

1 MicroxanoX - an R package for simulating an
2 *MIC*Robial ecosystem that can occupy *OX*ic or
3 *ANOX*ic states.

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5 **Abstract**

Ca. 100 words.

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9 **1. TODO**

- 10 • **update links**
11 • **update cross references**

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2. Required Metadata

2.1. Current code version

Ancillary data table required for subversion of the codebase.

Code metadata		
Nr.	description	Please fill in this column
C1	Current code version	v0.9.0
C2	Permanent link to code/repository used for this code version	https://github.com/UZH-PEG/microxanox
C3	Code Ocean compute capsule	
C4	Legal Code License	CC BY 4.0
C5	Code versioning system used	git
C6	Software code languages, tools, and services used	R
C7	Compilation requirements, operating environments	R ($\geq 4.1.0$), ADD PACKAGES
C8	If available Link to developer documentation/manual	
C9	Support email for questions	Rainer.Krug@uzh.ch; Rainer@krugs.de

3. Motivation and significance

Many ecosystems are exposed to gradual changes of environmental variables, to which the responses are not always as gradual as the change of the environmental variable. One example where the gradual change of a single environmental variable is causing an abrupt change of the system is the switch from an aerobic to anaerobic system. This system has been investigated by Bush et al. [1]. We wanted to take this investigation one step further, and look at the role an increased biodiversity plays in these dynamics [2]. For this purpose, we developed this package.

The `microxanox` package is a package for simulating a three functional group system (*CB*: cyanobacteria, *PB*: phototrophic sulfur bacteria, and *SB*: sulfate-reducing bacteria) with four chemical substrates (*P*: phosphorus, *O*: oxygen, *SR*: reduced sulfur, *SO*: oxidized sulfur). It includes feedback between biogeochemical processes and is based on [1] (See [1] for a detailed discussion of the model).

The aims of the `microxanox` package are twofold. Firstly, the package aims at reproducing the results shown by [1], which is accomplished in the [vignette Partial reproduction of Bush et al.](#) Secondly, to take these results one step further, it includes new functionality to address our research question as published in [2].

For this, we extended the model and added functionality for:

- Multiple strains (effectively unlimited) per functional group.
- Adding temporally varying oxygen diffusivity.

- Adding random noise in substrate concentrations.
- Including immigration.
- Setting minimum population abundances.

In addition to the model itself, the package includes some functions to analyse the results as well as visualize the results to provide a starting point for customized visualizations based on own requirements.

4. Software description

{»Describe the software in as much as is necessary to establish a vocabulary needed to explain its impact.«}

We will discuss the general structure and functionality of the package here without going into too much detail. A more detailed discussion can be found in the [User Guide](#).

The model by Bush et al. [1] is based on ODEs for the rates of change which are specified in the function `bushplus_dynamic_model()`. This augmented version of the model published in [1] can handle multiple strains within each of the three functional groups, temporal variation in oxygen diffusivity, and events.

The package is not intended to provide a modelling framework which can be adjusted easily to all needs, but primarily a tool to implement the model used by [1] and to extend it to our needs [2]. Consequently, any more substantial changes and adaptations are likely to need a change in the source code.

Nevertheless, the source code is structured in modular, so that e.g. the event definition can easily be changed, or other aspects can be adjusted. All values in the parameter object can be changed as needed and the general structure of the code should make it not too difficult to adapt the model to other similar systems.

4.1. Software Architecture

{»Give a short overview of the overall software architecture; provide a pictorial component overview or similar (if possible). If necessary provide implementation details.«}

The framework used when writing this package aims at reproducibility of the results. It builds on the following main considerations:

1. all parameters needed to run a simulation or find a stable state are contained in a single parameter object. This object is created by using the functions `new_..._parameter()`, `new_initial_state()` and `new_strain_parameter()`. Which one of the `new_..._parameter()` functions has to be used when, will be discussed in the section `@ref(runsim)` and in more detail in the [User Guide](#).
2. The function call `run_...(parameter)` will run the simulation using the parameter as defined in the object `parameter`.

- 74 3. The return value of the `run...(parameter)` function is identical to the
75 parameter object plus an additional slot named `results` which contains
76 the results of the run
- 77 4. As the return value contains all parameter, it is possible to re-run the
78 simulation by simply running `run...(result)`.

79 The point that the results object contains all parameter needed to run the
80 simulation, promotes reproducibility and makes incremental changes of individual
81 parameters and re-running the simulations much easier.

82 In the following sections we describe the general usage of the package: running
83 one simulation, finding steady states across an environmental gradient, calculating
84 measures of stability, and visualization.

