

1 **Microxanox - an R package to simulate ...**

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3 last-modified

- 4 1. set the context for and purpose of the work;
- 5 2. indicate the approach and methods;
- 6 3. outline the main results;
- 7 4. identify the conclusions and the wider implications.

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27	1 Plot of results of a simulation run using the function <code>plot_dynamics()</code> \$. De-	
28	tails can be found in the “User Guide” section “Three strains per functional	
29	group”.	9

30 Introduction

31 {»Biological justification and background - one paragraph«}

32 {»Based on abstract from Romana«}

33 Many ecosystems are exposed to gradual changes of environmental variables, to which the
34 responses are not always as gradual as the change of the environmental variable. One example
35 where the gradual change of a single environmental causing an abrupt change of the system is

the switch from an aerobic to anaerobic system. This system has been investigated by Bush et al. (2017). We wanted to take this investigation one step further, and look at the role of an increased biodiversity plays in these dynamics (REF NEEDED, 2222). For this purpose, we developed this package.

The `microxanox` package is a package for simulating a three functional group system (*CB*: cyanobacteria, *PB*: phototrophic sulfur bacteria, and *SB*: sulfate-reducing bacteria) with four chemical substrates (*P*: phosphorus, *O*: oxygen, *SR*: reduced sulfur, *SO*: oxidized sulfur). It includes feedback between biogeochemical processes and is based on (Bush et al., 2017) (See (Bush et al., 2017) for a detailed discussion of the model).

The aims of the `microxanox` package are twofold. Firstly, the package aims at reproducing the results shown by (Bush et al., 2017), which is accomplished in the `vignette Partial reproduction of Bush et al.` Secondly, to take these results one step further, it includes new functionality to address our research question as presented in (REF NEEDED, 2222).

For this, we extended the model and added functionality for:

- Multiple strains (effectively unlimited) per functional group.
- Adding temporally varying oxygen diffusivity.
- Adding random noise in substrate concentrations.
- Including immigration.
- Setting minimum population abundances.

In addition to the model itself, the package includes some functions to analyse the results as well as visualise the results to provide a starting point for customised visualisations based on own requirements.

The Model

The model is an implementation of the model described by (Bush et al., 2017). It is an ordinary differential equation (ODE) based numerical non-stochastic model which was implemented in form of an R package.

We use the notation from the Table S1 of the Supplementary information of (Bush et al., 2017)), and not the notation in the main manuscript of (Bush et al., 2017). In the main manuscript the notation is simplified to y_{S_PB} ($y_{S,PB}$) (which is y_{SR_PB} ($y_{SR,PB}$) in Table S1) and y_{S_SB} ($y_{S,SB}$) (which is y_{SO_SB} ($y_{SO,SB}$) in Table S1). We also use Pr_cB (Pr_B) instead of P_CB (P_{CB}).

All parameter and variables follow these base dimensions:

- Time: `hours`
- Volume: `litres`
- Substrate quantity: `micromoles`
- Organism quantity: `cells`

{» Add a more detailed description of the model and the additions «} {»TODO«}

The ODEs are solved using the “General Solver for Ordinary Differential Equations” of the `deSolve` package (Soetaert, Petzoldt, & Setzer, 2010).

Availability and Accessibility of the Package

The package is available in a [github repo/](#). The newest version is also available under the DOI or via RUniverse (REF NEEDED, 2222). This manuscript describes version 1.0 which is

78 available under [DOI](#) or installable within R by using `remotes::install_github("UZH-PEG",`
79 `ref = "v1.0")`.

80 The package will be updated based on further research activities. It will be tested continuously
81 for the last recent, current and devel version of R. {»If we want that, we have to include some,
82 even rudimentary, GITHUB tests.«} {»RMK: Agreed - let's discuss this when we talk about
83 the package paper.«}

84 Issues, questions and suggestions should be communicated through the issue tracker at [https:](https://github.com/UZH-PEG/microxanox/issues)
85 [//github.com/UZH-PEG/microxanox/issues](https://github.com/UZH-PEG/microxanox/issues)

86 The R Package

87 Documentation

88 The package contains the full documentetion of the functions, which includes

- 89 1. Standard R help for each function (`?COMMAND` in R)
- 90 2. Two vignettes accompanying the package:
 - 91 • A **User Guide**, also available on the R-Universe [Vignette 1](#). This gives an introduction
 - 92 of the package and its functions and provides a walk-through of the process of running,
 - 93 visualizing and extra and [Vignette 2](#)
- 94 3. This paper as a third vignette, also available under RUniverse [Vignette 3](#)

95 The modelling framework

96 The framework used when writing this package aims at reproducibility of the results. It builds
97 on the following main considerations:

- 98 1. all parameter needed to run a simulation or find a stable state are contained
99 in a single parameter object. This object is created by using the functions
100 `new_..._parameter()`, `new_initial_state()` and `new_strain_parameter()`. Which
101 one of the `new_..._parameter()` functions has to be used when, will be discussed in
102 the section [@ref\(runsim\)](#) and in the [User Guide](#).
- 103 2. The function call `run_...(parameter)` will run the simulation using the parameter as
104 defined in the object `parameter`.
- 105 3. The return value of the `run_...(parameter)` function is identical to the parameter
106 object plus an additional slot named `results` which contains the results of the run
- 107 4. As this return value contains all parameter, it is possible to re-run the simulation by
108 simply running `run_...(result)`.

