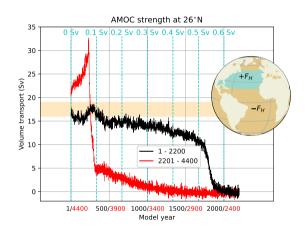
Big Data and Open Science

René van Westen

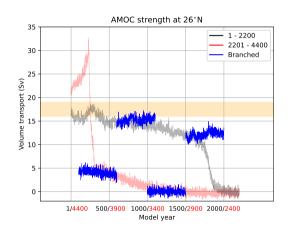
Institute for Marine and Atmospheric Research Utrecht
Utrecht University

20 February 2024

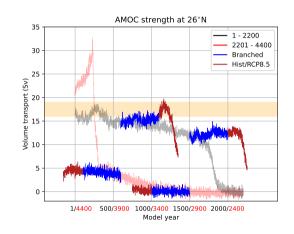
- Hysteresis experiment
 - 4,400 model years



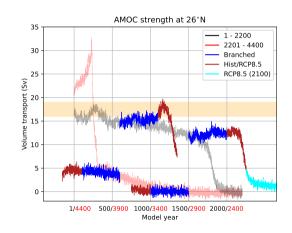
- Hysteresis experiment
 - 4,400 model years
- Branched simulations
 - 4×600 model years



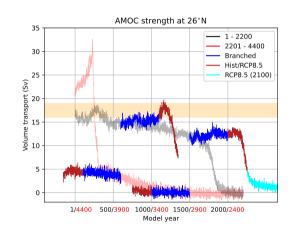
- Hysteresis experiment
 - 4,400 model years
- Branched simulations
 - \bullet 4 \times 600 model years
- Historical forcing and climate change
 - 4×250 model years



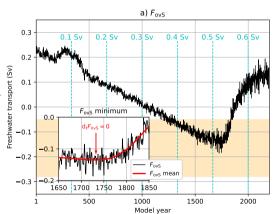
- Hysteresis experiment
 - 4,400 model years
- Branched simulations
 - 4×600 model years
- Historical forcing and climate change
 - 4×250 model years
- Constant 2100 RCP8.5 conditions.
 - 1×400 model years



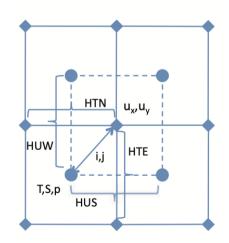
- Hysteresis experiment
 - 4,400 model years
- Branched simulations
 - 4×600 model years
- Historical forcing and climate change
 - 4×250 model years
- Constant 2100 RCP8.5 conditions
 - \bullet 1 \times 400 model years
- 8,200 models years in total
 - \bullet 1 monthly ocean file \rightarrow 1.1 Gb



$$F_{\mathrm{ov}}(y) = -rac{1}{S_0} \int_{-H}^0 \left[\int_{x_W}^{x_E} v^* \mathrm{d}x
ight] \left[\langle S \rangle - S_0
ight] \mathrm{d}z$$

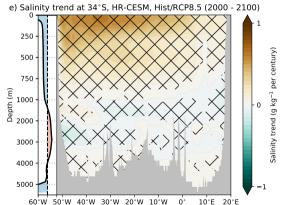


$$F_{\text{ov}}(y) = -\frac{1}{S_0} \int_{-H}^{0} \left[\int_{x_W}^{x_E} v^* dx \right] \left[\langle S \rangle - S_0 \right] dz$$



 $F_{\text{ov}}(y) = -\frac{1}{S_0} \int_{-H}^{0} \left[\int_{x_W}^{x_E} v^* dx \right] \left[\langle S \rangle - S_0 \right] dz \underset{\frac{1}{Q}}{\overset{750}{\underset{2000}{\downarrow}}}$

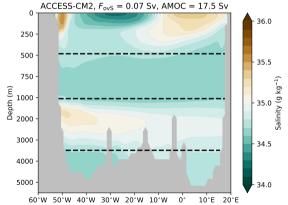
Statistical tests



•

$$F_{\text{ov}}(y) = -\frac{1}{S_0} \int_{-H}^{0} \left[\int_{x_W}^{x_E} v^* dx \right] \left[\langle S \rangle - S_0 \right] dz \stackrel{\text{fig. }}{\underset{0}{\text{dec}}}$$

