MFIE-Induced RCS Errors in CFIE Simulations of a Fan-Loaded Camera Box

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Outline

□ Background

- Integral equations
 - MFIE-induced errors
- CameraBox Problem Set from Austin RCS Benchmark Suite
- ☐ Problem-specific MFIE Induced Error
 - RCS pattern
 - Induced currents
- ☐ Rectification techniques
 - α parameter variation
 - Global mesh refinement
 - Local mesh refinement
- Conclusions

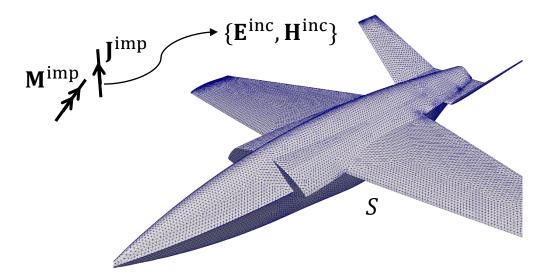


Background

- ☐ Integral-equation formulation
- ☐ Geometry discretized into elements
 - Basis functions defined on elements, eg. RWG basis functions
 - Fill impedance matrix Z
 - EFIE is accurate, slow to converge
 - MFIE converges quickly, can be less accurate

$$\mathbf{Z}^{\text{EFIE}}[m,n] = \frac{j\omega\mu_{\text{o}} \iint_{S} \mathbf{f}_{m}(\mathbf{r}) \cdot \mathbf{f}_{n}(\mathbf{r}') \frac{e^{-jkR}}{4\pi R} dS' dS}{+\frac{1}{j\omega\epsilon_{\text{o}}} \iint_{S} \iint_{S'} \nabla \cdot \mathbf{f}_{m}(\mathbf{r}) \nabla' \cdot \mathbf{f}_{n}(\mathbf{r}') \frac{e^{-jkR}}{4\pi R} dS' dS}$$

$$\mathbf{Z}^{\text{MFIE}}[m, n] = \frac{1}{2} \iint_{S} \mathbf{f}_{m}(\mathbf{r}) \cdot \mathbf{f}_{n}(\mathbf{r}') dS + \iint_{S} (\mathbf{f}_{m}(\mathbf{r}) \cdot \hat{n}) dS \times \iint_{S'} \left(\mathbf{f}_{n}(\mathbf{r}') \times \nabla' \frac{e^{-jkR}}{4\pi R}\right) dS'$$



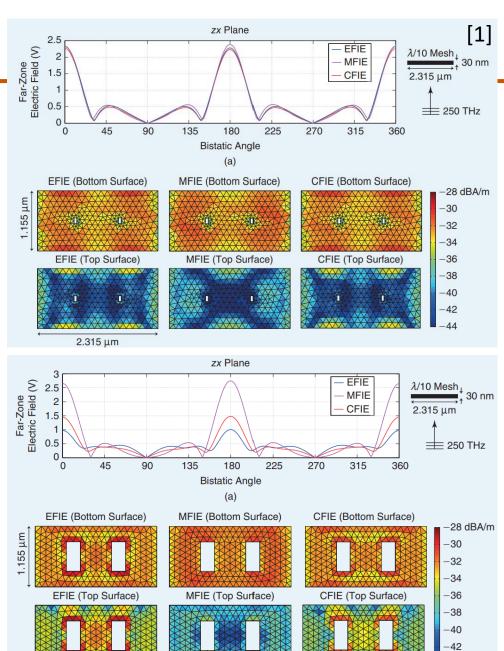


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 - EFIE is accurate, slow to converge
 - MFIE converges quickly, can be less accurate
 - CFIE combines relative strengths of the two methods
 - Uses combination parameter α , often $\alpha = 0.5$

$$\mathbf{Z}^{\text{CFIE}} = \alpha \mathbf{Z}^{\text{EFIE}} + (1 - \alpha) \mathbf{Z}^{\text{MFIE}}$$

- CFIE formulation can still lead to inaccuracy for certain types of geometries
 - Holes, thin surfaces, small gaps, etc.
- Has been demonstrated for pedagogical examples, but what about realistic geometries?



