

Microxanox - an R package for simulating an *MICRobial* ecosystem that can occupy *OXic* or *ANOXic* states.

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Abstract

Ca. 100 words.

Keywords: metadata quality; data curation; archival; long term storage; R package;

1. Required Metadata

1.1. Current code version

Ancillary data table required for subversion of the codebase.

Nr.	Code metadata description	Please fill in this column
C1	Current code version	v0.9.0
C2	Permanent link to code/repository used for this code version	https://github.com/UZH-PEG/microxanox
C3	Code Ocean compute capsule	
C4	Legal Code License	CC BY 4.0
C5	Code versioning system used	git
C6	Software code languages, tools, and services used	R
C7	Compilation requirements, operating environments	R (>= 4.1.0), ADD PACKAGES
C8	If available Link to developer documentation/manual	
C9	Support email for questions	Rainer.Krug@uzh.ch; Rainer@krugs.de

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13 2. Motivation and significance

14 Many ecosystems are exposed to gradual changes of environmental variables,
15 to which the responses are not always as gradual as the change of the environmen-
16 tal variable. One example where the gradual change of a single environmental
17 causing an abrupt change of the system is the switch from an aerobic to anaerobic
18 system. This system has been investigated by Bush et al. (2017). We wanted
19 to take this investigation one step further, and look at the role of an increased
20 biodiversity plays in these dynamics (REF NEEDED, 2222). For this purpose,
21 we developed this package.

22 The `microxanox` package is a package for simulating a three functional group
23 system (*CB*: cyanobacteria, *PB*: phototrophic sulfur bacteria, and *SB*: sulfate-
24 reducing bacteria) with four chemical substrates (*P*: phosphorus, *O*: oxygen, *SR*:
25 reduced sulfur, *SO*: oxidized sulfur). It includes feedback between biogeochemical
26 processes and is based on (Bush et al., 2017) (See (Bush et al., 2017) for a detailed
27 discussion of the model).

28 The aims of the `microxanox` package are twofold. Firstly, the package aims
29 at reproducing the results shown by (Bush et al., 2017), which is accomplished in
30 the vignette [Partial reproduction of Bush et al.](#) Secondly, to take these results
31 one step further, it includes new functionality to address our research question as
32 presented in (REF NEEDED, 2222).

33 For this, we extended the model and added functionality for:

- 34 • Multiple strains (effectively unlimited) per functional group.
- 35 • Adding temporally varying oxygen diffusivity.
- 36 • Adding random noise in substrate concentrations.
- 37 • Including immigration.
- 38 • Setting minimum population abundances.

39 In addition to the model itself, the package includes some functions to
40 analyse the results as well as visualise the results to provide a starting point for
41 customised visualisations based on own requirements.

