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(base) ubaid_hunts@ubaid-air Examples % python3 rll.py
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Imported GTPyhop version 1.0.
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```
Messages from find_plan will be prefaced with 'FP>'.
```

```
Messages from run_lazy_lookahead will be prefaced with 'RL  
L>'.
```

```
FP> find_plan, verbose=1:
```

```
    state = state1
```

```
    todo_list = [('lazy_navigate', '(4, 4)')]
```

```
FP> result = [('move', 'UP'), ('move', 'UP'), ('move', 'UP'  
'), ('move', 'UP'), ('move', 'RIGHT'), ('move', 'RIGHT'),  
(('move', 'RIGHT'), ('move', 'RIGHT'))]
```

```
Generated Plan (Lazy): [('move', 'UP'), ('move', 'UP'), ('  
move', 'UP'), ('move', 'UP'), ('move', 'RIGHT'), ('move',  
['RIGHT'), ('move', 'RIGHT'), ('move', 'RIGHT')]
```

```
Number of Steps (Lazy): 8
```

```
Total Evaluated Moves (Lazy): 26
```