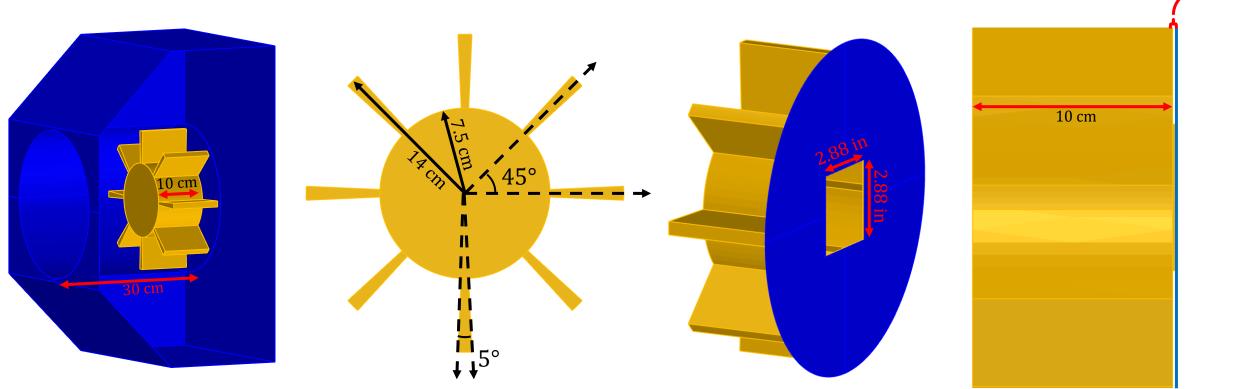
2.315 µm

0.06 in



Fan Loaded Camera Box

- ☐ Austin RCS Benchmark Suite contains a number of complex geometries for Radar Cross-Section (RCS) analysis
- ☐ Problem Set IIISD describes a fan-loaded camera box
 - Small gap between back of fan-assembly and cavity wall
 - 40 cm size model

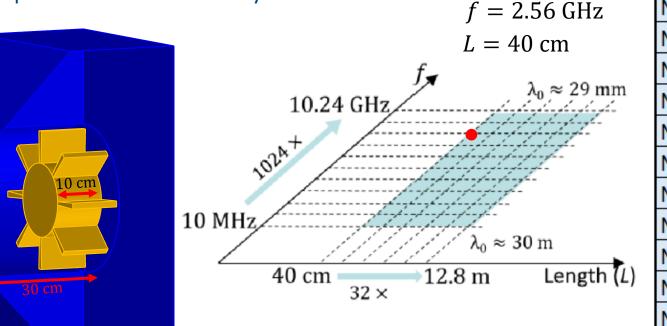


- [2] https://github.com/UTAustinCEMGroup/AustinCEMBenchmarks
- [3] J. T. Kelley, et al., "Reproducible measurements of 'fan blades in a pipe' CEM benchmark," 2023



Fan Loaded Camera Box

- ☐ Austin RCS Benchmark Suite contains a number of complex geometries for Radar Cross-Section (RCS) analysis
- ☐ Problem Set IIISD describes a fan-loaded camera box
 - Small gap between back of fan-assembly and cavity wall
 - Suite provides meshes at many densities



IIISD			
	Average Edge Length (m)	Patch Count	
Mesh YY	2.50E-02	6 084	
Mesh YZ	1.80E-02	12 304	
Mesh ZZ	1.30E-02	24 602	
Mesh ZA	9.00E-03	48 462	
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☐ Problem-specific MFIE Induced Error

- RCS pattern
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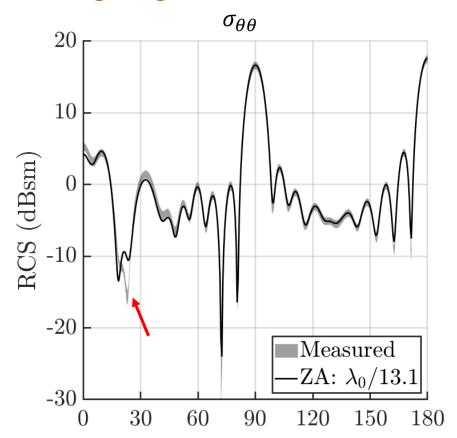
☐ Rectification techniques

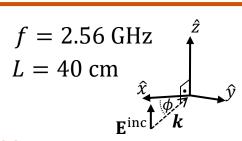
- α parameter variation
- Global mesh refinement
- Local mesh refinement

