

Revision: 1.0.0 Date: 11/30/2018

Command Handbook

For the HuskySat-1 Mission



Table of Contents

| Table of Contents | 2 |
|-----------------------------|----------|
| Commands | 3 |
| CMD BATT BAL ENABLE | 3 |
| CMD_BATT_RST | 3 |
| CMD_IGNORE_FSW | 3 |
| CMD_PPT_SINGLE_FIRE | 3 |
| CMD_PPT_TIME_UPD | 4 |
| CMD_ROLLCALL | 4 |
| GCMD_AUTOSEQ_ADD_1 | 4 |
| GCMD_AUTOSEQ_ADD_2 | 4 |
| GCMD_AUTOSEQ_ENABLE | 5 |
| GCMD_AUTOSEQ_GET_INDICES | 5 |
| GCMD_AUTOSEQ_GET_MET | 5 |
| GCMD_AUTOSEQ_REMOVE_CAN_ID | 5 |
| GCMD_AUTOSEQ_RM_AT_INDEX | 5 |
| GCMD_BATT_SET_BAL_AUTO | 6 |
| GCMD_BATT_SET_HEATER_CHECK | 6 |
| GCMD_BDOT_CONTROL | 6 |
| GCMD_BDOT_MAG_CONTROL | 6 |
| GCMD_BDOT_MAX_TUMBLE | 7 |
| GCMD_BDOT_POLE_OVERRIDE | 7 |
| GCMD_BDOT_SPAM | 8 |
| GCMD_COM2_RUN | 8 |
| GCMD_DIST_AUTOSHUTOFF | 9 |
| GCMD_DIST_RESET_MISSION | 10 |
| GCMD_DIST_SELF_RESTART | 10 |
| GCMD_DIST_SET_PD_OVC_BDOT | 10 |
| GCMD_DIST_SET_PD_OVC_COM2 | 10 |
| GCMD_DIST_SET_PD_OVC_EPS | 10 |
| GCMD_DIST_SET_PD_OVC_ESTIM | 10 |
| GCMD_DIST_SET_PD_OVC_PPT | 10 |
| GCMD_DIST_SET_PD_OVC_RAHS | 11 |
| GCMD_DIST_SET_PD_OVC_WHEELS | 11 |
| GCMD_DIST_SET_PD_STATE | 11 |
| GCMD_EPS_BATT_FULLDEF | 12 |
| GCMD_GEN_SET_PT_STATE | 13 |
| GCMD_MTQ_PMS | 13 |
| GCMD_MTQ_POP | 13 |
| GCMD_MTQ_PWM_TIME | 14 |
| GCMD_PPT_HALT | 14 |
| GCMD_PPT_MULTIPLE_FIRE | 14 |
| GCMD_RESET_MINMAX | 15 |
| GCMD_SP_SET_THRESH | 15 |
| GRND_EPOCH | 15 15 |
| TLE_1 TLE 2 | 15 |
| | 16 |
| TLE 3 | 16 16 |
| TLE 4 | 16 |
| TLE 5 | 16 |



Commands

CMD_BATT_BAL_ENABLE

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------------|-------------------------------|-------|-----|-----|---------|------------|----------|-----------|-------|
| CMD_BATT_BAL_ENABLE_ENABLE | enable? (or disable if false) | | 0 | 1 | 0 | 224 | 1 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |

CMD_BATT_RST

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------|--|-------|-----|-----|---------|------------|----------|-----------|-------|
| CMD_BATT_RST_CONFIRM | Do we really want to reset all stastics? | | 0 | 1 | 0 | 224 | 1 | UINT | |
| State FALSE | State | Value | | | | | | | |
| | 0 | | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |

CMD_IGNORE_FSW

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------|-----------------------------------|-------|-----|-----|---------|------------|----------|-----------|-------|
| CMD_IGNORE_FSW_IGNORE | ignore the bdot commands from fsw | | 0 | 1 | 0 | 224 | 1 | UINT | |
| F/ | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |

