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Anisotropic acoustic waves in rarefied nematic liquid crystals

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Why rarefied nematic liquid crystals?

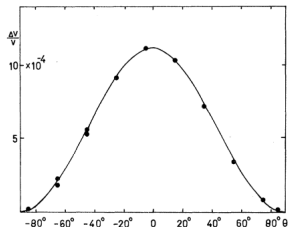


FIG. 2. Angular dependence of sound velocity. $T = 21^\circ\text{C}$, $\nu = 10$ MHz, and $H = 5$ kOe. θ is the angle between the field direction and propagation direction. Solid line is $12.5 \times 10^{-4} \cos^2 \theta$.

Acoustic waves travel in NLC faster in the direction parallel to the nematic director [MLS72].

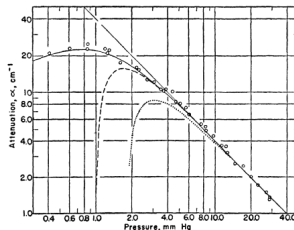
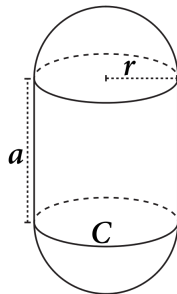


FIG. 1. Attenuation of sound at 1 Mc/sec. in helium. Circles—experimental results. Heavy full line—exact hydrodynamic. Light full line—first approximation, hydrodynamic and Burnett. Dashed line—second approximation, hydrodynamic. Dotted line—second approximation, Burnett.

First order theory better fits experimental data on acoustic attenuation at low pressure [Gre49].

In his seminal paper, Curtiss [Cur56] proposed a kinetic theory for spherocylindrical molecules as an idealisation of a polyatomic gas.

- ▶ He considered a larger configuration space made by **position**, **velocity**, the **Euler angles** for describing the orientation of each molecule, and the **angular velocity** with respect to a fixed coordinate system.
- ▶ Molecules would interact by **excluded volume**, which give rise to **short range interactions**, hence the **nematic ordering**.



This led Curtiss to formulate the following **Boltzmann** type equation,

$$\partial_t f + \nabla_{\mathbf{r}} \cdot (\mathbf{v}f) + \nabla_{\alpha} \cdot (\dot{\alpha}f) = C[f, f] \quad (1)$$

where $f(\mathbf{r}, \mathbf{v}, \alpha, \omega)$ is the usual first reduced distribution function and $C[f, f]$ is the collision operator defined as

$$C[f, f] = - \iiint\!\!\!\int (f'_1 f' - f_1 f)(\mathbf{k} \cdot \mathbf{g}) S(\mathbf{k}) d\mathbf{k} d\mathbf{v}_1 d\alpha_1 d\omega_1$$

with $\S(\mathbf{k})d\mathbf{k}$ being the surface element of the excluded volume and $\mathbf{g} = \mathbf{v} - \mathbf{v}_1$. Here without loss of generality the equation is stated in **absence of external force** and **torque**.

It is possible to prove that the following quantities are **collision invariants** for $C[f, f]$, i.e.

$$\iiint \psi^{(i)} d\mathbf{v}_1 d\boldsymbol{\omega}_1 d\boldsymbol{\alpha}_1 = 0.$$

- ▶ $\psi^{(1)} = 1$, the **number of particles** in the system;
- ▶ $\psi^{(2)} = m\mathbf{v}$, the **linear momentum**;
- ▶ $\psi^{(3)} = \mathbb{I}^1 \cdot \boldsymbol{\omega} + \mathbf{r} \times m\mathbf{v}$, the **angular momentum**;
- ▶ $\psi^{(4)} = \frac{1}{2}m\mathbf{v} \cdot \mathbf{v} + \frac{1}{2}\boldsymbol{\omega} \cdot \mathbb{I} \cdot \boldsymbol{\omega}$, the **kinetic energy of the system**.

¹The inertia tensor for the spherocylinder we are considering.

