
```

clear
close all
clc
%{ The following program will simulate the local behavior of the vertical
% and horizontal aircraft position around the equilibrium point.
%
% - Convert Linearized Jacobian Matrices to state-space form & transfer
%   functions.
% - Compute the poles and zeros & plot bode for each transfer function.
% - Plot the impulse, step, and high/low frequency sinusoidal
%   responses for each transfer function.
%}

% Model parameters
J = 0.0475; %kg m^2
m = 4; %kg
r = 0.25; %m
g = 9.81; % m/s^2
c = 0.05; %Ns/m

% Linearized Jacobian Matrices evaluated at the equilibrium point
A = [0 0 0 1 0 0;
     0 0 0 0 1 0;
     0 0 0 0 0 1;
     0 0 -g -c/m 0 0;
     0 0 0 0 -c/m 0;
     0 0 0 0 0 0];

B = [0 0;
     0 0;
     0 0;
     1/m 0;
     0 1/m;
     r/J 0];

C = [1 0 0 0 0 0;
     0 1 0 0 0 0];

D = [0 0;
     0 0];

% Convert Jacobian Matrices to State-Space Form
stateSpace = ss(A,B,C,D);
% Visualize the State-Space Form
disp('State-Space Form:')
display(stateSpace)

State-Space Form:

stateSpace =

    A =

           x1           x2           x3           x4           x5           x6

```

x1	0	0	0	1	0	0
x2	0	0	0	0	1	0
x3	0	0	0	0	0	1
x4	0	0	-9.81	-0.0125	0	0
x5	0	0	0	0	-0.0125	0
x6	0	0	0	0	0	0

```
B =
      u1      u2
x1      0      0
x2      0      0
x3      0      0
x4  0.25      0
x5      0  0.25
x6  5.263      0
```

```
C =
      x1  x2  x3  x4  x5  x6
y1      1  0  0  0  0  0
y2      0  1  0  0  0  0
```

```
D =
      u1  u2
y1      0  0
y2      0  0
```

Continuous-time state-space model.