85 4.1.1. *Running one simulation*

86 A typical simulation would look as shown in @ref(fig:runsim_example).

```
87 #> [1] "./figures/simflow.pdf"
```

88 The individual simulation (`run_simulation()` function) is the working horse
89 in this package. In this function, the ODEs are solved. The function needs only
90 one argument - an object as created by the function `new_runsim_parameter()`.
91 One parameter of this object is the `strain_parameter` which can be created
92 by the function `new_strain_parameter()`. For a detailed description of the
93 parameter, their meaning and how they are created please see the User Guide
94 which accompanies the package or is available at [User Guide](#)

95 After the parameter object has been defined, it can be used in the `run_simulation()`
96 function. The function returns an object which is identical to the parameter,
97 except of an additional slot containing the results. This design produces a fully
98 reproducible object as it can be used instead of a parameter object to be fed
99 back into the `run_simulation()` function to run the simulation again from the
100 parameter used to generate the results from.

101 The function `plot_dynamics()` plots a single simulation run, as returned from
102 the `run_simulation()` function. This function is only provided as a convenience
103 function to provide a way to easily see the results of a simulation run. An
104 example plot resulting from this function is shown in @ref(fig:plot-dynamics).

105 4.1.2. *Finding a Steady State of the model*

106 There are two methods for finding steady states. The first runs a separate
107 simulation for each combination of starting conditions and oxygen diffusivity
108 (let us term this the *Replication method*). The second runs only two simulations,
109 with step-wise and slowly temporally increasing or decreasing oxygen diffusivities
110 and recorded of state just before change to a new oxygen diffusivity (let us term
111 this the *Temporal method*).

112 4.1.2.1. *Replication Method.* The replication method is implementad in the func-
113 tion `run_replication_ssfind()` which takes a parameter object as returned by
114 the function `new_replication_ssfind_parameter()` and the number of cores
115 for multithreading the simulation.



Figure 1: Typical flow of a simulation. Dark Grey boxes: commands necessary for simulation; Light Grey: Saving of parameter and results; Lightest Grey: Different non specified commands.

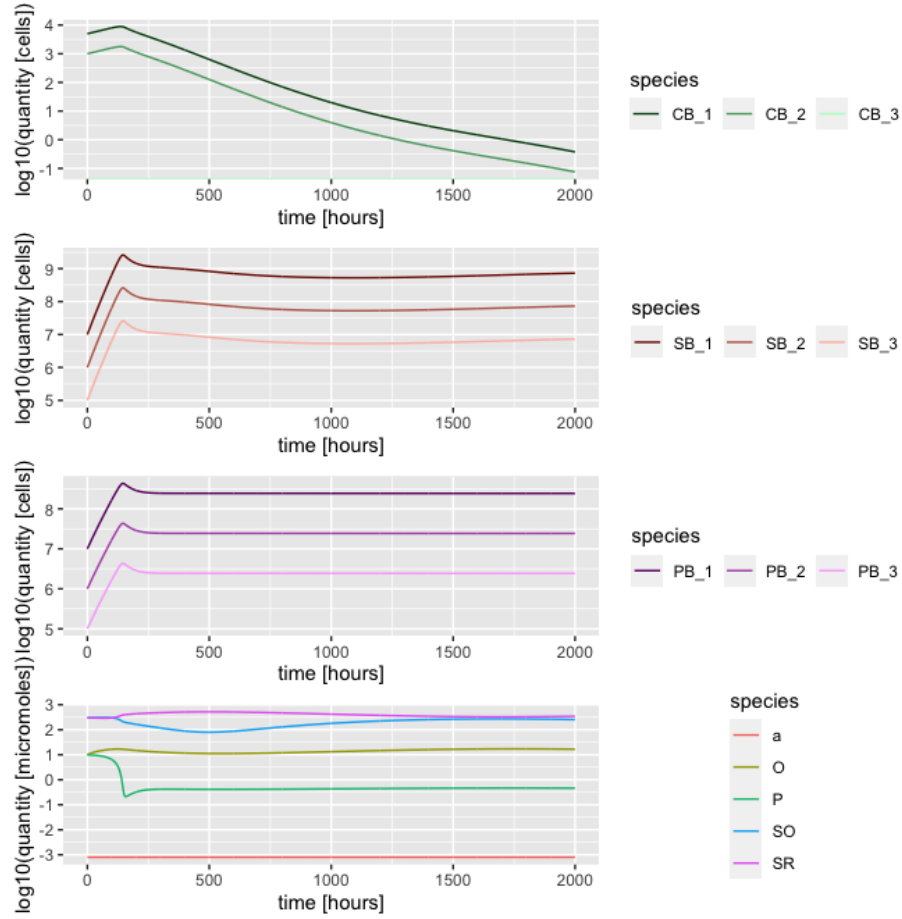


Figure 2: Plot of results of a simulation run using the function `plot_dynamics()`. Details can be found in the "User Guide" section "Three strains per functional group".