- Statistical tests
- Interpolation onto different grid

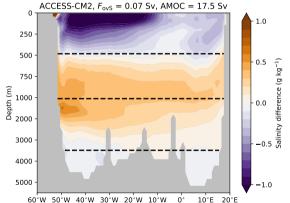




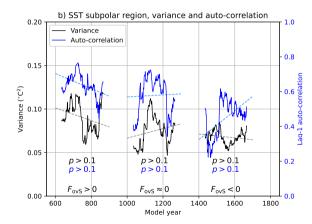
•

$$F_{\text{ov}}(y) = -\frac{1}{S_0} \int_{-H}^{0} \left[\int_{x_W}^{x_E} v^* dx \right] \left[\langle S \rangle - S_0 \right] dz \stackrel{\text{750}}{\underset{\text{do 2000}}{\stackrel{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}}{\overset{\text{750}}}}{\overset{\text{750}}}{\overset{\text{750}}}}}{\overset{\text{750}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}{\overset{\text{750}}}}$$

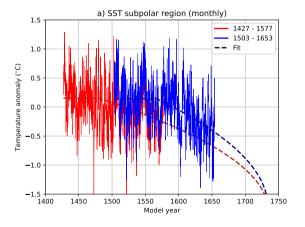
- Statistical tests
- Interpolation onto different grid



- Boers (2021)
 - Early Warning Indicators



- Boers (2021)
 - Early Warning Indicators
- Ditlevsen & Ditlevsen (2023)
 - Estimating the AMOC tipping point



FAIR Principles

- Findability
- Accessibility
- Interoperability
- Reuse

FAIR Principles

- Findability
 - Data are registered with a globally unique identifier
- Accessibility
 - Data are retrievable and permanently stored
- Interoperability
 - The data use a formal and accessible language
- Reuse
 - The data are richly described with metadata

Code availability

All Python code used for the analysis is available from the author upon request (boers@pikpotsdam.de) or on GitHub at https://github.com/niklasboers/AMOC_EWS.

niklasboers Add files via upload		be10717 · 3 years ago	1 Commits
BWS_functions.py	Add files via upload		3 years ago
model_data_comparison.py	Add files via upload		3 years ago
salinity.py	Add files via upload		3 years ago
shiftgrid.py	Add files via upload		3 years ago
ssts.py	Add files via upload		3 years ago

```
258
        weights = np.cos(np.radians(lat))
259
260
        weights = weights / np.sum(weights)
261
        print(weights)
262
        weights = np.tile(weights, (lon.shape[0], 1)).T
263
        sstav = sstav * weights
264
        ssty = ssty * weights
265
266
267
        # gl mean av = np.nanmean(sstav.reshape(sstav.shape[0], sstav.shape[1] * sstav.shape[2])[:, gloidx
268
        # gl mean = np.nanmean(sstv.reshape(sstv.shape[0], sstv.shape[1] * sstv.shape[2])[:, gloidx], axis
269
        # nh mean = np.nanmean(sstv.reshape(sstv.shape[0], sstv.shape[1] * sstv.shape[2])[:, nhidx], axis
270
271
        # amoc1 = np.nanmean(sstv.reshape(sstv.shape[0], sstv.shape[1] * sstv.shape[2])[:, sqi], axis = 1)
272
273
274
        ql mean av = np.nansum(sstav.reshape(sstav.shape[0], sstav.shape[1] * sstav.shape[2])[:, gloidx].
275
        gl mean = np.nansum(sstv.reshape(sstv.shape[0], sstv.shape[1] * sstv.shape[2])[:, gloidx], axis =
276
277
        nh mean = np.nansum(sstv.reshape(sstv.shape[0], sstv.shape[1] * sstv.shape[2])[:, nhidx], axis = 1
278
279
        amoc1 = np.nansum(ssty.reshape(ssty.shape[0], ssty.shape[1] * ssty.shape[2])[:, sqi], axis = 1) / |
280
281
282
        amoc2 = amoc1 - ql mean
283
        amoc2 = (amoc2 - np.mean(amoc2))
284
        np.savetxt('data/amoc idx niklas.txt', amoc2)
```

```
295
        var_sst_trend = np.zeros((la, lo))
        ar1 sst trend = np.zeros((la. lo))
296
297
        lambda sst trend = np.zeros((la. lo))
298
299
        \# count = 0
300
        # for i in range(la):
              for j in range(lo):
301
302
                 if np.sum(np.isnan(sstv[:, i, i])) == 0:
303
                      ts temp = sstv[:, i, j] - runmean(sstv[:, i, j], sm w)
304
                      sst var spatial[:, i, i] = runstd(ts temp, rmw)**2
305
                      p1. p0 = np.polyfit(time[bound: - bound], sst var spatial[:, i, i][bound: - bound]
306
307
                      var sst trend[i, i] = p1
308
                      sst ar1 spatial[:, i, i] = runac(ts temp, rmw)
300
                      p1. p0 = np.polyfit(time[bound: - bound], sst ar1 spatial[:, i, i][bound: - bound]
310
                      ar1 sst trend[i, i] = p1
311
312
313
                      # sst lambda spatial[:, i, i] = run fit a(ts temp, rmw)
314
                      # pl. p0 = np.polyfit(time[bound : - bound], sst lambda spatial[:, i, i][bound : - bound]
315
                      # lambda sst trend[i, i] = p1
316
                      count += 1
317
                      print(count)
318
319
        # np.save('data/am sst global runstd.npv', sst var spatial)
320
        # np.save('data/am sst global runac.npv', sst ar1 spatial)
        # # np.save('data/am sst global runlambda.npv', sst lambda spatial)
321
```

```
def fourrier surrogates(ts, ns):
           ts fourier = np.fft.rfft(ts)
           random phases = np.exp(np.random.uniform(0, 2 * np.pi, (ns. ts.shape[0] // 2 + 1)) * 1.0i)
           ts fourier new = ts fourier * random phases
10
          new ts = np.real(np.fft.irfft(ts fourier new))
           return new ts
12
      def kendall tau test(ts. ns. tau. mode1 = 'fourier', mode2 = 'linear');
13
14
           tlen = ts.shape[0]
15
16
           if mode1 == 'fourier':
               tsf = ts - ts.mean()
               nts = fourrier surrogates(tsf. ns)
18
19
           elif mode1 == 'shuffle':
20
               nts = shuffle_surrogates(ts, ns)
           stat = np.zeros(ns)
           tlen = nts.shape[1]
           if mode2 == 'linear':
               for i in range(ns):
24
                   stat[i] = st.linregress(np.arange(tlen), nts[i])[0]
26
           elif mode2 == 'kt':
               for i in range(ns):
28
                   stat[i] = st.kendalltau(np.arange(tlen), nts[i])[0]
           p = 1 - st.percentileofscore(stat. tau) / 100.
30
          return p
```