The hydrodynamic equations – notation

We first introduce the **number density**, i.e.

$$n(\mathbf{r}) = \iiint f(\mathbf{r}, \mathbf{v}, \alpha, \omega) d\mathbf{v} d\alpha d\omega.$$

Then we can give a meaning to the following *chevrons*, i.e.

$$\langle\langle \cdot \rangle\rangle(\mathbf{r}) := \frac{1}{n(\mathbf{r})} \iiint \cdot f(\mathbf{r}, \mathbf{v}, \alpha, \omega) d\mathbf{v} d\alpha d\omega.$$

Using this notation we can define **macroscopic stream velocity** and **macroscopic stream angular velocity** respectively as:

$$\mathbf{v}_0 := \langle\langle \mathbf{v} \rangle\rangle, \quad \omega_0 := \langle\langle \omega \rangle\rangle.$$

The Hydrodynamic Equations – Curtiss Balance Laws

Testing (1) against the first two **collision invariants** and integrating, Curtiss obtained the following **balance laws**:

$$\partial_t \rho + \nabla_{\mathbf{r}} \cdot (\rho \mathbf{v}_0) = 0,$$

$$\rho \left[\partial_t \mathbf{v}_0 + (\nabla_{\mathbf{r}} \mathbf{v}_0) \mathbf{v}_0 \right] + \nabla_{\mathbf{r}} \cdot (\rho \mathbb{P}) = 0,$$

where ρ is the **density** defined as $\rho(\mathbf{r}) = mn(\mathbf{r})$ and \mathbb{P} is the **pressure tensor** defined as $\mathbb{P} = \langle\langle \mathbf{V} \otimes \mathbf{V} \rangle\rangle$, with \mathbf{V} being the **peculiar velocity** $\mathbf{V} := \mathbf{v} - \mathbf{v}_0$.

The hydrodynamic equations – surprise balance laws

For the third collision invariant we took a different route than Curtiss, which led to the following balance law

$$\rho \left[\partial_t \boldsymbol{\eta} + (\nabla_{\mathbf{r}} \boldsymbol{\eta}) \mathbf{v}_0 \right] + \nabla_{\mathbf{r}} \cdot (\rho \mathbb{N}) = \boldsymbol{\xi}, \quad (2)$$

where $\boldsymbol{\eta}$ is the **macroscopic intrinsic angular momentum** defined as $\boldsymbol{\eta}(\mathbf{r}) = \langle \mathbb{I} \cdot \boldsymbol{\omega} \rangle$ and \mathbb{N} is the **couple tensor** defined as $\mathbb{N} = \langle \mathbf{V} \otimes (\mathbb{I} \boldsymbol{\omega}) \rangle$. Here $\boldsymbol{\xi}$ is defined in tensor notation as $\langle mn(\varepsilon_{lki} v_i v_k) \mathbf{e}_l \rangle$ and we proved that $\boldsymbol{\xi}$ vanishes (as stated by Curtiss in [Cur56]) in this particular setting.

Maxwell–Boltzmann distribution

In [Cur56] Curtiss gives an expression for the Maxwell–Boltzmann distribution, i.e. the distribution $f^{(0)}$ such that $C[f^{(0)}, f^{(0)}]$ vanishes:

$$f^{(0)}(\mathbf{v}, \boldsymbol{\omega}) = n \frac{\sin(\alpha_2) Q}{\int Q \sin(\alpha_2) d\alpha} \frac{m^{\frac{3}{2}}}{2\pi\theta} (\Gamma_1 \Gamma_2 \Gamma_3)^{\frac{1}{2}} \exp \left[-m \frac{|\mathbf{V}|^2}{2\theta} - \frac{\boldsymbol{\Omega} \cdot \mathbb{I} \cdot \boldsymbol{\Omega}}{2\theta} \right],$$

where the **peculiar angular velocity** defined as $\boldsymbol{\Omega} := \boldsymbol{\omega} - \boldsymbol{\omega}_0$, Γ_i are the moments of inertia of the spherocylinder we are considering and $Q := \exp \left[\frac{\boldsymbol{\omega}_0 \cdot \mathbb{I} \cdot \boldsymbol{\omega}_0}{2\theta} \right]$.

Notice in particular that we assumed $\boldsymbol{\omega}_0$ and the **kinetic temperature** $\theta = \langle \frac{m}{2} \mathbf{V} \cdot \mathbf{V} + \frac{1}{2} \boldsymbol{\Omega} \cdot \mathbb{I} \cdot \boldsymbol{\Omega} \rangle$ are fixed.

Momentum closure around the equilibrium

Now we can use the Maxwell–Boltzmann distribution to compute an approximation of the **pressure tensor** near the equilibrium, i.e.

$$\mathbb{P}^{(0)} = \theta \mathbf{Id}.$$

We can define the **pressure** as $p = \rho\theta$ and rewrite,

$$\left[\partial_t \mathbf{v}_0 + (\nabla_r \mathbf{v}_0) \mathbf{v}_0 \right] = -\frac{1}{\rho} \nabla p,$$

which is the well known **Euler equation** that if linearised yields the **wave equation**. **Unfortunately** the same procedure results in a **vanishing** $\mathbb{N}^{(0)}$.