116 *4.1.2.2. Temporal Method.* The temporal method involves two simulations for a
 117 particular system configuration (parameter set). In one simulation the oxygen
 118 diffusivity is *increased* in a step-wise fashion. In the other it is *decreased* in
 119 a step-wise fashion. That is, oxygen diffusivity is held at a constant level for
 120 long enough for steady state to be reach, that state is recorded, and then a
 121 slightly higher (or lower) oxygen diffusivity value is set. Hence, at that time
 122 point, the system is effectively started with initial conditions that are the state
 123 of the system in the previous time step.

124 This is implemented in the function `run_temporal_ssfind()`, which takes a
 125 parameter object as created by the function `new_temporal_ssfind_parameter()`.

126 For a more detailed walk-through of these two approaches and explanation
 127 please see the [User Guide](#).

128 *4.1.3. Extracting Stability Measures*

129 From the raw results returned by these `run_...()` functions, the stability
 130 measures can be extracted by using the function `get_stability_measures()`.
 131 These measures include non-linearity and hysteresis measures, of the response of
 132 the simulated system to environmental change.

133 *4.2. Use Cases*

134 We will now show two use cases which illustrate applications of the package.
 135 All use cases can be used as starting points for other investigations of the behavior
 136 of the system.

137 The first two use cases are described in detail in the User Guide and the
 138 Partial Reproduction Vignettes. The third is taken from REF NEEDED [2]
 139 for which this R package was designed. All of these use cases can be expanded
 140 to larger numbers of strains per functional group and variable values van be
 141 changed.

142 *4.2.1. Regime shifts during temporal environmental change*

143 In the [User Guide](#) we used a one strain system (section “1 strain per functional
 144 group”) and three strain system (section “3 strains per functional group”) to
 145 determine as an example the stable states during temporal environmental changes
 146 (the oxygen diffusivity). From these simulatiuons, we extracted measures of
 147 nonlinearity and hysteresis. See Fig @ref(fig:plot-dynamics) as an example plot
 148 of the simulations.

149 We saved all parameter and result objects, so that all results are completely
 150 reproducible. The general flow of the experiment is identical to the one shown
 151 in @ref(fig:runsim_example).

152 *4.2.2. The extent of hysteresis depends on community composition*

153 One of the reasons to develop this package was to reproduce the results
 154 presented in Bush et al. [1]. This was achieved as demonstrated in the [Partial
 155 Reproduction supplement](#). All aspects in the paper could be reproduced and are
 156 shown in the vignette.