Local X Simulation Response Convert State-Space Form to local X Transfer Function

```
[X_num, X_den] = ss2tf(A,B,C,D,1);
X_tf = tf(X_num(1,:),X_den);

% Visualize the local X transfer function
disp('local X Transfer Function:')
display(X_tf)

% Visualize local X Transfer Function Poles
disp('X Transfer Function Poles:')
display(pole(X_tf));

% Visualize local X Transfer Function Zeros
disp('local X Transfer Function Zeros:')
display(zero(X_tf));

% Impulse response of local X
figure(1)
impz(X_tf)
xlabel('time (s)')
ylabel('x - x_e position (m)')
title('Impulse response of local behavior of X')
grid on

% Step response of local X
```

```

figure(2)
step(X_tf)
xlabel('time (s)')
ylabel('x - x_e position (m)')
title('Step response of X local behavior')
grid on

% Bode Plot of local X
figure(3)
bode(X_tf)
grid on

% Sinuoidal input for local X
t_x = linspace(0, 1000, 100); % Time Vector for local X

% Low frequency at 0.01
omega_lw_x = 0.01;
u_X_low = sin(omega_lw_x*t_x); % Forcing Function for local X
XLowfreq = lsim(X_tf, u_X_low, t_x);

% High frequency at 1000
omega_hi_x = 1000;
u_X_hi = sin(omega_hi_x*t_x); % Forcing Function for local X
XHifreq = lsim(X_tf, u_X_hi , t_x);

% Plot Low Frequency Sinusoidal response for local X
figure(4)
plot(t_x,XLowfreq)
xlabel('time (s)')
ylabel('x - x_e position (m)')
title('Low Frequency Sinusoidal response of X local behavior')
grid on

% Plot High Frequency Sinusoidal response for local X
figure(5)
plot(t_x,XHifreq)
xlabel('time (s)')
ylabel('x - x_e position (m)')