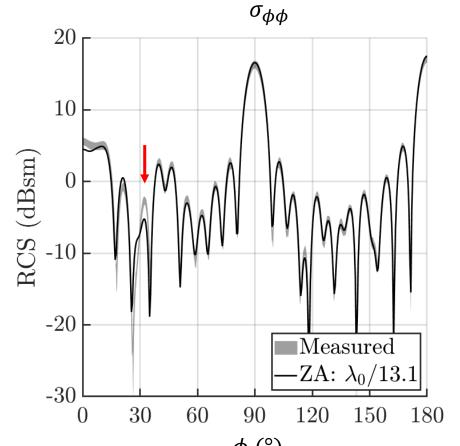
Conclusions



- ☐ Compute VV- and HH-polarized RCS patterns
- \Box CFIE, $\alpha = 0.5$
- \square Mesh ZA, $\lambda_0/13.1$, 72 693 RWGs
- \square Most of look-angles agree with measurement; notable exception in $\sigma_{\theta\theta}$





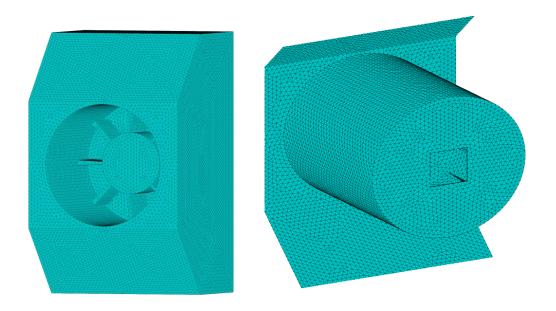


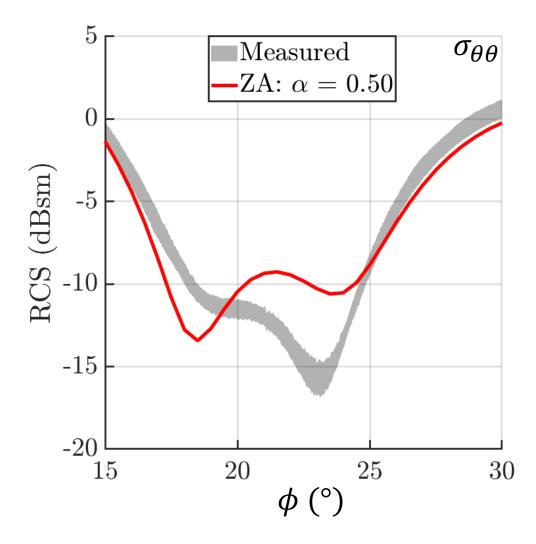
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☐ Error in RCS simulation is due to MFIE error

- Use mesh ZA from Benchmark Suite
- 48 462 surface patches
- Average edge length of 8.93×10^{-3} m
 - Mesh density is $\lambda_0/13.1$
- $\alpha = 0.5$