31

FAIR Principles score Boers (2021)

• Findability: 8/10

• Accessibility: 4/10

• Interoperability: 2/10

• **R**euse: 1/10

FAIR Principles score Boers (2021)

- Findability: 8/10
- Accessibility: 4/10
- Interoperability: 2/10
- **R**euse: 1/10
- Overall score: 4/10

20 February 2024

Code availability

Computer code (Matlab and R) can be found in the following repository: https://doi.org/10.17894/ucph.b8f99b67-d4e6-4a2e-b518-00bddeed323b.

▼ Name	♦ Date	♦ Size
AMOCdata.txt	2023-07-09 14:26:01	102002
AMOCestimation.html	2023-07-09 19:33:42	1387093
AMOCestimation.Rmd	2023-07-09 19:33:42	22614
EstimMatrix_1000repetitions.xlsx	2023-07-09 14:26:01	106797
SimulatedTraces.Rdata	2023-07-09 14:26:01	14111716
Supplementary_Information.pdf	2023-07-09 14:26:01	181285

Estimation of tipping time from AMOC fingerprint

The following code chunk loads the AMOC fingerprint data and estimates parameters. Estimates are reported.

Code

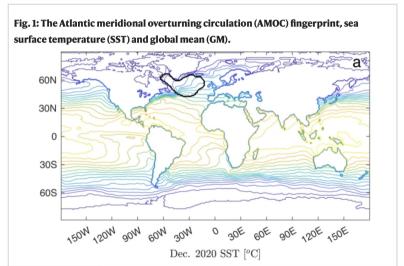
```
## t0 alpha0 mu0 sigma2 tau a m lambda0 tc
## 1924.00 3.06 0.25 0.30 132.52 0.87 -1.51 -2.69 2056.52
```