CMD_PPT_SINGLE_FIRE

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|--------------------------------|------------------------------|-------|-----|-----|---------|---------------|-------------|--------------|-------|
| CMD_PPT_SINGLE_FIRE_WITH_PULSE | E Do we fire or just charge? | | 0 | 1 | 0 | 224 | 1 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |



UINT

CMD_PPT_SINGLE_FIRE_OVERRIDE

| Do we fire or just char | ge? |
|-------------------------|-----|
|-------------------------|-----|

State

FALSE TRUE

| Value | |
|-------|--|
| 0 | |
| | |

0

1

0

CMD_PPT_SINGLE_FIRE_OVERRIDE_SMT

Whether the Schmidt Trigger is checked

| State | Value |
|-------|-------|
| FALSE | 0 |
| TRUE | 1 |

1

226 UINT

225

1

CMD_PPT_TIME_UPD

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------------|--------------------------------|-----|-------|---------|------------|----------|-----------|--------|
| CMD_PPT_TIME_UPD_CHARGE | PPT Main Capacitor Charge Time | 0 | 65535 | 0 | 224 | 16 | UINT | 2^-15s |
| CMD_PPT_TIME_UPD_IGN_DELAY | PPT Main Igniter Delay | 0 | 65535 | 0 | 240 | 16 | UINT | 2^-15s |
| CMD_PPT_TIME_UPD_IGN_CHARGE | PPT Igniter Charge Time | 0 | 65535 | 0 | 256 | 16 | UINT | 2^-15s |
| CMD_PPT_TIME_UPD_COOLDOWN | PPT Cooldown Time | 0 | 65535 | 0 | 272 | 16 | UINT | 2^-15s |

CMD_ROLLCALL

| Item Name | Description | Min Max | | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------|--------------------------------|---------|---------------|---------|------------|----------|-----------|--------|
| CMD_ROLLCALL_MSP | | 0 | 255 | 0 | 224 | 8 | UINT | |
| CMD_ROLLCALL_MET | Mission Elapsed Time | 0 | 1099511627775 | 0 | 232 | 40 | UINT | 2^-8 s |
| CMD_ROLLCALL_TYPE | Rollcall Type (Unused for now) | 0 | 255 | 0 | 272 | 8 | UINT | |

GCMD_AUTOSEQ_ADD_1

propertires of autosequencer entry

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------------|------------------------------------|-----|------------|---------|---------------|-------------|--------------|------------|
| GCMD_AUTOSEQ_ADD_1_CAN_ID | the CAN Id of the message to add | 0 | 536870911 | 0 | 224 | 29 | UINT | |
| GCMD_AUTOSEQ_ADD_1_MET | the MET of the entry to add | 0 | 4294967295 | 0 | 253 | 32 | UINT | 2^- 15s |
| GCMD_AUTOSEQ_ADD_1_SENDFLG | whether the CAN packet should send | 0 | 1 | 0 | 285 | 1 | UINT | |

GCMD_AUTOSEQ_ADD_2



Rit

Rit

data of CAN packet to be added to the autosequencer

| Item Name | Description | Min | Max | Default | Offset | Size | Туре | Units |
|-------------------------|---|-----|----------------------|---------|--------|------|------|-------|
| GCMD_AUTOSEQ_ADD_2_DATA | the data of the CAN packet to be added to the autosequencer | 0 | 18446744073709600768 | 0 | 224 | 64 | UINT | |

GCMD_AUTOSEQ_ENABLE

| Descript | cion | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------|---------------|-------------------|-------------------|------------------------------|------------------------------|-----------------------|-----------------------|-----------------------|
| | | 0 | 255 | 0 | 224 | 8 | UINT | |
| State | Value | | | | | | | |
| FALSE | 0 | | | | | | | |
| TRUE | 1 | | | | | | | |
| NULL | 2 | | | | | | | |
| | | | | | | | | |
| | FALSE TRUE | FALSE 0 TRUE 1 | FALSE 0 TRUE 1 | State Value FALSE 0 TRUE 1 | State Value FALSE 0 TRUE 1 | StateValueFALSE0TRUE1 | StateValueFALSE0TRUE1 | StateValueFALSE0TRUE1 |