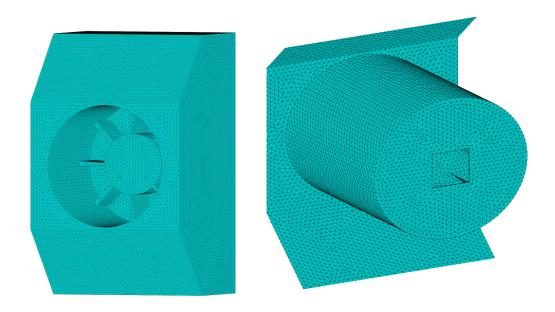


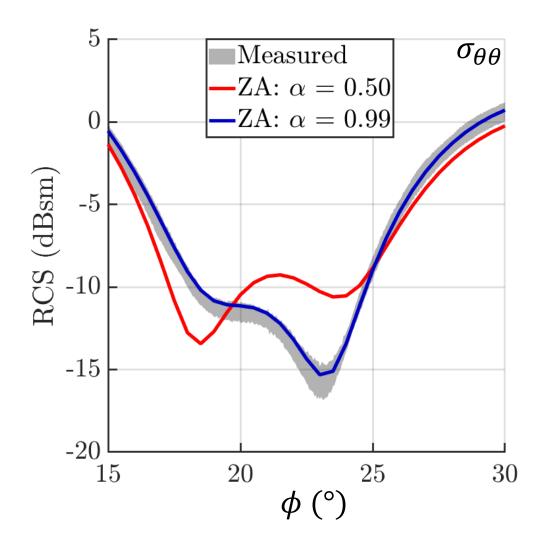




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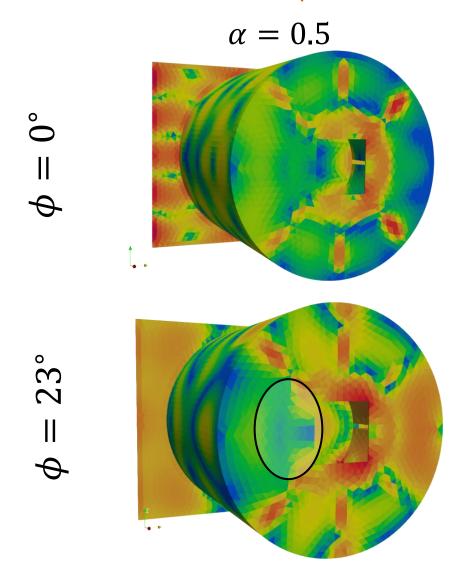
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- Increasing α dramatically improves results

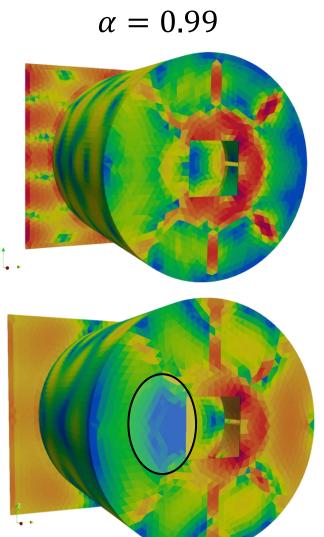


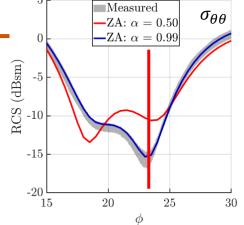


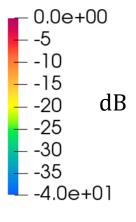


lacktriangle Visualize surface currents on back plate with change in α











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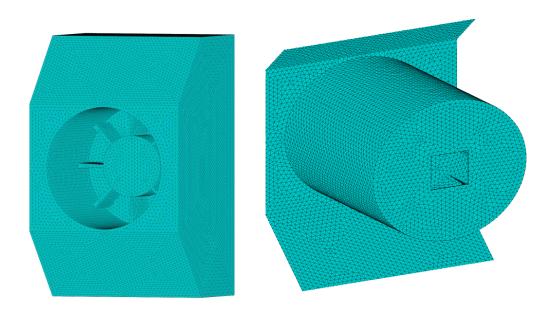
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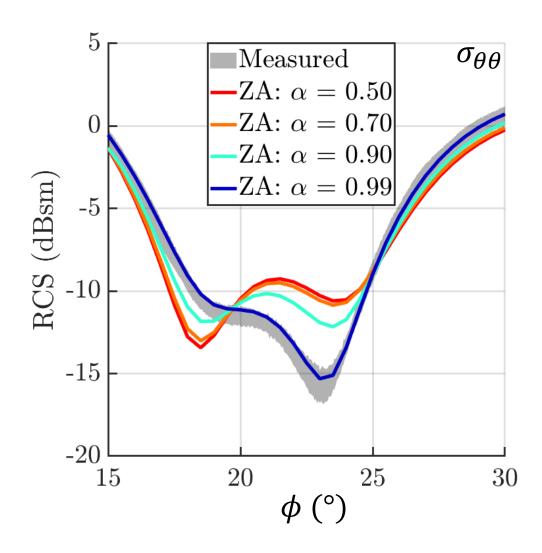


α Parameter Variation

Error in RCS simulation is due to MFIE error

- Use mesh ZA from Benchmark Suite
- 48 462 surface patches
- Average edge length of 9×10^{-3} m
 - Mesh density is $\lambda_0/13.1$
- $\alpha = 0.5$
- Need to push all the way to EFIE to see improvement