42 3. Software description

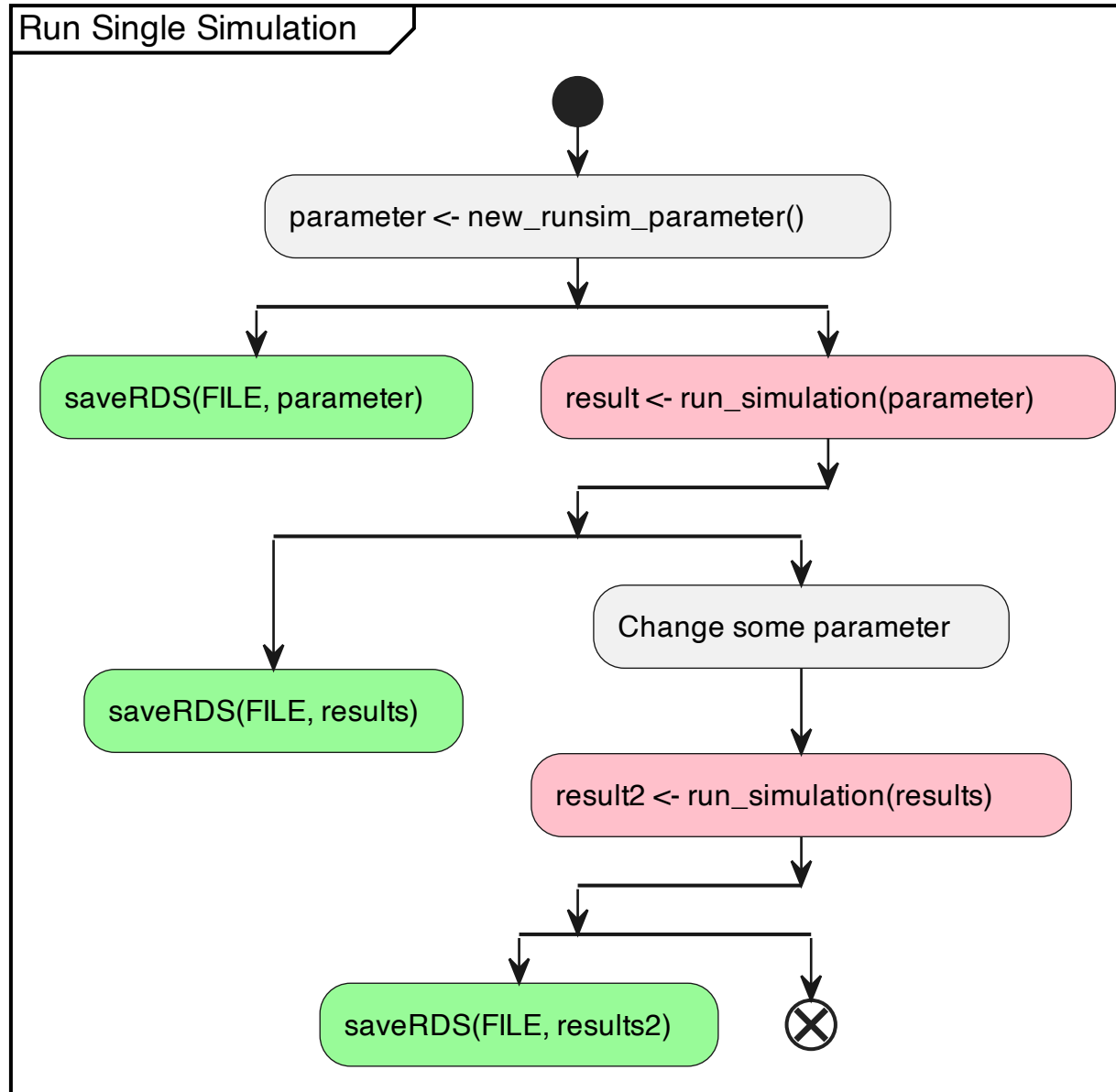
43 {»Describe the software in as much as is necessary to establish a vocabulary
44 needed to explain its impact.«}

```
@startuml
partition "Run Single Simulation" {
  start
  :parameter <- new_runsim_parameter();
  split
  #palegreen:saveRDS(FILE, parameter);
```

```

    detach
  split again
    #pink:result <- run_simulation(parameter);
  end split
  split
    #palegreen:saveRDS(FILE, results);
    detach
  split again
    :Change some parameter;
    #pink:result2 <- run_simulation(results);
  end split
  split
    #palegreen:saveRDS(FILE, results2);
    detach
  split again
    end
  end split
}
@enduml

```



45 The package is not intended to provide a modelling framework which can
 46 be adjusted easily to all needs, but primarily a tool to implement the model
 47 used by (Bush et al., 2017) and to extend it to our needs (REF NEEDED, 2222).
 48 Consequently, any more substantial changes and adaptaitions, are likely to need
 49 a change in the source code.

51 Nevertheless, the model is structured in a way which builds on a modular

52 structuere, so that e.g. the event definition can easily be changed. or other
53 aspects can be adjusted. All values in the parameter object can be changed as
54 needed and the general structure of the code should make it not to difficult to
55 adapt the model to other similar systems.