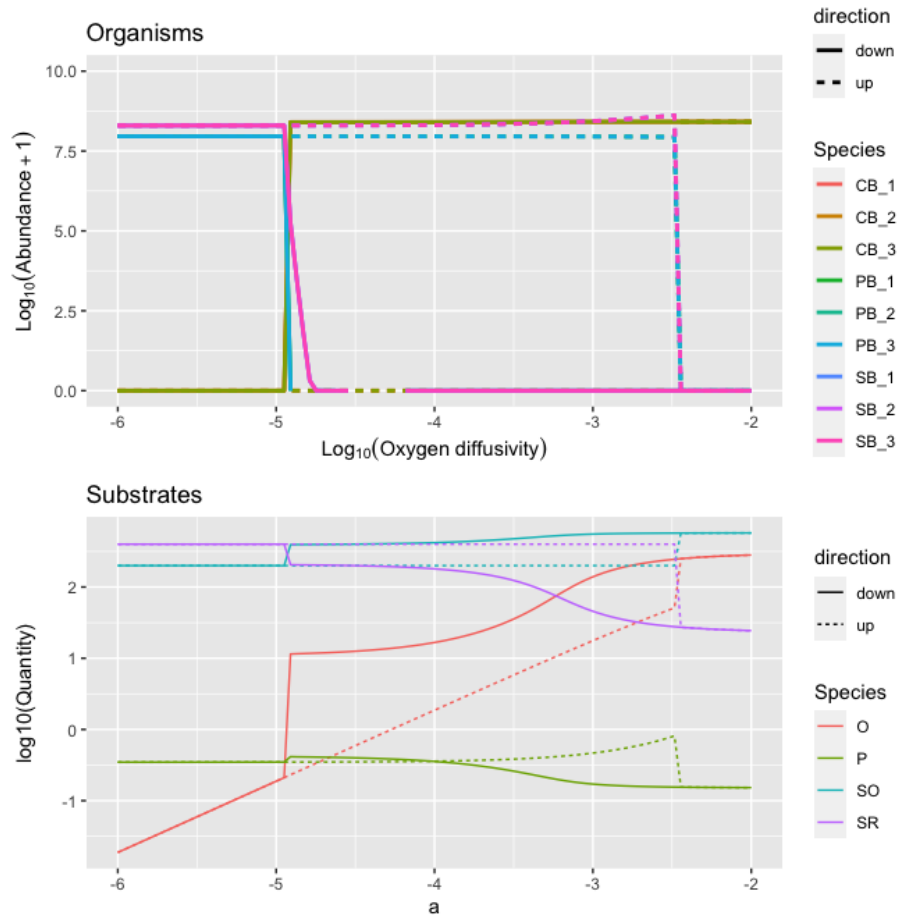


Figure 3: Plot of the stable states of the simulation runs under different oxygen diffusivity. The top graph are the Organisms (each initially with three strains) while the lower graph is the substrate availability under the same oxygen diffusivities. Details can be found in the "User Guide" section "Three strains per functional group".

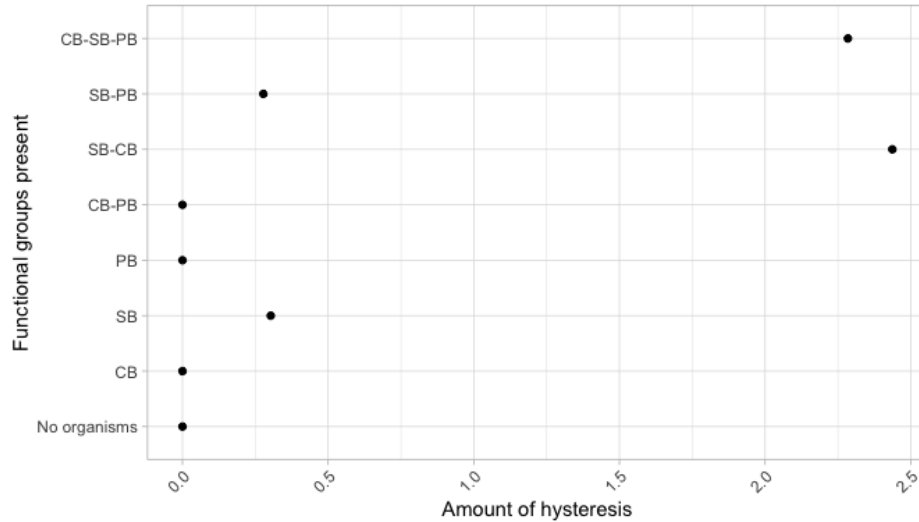


Figure 4: Hysteresis of all assessed combinations of variability.

Ass all objects were saved, results can be easily reproduced and parameter can be changed to assess the impact of these changes (e.g. to conduct a sensitivity analysis).

4.2.3. Effects of functional diversity on regime shifts

As discussed in the paper [2], the role biodiversity plays in abrupt regime shifts based on gradual changing environmental parameter is not well understood. This model (as part of the package) has been used to investigate these dynamics and the results are available in REF NEEDED [2].

{»More details from the paper.«} {»Romana will provide two or three sentences«}

5. Impact

{»This is the main section of the article and the reviewers weight the description here appropriately Indicate in what way new research questions can be pursued as a result of the software (if any). Indicate in what way, and to what extent, the pursuit of existing research questions is improved (if so). Indicate in what way the software has changed the daily practice of its users (if so). Indicate how widespread the use of the software is within and outside the intended user group. Indicate in what way the software is used in commercial settings and/or how it led to the creation of spin-off companies (if so).«}

178 The free and open source implementation and extension of the model used
179 in Bush et al. [1] provides the means of reproducing the results published while
180 at the same time provides the means of doing investigations which extend the
181 original publication, as done in REF NEEDED [2].

182 The combination of all parameter in a single parameter object as well as the
183 return of the simulation as a result object which inherits from the parameter
184 object and adds a results slot provides a relatively easy to use framework to
185 implement reproducible experiments.

186 6. Conclusions

187 Set out the conclusion of this original software publication.

188 7. Conflict of Interest

189 We wish to confirm that there are no known conflicts of interest associated
190 with this publication and there has been no significant financial support for this
191 work that could have influenced its outcome.

192 8. Acknowledgements

193 Optionally thank people and institutes you need to acknowledge.

194 References

- 195 [1] Timothy Bush, Muhe Diao, Rosalind J. Allen, Ruben Sinnige, Gerard
196 Muyzer, and Jef Huisman. Oxic-anoxic regime shifts mediated by feed-
197 backs between biogeochemical processes and microbial community dynamics.
198 *Nature Communications*, 8(1):789, October 2017. ISSN 2041-1723. doi:
199 10.1038/s41467-017-00912-x.
- 200 [2] Author REF NEEDED. REFERNECE NEEDED. *Journal of missing*
201 *references*, 2222.