Estimation of tipping time from AMOC fingerprint

The following code chunk loads the AMOC fingerprint data and estimates parameters. Estimates are reported.

```
Hide
```

```
### Estimation on AMOC data ###
##################################
## Read data
AMOC.data = read.table("AMOCdata.txt", header = TRUE)
## time: calendar time in years
## AMOCO: SST (sea surface temperature) in subpolar gyre, subtracted the monthly mean
## AMOC1: AMOC0 subtracted the global mean SST
## AMOC2: AMOC0 subtracted two times the global mean SST (Arctic amplification)
## GM: global mean SST
## Adding fingerprint with 3 times subtracted global warming for robustness analysis
AMOC.data$AMOC3 = AMOC.data$AMOC0 - 3 * AMOC.data$GM
```



FAIR Principles score Ditlevsen & Ditlevsen (2023)

- Findability: 10/10
- Accessibility: 7/10
- Interoperability: 7/10
- **R**euse: 6/10

FAIR Principles score Ditlevsen & Ditlevsen (2023)

• Findability: 10/10

• Accessibility: 7/10

• Interoperability: 7/10

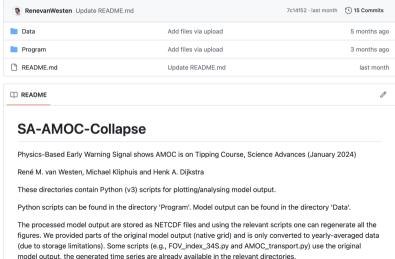
• **R**euse: 6/10

• **Overall score**: 7.5/10

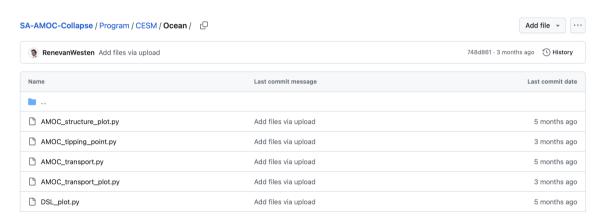
20 February 2024

Software and model output

The (processed) model output and analysis scripts are provided at: https://doi.org/10.5281/zenodo.10461549. The reanalysis and assimilation products can be accessed through GLORYS12V1 (https://doi.org/10.48670/moi-00021), SODA3.15.2 (http://soda.umd.edu), ORAS5 (https://doi.org/10.24381/cds.67e8eeb7), ORA-20C (https://icdc.cen.uni-hamburg.de/thredds/catalog/ftpthredds/EASYInit/ora20c/opa0/catalog.html), and ECCO-V4r4 (https://ecco-group.org/products-ECCO-V4r4.htm).



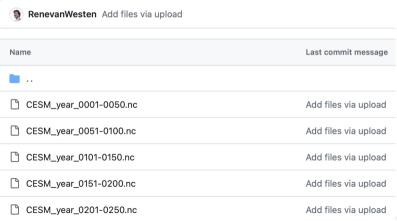
10 / 11



```
def ReadinData(filename, depth min index, depth max index):
15
             fh = netcdf.Dataset(filename, 'r')
16
18
             #First get the u-grid
                   = fh.variables['vear'][:]
                                                                                                           #Model year
                   = fh.variables['ULONG'][:]
                                                                                                           #Longitude
21
             lat
                   = fh.variables['ULAT'][:]
                                                                                                       #Latitude
             depth = fh.variables['z t'][depth min index:depth max index]
                                                                             #Denth (m)
             layer = fh.variables['dz'][depth_min_index:depth_max_index]
                                                                                    #Laver thickness (m)
             grid_x = fh.variables['DXU'][:]
                                                                                       #Zonal grid cell length (m)
             v vel = fh.variables['VVEL'][:, depth min index:depth max index. 0] #Meridional velocity (m/s)
26
27
             fh.close()
             return year, lon, lat, depth, layer, grid x, y yel
30
31
22
      #-----MAIN SCRIPT STARTS HERE------
33
34
35
      depth min
                     = 0
     depth max
                     = 1000
37
38
39
40
      files = glob.glob(directory+'Data/AMOC section 26N/CESM year *.nc')
      files.sort()
41
```

```
67
68
      for depth i in range(len(depth)):
69
              #Determine the total length of the section, based on non-masked elements
              layer_field[depth_i] = layer[depth_i]
70
71
              layer field[depth i] = ma.masked array(layer field[depth i], mask = v vel all[0, depth i].mask)
73
              #Determine where the layer needs to be adjusted, partial depth cells
74
              depth diff
                              = np.sum(layer field, axis = 0) - depth u
75
76
              if depth i == len(depth) - 1:
77
                      #Last layer, get the depth difference with respect to top and depth max boundary
78
                      depth diff
                                      = laver field[depth il - (depth max - depth top[depth il)
79
80
              #If the depth difference is negative (i.e. bottom is not reached), set to zero
              depth diff
                              = ma.masked where(depth diff < 0, depth diff)
81
82
              depth diff
                              = depth diff.filled(fill value = 0.0)
83
              #Subtract the difference of the current layer with the difference
94
85
              laver field[depth i] = laver field[depth i] - depth diff
96
```