title('High Frequency Sinusoidal X local behavior')
grid on

local X Transfer Function:

X_tf =

    0.25 s^4 + 0.003125 s^3 - 51.63 s^2 - 0.6454 s
-----
    s^6 + 0.025 s^5 + 0.0001563 s^4

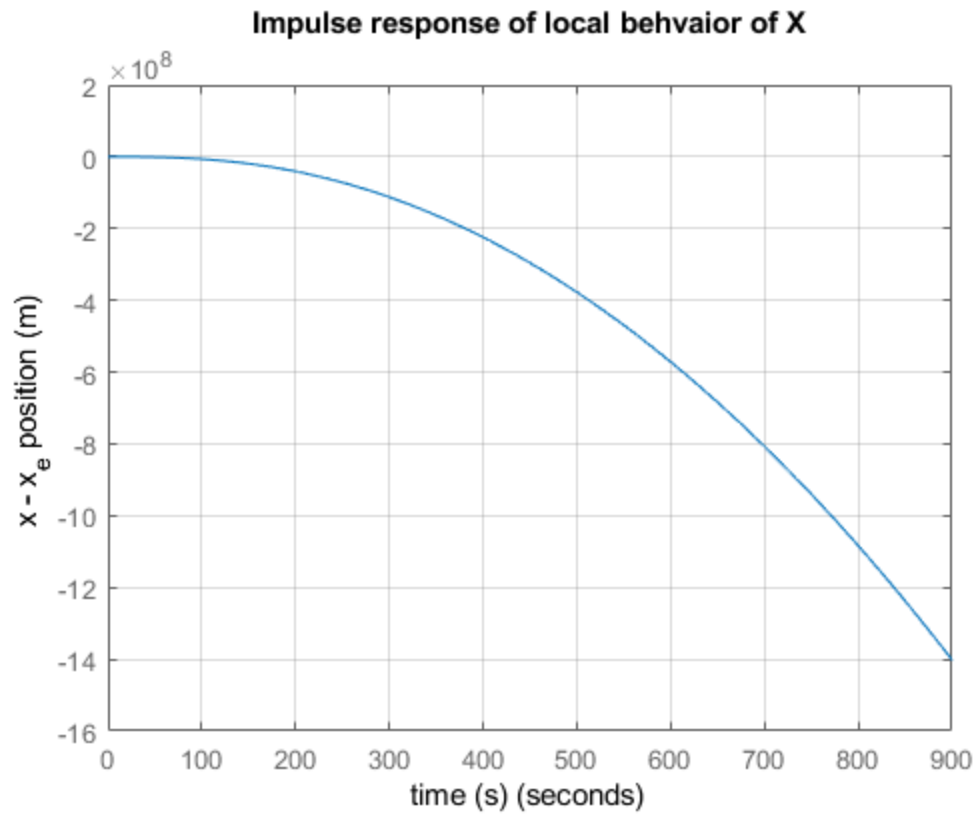
Continuous-time transfer function.
X Transfer Function Poles:
    0.0000 + 0.0000i
    0.0000 + 0.0000i
    0.0000 + 0.0000i

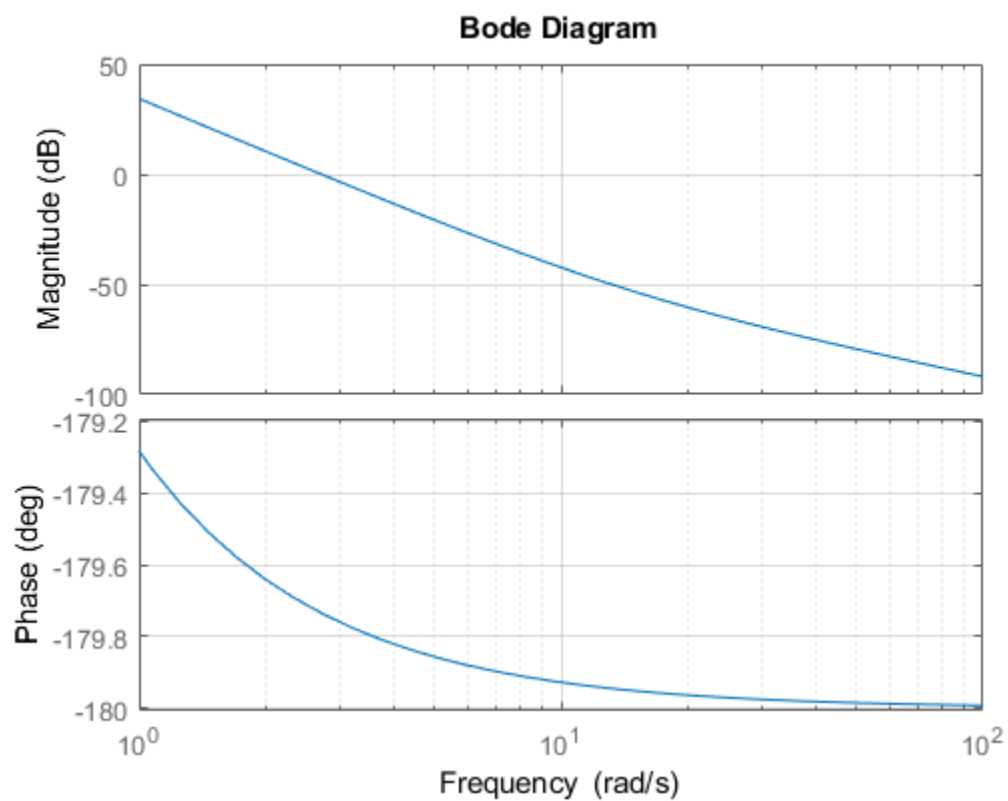
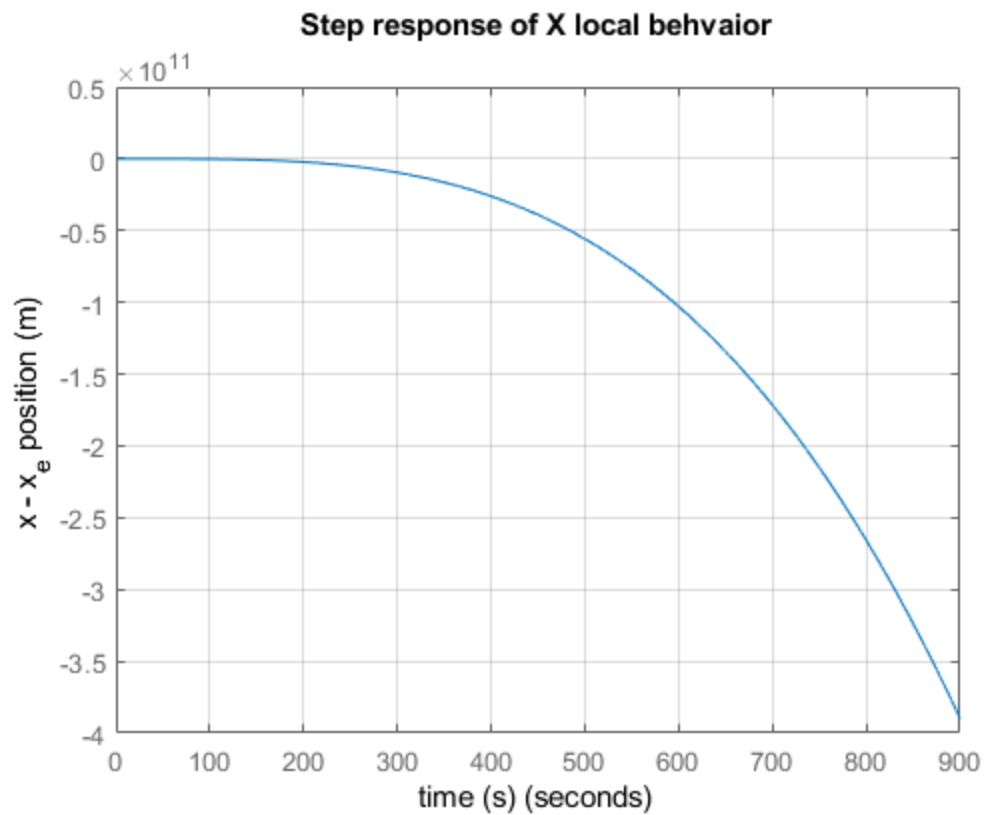
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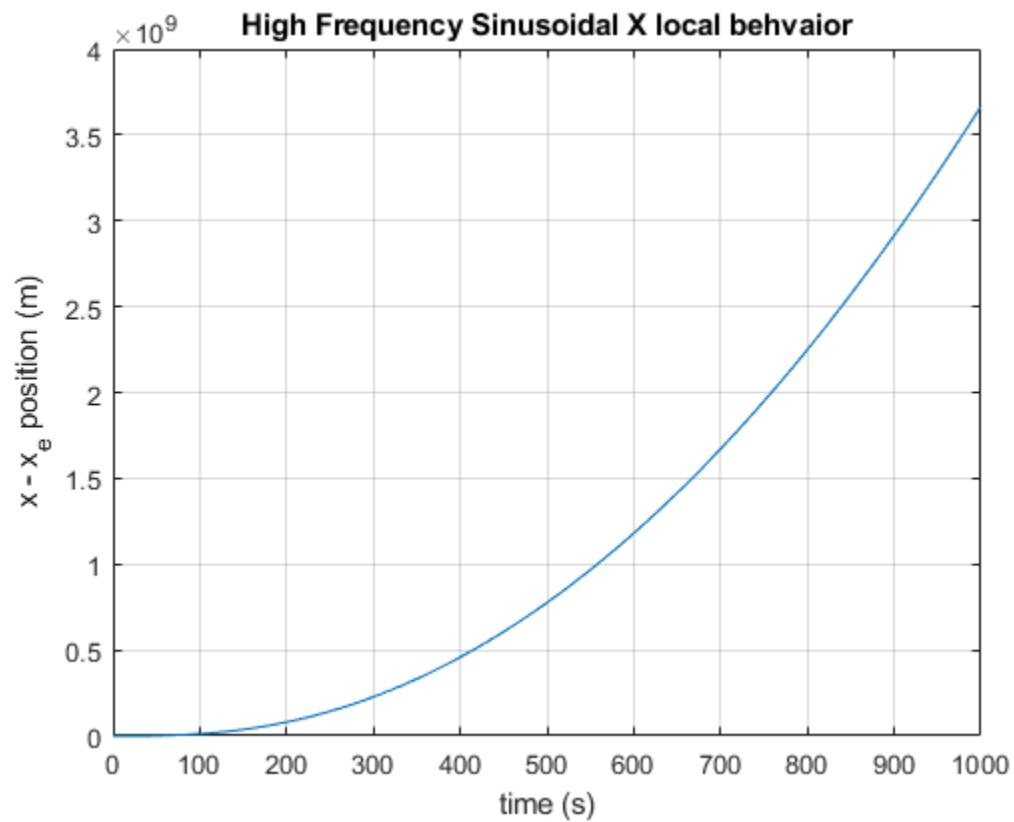
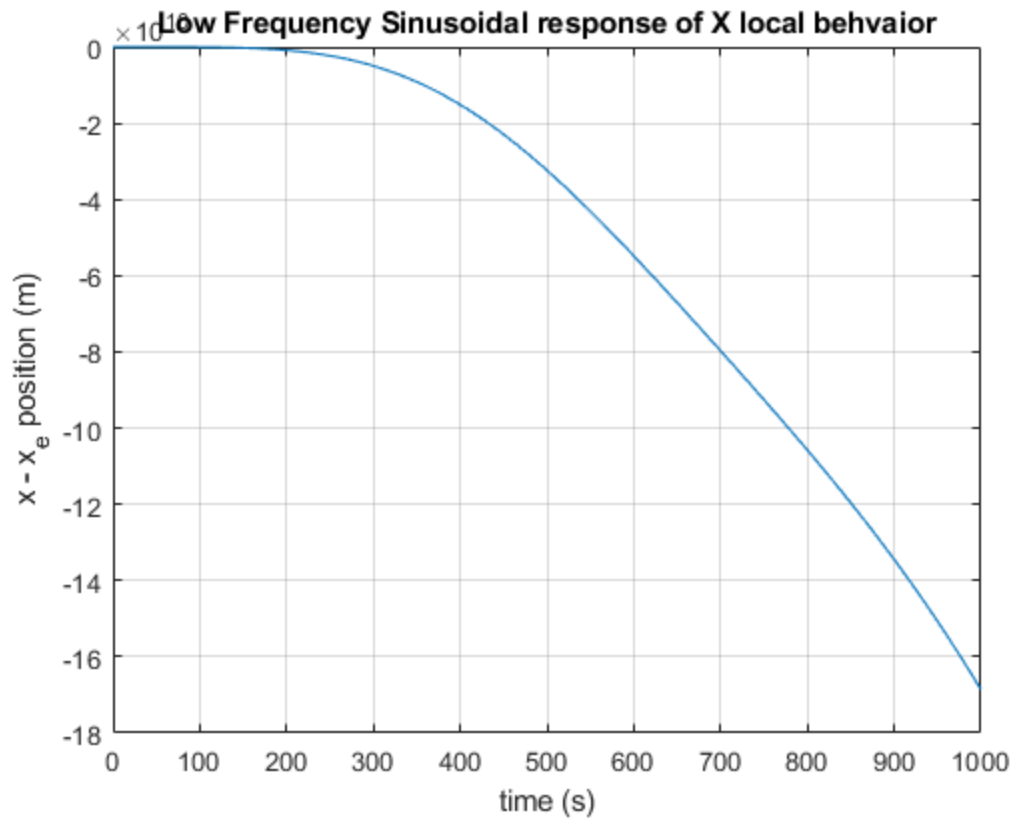
$0.0000 + 0.0000i$
 $-0.0125 + 0.0000i$
 $-0.0125 - 0.0000i$

local X Transfer Function Zeros:

0
14.3710
-14.3710
-0.0125







Local Y Simulation Response Convert State-Space Form to Y Transfer Function

