Robot Encoder

Local Compute

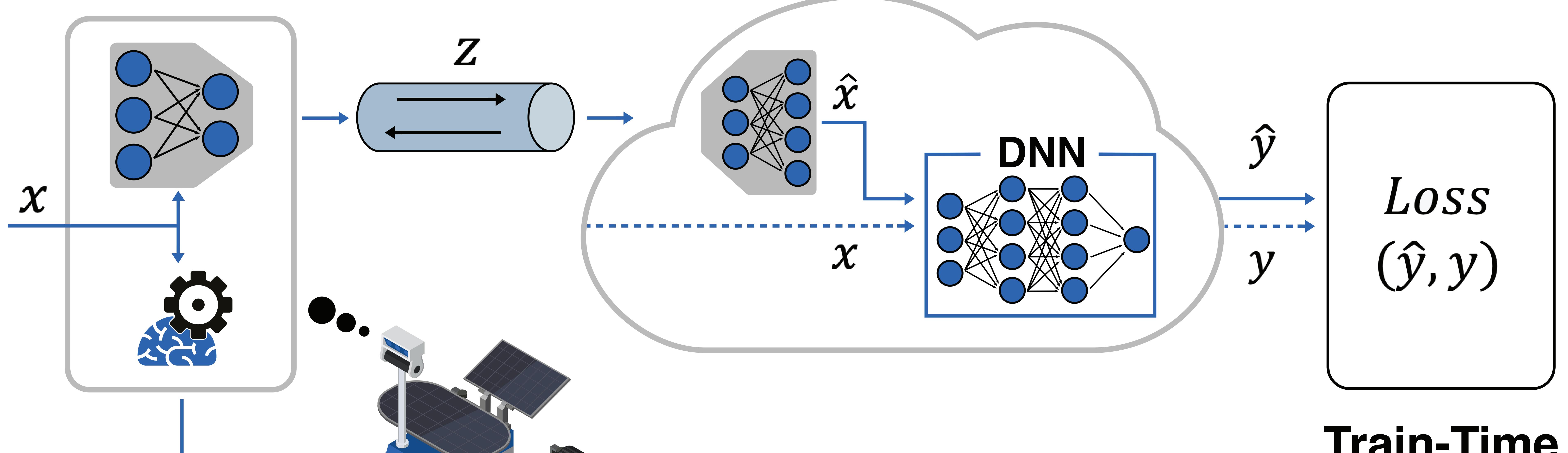
Server Decoder

Server Task Model

$$p(z|x;\theta_{enc.})$$

 $q(x|z;\theta_{dec.})$

 $y = f(x; \theta_{task})$



Train-Time
Only