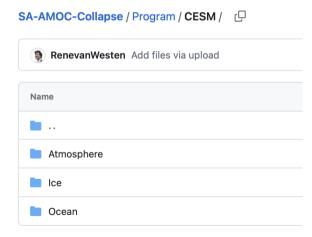
SA-AMOC-Collapse / Data / CESM / Data / AMOC_section_26N /



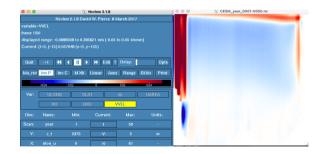


```
129
 130 \times def Kendall tau test(data, num surr, time data = False):
 131
                 """Conducts the Kendall-Fourier test (adapted from Boers 2021)"""
 132
 133
                 #Remove masked elements (if present)
 134
                mask index = np.where(data.mask == False)[0]
 135
                             = data[mask index]
                data
 136
 137
                if type(time_data) == type(False):
 138
                        #No time array is provided, use dummy variable
 139
                        trend, base = stats.linregress(np.arange(len(data)),data)[0], stats.linregress(np.arange(len(data)),data)[1]
 140
                else:
 141
                        #Time array is provided, use these to fit the trends
 142
                        time data
                                        time data[mask index]
 143
                        trend, base
                                        = stats.linregress(time_data,data)[0], stats.linregress(time_data,data)[1]
 144
 145
                 #Make time mean zero and create surrogate data
 146
                data 0
                            = data - np.mean(data)
 147
                data surr = Fourrier surrogates(data 0, num surr)
 148
 140
                 #Determine the linear regression of the surrogate time series
 150
                 stat surr = np.zeros(num surr)
 151
 152
                for surr i in range(num surr):
 153
                        #Determine the linear regression
 154
                        stat surr[surr i] = stats.linregress(np.arange(len(data)), data surr[surr i])[0]
 155
 156
                #Determine the significant level w.r.t. trend
157
                p = 1 - stats.percentileofscore(stat surr, trend) / 100.
 158
 159
                return p, trend, base
1/0
```

- Structure your scripts and data
 - (Sub)folders are great



- Structure your scripts and data
 - (Sub)folders are great
- Upload semi-raw model output
 - Helps to understand data processing

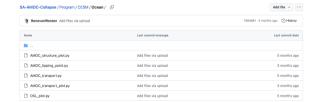


- Structure your scripts and data
 - (Sub)folders are great
- Upload semi-raw model output
 - Helps to understand data processing
- Remove personal comments

- Structure your scripts and data
 - (Sub)folders are great
- Upload semi-raw model output
 - Helps to understand data processing
- Remove personal comments
- Add comments!
 - Use names for iterable objects

```
for depth i in range(len(depth)):
              WDetermine the total length of the section, based on non-masked elements
              layer_field[depth_i] = layer[depth_i]
              layer field(depth il ... ma.masked array(layer field(depth il. mask = v vel all[0, depth il.mask)
73
              #Determine where the layer needs to be adjusted, partial depth cells
                             = np.sum(layer_field, axis = 0) - depth_u
              if depth i == len(depth) - 1:
                      Blast layer, get the denth difference with respect to top and denth may boundary
                                   | layer field[depth i] - (depth max - depth top[depth i])
              WIf the depth difference is negative (i.e. bottom is not reached), set to zero
81
                              = ma, masked where(depth diff < 0, depth diff)
              depth diff
                              = depth diff.filled(fill value = 8.8)
              #Subtract the difference of the current laver with the difference
              layer field(depth il = layer field(depth il - depth diff
```

- Structure your scripts and data
 - (Sub)folders are great
- Upload semi-raw model output
 - Helps to understand data processing
- Remove personal comments
- Add comments!
 - Use names for iterable objects
- Upload all data and plotting scripts
 - For large files, this can be a problem



- Structure your scripts and data
 - (Sub)folders are great
- Upload semi-raw model output
 - Helps to understand data processing
- Remove personal comments
- Add comments!
 - Use names for iterable objects
- Upload all data and plotting scripts
 - For large files, this can be a problem
- Run and check your scripts
 - One work day for each publication

