# Static energy consumption analysis for LLVM IR programs

**Neville Grech**, Kyriakos Georgiou, James Pallister, Steve Kerrison, Jeremy Morse and Kerstin Eder

University of Bristol

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#### Motivation

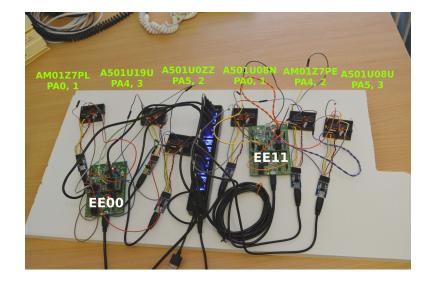
#### Software has final control of energy consumption:

- Instructions executed on processor causes circuit switching.
- ▶ Operation of software determines what clock domains can be gated.
- Amount of work performed by software determines how long the system draws power for.

#### Energy transparency enables decision making:

- Making energy information available to the developer allows for energy-based design decisions.
- Performing measurements requires dual-skill developers, instrumentation, and actual working hardware, presenting a burden to development.
- ▶ A solution then, is energy estimation from software.

# Measuring energy is time consuming and complex.



# Summary of our technique.

- Produce basic-block energy costs using processor energy model, and compiler infrastructure.
- Simplify program to make it ameanable to analysis.
- ► Extract cost relations (CRs), characterising the energy consumed by the program.
- Solve CRs and infer a closed form formula.

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#### Example, Levenshtein distance algorithm, i.e.:

- ▶ Initialize distance-table for string, length A.
- Initialize distance-table for string, length B.
- For each element of A, for each element of B, calculate insert/delete/modify distance.

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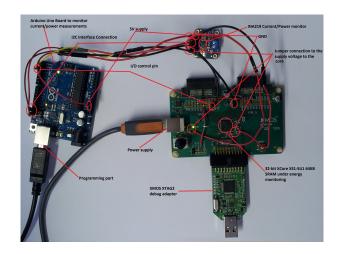
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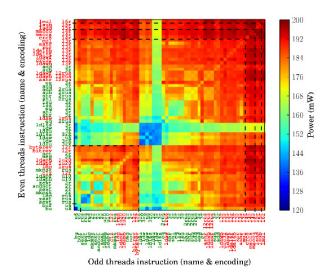
- ▶ Initialize distance-table for string, length A.
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- For each element of A, for each element of B, calculate insert/delete/modify distance.

$$(A(53B+16)+35B+31)$$
 nJ, (1)

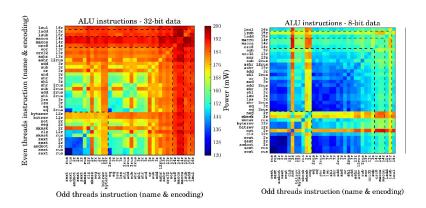
# Energy measuring, set up.



#### ISA Characterization



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# Understanding our processors

#### XMOS:

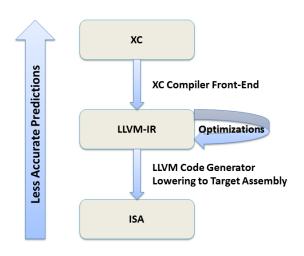
- Hardware multithreading microcontroller.
- ▶ No caches, branch prediction, or other timing unpredictable features.
- Designed for high frequency IO control.

#### ARM Cortex-M3:

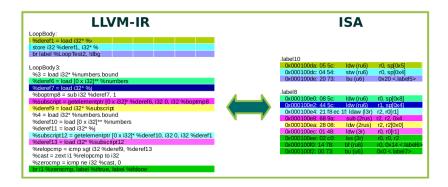
- Instructions grouped by characteristics (memory access, control flow, division, other).
- ▶ Average energy collected for each group of instructions.
- ► Energy assigned to LLVM-IR instructions.

This energy model is less accurate than the XCore model, but required less effort to produce.

