NASA), Michael Acheson (NASA), Irene Gregory (NASA), Evangelos Theodorou (Georgia Tech)</p>
2:45-3:00pm	<p><i>AK: Attentive Kernel for Information Gathering</i></p> <p>Weizhe Chen, Roni Khadon, Lantao Liu (Indiana University, Bloomington)</p>
3:00-3:30pm	<p>Early Career Spotlight Talk: Jens Kober</p> <p>Teaching Robots Through Interactions</p> <p>Jens Kober, TU Delft</p> <p>Chair: Dylan Shell</p>
3:30-4:00pm	<p>Paper Session 8: Short talks</p> <p>Chair: Abdeslam Boularias (Rutgers University)</p>

3:30-3:35pm	<p><i>SVAM: Saliency-guided Visual Attention Modeling by Autonomous Underwater Robot</i></p> <p>Md Jahidul Islam (University of Florida), Ruobing Wang (University of Minnesota), Junaed Sattar (University of Minnesota)</p>
3:35-3:40pm	<p><i>TNS: Terrain Traversability Mapping and Navigation System for Autonomous Excavators</i></p> <p>Tianrui Guan (University of Maryland, College Park), Zhenpeng He (Baidu Research Institute), Ruitao Song (Baidu Research Institute), Dinesh Manocha (University of Maryland at College Park), Liangjun Zhang (Baidu Research Institute)</p>
3:40-3:45pm	<p><i>Hydra: A Real-time Spatial Perception System for 3D Scene Graph Construction and Optimization</i></p> <p>Nathan Hughes, Yun Chang, Luca Carlone (MIT)</p>
3:45-3:50pm	<p><i>FaDIV-Syn: Fast Depth-Independent View Synthesis using Soft Masks and Implicit Blending</i></p> <p>Andre Rochow (University of Bonn), Max Schwarz (University of Bonn), Michael Weinmann (TU Delft), Sven Prof. Behnke (University of Bonn)</p>
3:50-3:55pm	<p><i>CALL: Coarse-to-Fine ALIGNments Based Unsupervised Domain Adaptation of Traversability Prediction for Deployable Autonomous Navigation</i></p> <p>Zheng Chen, Durgakant Pushp, Lantao Liu (Indiana University, Bloomington)</p>
3:55-4:00pm	Q&A
4:00-5:30pm Arledge	<p>Poster session</p> <p>Coffee served in North Lobby</p>
5:30-5:35pm	<p>Banquet travel instructions</p> <p>Matei Ciocarlie</p> <p>Travel to banquet</p> <p>We recommend taking the 1 train (a 35-40 minute trip) or an Uber/Yellow Cab (20-30 minutes depending on traffic).</p>
7:00-10:00pm Pier 40	<p>Banquet</p> <p>Boarding starts at 6:30pm, ship leaves dock at 7:00pm</p>

Thursday, June 30: Main Conference, Day 3

Youtube broadcast link: <https://youtu.be/kA2BeKyqkGs>

9:00-10:00am <i>Arledge Aud. Lerner Hall</i>	Paper Session 9: Hybrid short talks Chair: Elaine Short (Tufts University)
9:00-9:05am	<i>KernelGPA: A Deformable SLAM Back-end</i> Fang Bai, Adrien Bartoli (Université Clermont Auvergne)
9:05-9:10am	<i>CURL: Continuous, Ultra-compact Representation for LiDAR</i> Kaicheng Zhang, Ziyang Hong, Shida Xu, Sen Wang (Heriot-Watt University)
9:10-9:15am	<i>SEER: Unsupervised and sample-efficient environment specialization of image descriptors</i> Peer Neubert, Stefan Schubert (TU Chemnitz)
9:15-9:20am	<i>Sub-1.5 Time-Optimal Multi-Robot Path Planning on Grids in Polynomial Time</i> Teng Guo, Jingjin Yu (Rutgers University)
9:20-9:30am	Q&A
9:30-9:35am	<i>Occupancy-SLAM: Simultaneously Optimizing Robot Poses and Continuous Occupancy Map</i> Liang Zhao, Yingyu Wang, Shoudong Huang (Robotics Institute, University of Technology Sydney)
9:35-9:40am	<i>Conflict-Based Steiner Search for Multi-Agent Combinatorial Path Finding</i> Zhongqiang Ren (CMU), Sivakumar Rathinam (Texas A&M University), Howie Choset (CMU)
9:40-9:45am	<i>Traversing Supervisor Problem: An Approximately Optimal Approach to Multi-Robot Assistance</i> Tianchen Ji, Roy Dong, Katherine Driggs-Campbell (University of Illinois at Urbana-Champaign)
9:45-9:50am	<i>Cooperative Multi-Agent Trajectory Generation with Modular Bayesian Optimization</i> Gilhyun Ryou, Ezra Tal, Sertac Karaman (Massachusetts Institute of Technology)
9:50-10:00am	Q&A
10:00-10:30am <i>N. Lobby</i>	Coffee break
10:30-11:30am <i>Arledge</i>	Paper Session 10: Short talks Chair: Andy Zheng (Google)
10:30-10:35am	<i>Soft Robots Learn to Crawl: Jointly Optimizing Design and Control with Sim-to-Real Transfer</i> Charles Schaff (Toyota Technological Institute at Chicago), Audrey Sedal (McGill University), Matthew Walter (Toyota Technological Institute at Chicago)
10:35-10:40am	<i>End-to-End Learning of Hybrid Inverse Dynamics Models for Precise and Compliant Impedance Control</i> Moritz Reuss (KIT), Niels van Duijkeren (Bosch Corporate Research), Robert Krug (Bosch Corporate Research), Philipp Becker (KIT), Vaisakh Shaj (KIT), Gerhard Neumann (KIT)