56 3.1. Software Architecture

57 {»Give a short overview of the overall software architecture; provide a pic-
58 torial component overview or similar (if possible). If necessary provide im-
59 plementation details.«}

60 The framework used when writing this package aims at reproducibility of
61 the results. It builds on the folowing main considerations:

- 62 1. all parameter needed to run a simulation or find a stable state are contained
63 in a single parameter object. This object is created by using the functions
64 `new_..._parameter()`, `new_initial_state()` and `new_strain_parameter()`.
65 Which one of the `new_..._parameter()` functions has to be used when,
66 will be discussed in the section `@ref(runsim)` and in the [User Guide](#).
- 67 2. The function call `run_...(parameter)` will run the simulation using the
68 parameter as defined in the object `parameter`.
- 69 3. The return value of the `run_...(parameter)` function is identical to the
70 parameter object plus an additional slot named `results` which contains the
71 results of the run
- 72 4. As this return value contains all parameter, it is possible to re-run the
73 simulatuion by simply running `run_...(result)`.

74 The point that the results object contains all parameter needed to run the
75 simulation, promotes reproducibility and makes incremental changes of individual
76 parameters and re-running the simulations much easier.

77 A typical simulation would look as followed:

```
## Create the parameter
parameter <- new_runsim_parameter()
# manually setting certain parameter

## Run the simulation and save the result
result <- run_simulation(parameter)
saveRDS(result, "sim1.rds")

## Do other stuff, e.g. plotting

## Load results, change some parameter, and rerun the simulation and save the result
parameter <- loadRDS("sim1.rds")
# change some parameter
result <- run_simulation(parameter)
saveRDS(result, "sim2,rds")
```

78 3.2. Software Functionalities

79 {»Present the major functionalities of the software.«}

80 We will now discuss the general structure and functionality of the package
81 without going into too much detail. A more detailed discussion can be found in
82 the [User Guide](#).

83 The ODEs for the rates of change are specified in the function `bushplus_dynamic_model()`.
84 This augmented version of the model published in ([Bush et al., 2017](#)) can handle
85 multiple strains within each of the three functional groups, temporal variation
86 in oxygen diffusivity, and events.

87 In the following sections we describe the general usage of the package: running
88 one simulation, finding steady states across an environmental gradient, calculating
89 measures of stability, and visualization.

90 4. Illustrative Examples

91 {»Present the major functionalities of the software.«}

92 4.0.1. Running one simulation

93 The individual simulation (`run_simulation()` function) is the working horse
94 in this package. In this function, the ODEs are solved. The function needs only
95 one argument - an object as created by the function `new_runsim_parameter()`.
96 One parameter of this object is the `strain_parameter` which can be created
97 by the function `new_strain_parameter()`. For a detailed description of the
98 parameter and how they are created please see the User Guide and which
99 accompanies the package or is available at [User Guide](#)

100 After the parameter object has been defined, it can be used in the `run_simulation()`
101 function. The function returns an object which is identical to the parameter,
102 except of an additional slot containing the results. This design produces a fully
103 reproducible object as it can be used instead of a parameter object to be fed
104 back into the `run_simulation()` function to run the simulation again from the
105 parameter used to generate the results from.

106 The function `plot_dynamics()` plots a single simulation run, as returned from
107 the `run_simulation()` function. This function is only provided as a convenience
108 function to provide a way to easily see the results of a simulation run. An
109 example plot resulting from this function is shown in [@ref\(fig:plot-dynamics\)](#).

110 4.0.2. Finding a Steady State of the model

111 There are two methods for finding steady states. The first runs a separate
112 simulation for each combination of starting conditions and oxygen diffusivity
113 (let us term this the *Replication method*). The second runs only two simulations,
114 with step-wise and slowly temporally increasing or decreasing oxygen diffusivities
115 and recorded of state just before change to a new oxygen diffusivity (let us term
116 this the *Temporal method*).