GCMD_AUTOSEQ_GET_INDICES

get indices of the specified packet in the autosequencer

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------------|-------------|-----|-----------|---------|------------|----------|-----------|-------|
| GCMD_AUTOSEQ_GET_INDICES_ID | the CAN Id | 0 | 536870911 | 0 | 224 | 29 | UINT | |

GCMD_AUTOSEQ_GET_MET

get MET of the item at the specified index of the autosequencer

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------------|-------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_AUTOSEQ_GET_MET_INDEX | the index | 0 | 255 | 0 | 224 | 8 | UINT | |

GCMD_AUTOSEQ_REMOVE_CAN_ID

remove all occurrence of the specified CAN Id in the autosequencer

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------------|---|-----|-----------|---------|---------------|-------------|--------------|-------|
| GCMD_AUTOSEQ_REMOVE_CAN_ID_ID | remove all occurrences of the specified CAN Id in the autosequencer | 0 | 536870911 | 0 | 224 | 29 | UINT | |

GCMD_AUTOSEQ_RM_AT_INDEX

remove the autosequencer entry at the specified index

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|--------------------------------|-------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_AUTOSEQ_RM_AT_INDEX_INDEX | the index | 0 | 255 | 0 | 224 | 8 | UINT | |



GCMD_BATT_SET_BAL_AUTO

Sets the state of battery balancer automation

| Item Name | Description | | Min | Max | Default | Offset | Size | Type | Units |
|------------------------------|---|---|-----|-----|---------|--------|------|------|-------|
| GCMD_BATT_SET_BAL_AUTO_STATE | What state the battery balancer automation should be set to | | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State Value | | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |

GCMD_BATT_SET_HEATER_CHECK

enables/disables battery heater automation

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------------------|--------------------------------|---|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_BATT_SET_HEATER_CHECK_STATE | the state of heater automation | | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State Value | | | | | | | | |
| | FALSE | | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |

GCMD_BDOT_CONTROL

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------------------|--|-------|-----|-----|---------|---------------|-------------|--------------|-------|
| GCMD_BDOT_CONTROL_MODE | Chooses mode that bdot is in: 0 = NORMAL_MODE , 1 = SLEEP_MODE | | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State | Value | | | | | | | |
| | NORMAL_MODE | 0 | | | | | | | |
| | SLEEP_MODE | 1 | | | | | | | |
| | SPAM_MAG_SELF_TEST | 2 | | | | | | | |
| | SPAM | 3 | | | | | | | |
| | | | | | | | | | |

GCMD_BDOT_MAG_CONTROL

| Item Name | Description | Min | Max | Default | Offset | | | Units |
|----------------------------|---|-----|-----|---------|--------|---|------|-------|
| GCMD_BDOT_MAG_CONTROL_MODE | Choose the best fit magnetometer from ground. 0 | 0 | 3 | 0 | 224 | 2 | UINT | |



= Auto, 1 = BDOT, 2 = SP1, 3 = SP2

| State | Value |
|-----------|-------|
| AUTO_MODE | 0 |
| BDOT_MODE | 1 |
| SP1_MODE | 2 |
| SP2_MODE | 3 |

GCMD_BDOT_MAX_TUMBLE

| Item Name | Description | Min | Max | Default | Offset | | Type | Units |
|---------------------------|--|-----|-------|---------|--------|----|------|---------|
| GCMD_BDOT_MAX_TUMBLE_TIME | Chooses the maximum time bdot is tumbling continuously. If bdot tumbles for longer than this time, will automatically go into sleep mode. Units: Minutes | 0 | 65535 | 0 | 224 | 16 | UINT | minutes |