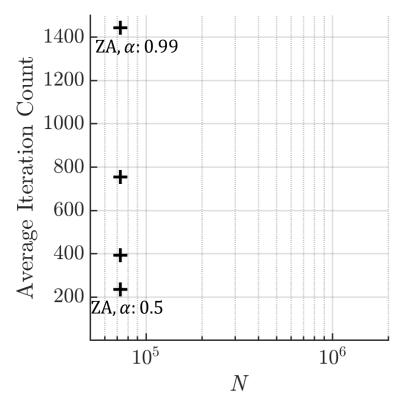


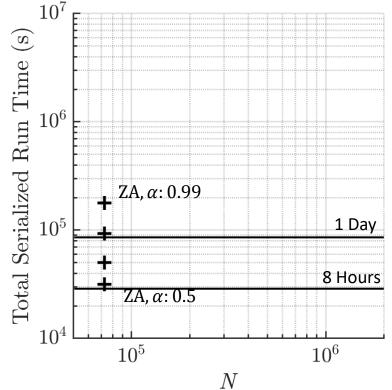


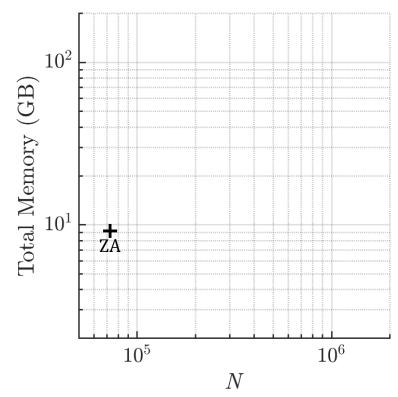
α Parameter Variation

- \Box Increasing α increases the number of iterations necessary to converge in solve stage
 - TFQMR convergence is at 1×10^{-4}
 - Number of iterations increases by $\sim \times 7$
 - Serialized run-time increases by $\sim \times 6$

• Only are computing in narrow window; solve stage dominates full RCS sweep





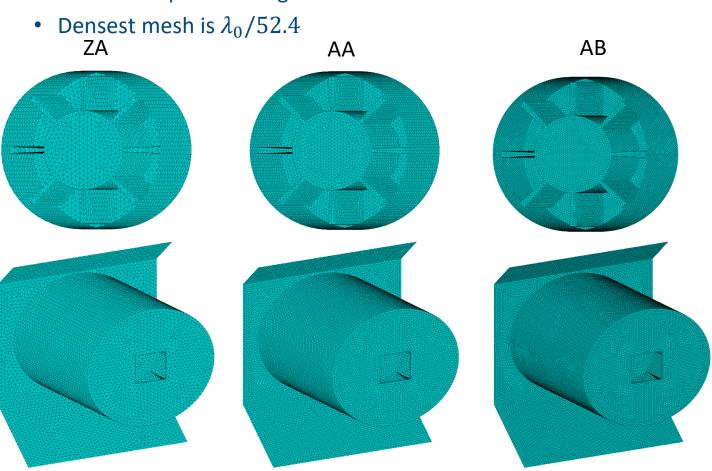




Global Mesh Refinement

\Box Instead of increasing α , can refine the mesh

 Increased resolution will allow more accurate capture of currents in problem region

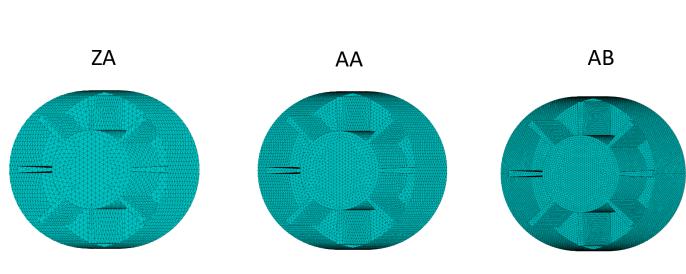


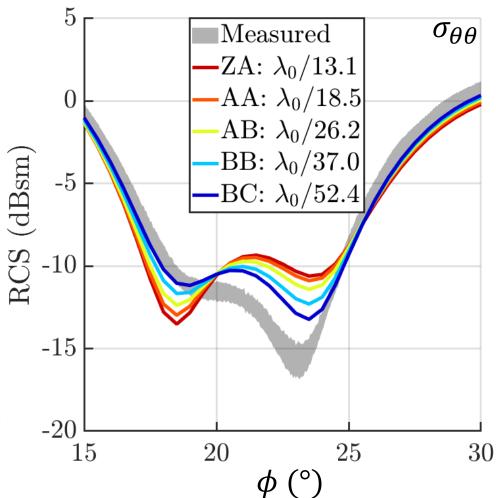
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Global Mesh Refinement

- \square Instead of increasing α , can refine the mesh
 - Increased resolution allows more accurate capture of currents in problem region
 - Densest mesh is $\lambda_0/52.4$
- \square Accuracy improves more slowly than α increase

