

# GPIO BFM – Quick Reference

**NOTE: As of UVVM v3.x, all shared variables have been made protected. This means that any access to shared variables must be done using get- and set-methods. This documentation has not yet been updated with the methods for accessing these variables, but will be very soon.**

**BFM**



**gpio\_set (data\_value, msg, data\_port, [scope, [msg\_id\_panel, [config]]])**

**Example:** gpio\_set(C\_BAUD\_RATE, "Setting Baudrate to 9600", data\_port, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_set(C\_BAUD\_RATE, "Setting Baudrate to 9600", data\_port);

**gpio\_get (data\_value, msg, data\_port, [scope, [msg\_id\_panel, [config]]])**

**Example:** gpio\_get(v\_baudrate, "Read baudrate", data\_port, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_get(v\_baudrate, "Read baudrate", data\_port);

**gpio\_check (data\_exp, msg, data\_port, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

**Example:** gpio\_check(x"3B", "Check data from UART RX", data\_port, ERROR, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_check(x"3B", "Check data from UART RX", data\_port);

**gpio\_check\_stable (data\_exp, stable\_req, msg, data\_port, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

**Example:** gpio\_check\_stable(x"3B", 100 us, "Check data from UART RX has been stable for 100 us", data\_port, ERROR, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_check\_stable(x"3B", 100 us, "Check data from UART RX has been stable for 100 us", data\_port);

**gpio\_expect (data\_exp, msg, data\_port, [timeout, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

**Example:** gpio\_expect(x"0D", "Read UART RX until CR is found", data\_port, 10 ms, ERROR, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_expect(x"0D", "Read UART RX until CR is found", data\_port);

**gpio\_expect\_stable (data\_exp, stable\_req, stable\_req\_from, msg, data\_port, [timeout, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

**Example:** gpio\_expect\_stable(x"0D", 100 us, FROM\_NOW, "Read UART RX until CR is found and check it remains stable for 100 us", data\_port, 10 ms, ERROR, C\_SCOPE, shared\_msg\_id\_panel, gpio\_bfm\_config);  
**Example:** gpio\_expect\_stable(x"0D", 100 us, FROM\_LAST\_EVENT, "Read UART RX and check it has been stable for 100 us since the last event", data\_port);

*gpio\_bfm\_pkg.vhd*



**UVVM™**

VHDL 2008 only

#### BFM Configuration record 't\_gpio\_bfm\_config'

Record element	Type	C_GPIO_BFM_CONFIG_DEFAULT
clock_period	time	-1 ns
match_strictness	t_match_strictness	MATCH_EXACT
id_for_bfm	t_msg_id	ID_BFM
id_for_bfm_wait	t_msg_id	ID_BFM_WAIT
timeout	time	-1 ns

#### BFM non-signal parameters

Name	Type	Example(s)	Description
data_value	std_logic_vector	x"D3"	The data value to be written to the register.
data_exp	std_logic_vector	x"0D" or C_UART_CR	The data value expected when reading the register. A mismatch results in an alert 'alert_level'.
stable_req	time	1 ms	The time that the expected data value should remain stable in the register.
stable_req_from	t_from_point_in_time	FROM NOW or FROM_LAST_EVENT	The point in time where stable_req starts.
timeout	time	10 ms or C_CLK_PERIOD	The maximum time to pass before the expected data must be found. A timeout result in an alert 'alert_level'.
alert_level	string	ERROR or TB_WARNING	Set the severity for the alert that may be asserted by the method.
msg	string	"Set baudrate to 1MHz"	A custom message to be appended in the log/alert.
scope	string	"GPIO_BFM" or C_SCOPE	A string describing the scope from which the log/alert originates. In a simple single sequencer typically "GPIO_BFM". In a verification component, typically "GPIO_VVC".
msg_id_panel	t_msg_id_panel	shared_msg_id_panel	Optional msg_id_panel, controlling verbosity within a specified scope. Defaults to a common ID panel defined in the adaptations package.
config	t_gpio_bfm_config	C_GPIO_BFM_CONFIG_DEFAULT	Configuration of BFM behaviour and restrictions. See section 0 for details.