# Mapping LLVM IR blocks to machine instructions



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# Resource Analysis Example

#### Original program

```
int fact(int i) {
  if (i<=0)<sup>a</sup>
    return 1<sup>b</sup>;
  return (i*<sup>d</sup> fact(i-1))<sup>c</sup>;
}
```

### Resource Analysis Example

#### Original program

#### **Extracted cost relations**

```
\begin{array}{lll} \textbf{int} & \texttt{fact(int i)} & \{ & & \\ \textbf{if (i} <= 0)^a & & & \\ & \textbf{return 1}^b; & & \\ & \textbf{return (i*}^d \, \texttt{fact(i)} = C_a + C_c(i) & & \\ & \textbf{if i} <= 0 \\ & \textbf{return (i*}^d \, \texttt{fact(i-1)})^c; & C_c(i) = C_d + C_{fact}(i-1) \\ \} \end{array}
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```

- Substitute C<sub>a</sub>, C<sub>b</sub>, C<sub>d</sub> with actual energy required to execute low level instructions.
- Solve relations using off the shelf solvers to obtain closed form solution.
- Result:  $C_{fact}(i) = 4563 + 7878i \ pJ$ .

### Linguistic Abstraction

Various language subsets of LLVM IR have been formalised. For analysis purposes, we abstract LLVM IR as follows:

$$\begin{array}{ll} \mathit{inst} = \mathsf{br} \ \mathit{p} \ \mathit{BB}_1 \ \mathit{BB}_2 & \mathsf{conditional} \ \mathsf{branch} \ \mathsf{instruction} \\ | \ \mathit{x} = \mathsf{op} \ \mathit{a}_1...\mathit{a}_n & \mathsf{generic} \ \mathsf{side} \ \mathsf{effect-free} \ \mathsf{operation} \\ | \ \mathit{x} = \phi \ \langle \mathit{BB}_1, \mathit{x}_1 \rangle ... \langle \mathit{BB}_n, \mathit{x}_n \rangle & \mathsf{phi} \ \mathsf{nodes} \\ | \ \mathit{x} = \mathsf{call} \ \mathit{f} \ \mathit{a}_1 \ ... \ \mathit{a}_n \\ | \ \mathit{x} = \mathsf{memload} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{load} \ \mathsf{operation} \\ | \ \mathsf{memstore} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{ret} \ \mathit{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{a} & \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{a} & \mathsf{dynamic} \ \mathsf{dynamic} \ \mathsf{memory} \ \mathsf{store} \ \mathsf{operation} \\ | \ \mathsf{a} & \mathsf{dynamic} \ \mathsf{dy$$

where metavariable names p,f,a,x are predicates, function names, generic arguments and variables respectively.

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Abstract semantics are standard, except:

- $\triangleright$  x = memload simply invalidates x i.e., x =?.
- memstore may set any area in memory.



Cost relations characterise the cost of executing a program or basic block, for example block *a*:

$$C_a(x,y) = S_a + C_b(x + n_1, y + m_1) + C_c(x + n_2, y + m_2) + ...$$
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Next: How do we infer cost relations from existing programs?

# Symbolic Evaluation

At the core of our resource analysis mechanism is a symbolic evaluation function *seval*.

- ► Given a block of code BB, and a variable x, seval(BB,x) symbolically executes a slice from this block to produce a result.
- Abstracts away the effect of dynamic memory reads and writes, i.e., memload and memstore
- Hence we can produce simple expressions, which can be handled by existing solvers.

# Symbolic Evaluation cont.

#### Symbolic evaluation is used:

- ▶ On branch predicates to infer side conditions for cost relations.
- ➤ To summarise the effect of executing a block on a variable (e.g. induction variable).

#### Example:

#### LoopIncrement:

```
%postinc = add i32 %i.0, 1
%exitcond = icmp eq i32 %postinc, %1
br i1 %exitcond, label %return, label %LoopBody
```

In this case seval(BB,%exitcond) is (%i.0+1) = %1, found by traversing the structure of the LLVM block backwards.

#### Cost Relations Arguments

To simplify the analysis, we only consider variables and arguments that affect the control flow, e.g.:

```
int accumulate(int n) {
   int res = n;
   while (n--) res+=n;
   return res;
}
```

- ▶ Only the value of n affects the control flow, not res. CRs will therefore be parametric with n.
- Computed using data flow analysis techniques.

### Analysing Nested Loop Structures

Certain classes of programs require further analysis/transformation.

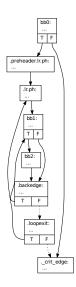
```
void bubbleSort(int numbers[], int array_size) {
  int i, j, temp;
  for (i = (array_size - 1); i >= 0; i--) {
    for (j = i; j > 0; j--) {
      if (numbers[j-1] > numbers[j]) {
        temp = numbers[j-1];
        numbers[j-1] = numbers[j];
        numbers[j] = temp;
```

Unfortunately, the high level loop structure is mangled by compiler optimisations.

# LLVM IR (clang -O3)

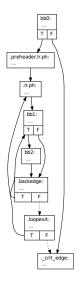
```
define void @bubbleSort(i32* nocapture %numbers, i32 %array size) {
hh0.
 %i.02 = add nsw i32 %arrav size. -1
 %1 = icmp sgt i32 %i.02.0
  br i1 %1, label %.preheader.lr.ph, label %._crit_edge
.preheader.lr.ph:
  %2 = sext i32 \%i.02 to i64
  br label %.lr.ph
.loopexit:
 %i.0 = add nsw i32 %i.03. -1
 %3 = icmp sgt i32 %i.0.0
 %indvars.iv.next = add i64 %indvars.iv. -1
  br i1 %3, label %.lr.ph, label %, crit edge
.lr.ph:
 %indvars.iv = phi i64 [ %2, %.preheader.lr.ph ], [ %indvars.iv.next, %.loopexit ]
 %i.03 = phi i32 [ %i.02, %.preheader.lr.ph ], [ %i.0, %.loopexit ]
  br label %bb1
bb1:
  %indvars.iv4 = phi i64 [ %indvars.iv, %.lr.ph ], [ %indvars.iv.next5, %.backedge ]
 %j.01 = phi i32 [ %i.03, %.lr.ph ], [ %5, %.backedge ]
 \%5 = add nsw i32 \%j.01, -1
 %6 = sext i32 %5 to i64
 %7 = getelementptr inbounds i32* %numbers, i64 %6
 \%8 = 10ad i32* \%7, align 4,
 %9 = getelementptr inbounds i32* %numbers, i64 %indvars.iv4
 %10 = load i32* %9, align 4,
 %11 = icmp sgt i32 %8, %10
  br i1 %11, label %bb2, label %.backedge
.backedge:
  %12 = icmp sgt i32 %5, 0
  %indvars.iv.next5 = add i64 %indvars.iv4, -1
  br i1 %12, label %bb1, label %.loopexit
bb2:
  store i32 %10, i32* %7, align 4, !tbaa !0
  store i32 %8, i32* %9, align 4, !tbaa !0
 br label %.backedge
. crit edge:
  ret void
```

### **Extracting Loop Structure**

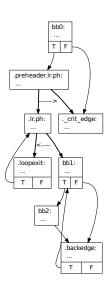


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# **Extracting Loop Structure**



- The compiler turns nested loops into CFG structures without cover points (left).
- However, these can be transformed in a lot of cases (right).
- Energy conservation semantics preserved for typical while or for loops compiled by clang or xcc.



#### Benchmarks.

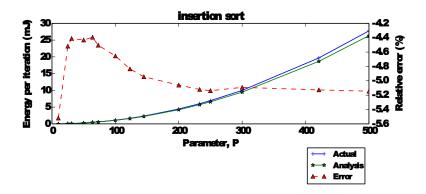
- ▶ Selection of benchmarks from existing suites .
  - Levenshtein distance, Matrix multiply (BEEBS).
  - Multiply-accumulate, JPEG DCT (WCET).
  - ▶ Additionally, insertion sort and base64 encoding algorithms.
- Each benchmark analyzed by our technique to produce a cost formula.
- ▶ Evaluated over a range of different input sizes to determine accuracy.

# Formulae produced from benchmarks.

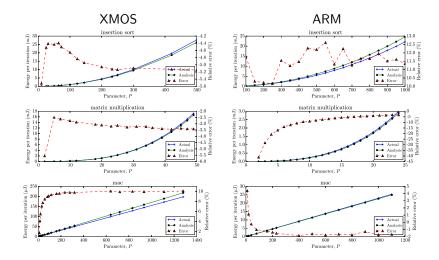
	ARM (nJ)	XMOS (nJ)
base64	$158 + 94 \cdot \left\lfloor \frac{P-1}{3} \right\rfloor$	$1270 + 734 \cdot \left\lfloor \frac{P-1}{3} \right\rfloor$
mac	23P + 14	133P + 192
levenshtein	47AB + 14A + 31B + 44	$559AB + 78A + 571 + \max(225B, 180B + 213)$
insertion sort	$25P^2 + 11P + 7.1$	$105P^2 + 30P + 75$
matrix multiply	$20P^3 + 13P^2 + 97P + 84$	$144P^3 + 200P^2 + 77P + 332$
jpegdct	54 mJ <sup>‡</sup>	463 mJ <sup>‡</sup>

Table: Formulae and error values for each benchmark.

# Example result.



#### Other results.



#### Discussion.

- Our energy estimations are within roughly 10% of measured energy for XMOS.
- ▶ Worse estimation for ARM, where we do not have a detailed energy model, but within 30% (most 15%).
- ► Generic technique (LLVM), requires either a detailed energy model, or as we have shown an approximation is sufficient too.
- ▶ The analysis itself requires little computational resources.
- ▶ Can be integrated into a development workflow.