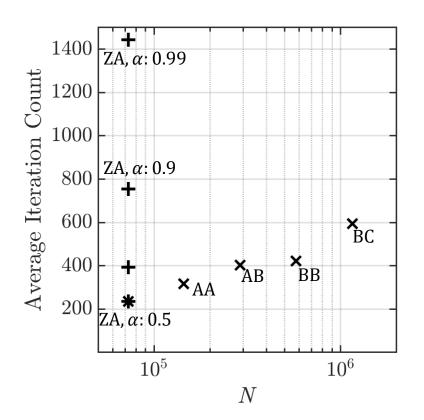


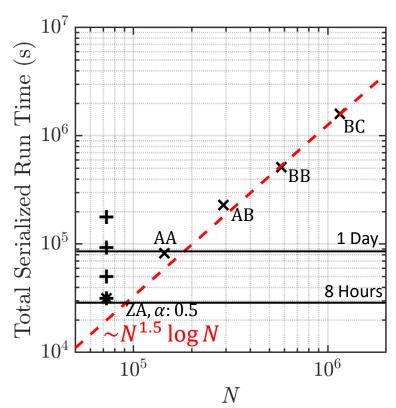


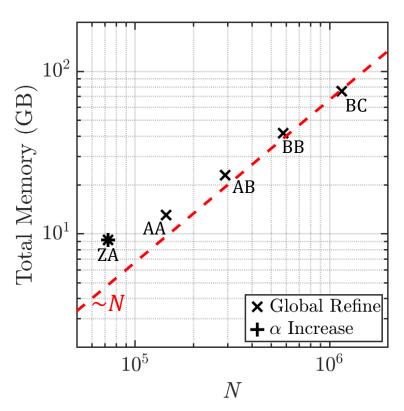


Global Mesh Refinement

- $lue{}$ Compared to lpha increase, global mesh refinement iterations grow much more slowly
- Increased memory costs in fill stage, increased time costs





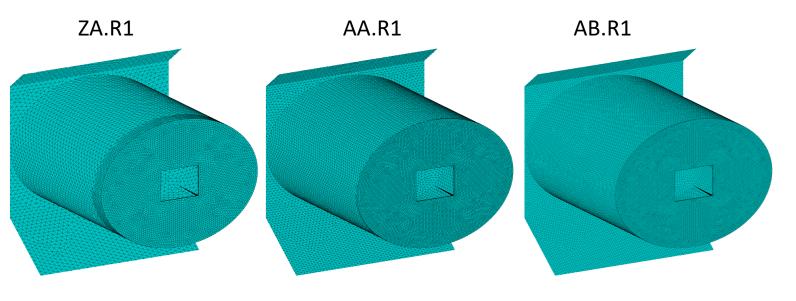




Local Mesh Refinement

☐ No need to globally refine mesh

- Locally refining the mesh in the problem region can save on computational costs
- One level of refinement from 'base' mesh