GCMD_BDOT_POLE_OVERRIDE

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|--------------------------------|--|---------------------------------|-----|-----|---------|---------------|-------------|--------------|-------|
| GCMD_BDOT_POLE_OVERRIDE_GAIN_X | Percentage dipole gain on x axis | | 0 | 255 | 0 | 224 | 8 | UINT | pct |
| GCMD_BDOT_POLE_OVERRIDE_GAIN_Y | Percentage dipole gain | ercentage dipole gain on y axis | | 255 | 0 | 232 | 8 | UINT | pct |
| GCMD_BDOT_POLE_OVERRIDE_GAIN_Z | Percentage dipole gain | on z axis | 0 | 255 | 0 | 240 | 8 | UINT | pct |
| GCMD_BDOT_POLE_OVERRIDE_X | Flips the dipole signs on sending command to m | | 0 | 2 | 0 | 248 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |

GCMD_BDOT_POLE_OVERRIDE_Y

Flips the dipole signs on bdot y axis before sending command to mtq

| State | Value |
|-------|-------|
| FALSE | 0 |
| TRUE | 1 |
| NULL | 2 |

2 0 250 2 UINT

GCMD_BDOT_POLE_OVERRIDE_Z

Flips the dipole signs on bdot \boldsymbol{z} axis before sending command to \boldsymbol{mtq}

| State | Value |
|-------|-------|
|-------|-------|

0 2 0 252 2 UINT



FALSE 0
TRUE 1
NULL 2

GCMD_BDOT_SPAM

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------------|---|------------------------|------|-------|---------|---------------|-------------|--------------|---------|
| GCMD_BDOT_SPAM_TIME_ON | Chooses the amount of SPAM | of minutes in between | 0 | 65535 | 0 | 224 | 16 | UINT | minutes |
| GCMD_BDOT_SPAM_TIME_OFF | Chooses the amount o | of time SPAM should be | 0 | 65535 | 0 | 240 | 16 | UINT | minutes |
| GCMD_BDOT_SPAM_MAGNITUDE_X | What magnitude the magnetorquer should spam on x axis | | -100 | 100 | 0 | 256 | 8 | INT | |
| GCMD_BDOT_SPAM_MAGNITUDE_Y | What magnitude the magnetorquer should spam on y axis | | -100 | 100 | 0 | 264 | 8 | INT | |
| GCMD_BDOT_SPAM_MAGNITUDE_Z | What magnitude the n spam on z axis | nagnetorquer should | -100 | 100 | 0 | 272 | 8 | INT | |
| GCMD_BDOT_SPAM_CONTROL | Turn spam on or off | | 0 | 2 | 0 | 280 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |

2

NULL

GCMD_COM2_RUN

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------------|--------------------------------|--------------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_COM2_RUN_FILENO | Which file to run | | 0 | 255 | 0 | 224 | 8 | UINT | |
| GCMD_COM2_RUN_JUMP | Do you want to jump the queue? | | 0 | 1 | 0 | 232 | 1 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |
| GCMD_COM2_RUN_CLEAR | Do you want to clear | the queue and run? | 0 | 1 | 0 | 233 | 1 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |



GCMD_DIST_AUTOSHUTOFF

Set the status of dist autoshutoff for each power domain

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------------|---|--------------------------------|-----|-----|---------|---------------|-------------|--------------|-------|
| GCMD_DIST_AUTOSHUTOFF_COM2 | Whether autosh domain | nutoff is enabled on the power | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| GCMD_DIST_AUTOSHUTOFF_RAHS | Whether autosh domain | nutoff is enabled on the power | 0 | 3 | 0 | 226 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| GCMD_DIST_AUTOSHUTOFF_BDOT | SHUTOFF_BDOT Whether autoshutoff is enabled on the pow domain | | 0 | 3 | 0 | 228 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| GCMD_DIST_AUTOSHUTOFF_ESTIM | Whether autosh domain | nutoff is enabled on the power | 0 | 3 | 0 | 230 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| GCMD_DIST_AUTOSHUTOFF_EPS | Whether autosh domain | nutoff is enabled on the power | 0 | 3 | 0 | 232 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| GCMD_DIST_AUTOSHUTOFF_PPT | Whather autoch | nutoff is enabled on the power | 0 | 3 | 0 | 234 | 2 | UINT | |



domain

| State | Value |
|-------|-------|
| FALSE | 0 |
| TRUE | 1 |
| NULL | 2 |

GCMD_DIST_RESET_MISSION

Resets MET and autosequencer, also sets the autosequencer to be reinitialized on next powerup