109 The point that the results object contains all parameter needed to run the simulation, promotes
110 reproducibility and makes incremental changes of individual parameters and re-running the
111 simulations much easier.

112 A typical simulation would look as followed:

```
## Create the parameter  
parameter <- new_runsim_parameter()  
# manually setting certain parameter  
  
## Run the simulation and save the result
```

```
result <- run_simulatrion(parameter)
saveRDS(result, "sim1.rds")

## Do other stuff, e.g. plotting

## Load results, change some parameter, and rerun the simulation and save the result
parameter <- loadRDS("sim1.rds")
# change some parameter
result <- run_simulatrion(parameter)
saveRDS(result, "sim2.rds")
```

113 Using the package

114 We will now discuss the general structure and functiuonality of the package without going into
115 to much detail. A more detailed discussion can be found in the [User Guide](#).

116 The ODEs for the rates of change are specified in the function `bushplus_dynamic_model()`.
117 This augmented version of the model published in ([Bush et al., 2017](#)) can handle multiple
118 strains within each of the three functional groups, temporal variation in oxygen diffusivity,
119 and events.

120 In the following sections we describe the general usage of the package: running one simulation,
121 finding steady states across an environmental gradient, calculating measures of stability, and
122 visualisation.

Running one simulation

The individual simulation (`run_simulation()` function) is the working horse in this package. In this function, the ODEs are solved. The function needs only one parameter - an object as created by the function `new_runsim_parameter()`. One parameter of this object is the `strain_parameter` which can be created by the function `new_strain_parameter()`. For a detailed description of the parameter and how they are created please see the User Guide and which accompnies the package or is available at [User Guide](#)

After the paramter object has been defined, it can be used in the `run_simulation()` function. The function returns an object which is identical to the parameter, except of an additional slot containing the results. This design produces a fully reproducible object as it can be used instead of a parameter object to be fed back into the `run_simulation()` function to run the simulation again from the parameter used to generate the results from.

The function `plot_dynamics()` plots a single simulation run, as returned from the `run_simulation()` function. This functio is only provided as a convenience function to provide a way to easily see the results of a simulation run. An example plot resulting from this function is shown in @ref(fig:plot-dynamics).

Find a Steady State of the model

There are two methods for finding steady states. The first runs a separate simulation for each combination of starting conditions and oxygen diffusivity (let us term this the *Replication method*). The second runs only two simulations, with step-wise and slowly temporally increasing or decreasing oxygen diffusivities and recorded of state just before change to a new oxygen diffusivity (let us term this the *Temporal method*).