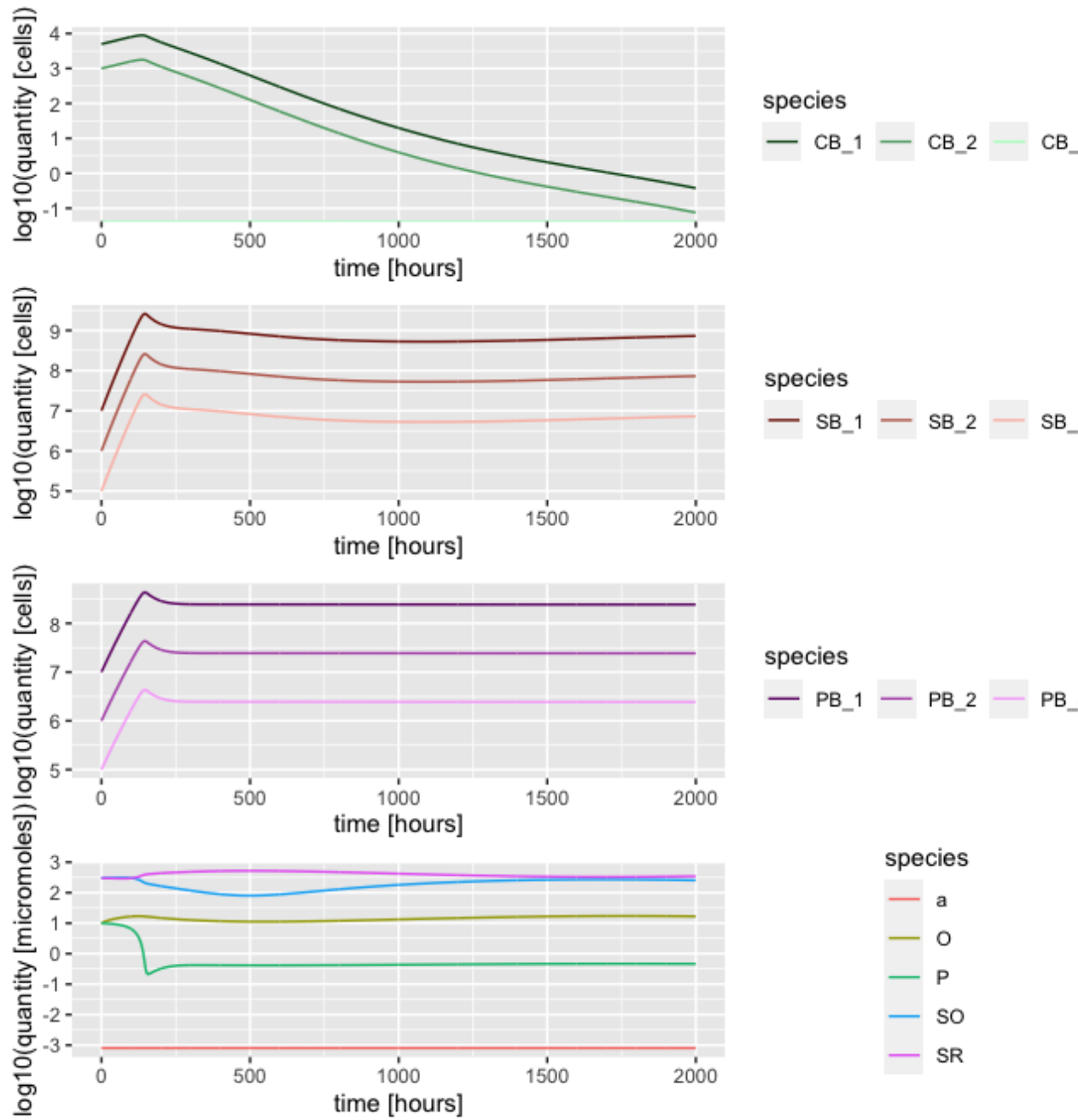


Figure 1: Plot of results of a simulation run using the function `plot_dynamics()`. Details can be found in the "User Guide" section "Three strains per functional group".