```
[Y_num, Y_den] = ss2tf(A,B,C,D,2);
disp('Y Transfer Function:')
Y_tf = tf(Y_num(2,:),Y_den);

% Visualize the Y transfer function
disp('Y Transfer Function:')
display(Y_tf)

% Visualize Y Transfer Function Poles
disp('Y Transfer Function Poles:')
display(pole(Y_tf));

% Visualize Y Transfer Function Zeros
disp('Y Transfer Function Zeros:')
display(zero(Y_tf));

% Impulse response of local Y
figure(6)
impz(Y_tf)
xlabel('time (s)')
ylabel('y - y_e position (m)')
title('Impulse response of Y local behavior')
grid on

% Step response of local Y
figure(7)
step(Y_tf)
xlabel('time (s)')
ylabel('y - y_e position (m)')
title('Step response of Y local behavior')
grid on

% Bode Plot of local Y
figure(8)
bode(Y_tf)
grid on

% Sinuoidal input for local Y
t_y = linspace(0, 1000, 1000); % Time Vector for local Y

% Low frequency at 0.01
omega_low_y = 0.01;
u_Y_low = sin(omega_low_y*t_y); % Forcing Function for local Y
YLowfreq = lsim(Y_tf, u_Y_low, t_y);

% High frequency at 1000
omega_hi_y = 1000;
u_Y_hi = sin(omega_hi_y*t_y); % Forcing Function for local Y
YHifreq = lsim(Y_tf, u_Y_hi , t_y);

% Plot Low Frequency Sinusoidal response for local Y
figure(9)
```

```

plot(t_y,YLowfreq)
xlabel('time (s)')
ylabel('y - y_e position (m)')
title('Low Frequency Sinusoidal response of Y local behavior')
grid on

```

```

% Plot High Frequency Sinusoidal response for local Y
figure(10)
plot(t_y,YHifreq)
xlabel('time (s)')
ylabel('y - y_e position (m)')
title('High Frequency Sinusoidal of Y local behavior')
grid on

```

Y Transfer Function:
Y Transfer Function:

Y_tf =

$$\frac{0.25 s^4 + 0.003125 s^3}{s^6 + 0.025 s^5 + 0.0001563 s^4}$$

Continuous-time transfer function.

Y Transfer Function Poles:

```

0.0000 + 0.0000i
0.0000 + 0.0000i
0.0000 + 0.0000i
0.0000 + 0.0000i
-0.0125 + 0.0000i
-0.0125 - 0.0000i