GCMD_DIST_SELF_RESTART

Causes dist to self-restart

GCMD_DIST_SET_PD_OVC_BDOT

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------------|-------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_BDOT_OVC | Set PD overcurrent BDOT | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_OVC_COM2

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------------|-------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_COM2_OVC | set PD Overcurrent Com2 | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_OVC_EPS

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------------------------|------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_EPS_OVC | Set PD Overcurrent EPS | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_OVC_ESTIM

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|--------------------------------|--------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_ESTIM_OVC | Set PD overcurrent ESTIM | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_OVC_PPT

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------------------------|------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_PPT_OVC | Set PD overcurrent PPT | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |
| | | | | | | | | |



GCMD_DIST_SET_PD_OVC_RAHS

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------------|-------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_RAHS_OVC | Set PD overcurrent RAHS | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_OVC_WHEELS

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|---------------------------------|--------------------------|-----|------|---------|------------|----------|-----------|-------|
| GCMD_DIST_SET_PD_OVC_WHEELS_OVC | Set PD Overcurrent Weels | 0.0 | 15.0 | 0.0 | 224 | 32 | FLOAT | Α |

GCMD_DIST_SET_PD_STATE

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------------|---|--------------------------|-----|-----|---------|---------------|-------------|--------------|-------|
| GCMD_DIST_SET_PD_STATE_COM1 | Enables or disables power domain | the power switch to com1 | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL 2 | | | | | | | | |
| | | | | | | | | | |
| GCMD_DIST_SET_PD_STATE_COM2 | GCMD_DIST_SET_PD_STATE_COM2 Enables or disables the power switch to com2 power domain | | 0 | 3 | 0 | 226 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |
| GCMD_DIST_SET_PD_STATE_RAHS | Enables or disables power domain | the power switch to rahs | 0 | 3 | 0 | 228 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |
| GCMD_DIST_SET_PD_STATE_BDOT | Enables or disables power domain | the power switch to BDOT | 0 | 3 | 0 | 230 | 2 | UINT | |
| | | | _ | | | | | | |

Value

0

1

State

FALSE

TRUE



| ısky ^{v. v.} tellite Lab | | | | | | | | |
|--------------------------------------|--|--|---|---|---|-----|---|--------|
| | NULL | 2 | | | | | | |
| | | | | | | | | |
| GCMD_DIST_SET_PD_STATE_ESTIM | Enables or disables the power switch to the estimator power domain | | | 3 | 0 | 232 | 2 | UINT |
| | State | Value | | | | | | |
| | FALSE | 0 | | | | | | |
| | TRUE | 1 | | | | | | |
| | NULL | 2 | | | | | | |
| COMP. DICT. CET. DD. CTATE, MULEILO | Fundan ou disable | | 0 | 2 | 0 | 224 | 2 | LITALT |
| GCMD_DIST_SET_PD_STATE_WHEELS | | s the power switch to the empty power domain) | 0 | 3 | 0 | 234 | 2 | UINT |
| | State | Value | | | | | | |
| | FALSE | 0 | | | | | | |
| | TRUE | 1 | | | | | | |
| | NULL | 2 | | | | | | |
| GCMD_DIST_SET_PD_STATE_EPS | Enables or disables | s the power switch to the EPS | 0 | 3 | 0 | 236 | 2 | UINT |
| | State | Value | | | | | | |
| | FALSE | 0 | | | | | | |
| | TRUE | 1 | | | | | | |
| | NULL | 2 | | | | | | |
| | | | | | | | | |
| GCMD_DIST_SET_PD_STATE_PPT | Enables or disables power domain | Enables or disables the power switch to the PPT power domain | | 3 | 0 | 238 | 2 | UINT |
| | State | Value | | | | | | |
| | FALSE | 0 | | | | | | |
| | TRUE | 1 | | | | | | |
| | NULL | 2 | | | | | | |
| | | | | | | | | |