117 *4.0.2.1. Replication Method.* The replication method is implemented in the func-
118 tion `run_replication_ssfind()` which takes a parameter object as returned by
119 the function `new_replication_ssfind_parameter()` and the number of cores
120 for multithreading the simulation.

121 *4.0.2.2. Temporal Method.* The temporal method involves two simulations for a
122 particular system configuration (parameter set). In one simulation the oxygen
123 diffusivity is *increased* in a step-wise fashion. In the other it is *decreased* in
124 a step-wise fashion. That is, oxygen diffusivity is held at a constant level for
125 long enough for steady state to be reached, that state is recorded, and then a
126 slightly higher (or lower) oxygen diffusivity value is set. Hence, at that time
127 point, the system is effectively started with initial conditions that are the state
128 of the system in the previous time step.

129 This is implemented in the function `run_temporal_ssfind()`, which takes a
130 parameter object as created by the function `new_temporal_ssfind_parameter()`
131 and a number indicating the .

132 For a more detailed walk-through of these two approaches and explanation
133 please see the [User Guide](#).

134 *4.0.3. Extracting Stability Measures*

135 From the raw results returned by these `run_...()` functions, the stability
136 measures can be extracted by using the function `get_stability_measures()`.
137 These measures include non-linearity and hysteresis measures, of the response of
138 the simulated system to environmental change.

139 **5. Impact**

140 {»This is the main section of the article and the reviewers weight the de-
141 scription here appropriately Indicate in what way new research questions can be
142 pursued as a result of the software (if any). Indicate in what way, and to what
143 extent, the pursuit of existing research questions is improved (if so). Indicate in
144 what way the software has changed the daily practice of its users (if so). Indicate
145 how widespread the use of the software is within and outside the intended user
146 group. Indicate in what way the software is used in commercial settings and/or
147 how it led to the creation of spin-off companies (if so).«}

148 The first two use cases are described in detail in the User Guide and the
149 Partial Reproduction Vignettes. The third is taken from the REF NEEDED
150 (2222) for which this R package was designed. All of these use cases can be
151 expanded to larger numbers of strains per functional group and variable values
152 can be changed.

153 *5.1. Regime shifts during temporal environmental change*

154 In the [User Guide](#) we used a one strain system (section “1 strain per functional
155 group”) and three strain system (section “3 strains per functional group”) to
156 determine as an example the stable states during temporal environmental changes

(the oxygen diffusivity). From these simulations, we extracted measures of nonlinearity and hysteresis. See Fig @ref(fig:plot-dynamics) as an example plot of the simulations.

5.2. *The extent of hysteresis depends on community composition*

One of the reasons to develop this package was to reproduce the results presented in Bush et al. (2017), this was achieved as demonstrated in the [Partial Reproduction supplement](#). All aspects in the paper could be reproduced and are shown in the vignette.

5.3. *Effects of functional diversity on regime shifts*

As discussed in the paper (REF NEEDED, 2222), the role biodiversity plays in abrupt regime shifts based on gradual changing environmental parameter is not well understood. This model (as part of the package) has been used to investigate these dynamics and the results are available in REF NEEDED (2222).

{»More details from the paper.«} {»Romana will provide two or three sentences«}

6. Conclusions

Set out the conclusion of this original software publication.

7. Conflict of Interest

We wish to confirm that there are no known conflicts of interest associated with this publication and there has been no significant financial support for this work that could have influenced its outcome.

8. Acknowledgements

Optionally thank people and institutes you need to acknowledge.

