

On the convergence of eigenvalues for mixed formulations

PAPER BY: Daniele Boffi*, Franco Brezzi* and Lucia Gastaldi*

Presented by:
Umberto Zerbinati

*University of Pavia

Finite Element Reading Group, 25th of October 2022

Oxford Mathematics

Virtual Handouts



All code to reproduce what shown in this slides can be found in the following git repository:



https://github.com/UZerbinati/BrezziBoffiGastaldi

On the convergence of eigenvalues for mixed formulations Mixed Eigenvalue Problem



- Solved Bernstein's minimal surface problem together with Enrico Bombieri.
- Solved 19th Hilbert problem, regarding the regularity of elliptic PDE.
- He is the father of modern calculus of variation and he is responsible for introducing the notion of Γ-convergence.



Enio De Giorgi 1928–1996

The Abstract Problem Mixed Eigenvalue Problem



- ▶ Two Hilbert spaces Φ and Ξ are considered.
- Two continuous bilinear forms are also considered,

$$a(\cdot,\cdot):\Phi\times\Phi\to\mathbb{R}, \qquad b(\cdot,\cdot):\Phi\times\Xi\to\mathbb{R}.$$

$$A: \Phi \to \Phi^*, \ (A\phi): \Phi \to \mathbb{R}, \ (A\phi)\varphi \mapsto \mathsf{a}(\phi,\varphi), \\ B: \Phi \to \Xi^*, \ (B\phi): \Xi \to \mathbb{R}, \ (B\phi)\xi \mapsto \mathsf{b}(\phi,\xi), \\$$

• We assume $a(\cdot, \cdot)$ is **symmetric** and **positive semidefinite**.

The Abstract Problem Mixed Eigenvalue Problem



Given any
$$(f,g) \in \Phi^* \times \Xi^*$$
 find $(\psi,\chi) \in \Phi \times \Xi$ such that
$$\begin{cases} a(\psi,\varphi) + b(\varphi,\chi) = \langle f,\varphi \rangle & \forall \varphi \in \Phi \\ b(\psi,\xi) = \langle g,\xi \rangle & \forall \xi \in \Xi \end{cases}$$
 (1)

Given any
$$(f,g) \in \Phi^* \times \Xi^*$$
 find $(\psi,\chi) \in \Phi \times \Xi$ such that
$$\begin{cases} A\psi + B^T\chi = f \\ B\psi = g \end{cases}$$

The Inf-Sup Stability A Gentile Introduction to **Brezzi**'s Theory



Banach Closed Range Theorem

Given a closed linear operator $B:\Phi\to\Xi^*$, the following statements are equivalent:

- ▶ Range(B) is closed in Ξ^* ,
- ► Range(B) = $\left[Ker(B^T)\right]^0$, where Z^0 is the the **polar** set of Z, i.e. $Z^0 = \left\{f \in Z^* \text{ s.t } \langle f, z \rangle = 0 \ \forall z \in Z\right\}$.
- ▶ it exists $L_B \in \mathcal{L}\Big(Range(B), Ker(B)^{\perp}\Big)$ and $\beta \geq 0$ such that:

$$\beta \|L_B g\|_{\Phi} \leq \|g\|_{\Xi^*}, \ \forall g \in Range(B).$$

The Inf-Sup Stability A Gentile Introduction to **Brezzi**'s Theory



Brezzi's **Theorem**

Assuming that the range of B is Ξ^* and that $a(\cdot, \cdot)$ is coercive in the kernel of B, then it exists one and only one solution to (1).

How do can one verify that B is a **onto**?

Inf-Sup **Condition**

The operator B is surjective if and only if it exists $\beta > 0$ such that

$$\inf_{\xi\in\Xi_{\varphi\in\Phi}}\sup_{\|\varphi\|_{\Phi}\|\xi\|_{\Xi}}\geq\beta$$

The Discrete Case Inf-Sup Stable Finite Element Pairs



- ▶ We introduce two discrete spaces $\Phi_h \subset \Phi$ and $\Xi_h \subset \Xi$.
- Previous result holds also for the discrete problem,

Given any $(f,g) \in \Phi^* \times \Xi^*$ find $(\psi_h, \chi_h) \in \Phi_h \times \Xi_h$ such that

$$\begin{cases} a(\psi_h, \varphi_h) + b(\varphi_h, \chi_h) = \langle f, \varphi_h \rangle & \forall \varphi \in \Phi_h \\ b(\psi_h, \xi_h) = 0 & \forall \xi \in \Xi_h \end{cases}$$
 (2)