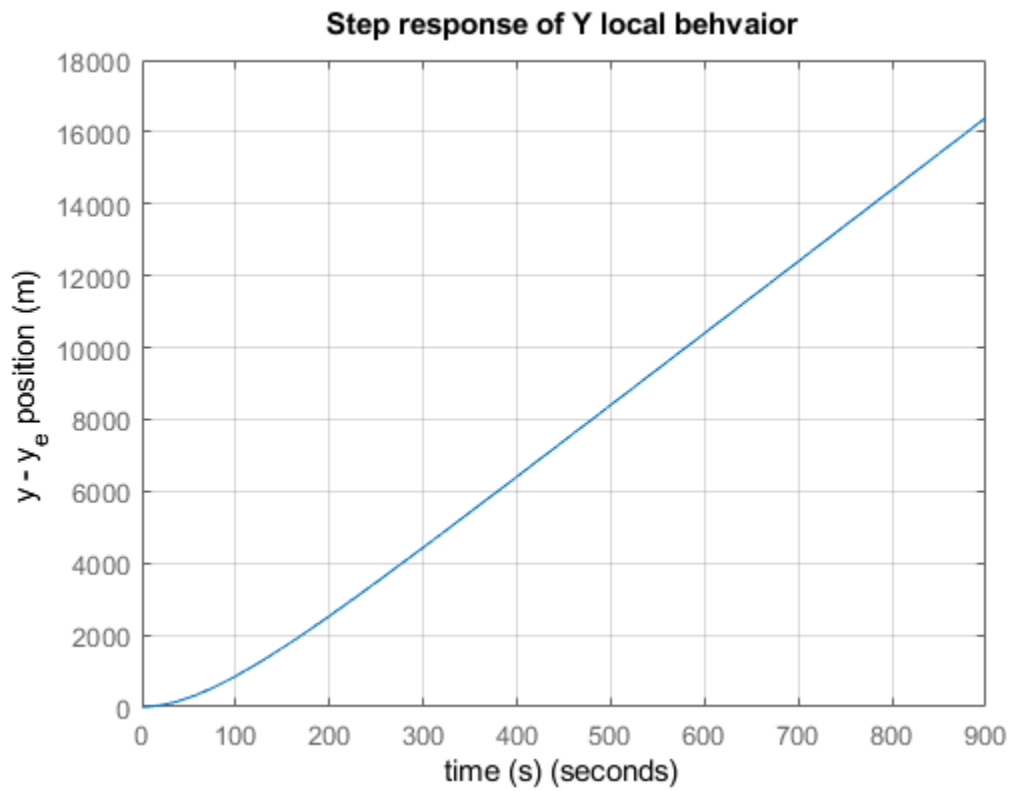
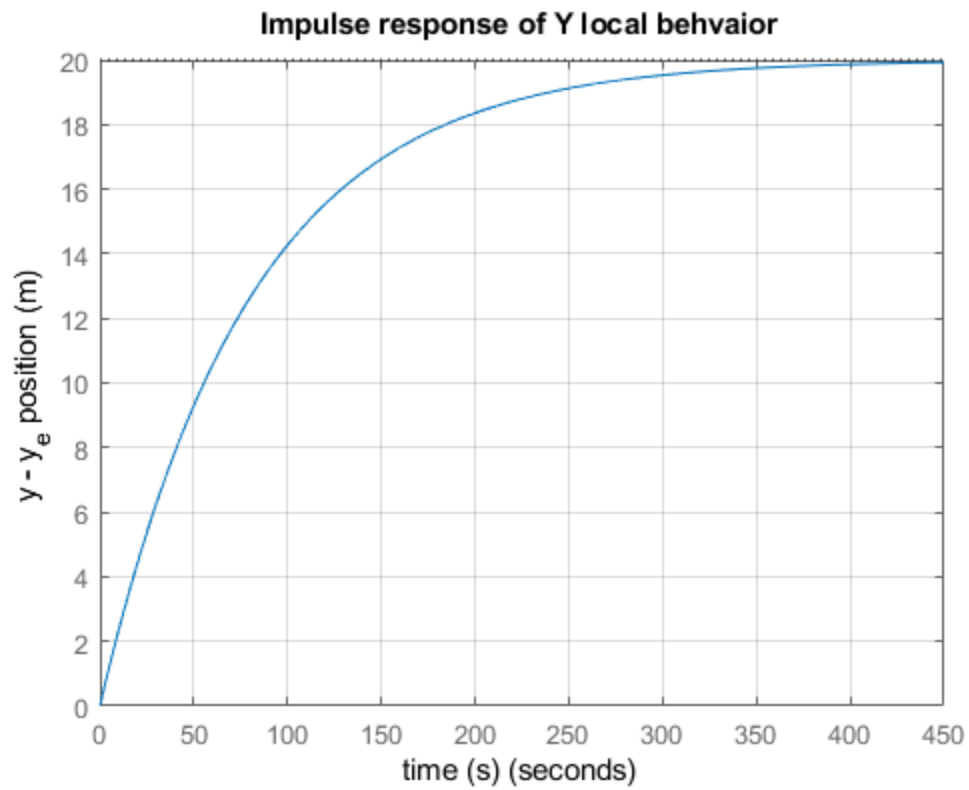
```