References

- Bush, T., Diao, M., Allen, R.J., Sinnige, R., Muyzer, G., Huisman, J., 2017. Oxidic-anoxic regime shifts mediated by feedbacks between biogeochemical processes and microbial community dynamics. *Nature Communications* 8, 789. doi:[10.1038/s41467-017-00912-x](https://doi.org/10.1038/s41467-017-00912-x)
- REF NEEDED, A., 2222. REFERNECE NEEDED. *Journal of missing references*.

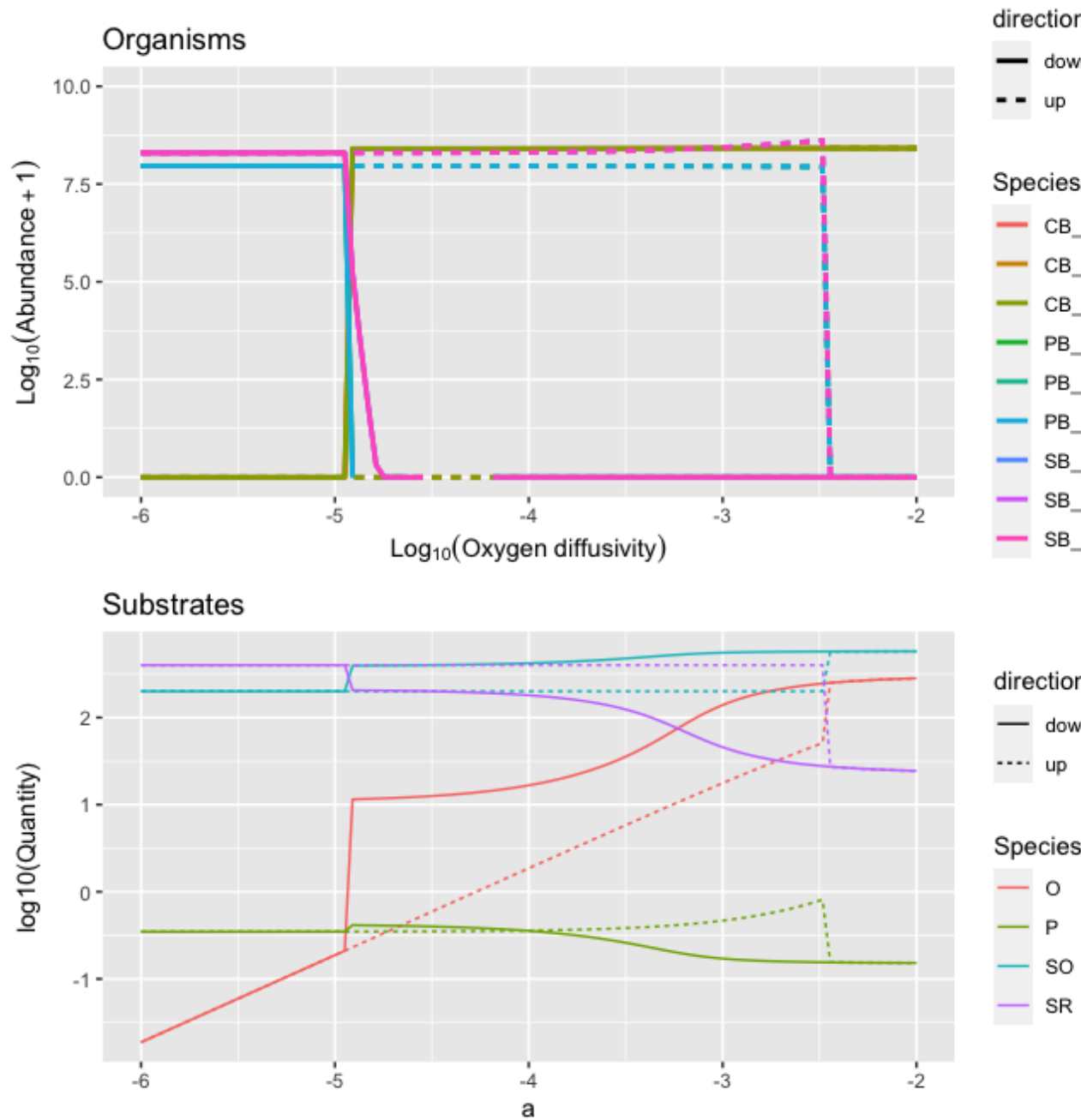