The pair (Φ_h, Ξ_h) is **inf-sup stable** if it exists β_h independent from h such that:

$$\inf_{\xi_h \in \Xi_h \varphi_h \in \Phi_h} \sup_{\|\varphi_h\|_{\Phi} \|\xi_h\|_{\Xi}} \geq \beta_h$$

On the Necessity of the Inf-Sup For the Source Problem



We introduce the **solution operator**, i.e.

$$S: \Phi^* \times \Xi^* \to \Phi \times Xi \text{ s.t } S(f,g) = (\psi,\chi) \text{ as in } (1),$$

 $S_h: \Phi_h^* \times \Xi_h^* \to \Phi_h \times Xi \text{ s.t } S_h(f,g) = (\psi_h,\chi_h) \text{ as in } (2).$

Proposition Necessity of the Inf-sup

If it exists a constant C>0 such that for all $(f,g)\in\Phi^*\times\Xi^*$ and for all h>0

$$||S_h(f,g)||_{\Phi \times \Xi} \le C \Big(||f||_{\Phi_h^*} + ||g||_{\Xi_h^*} \Big)$$
 (3)

then the bilinear form $a(\cdot, \cdot)$ is elliptic in the kernel of B and the pair (Φ_h, Ξ_h) is **inf-sup** stable.

On the Necessity of the Inf-Sup For the Source Problem



When dealing with an mixed problem such that $a(\cdot, \cdot)$ is elliptic in the kernel the **inf-sup stability** condition is not only **sufficient** it is also **necessary**.

Remark

When proving the existence and uniqueness of solution for 1 and 2, hypothesis can be weaken, i.e. we can require

 $A: Ker(B) \rightarrow Ker(B)^*$ to be an isomorphism.

Eigenvalue Problems Abstract Setting for Compact Selfadjoint Operators



We are now ready to introduce an eigenvalue problem. Given an Hilbert space H and a selfadjoint compact operator $T:H\to H$, we call eigenvalue of T the $\lambda\in\mathbb{R}$ such that

$$\lambda Tu = u \text{ with } u \in H \setminus \{0\}.$$

In particular it is well known that for the above described operator T it exists a sequence $\{\lambda_i\}_{i\in\mathbb{N}}$ such that

$$\lambda_i T u_i = u_i,$$
 $\lim_{i \to \infty} \lambda_i = +\infty \text{ and } \lambda_i \ge 0 \ \forall i \in \mathbb{N}.$ (4)

Eigenvalue Problems The Discrete Case



We now consider for all h > 0 the selfadjoint non negative operator $T_h: H \to H$, with finite range H_h . Let's denote N(h) is the dimension of H_h . We are interested in the eigenvalues,

$$\lambda^h T u^h = u^h \text{ with } u^h \in H_h \setminus \{0\}.$$

The same characterization of the eigenvalue presented above holds also in the discrete case.

Eigenvalue Problems Discrete Approximation



If we assume that the discrete approximation operator T_h converges to T with respect to the norm of $\mathcal{L}(H,H)$, i.e.

$$\lim_{h\to 0}\|T-T_h\|_{\mathcal{L}(H,H)}=0$$

then $\forall \varepsilon > 0$ and $\forall n \in \mathbb{N}$ it exists $h_0 > 0$ such that $\forall h > h_0$

$$\max_{i=1,\dots,m(N)} \left| \lambda_i - \lambda_i^h \right| \le \varepsilon, \tag{5}$$

$$\delta\left(\bigoplus_{i=1}^{m(N)} E_i, \bigoplus_{i=1}^{m(N)} E_i^h\right) \le \varepsilon.$$
 (6)

m(N) is the number of eigenvalues corresponding to N distinct ones, $E_i = \langle u_i \rangle$ and $E_i^h = \langle u_i^h \rangle$. The converse also holds true.

Eigenvalue Problems Necessity and Sufficiency of the Inf-Sup



We consider two Hilbert space H_{Φ} and H_{Ξ} such that we cam identify H_{Φ} with H_{Φ}^* , H_{Ξ} with H_{Ξ}^* and

$$\Phi \subset H_{\Phi} \subset \Phi^*, \qquad \Xi \subset H_{\Xi} \subset \Xi^*.$$

Notice often either H_{Φ} can't be Φ or H_{Ξ} can't be Ξ .