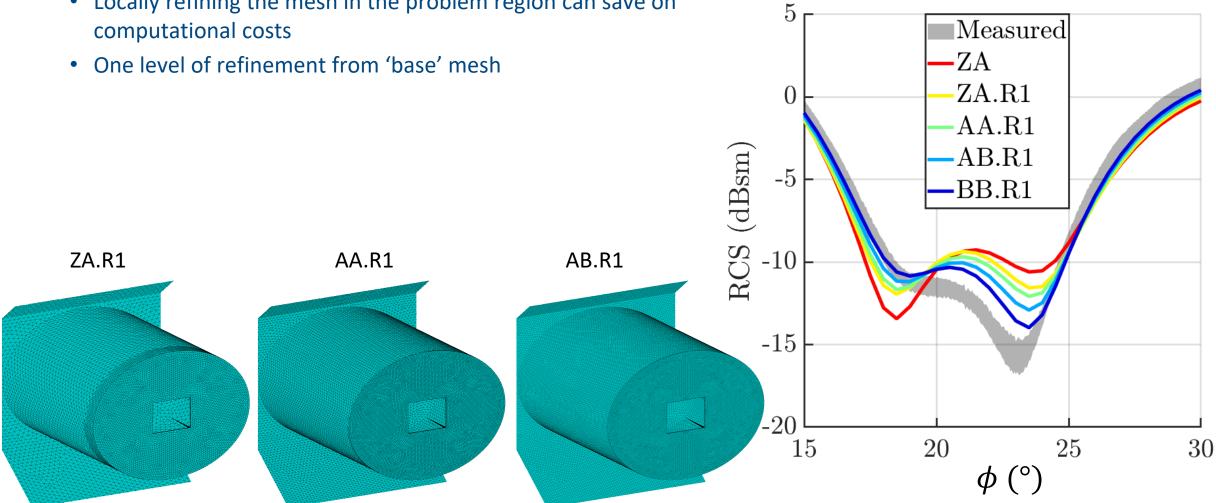
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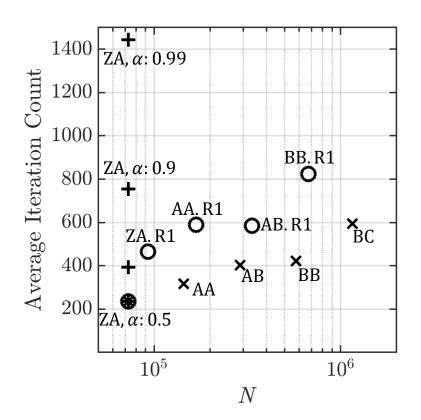
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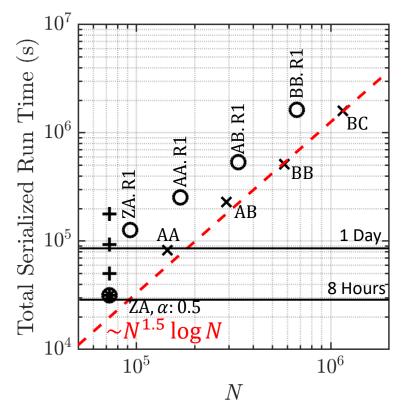


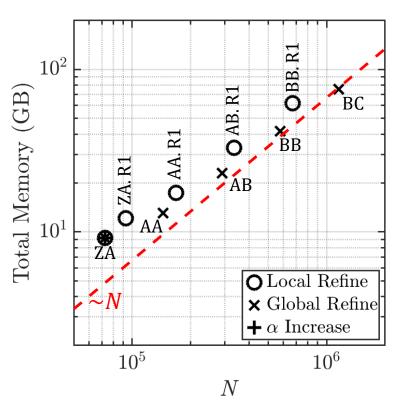


Local Mesh Refinement

- ☐ Compared to global refine, iterations grow more quickly due to uneven mesh
- Costs appear to grow at similar rate
 - How do we more accurately compare local vs. global refine strategies?