10:40-10:45am	<i>FuseBot: RF-Visual Mechanical Search</i> Tara Boroushaki , Laura Dodds, Nazish Naeem, Fadel Adib (MIT)
10:45-10:50am	<i>Learning Interpretable, High-Performing Policies for Autonomous Driving</i> Rohan R Paleja (Georgia Tech), Yaru Niu (Georgia Tech), Andrew Silva (Georgia Tech), Chace O Ritchie (UKY), Sugju Choi (Georgia Tech), Matthew Gombolay (Georgia Tech)
10:50-10:55am	<i>Learning Forward Dynamics Model and Informed Trajectory Sampler for Safe Quadruped Navigation</i> Yunho Kim, Chanyoung Kim, Jemin Hwangbo (KAIST)
10:55-11:00am	Q&A
11:00-11:05am	<i>Meta Value Learning for Fast Policy-Centric Optimal Motion Planning</i> Siyan Xu, Minghui Zhu (The Pennsylvania State University)
11:05-11:10am	<i>Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets</i> Frederik D Ebert (UC Berkeley), Yanlai Yang (UC Berkeley), Karl Schmeckpeper (University of Pennsylvania), Bernadette K Bucher (University of Pennsylvania), Georgios Georgakis (University of Pennsylvania), Kostas Daniilidis (University of Pennsylvania), Chelsea Finn (Stanford), Sergey Levine (UC Berkeley)
11:10-11:15am	<i>Invariance Through Latent Alignment</i> Takuma Yoneda (Toyota Technological Institute at Chicago), Ge Yang (University of Chicago), Matthew Walter (Toyota Technological Institute at Chicago), Bradly C Stadie (Vector Institute)
11:15-11:20am	<i>Correcting Robot Plans with Natural Language Feedback</i> Pratyusha Sharma (MIT), Balakumar Sundaralingam (NVIDIA), Valts Blukis (NVIDIA), Chris Paxton (NVIDIA), Tucker Hermans (University of Utah), Antonio Torralba (MIT), Jacob Andreas (MIT), Dieter Fox (NVIDIA)
11:20-11:30pm	Q&A
11:30-12:30pm	Test of Time Award and Panel Chair: Gaurav Sukhatme (University of Southern California)
12:30-2:00pm	Lunch Tour Columbia Robotics Labs (limited to X attendees, signup sheet at registration desk)
2:00-3:00pm	Paper Session 11: Short talks Chair: Jens Kober (TU Delft)
2:00-2:05pm	<i>Action Conditioned Tactile Prediction: case study on slip prediction</i> Willow Mandil, Amir Ghalamzan, Kiyanoush Nazari (University of Lincoln)
2:05-2:10pm	<i>Sample Efficient Grasp Learning Using Equivariant Models</i> Xupeng Zhu, Dian Wang, Ondrej Biza, Guanang Su, Robin Walters, Robert Platt (Northeastern University)
2:10-2:15pm	<i>Understanding Dynamic Tactile Sensing for Liquid Property Estimation</i> Hung-Jui Huang, Xiaofeng Guo, Wenzhen Yuan (CMU)
2:15-2:20pm	<i>Adaptive Manipulation of Conductive, Nonmagnetic Objects via a Continuous Model of Magnetically Induced Force and Torque</i>

Griffin Tabor (University of Utah), Lan Pham (Relativity Space), Jake Abbott (University of Utah), Tucker Hermans (University of Utah)

2:20-2:30pm

Q&A

2:30-2:35pm

Distributed Optimisation and Deconstruction of Bridges by Self-Assembling Robots

Edward Bray, Roderich Gross (The University of Sheffield)

2:35-2:40pm

Learning Mixed Strategies in Trajectory Games

Lasse Peters (Delft University of Technology), David Fridovich-Keil (Stanford), Laura Ferranti (Delft University of Technology), Cyrill Stachniss (University of Bonn), Javier Alonso-Mora (Delft University of Technology), Forrest J Laine (UC Berkeley)

2:40-2:45pm

Decentralized Safe Multi-Agent Stochastic Optimal Control using Deep FBSDEs and ADMM

Marcus A Pereira, Augustinos D Saravanos, Oswin So, Evangelos Theodorou (Georgia Tech)

2:45-2:50pm

PropEM-L: Radio Propagation Environment Modeling and Learning for Communication-Aware Multi-Robot Exploration

Lillian Clark (University of Southern California), Jeffrey Edlund (JPL, CalTech), Tiago Stegun Vaquero (JPL, CalTech), Marc Sanchez Net (JPL, CalTech), Ali Agha (JPL)

2:50-3:00pm

Q&A

3:00-4:30pm

Poster session

Arledge

Coffee served in North Lobby

4:30-5:00pm

Award ceremony

Arledge

Robert Platt (Awards Committee Chair)

5:00-6:00pm

RSS Town Hall

Kris Hauser (Program Chair), Dylan Shell (General Chair)

6:00-6:10pm

Close of Main Conference