# BFM details

## 1 BFM procedure details and examples

Procedure	Description
<b>gpio_set()</b>	<p><b>gpio_set (data_value, msg, data_port, [scope, [msg_id_panel, [config]]])</b></p> <p>The gpio_set() procedure will write the given data in 'data_value' to the DUT. When called, the gpio_set() procedure will write to the DUT register immediately, except bits set to "don't care" ('-').</p> <ul style="list-style-type: none"> <li>- The default value of scope is C_SCOPE ("GPIO BFM")</li> <li>- The default value of msg_id_panel is shared_msg_id_panel, defined in UVVM_Util.</li> <li>- The default value of config is C_GPIO_BFM_CONFIG_DEFAULT.</li> <li>- A log message is written if ID_BFM is enabled for the specified message ID panel.</li> <li>- Data_value is normalised to data_port direction.</li> </ul> <p>Example:  <pre>gpio_set(C_BAUDRATE_9600, "Set baudrate to 9600", data_port, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);</pre> Suggested usage (requires local overload, see section 4):  <pre>gpio_set(C_BAUDRATE_9600, "Set baudrate to 9600", data_port);</pre></p>
<b>gpio_get()</b>	<p><b>gpio_get (data_value, msg, data_port, [scope, [msg_id_panel, [config]]])</b></p> <p>The gpio_get() procedure reads the DUT register and returns it in the 'data_value' parameter.</p> <ul style="list-style-type: none"> <li>- The default value of scope is C_SCOPE ("GPIO BFM")</li> <li>- The default value of msg_id_panel is shared_msg_id_panel, defined in UVVM_Util.</li> <li>- The default value of config is C_GPIO_BFM_CONFIG_DEFAULT.</li> <li>- A log message is written if ID_BFM is enabled for the specified message ID panel.</li> </ul> <p>Example:  <pre>gpio_get(v_baudrate, "Read baudrate", data_port, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);</pre> Suggested usage (requires local overload, see section 4):  <pre>gpio_get(v_baudrate, "Read baudrate", data_port);</pre></p>
<b>gpio_check()</b>	<p><b>gpio_check (data_exp, msg, data_port, [alert_level, [scope, [msg_id_panel, [config]]]])</b></p> <p>The gpio_check() procedure reads the DUT register and compares the data with the expected data in 'data_exp'. If the DUT data does not match 'data_exp', an alert with severity 'alert_level' will be triggered. If the DUT data matches 'data_exp', a message with ID config.id_for_bfm will be logged. Bits set to "don't care" ('-') will not be checked.</p> <ul style="list-style-type: none"> <li>- The default value of alert_level is ERROR.</li> <li>- The default value of scope is C_SCOPE ("GPIO BFM")</li> <li>- The default value of msg_id_panel is shared_msg_id_panel, defined in UVVM_Util.</li> <li>- The default value of config is C_GPIO_BFM_CONFIG_DEFAULT.</li> </ul>

- A log message is written if ID\_BFM is enabled for the specified message ID panel.
- Data\_exp is normalised to data\_port direction.

Example:

```
gpio_check(x"3B", "Check data from UART RX", data_port, ERROR, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);
```

Suggested usage (requires local overload, see section 4):

```
gpio_check(x"3B", "Check data from UART RX", data_port);
```

## gpio\_check\_stable()

**gpio\_check\_stable (data\_exp, stable\_req, msg, data\_port, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

The gpio\_check\_stable() procedure reads the DUT register and compares the data with the expected data in 'data\_exp', it also checks that the DUT register has been stable for the 'stable\_req' time (see section 1.1). If the DUT data does not match 'data\_exp' or is not stable, an alert with severity 'alert\_level' will be triggered. If the DUT data matches 'data\_exp' and is stable, a message with ID config.id\_for\_bfm will be logged. Note that it is not possible to use the "don't care" ('-') operator in 'data\_exp' to ignore changes in a subset of a std\_logic\_vector.