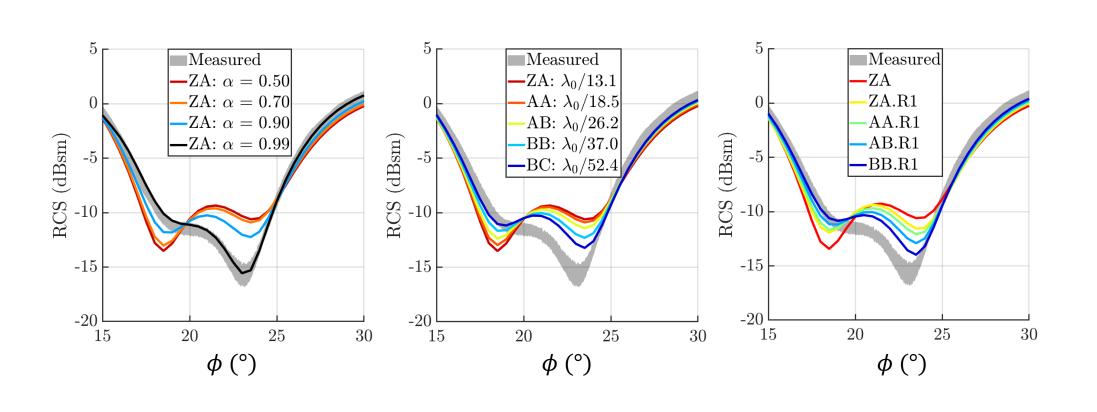


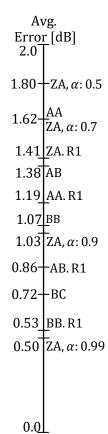




Method Comparison

☐ Reference is the data published on the Benchmark Suite

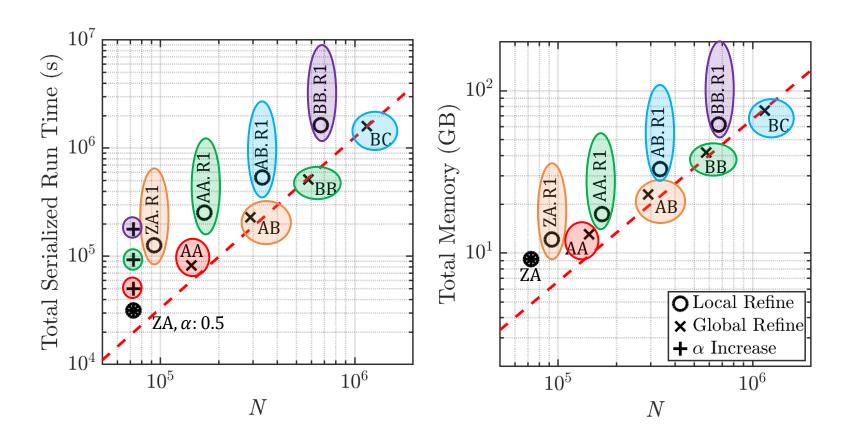


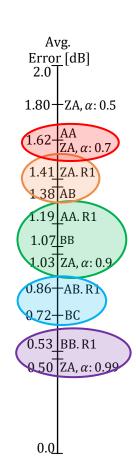




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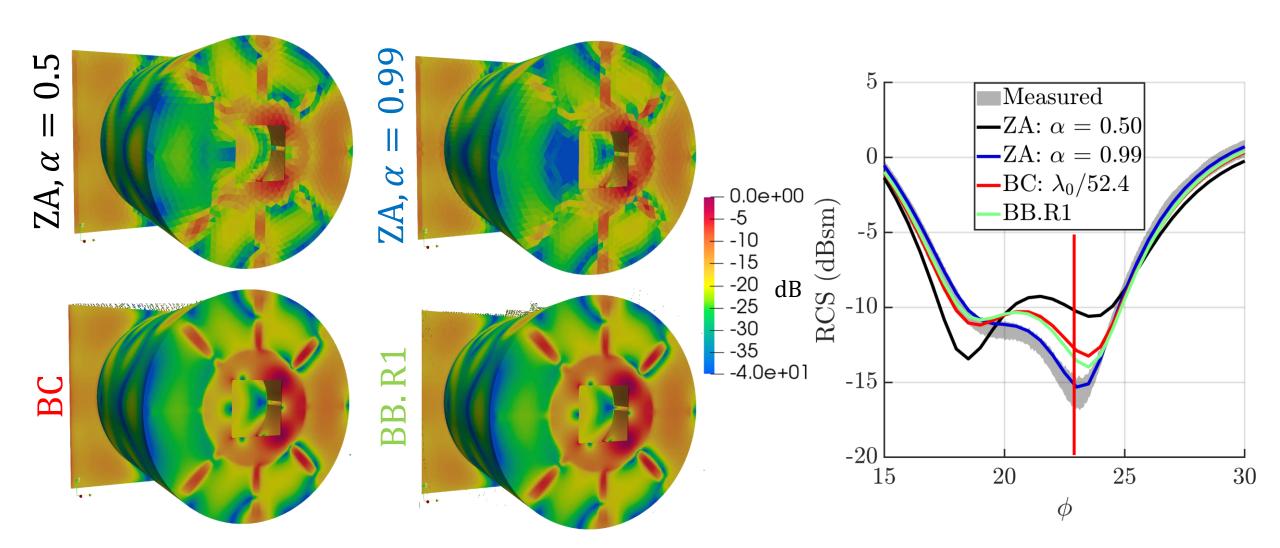






Method Comparison

☐ Visualize surface currents on back plate for most accurate/expensive simulation from each method





Conclusions

- In a realistic, complex geometry, MFIE can on occasion induce large errors in RCS
- ☐ Investigated 3 ways to decrease errors
 - α control
 - No memory increase
 - Number of iterations grows quickly
 - Moderate increase in solve time
 - Global mesh refinement
 - Largest memory and cost increases
 - Slow iteration count growth
 - Local mesh refinement
 - Moderate-large cost increase
 - Moderate iteration count growth
- Best results from combination of strategies, or more targeted local mesh refinement