Proposition Convergence of Discrete Eigenvalue Problem

Assuming that $a(\cdot,\cdot)$ is elliptic in the kernel of B_h and the discrete inf-sup condition holds then S_h converges in $\mathcal{L}(H_{\Phi},H_{\Xi})$ to S if and only if $S:H_{\Phi}\times H_{\Xi}\to H_{\Phi}\times H_{\Xi}$ is compact. The converse holds true.

The Story Doesn't End Here Motivating Example – Stokes Eigenvalue Problem with Q1-P0



```
\begin{array}{lll} \mathsf{msh} &= & \mathsf{UnitSquareMesh}(10,10,\mathsf{quadrilateral=True}) \\ \mathsf{V} &= & \mathsf{VectorFunctionSpace}(\mathsf{msh}, \ "Q", \ 1) \\ \mathsf{Q} &= & \mathsf{FunctionSpace}(\mathsf{msh}, \ "DG", \ 0) \\ \mathsf{X} &= & \mathsf{V*Q} \\ \mathsf{u},\mathsf{p} &= & \mathsf{TrialFunctions}(\mathsf{X}) \\ \mathsf{v},\mathsf{q} &= & \mathsf{TestFunctions}(\mathsf{X}) \\ \mathsf{a} &= & (\mathsf{inner}(\mathsf{grad}(\mathsf{u}), \ \mathsf{grad}(\mathsf{v})) - \mathsf{inner}(\mathsf{p}, \ \mathsf{div}(\mathsf{v})) \\ &+ & \mathsf{inner}(\mathsf{div}(\mathsf{u}), \ \mathsf{q})) * \mathsf{dx} + 1e8 * \mathsf{inner}(\mathsf{u}, \mathsf{v}) * \mathsf{ds} \\ \mathsf{m} &= & \mathsf{inner}(\mathsf{u}, \mathsf{v}) * \mathsf{dx} \\ \mathsf{sol} &= & \mathsf{Function}(\mathsf{X}) \\ \end{array}
```

The Story Doesn't End Here Motivating Example – Stokes Eigenvalue Problem Q1-P0



```
A = assemble (a)
M = assemble (m)
Asc, Msc = A.M. handle, M.M. handle
E = SLEPc.EPS().create()
E.setType(SLEPc.EPS.Type.ARNOLDI)
E.setProblemType(SLEPc.EPS.ProblemType.GHEP);
E.setOperators(Asc,Msc)
PC = ST.getKSP().getPC();
PC.setType("svd");
E.setST(ST);
E.solve();
```

The Story Doesn't End Here Motivating Example – Stokes Eigenvalue Problem Q1-P0



N	Reference	Q1-P0
1	52.34468	53.56885
2	92.12438	97.57386
3	92.12438	97.57386
4	128.209	97.573867

- ▶ The numerical experiment for the Q1-P0 are obtained using a 10×10 uniform square grid, while the reference value are obtained using Hood-Taylor finite element pair on a 20×20 square mesh.
- ▶ As $h \rightarrow 0$ we would see a degraded rate of convergence.

Two Type Of Problems Problem of Type $(f \ 0)$



More often the note in practice when we are interested in eigenvalue problem where either f or g is zero. For example we call problem of type $(f \ 0)$,

Find
$$(\psi, \chi) \in \Phi \times \Xi$$
 and $\lambda \in \mathbb{R}$ such that
$$\begin{cases} a(\psi, \varphi) + b(\varphi, \chi) = \lambda \langle \psi, \varphi \rangle & \forall \varphi \in \Phi, \\ b(\psi, \xi) = 0 & \forall \xi \in \Xi. \end{cases}$$
(7)

Which $\underline{\operatorname{can not}}$ be cast as an eigenvalue problem of the form of (1).

Two Type Of Problems Problem of Type $(f \ 0)$



To recast (7) as an eigenvalue problem we need to introduce

$$M_{\Phi}: \Phi^* \to \Phi^* \times \Xi^*$$
 $M_{\Phi}^*: \Phi \times \Xi \to \Phi$ $f \mapsto (f, 0)$ $(\varphi, \xi) \mapsto \varphi$

then we can study the eigenvalue problem corresponding to

$$T_{\Phi} := C_{\Phi}^* \circ S \circ C_{\phi} : \Phi^* \to \Phi \tag{8}$$

▶ What are the necessary and sufficient conditions to solve an eigenvalue problem like (7) ?