- The default value of alert\_level is ERROR.
- The default value of scope is C\_SCOPE ("GPIO BFM")
- The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util.
- The default value of config is C\_GPIO\_BFM\_CONFIG\_DEFAULT.
- A log message is written if ID\_BFM is enabled for the specified message ID panel.
- Data\_exp is normalised to data\_port direction.

Example:

```
gpio_check_stable(x"3B", 100 us, "Check data from UART RX has been stable for 100 us", data_port, ERROR, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);
```

Suggested usage (requires local overload, see section 4):

```
gpio_check_stable(x"3B", 100 us, "Check data from UART RX has been stable for 100 us", data_port);
```

## gpio\_expect()

**gpio\_expect (data\_exp, msg, data\_port, [timeout, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

The gpio\_expect() procedure reads a register until the expected data, 'data\_exp', is matched or until a timeout value is reached.

If the received data does not match 'data\_exp' within the timeout delay, an alert with severity 'alert\_level' will be triggered. If the DUT data matches 'data\_exp', a message with ID config.id\_for\_bfm will be logged.

- The default timeout is -1 ns.
- The default value of alert\_level is ERROR.
- The default value of scope is C\_SCOPE ("GPIO BFM")
- The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util.
- The default value of config is C\_GPIO\_BFM\_CONFIG\_DEFAULT.
- A log message is written if ID\_BFM ID is enabled for the specified message ID panel.
- Data\_exp is normalised to data\_port direction.

Example:

```
gpio_expect(x"0B", "Read UART RX until CR is found", data_port, 10 ms, ERROR, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);
```

Suggested usage (requires local overload, see section 4):

```
gpio_expect(x"0B", "Read UART RX until CR is found", data_port, 10 ms);
```

## gpio\_expect\_stable()

**gpio\_expect\_stable (data\_exp, stable\_req, stable\_req\_from, msg, data\_port, [timeout, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**

The gpio\_expect\_stable() procedure reads a register until the expected data, 'data\_exp', is matched or until a timeout value is reached. It also checks that the register remains stable for the 'stable\_req' time, sampled after the 'stable\_req\_from' point in time (see section 1.1).

If the received data does not match 'data\_exp' within the timeout delay or it doesn't remain stable, an alert with severity 'alert\_level' will be triggered. If the DUT data matches 'data\_exp' and is stable, a message with ID config.id\_for\_bfm will be logged.

- The default timeout is -1 ns.
- The default value of alert\_level is ERROR.
- The default value of scope is C\_SCOPE ("GPIO BFM")
- The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util.
- The default value of config is C\_GPIO\_BFM\_CONFIG\_DEFAULT.
- A log message is written if ID\_BFM ID is enabled for the specified message ID panel.
- Data\_exp is normalised to data\_port direction.

Example:

```
gpio_expect_stable(x"0B", 100 us, FROM_NOW, "Read UART RX until CR is found and check it remains stable for 100 us",
    data_port, 10 ms, ERROR, C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);
```

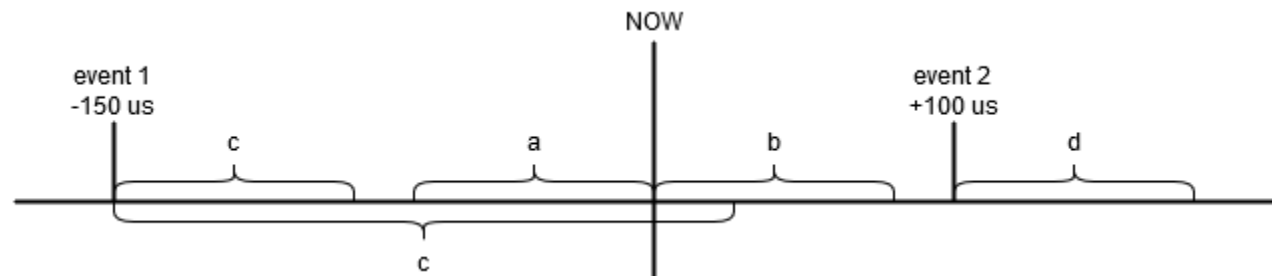
Suggested usage (requires local overload, see section 4):

```
gpio_expect_stable(x"0B", 100 us, FROM_LAST_EVENT, "Read UART RX and check it has been stable for 100 us since the last
    event", data_port);
```