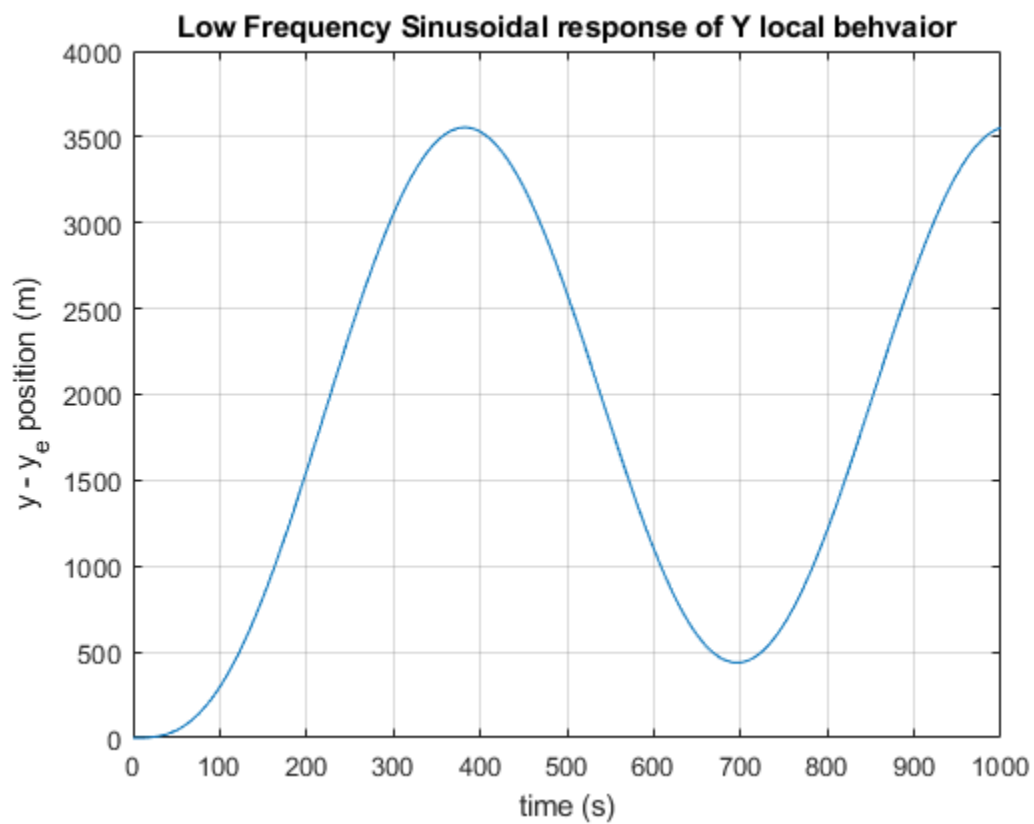
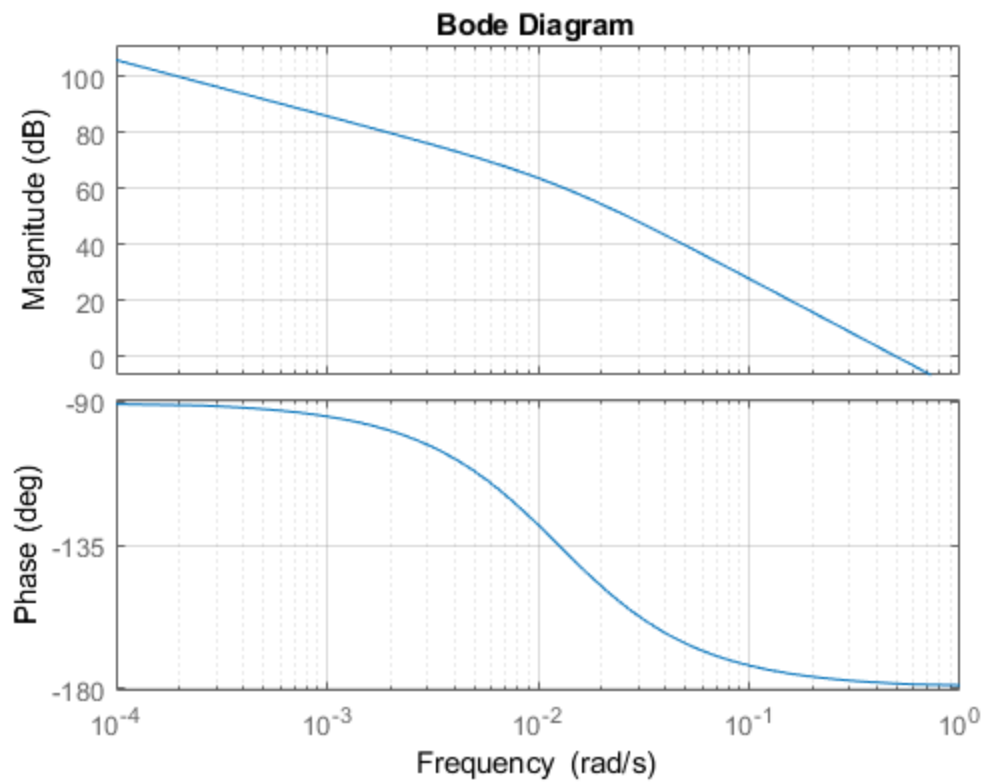
Y Transfer Function Zeros:

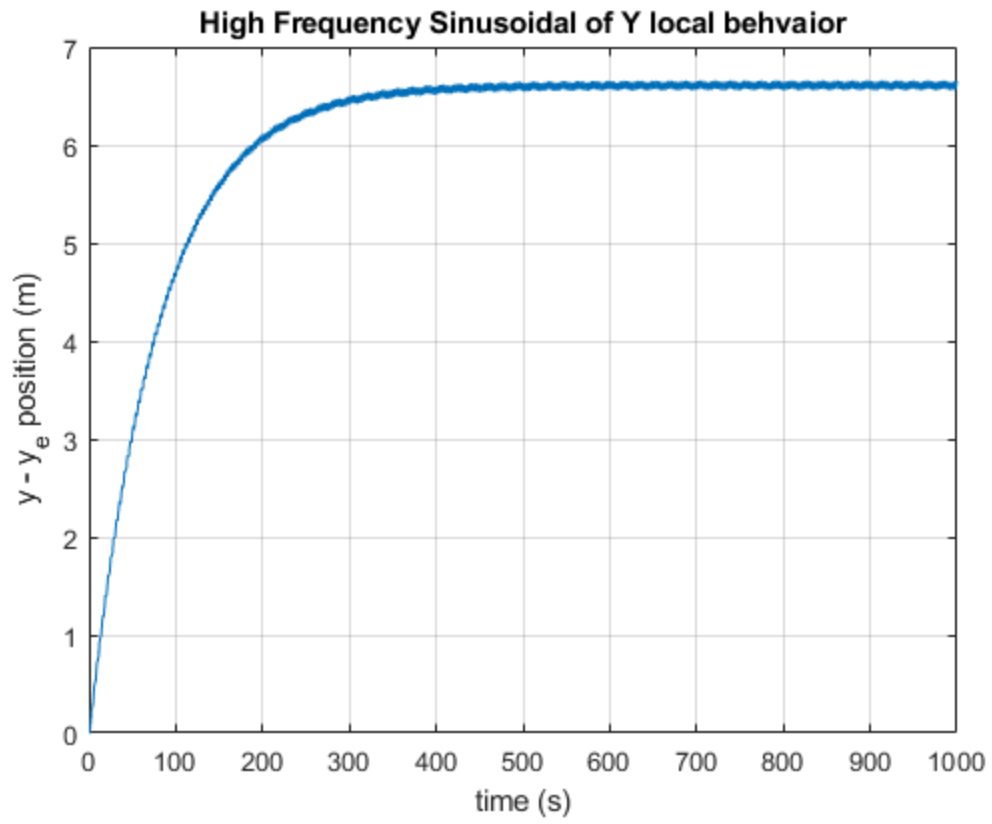
```

0
0
0
-0.0125

```





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