Proposition Existence of Solutions

If $a(\cdot, \cdot)$ is elliptic in the kernel of B_h , then problem (7) admits at least one solution (ψ_h, χ_h) . Moreover ψ in uniquely determined by f and

$$\|\psi_h\|_{\Phi} \leq C\|f\|_{\Phi_h^*}.$$

Furthermore if it exists C>0 such that for every h>0 and for every $(\psi_h,\chi_h,f)\in\Phi_h\times\Xi_h\times\Xi^*$ the above inequality is verified then the operator T_Φ^h is defined for all element in Φ and a elliptic in the kernel of B_h .

Problem of Type $(f \quad 0)$ Weak Approximability



Definition Weak Approximability

Let Ξ_0^H be the range of $C_{\Xi}^* \circ S \circ C_{\Phi}$. We say that Ξ_0^H verifies the **weak approximability** if for every $\chi \in \Xi_0^H$

$$\sup_{\varphi_h \in \mathit{Ker}(\mathcal{B}_h)} \frac{b(\varphi_h, \chi)}{\|\varphi\|_{\Phi}} \leq \omega_1(h) \|\chi\|_{\Xi_0^H}, \ \lim_{h \to 0} \omega_1(h) = 0.$$

Remark

The above definition is an approximability condition in fact using the fact that $b(\varphi_h,\chi^I)=0$ for all $\chi^I\in\Xi_h$ to rewrite the weak approximability as for all $\chi\in\Xi_0^H\inf_{\chi^I\in\Xi_h}\|\chi-\chi^I\|_{\Xi}\leq\omega_1(h)\|\chi\|_{\Xi_0^H}.$

25th of October 2022 Mixed Eigenvalue Problem



Definition Strong Approximability

Let Φ_0^H be the range of $C_{\Phi}^* \circ S \circ C_{\Phi}$. We say that Φ_0^H verifies the **strong approximability** if for every $\psi \in \Phi_0^H$

$$\inf_{\psi^I \in Ker(B_h)} \left\| \psi - \psi^I \right\|_{\Phi} \le \omega_2(h) \|\psi\|_{\Phi_0^H}, \ \lim_{h \to 0} \omega_2(h) = 0.$$



Proposition Convergence

If $a(\cdot,\cdot)$ is elliptic in the kernel of B_h and the weak approximability of Ξ_0^H and strong approximability of Φ_0^H are verified, then for all $f\in H_\Phi$

$$\left\| T_{\Phi}f - T_{\Phi}^{h}f \right\|_{\Phi} \leq \omega_{3}(h), \lim_{h \to 0} \omega_{3}(h) = 0.$$
 (9)

Vice versa if the sequence T_{Φ}^h is bounded in $\mathcal{L}(\Phi^*, \Phi)$ and converges uniformly to T_{Φ} in $\mathcal{L}(\Phi^*, \Phi)$ then $a(\cdot, \cdot)$ is elliptic in the kernel of B_h , moreover the strong and weak approximability conditions are verified respectively for Φ_0^H and Ξ_0^H .

An additional Example

A Connection with Charlie's presentation



We solve the Stokes eigenvalue problem using Scott-Vogelious(**ish**) finite element pair and criss-cross. mesh.

```
\begin{array}{lll} msh &=& \textbf{UnitSquareMesh}(10,10,\text{diagonal="cross"}) \\ V &=& \textbf{VectorFunctionSpace}(msh, "CG", 4) \\ Q &=& \textbf{FunctionSpace}(msh, "DG", 3) \\ X &=& V*Q \\ u,p &=& \textbf{TrialFunctions}(X) \\ v,q &=& \textbf{TestFunctions}(X) \\ a &=& (\text{inner}(\text{grad}(u), \text{grad}(v)) - \text{inner}(p, \text{div}(v)) \\ &+& \text{inner}(\text{div}(u), q))*dx + 1e8*\text{inner}(u,v)*ds \\ m &=& \text{inner}(u,v)*dx \\ sol &=& \textbf{Function}(X) \end{array}
```