Figure 2: Plot of the stable states of the simulation runs under different oxygen diffusivity. The top graph are the Organisms (each initially with three strains) while the lower graph is the substrate availability under the same oxygen diffusivities. Details can be found in the "User Guide" section "Three strains per functional group".

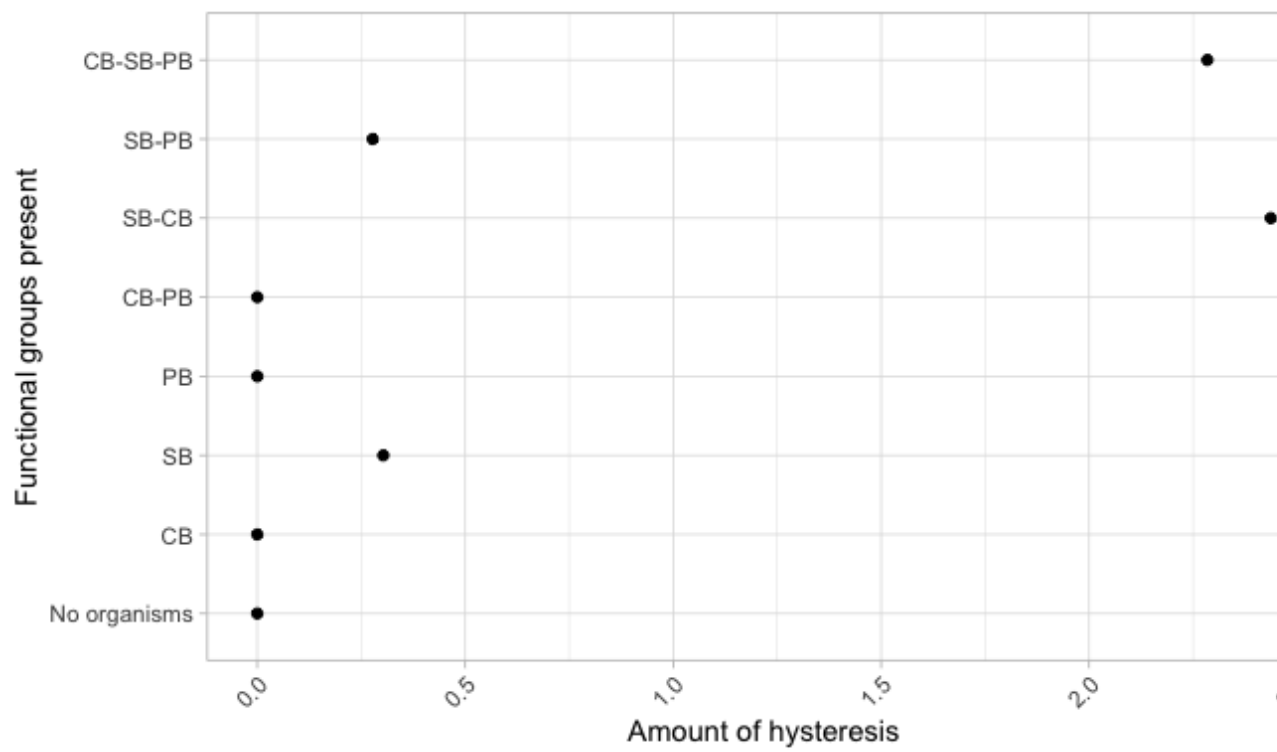


Figure 3: Hysteresis of all assessed combinations of variability.