## 1.1 Checking stability

The procedures gpio\_check\_stable and gpio\_expect\_stable can check if the DUT data port is stable for a certain time. There are different scenarios where we could check stability:

- a. To check that data has been stable for a certain time before now, use gpio\_check\_stable().
- b. To check that data, which is already same as expected, remains stable for a certain time from now, use gpio\_expect\_stable(FROM\_NOW).
- c. To check that data, which is already same as expected, remains stable for a certain time from the last change, use gpio\_expect\_stable(FROM\_LAST\_EVENT).
- d. To check that data remains stable after it is equal than expected, use gpio\_expect\_stable(FROM\_NOW). Note that in this case the 'stable\_req\_from' parameter does not have any influence since the event has not occurred.



## 2 BFM Configuration record

Type name: t\_gpio\_bfm\_config

Record element	Type	C_GPIO_BFM_CONFIG_DEFAULT	Description
clock_period	time	-1 ns	Specifies the clock period
match_strictness	t_match_strictness	MATCH_EXACT	Matching strictness for std_logic values in check procedures. MATCH_EXACT requires both values to be the same. Note that the expected value can contain the don't care operator '-' in the gpio_check() procedure. However, the don't care operator cannot be used in the gpio_check_stable() procedure. MATCH_STD allows comparisons between 'H' and '1', 'L' and '0' and '-' in both values.
id_for_bfm	t_msg_id	ID_BFM	The message ID used as a general message ID in the GPIO BFM
id_for_bfm_wait	t_msg_id	ID_BFM_WAIT	The message ID used for logging waits in the GPIO BFM
timeout	time	-1 ns	Timeout value for the expect procedures. This is only used if no timeout parameter is given in the procedures.

### 3 Compilation

The GPIO BFM may only be compiled with VHDL 2008. It is dependent on the UVVM Utility Library (UVVM-Util), which is only compatible with VHDL 2008. See the separate UVVM-Util documentation for more info. After UVVM-Util has been compiled, the gpio\_bfm\_pkg.vhd BFM can be compiled into any desired library. See UVVM Essential Mechanisms located in uvvm\_vvc\_framework/doc for information about compile scripts.

#### 3.1 Simulator compatibility and setup

See README.md for a list of supported simulators.  
For required simulator setup see UVVM-Util Quick reference.

### 4 Local BFM overloads

A good approach for better readability and maintainability is to make simple, local overloads for the BFM procedures in the TB process. This allows calling the BFM procedures with the key parameters only e.g.

```
gpio_expect(x"F5", "Read UART RX until 0xF5 is found", data_port, 2 ms);
```

rather than

```
gpio_expect(x"F5", "Read UART RX until 0xF5 is found", data_port, 2 ms, ERROR,  
C_SCOPE, shared_msg_id_panel, C_GPIO_BFM_CONFIG_DEFAULT);
```

By defining the local overload as e.g.:

```
procedure gpio_check(  
  constant data_exp      : in std_logic_vector;  
  constant msg           : in string;  
  constant data_port     : in std_logic_vector;  
  constant timeout       : in time) is  
begin  
  gpio_check(data_exp,      -- keep as is  
             msg,          -- keep as is  
             data_port,    -- keep as is  
             timeout,      -- keep as is  
             error,        -- Just use the default  
             C_SCOPE,      -- Just use the default  
             shared_msg_id_panel, -- Use global, shared msg id panel  
             C_GPIO_CONFIG_LOCAL); -- Use locally defined configuration or C_GPIO_BFM_CONFIG_DEFAULT  
  
end;
```

Using a local overload like this also allows the following – if wanted:

- Set up defaults for constants. May be different for two overloads of the same BFM
- Apply dedicated message ID panel to allow dedicated verbosity control

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