GCMD_EPS_BATT_FULLDEF

| Item Name | Description | Min | Max | Default | Offset | Size | Type | Units |
|----------------------------------|--|-----|-----|---------|--------|------|-------|-------|
| GCMD_EPS_BATT_FULLDEF_CONST_VOLT | Limits for detecting a full state on the battery (voltage must be greater than this value) | 0.0 | 8.0 | 0.0 | 224 | 32 | FLOAT | V |
| GCMD_EPS_BATT_FULLDEF_CHG_CURR | Limits for detecting a full state on the battery (current must be less than this value) | 0.0 | 1.0 | 0.0 | 256 | 32 | FLOAT | Amps |



GCMD_GEN_SET_PT_STATE

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------|-------------------|---------------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_GEN_SET_PT_STATE_1 | enables or disabl | es Power Tracker #1 | 0 | 3 | 0 | 224 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |
| GCMD_GEN_SET_PT_STATE_2 | enables or disabl | es Power Tracker #2 | 0 | 3 | 0 | 226 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |
| GCMD_GEN_SET_PT_STATE_3 | enables or disabl | es Power Tracker #3 | 0 | 3 | 0 | 228 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | NULL | 2 | | | | | | | |
| | | | | | | | | | |

GCMD_MTQ_PMS

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|---------------------|------------------|-------------------|------|-----|---------|------------|----------|-----------|-------|
| GCMD_MTQ_PMS_X | Sets permamenen | t dipole strength | -100 | 100 | 0 | 224 | 8 | INT | |
| GCMD_MTQ_PMS_Y | Sets permamenen | t dipole strength | -100 | 100 | 0 | 232 | 8 | INT | |
| GCMD_MTQ_PMS_Z | Sets permamenen | t dipole strength | -100 | 100 | 0 | 240 | 8 | INT | |
| GCMD_MTQ_PMS_ENABLE | turns on permane | nt magnet setting | 0 | 2 | 0 | 248 | 2 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |

GCMD_MTQ_POP

TRUE

NULL

1 2

| Item Name Description Min Max Default Bit Offset Bit Size Data Type Ur | Inits |
|--|-------|
|--|-------|



GCMD_MTQ_POP_X 0 2 0 224 2 UINT flips the polarity on mtq x axis State Value **FALSE** 0 **TRUE** 1 2 NULL $\mathsf{GCMD}_\mathsf{MTQ}_\mathsf{POP}_\mathsf{Y}$ flips the polarity on mtq y axis 0 2 0 226 2 UINT State Value **FALSE** 0 TRUE 1 2 NULL GCMD_MTQ_POP_Z flips the polarity on mtq z axis 0 2 0 228 2 UINT State Value 0 **FALSE TRUE** 1 NULL 2

GCMD_MTQ_PWM_TIME

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------------------------|-------------|-----|-----|---------|------------|----------|-----------|---------|
| GCMD_MTQ_PWM_TIME_ACTUATION | | 0 | 255 | 0 | 224 | 8 | UINT | seconds |
| GCMD_MTQ_PWM_TIME_MEASUREMENT | | 0 | 255 | 0 | 232 | 8 | UINT | seconds |

GCMD_PPT_HALT

| Item Name | Description | | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------------------|---------------------|----------------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_PPT_HALT_CONFIRM | Are you sure you wa | ant to halt the ppt? | 0 | 1 | 0 | 224 | 1 | UINT | |
| | State | Value | | | | | | | |
| | FALSE | 0 | | | | | | | |
| | TRUE | 1 | | | | | | | |
| | | | | | | | | | |

GCMD_PPT_MULTIPLE_FIRE

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------------------------|------------------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_PPT_MULTIPLE_FIRE_COUNT | How many times to fire | 0 | 255 | 0 | 224 | 8 | UINT | |