Balance laws for kinetic temperature

We need another way to formulate the **constitutive relation** for the **couple tensor**. We begin by observing that from $\psi^{(4)}$ we get the following balance law:

$$\dot{\psi} + \nabla_r \mathbf{v}_0 : \mathbb{P} + \nabla_r \boldsymbol{\omega}_0 : \mathbb{N} - \nabla \cdot [\mathbb{P}^T \mathbf{v}_0 + \mathbb{N}^T \boldsymbol{\omega}_0] \geq 0$$

where $\psi = \langle\langle \theta \rangle\rangle$. We add ξ and observe that if we integrate with appropriate boundary condition the expression is the **rate of work** theorem that was the starting point of Leslie–Ericksen theory:

$$\dot{\psi} + \nabla_r \mathbf{v}_0 : \mathbb{P} + \nabla_r \boldsymbol{\omega}_0 : \mathbb{N} - \nabla \cdot [\mathbb{P}^T \mathbf{v}_0 + \mathbb{N}^T \boldsymbol{\omega}_0] + \xi \geq 0. \quad (3)$$

Since we are happy with our **pressure tensor** so far we make the following **ansatz**

$$\psi = \psi(\nu, \nabla \nu)$$

where ν is the **nematic director**. Expanding the total derivative and using the Ericksen identity we get the following expression in tensor notation

$$\dot{\psi} = \varepsilon_{iqp} \left[(\nu_q \frac{\partial \psi}{\partial (\nu_p)} + \partial_k (\nu_q) \frac{\partial \psi}{\partial (\partial_k \nu_p)}) \omega_i^0 + \nu_q \frac{\partial \psi}{\partial (\partial_k \nu_p)} \partial_k \omega_i^0 \right] \\ - \frac{\partial \psi}{\partial (\partial_k \nu_p)} \partial_q (\nu_p) \partial (\nu_q^0)$$

Substituting this expression into (3) and considering thermodynamic processes for which the exact divergences disappear, we get:

$$\left[\mathbb{P}_{ij} + \frac{\partial \psi}{\partial (\partial_j \nu_p)} \partial_i (\nu_p) \right] \partial_j (\nu_i) + \left[N_{ij} - \varepsilon_{iqp} \nu_q \frac{\partial \psi}{\partial (\partial_j \nu_p)} \right] \partial_j (\omega_i^0) \\ \left[P_{pq} - \frac{\partial \psi}{\partial (\partial_p \nu_k) \partial_q (\nu_k)} \right] \varepsilon_{iqp} \omega_i^0 \geq 0.$$

Since the above expression must hold for all thermodynamic processes for which the exact divergences disappear, we get the following **constitutive relations**:

$$\mathbb{P} = \nabla \boldsymbol{\nu}^T \frac{\partial \psi}{\partial (\nabla \boldsymbol{\nu})} + \mathbb{P}^{(0)}, \quad N_{ij} = \varepsilon_{iqp} \nu_q \frac{\partial \psi}{\partial (\partial_j \nu_p)} = \boldsymbol{\nu} \times \frac{\partial \psi}{\partial (\nabla \boldsymbol{\nu})}.$$

It can be shown that steady spherical solutions of (2) are of the form $\boldsymbol{\nu} = \frac{\mathbf{r}}{|\mathbf{r}|}$ and that $\nabla \boldsymbol{\nu}^T \nabla \boldsymbol{\nu} = \mathbf{Id} - \boldsymbol{\nu} \otimes \boldsymbol{\nu}$. Therefore for this particular case we have the following choice of **pressure tensor**:

$$\mathbb{P} = \mathbb{P}^{(0)} + \mathbf{Id} + \boldsymbol{\nu} \otimes \boldsymbol{\nu}.$$

If we linearise the **Euler equation** with this choice of **pressure tensor** we get the wave equation:

$$\partial_t^2 p - \nabla \cdot \left[(\mathbf{Id} + \boldsymbol{\nu} \otimes \boldsymbol{\nu}) \nabla p \right] = 0.$$

It is well known that a planar wave




$$p(\mathbf{r}, t) = A \cos(\mathbf{k} \cdot \mathbf{r} - \omega t)$$

travelling in a transversely isotropic medium has speed of sound

$$c_s = (1 + \cos(\theta))^2$$

where θ is the angle between \mathbf{k} and $\boldsymbol{\nu}$.

References

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