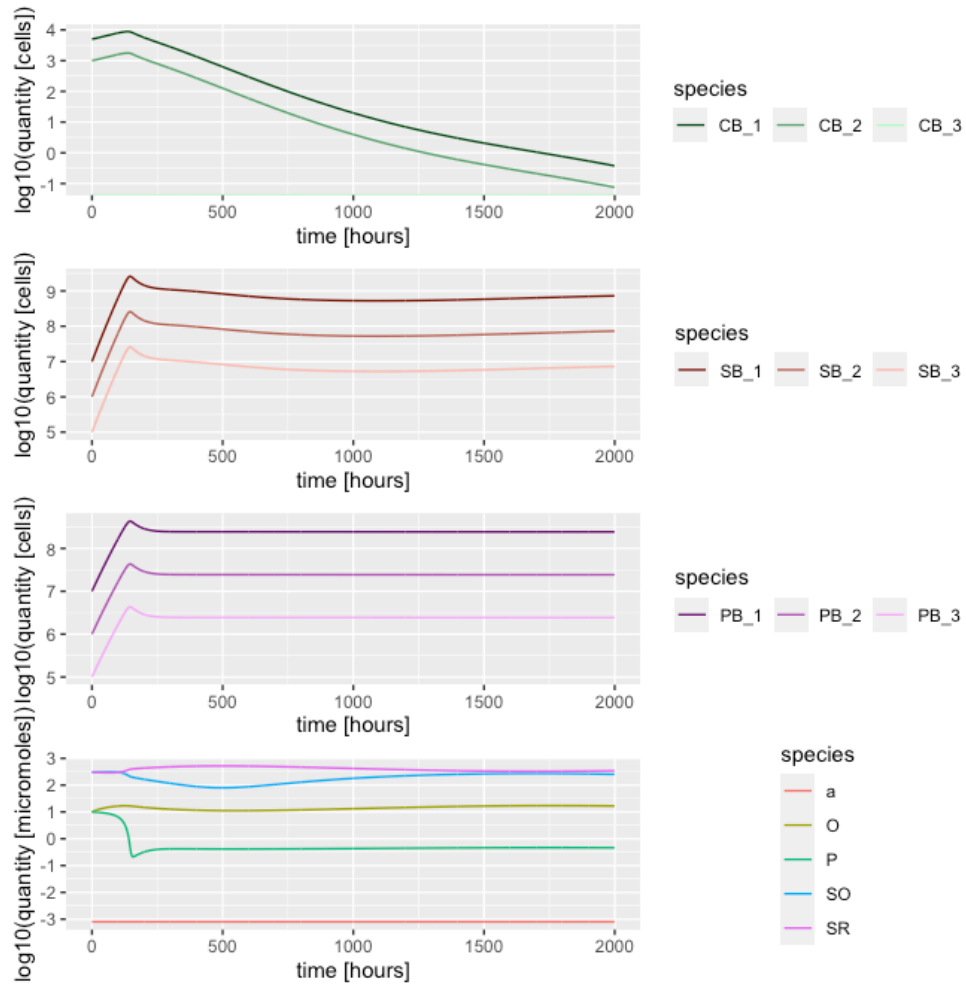


Figure 1: Plot of results of a simulation run using the function `plot_dynamics()`⁴. Details can be found in the “User Guide” section “Three strains per functional group”.

145 **Replication Method** The replication method is implemented in the function `run_replication_ssfind()`
146 which takes a parameter object as returned by the function `new_replication_ssfind_parameter()`
147 and the number of cores for multithreading the simulation.

148 **Temporal Method** The temporal method involves two simulations for a particular system
149 configuration (parameter set). In one simulation the oxygen diffusivity is *increased* in a step-
150 wise fashion. In the other it is *decreased* in a step-wise fashion. That is, oxygen diffusivity is
151 held at a constant level for long enough for steady state to be reached, that state is recorded,
152 and then a slightly higher (or lower) oxygen diffusivity value is set. Hence, at that time point,
153 the system is effectively started with initial conditions that are the state of the system in the
154 previous time step.

155 This is implemented in the function `run_temporal_ssfind()`, which takes a parameter object
156 as created by the function `new_temporal_ssfind_parameter()` and a number indicating the
157 .

158 For a more detailed walk-through of these two approaches and explanation please see the [User](#)
159 [Guide](#).

160 **Extract Stability Measures**

161 From the raw results returned by these `run_...()` functions, the stability measures can be
162 extracted by using the function `get_stability_measures()`. These measures include non-
163 linearity and hysteresis measures, of the response of the simulated system to environmental
164 change.

Use cases

The first two use cases come from the User Guide and the Partial Reproduction Vignettes. The third comes from a research article that relied on the package. All of these use cases can be expanded to larger numbers of strains per functional group.

Regime shifts during temporal environmental change

In the [User Guide](#) we used a one strain system (section “1 strain per functional group”) and three strain system (section “3 strains per functional group”) to analyse as an example the determination of the stable states during temporal environmental change (the oxygen diffusivity). From these simulations, we extracted measures of nonlinearity and hysteresis.

The extent of hysteresis depends on community composition

One of the reasons to develop this package was to reproduce the results presented in Bush et al. (2017), this was achieved as demonstrated in the [Partial Reproduction supplement](#). All aspects in the paper could be reproduced.

Effects of functional diversity on regime shifts

As discussed in the paper ([REF NEEDED, 2222](#)), the role biodiversity plays in abrupt regime shifts based on gradual changing environmental parameter is not well understood. This model (as part of the package) has been used to investigate these dynamics and the results are available in [REF NEEDED \(2222\)](#).

183 {»More details from the paper.«}

184 {»Romana will provide two or three sentences«}

185 **General usability and flexibility of the model**

186 The package is not intended to provide a modelling framework which can be adjusted easily
187 to all needs, but primarily a tool to implement the model used by (Bush et al., 2017) and to
188 extend it to our needs (REF NEEDED, 2222). Consequently, any more substantial changes
189 and adaptaitions, are likely to need a change in the source code.

190 Nevertheless, the model is structured in a way which builds on a modular structuere, so that
191 e.g. the event definition can easily be changed. or other aspects can be adjusted. All values in
192 the parameter object can be changed as needed and the general structure of the code should
193 make it not to difficult to adapt the model to other similar systems.

194 **Conclusions**

195 {»Dependant on journal«}

196 **References**

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