GCMD_PPT_MULTIPLE_FIRE_OVERRIDE

Ppt fire override

0

1

0

232

UINT

1

| State | Value |
|-------|-------|
| FALSE | 0 |
| TRUE | 1 |

GCMD_RESET_MINMAX

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------------------------|--------------------------------|-----|-----|---------|------------|----------|-----------|-------|
| GCMD_RESET_MINMAX_BDOT | Whether to reset the subsystem | 0 | 1 | 0 | 224 | 1 | UINT | |
| GCMD_RESET_MINMAX_PPT | Whether to reset the subsystem | 0 | 1 | 0 | 225 | 1 | UINT | |
| GCMD_RESET_MINMAX_DIST | Whether to reset the subsystem | 0 | 1 | 0 | 226 | 1 | UINT | |
| GCMD_RESET_MINMAX_GEN | Whether to reset the subsystem | 0 | 1 | 0 | 227 | 1 | UINT | |
| GCMD_RESET_MINMAX_BATT | Whether to reset the subsystem | 0 | 1 | 0 | 228 | 1 | UINT | |
| GCMD_RESET_MINMAX_ESTIM | Whether to reset the subsystem | 0 | 1 | 0 | 229 | 1 | UINT | |
| GCMD_RESET_MINMAX_MPC | Whether to reset the subsystem | 0 | 1 | 0 | 230 | 1 | UINT | |
| GCMD_RESET_MINMAX_SENSORPROC | Whether to reset the subsystem | 0 | 1 | 0 | 231 | 1 | UINT | |
| GCMD_RESET_MINMAX_MTQ | Whether to reset the subsystem | 0 | 1 | 0 | 232 | 1 | UINT | |
| | | | | | | | | |

GCMD_SP_SET_THRESH

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|---------------------------|--|-----|-------|---------|---------------|-------------|--------------|--------------------|
| GCMD_SP_SET_THRESH_THRESH | Any magnetometer reading outside of +/- the set threshold will be discarded as invalid | 0 | 65535 | 0 | 224 | 16 | UINT | 1/73 nanoTeslas |

GRND_EPOCH

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|----------------|-------------|-----|---------------|---------|------------|----------|-----------|--------|
| GRND_EPOCH_VAL | | 0 | 1099511627775 | 0 | 224 | 40 | UINT | 2^-8 s |

TLE_1

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-------------|-------------------------|----------|---------|---------|------------|----------|-----------|---------|
| TLE_1_BSTAR | TLE BSTAR drag term | -3.4e+38 | 3.4e+38 | 0.0 | 224 | 32 | FLOAT | |
| TLE_1_MNA | TLE ID and Mean anomaly | -3.4e+38 | 3.4e+38 | 0.0 | 256 | 32 | FLOAT | degrees |



TLE_2

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------|--------------------------------|-----------|----------|---------|------------|----------|-----------|-------|
| TLE_2_DAY | TLE ID and Days since J2000 TT | -1.7e+308 | 1.7e+308 | 0.0 | 224 | 64 | FLOAT | |

TLE_3

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------|-------------------------|----------|---------|---------|------------|----------|-----------|---------|
| TLE_3_INC | TLE Orbital inclination | -3.4e+38 | 3.4e+38 | 0.0 | 224 | 32 | FLOAT | degrees |
| TLE_3_ECC | TLE ID and Eccentricity | -3.4e+38 | 3.4e+38 | 0.0 | 256 | 32 | FLOAT | |

TLE_4

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|------------|-----------------------------------|----------|---------|---------|------------|----------|-----------|---------|
| TLE_4_RAAN | TLE Rt ascension of the asc. node | -3.4e+38 | 3.4e+38 | 0.0 | 224 | 32 | FLOAT | degrees |
| TLE_4_AOP | TLE ID and Argument of perigee | -3.4e+38 | 3.4e+38 | 0.0 | 256 | 32 | FLOAT | degrees |

TLE_5

| Item Name | Description | Min | Max | Default | Bit Offset | Bit Size | Data Type | Units |
|-----------|------------------------|-----------|----------|---------|------------|----------|-----------|-----------------|
| TLE_5_MNM | TLE ID and mean motion | -1.7e+308 | 1.7e+308 | 0.0 | 224 | 64 | FLOAT | revolutions/day |