Udari Madhushani Sehwag

RESEARCH INTEREST

My research vision is to embed AI agents with the ability to enhance their capabilities through collective intelligence, ultimately enabling them to seamlessly coexist with humans, augmenting their cognitive and physical capabilities. In my research work I primarily focus on developing socially intelligent and aligned AI agents. **Key Topics**: Generative AI (LLMs - collective alignment, social intelligence, human behaviour proxy, policy and governance, responsible AI), Multi-agent reinforcement learning (generalization, evolution of cooperation, communication), Game theory, Robotics, Bandit theory.

PhD thesis: Learning through social interactions and learning to socially interact in multi-agent learning

EDUCATION

Degree	Institution	Years
Ph.D. (Artificial Intelligence)	Princeton University, USA	2017 - 2023
M.A. (Artificial Intelligence)	Princeton University, USA	2017 - 2019
B.Sc. (Robotics & Control Theory)	University of Peradeniya, Sri Lanka	2011 - 2015

Honors

Graduate Honors (Princeton University)

• Harold W. Dodds Fellowship (prestigious honorific fellowship from Graduate School)	2021-22
• Britt and Eli Harari Fellowship	2020-21
• Larisse Rosentweig Klein Memorial Award	Fall 2019
Martin Summerfield Graduate Fellowship	2018-19
• Athena-Feron Prize for Mathematical Excellence	Fall 2018
• Elliotte Robinson Little '25 Student Aid Fund Fellowship	2017-18

Other Awards

• Presidential Award for Scientific Research (Sri Lanka)	2019
• Best Undergraduate Project Award (IEEE Sri Lanka Section)	December 2015

EXPERIENCE

Visiting Postdoc

• Stanford University, California, USA August 2023 - Present Focus: Collective alignment, Socially intelligent generative agents, Policy and governance, Safety, Robotics

Research Scientist

JPMorgan AI Research, New York, USA
 Focus: Collective alignment, Socially intelligent generative agents, Policy and governance, LLMs as human proxy, Safety

Research Internships

Google Deepmind, London, UK
 Mentors: Daniel Hennes and Edgar Duenez-Guzman
 Project: Zero-shot Generalization in Mixed Motive Games

May 2022 - Sep 2022

• Facebook AI Research, Menlo Park, California, USA	May 2021 - August 2021
Mentors: Kalesha Bullard and Roberto Calandra Project: Incentivizing Coordination in Multi-Agent Reinforcement Learning	
• Siemens, Princeton, New Jersey, USA	May 2020 - August 2020
Mentors: Biswadip Dey and Amit Chakraborty	
Project: Using Hamiltonian Monte Carlo Sampling for Reinforcement Learning	Problems in High-dimension
Assistant in Research	
· · · · · · · · · · · · · · · · · · ·	September 2017 - May 2023 anuary 2016 - August 2017
Guest Lectures	anaar, 2010 11agast 2011
• MAE 545 Collective Intelligence: Dynamics and Control of Multi-Agent Syste (Princeton University)	ms Fall 2022
Assistant in Teaching	
• MAE 542 Advanced Dynamics (Princeton University)	Fall 2020
• MAE 502/APC 506 Mathematical Methods of Engineering Analysis (Princeto	
• MAE 345/MAE 549 Introduction to Robotics (Princeton University)	Fall 2019
• EE 554 Microwave Techniques (University of Peradeniya), Sri Lanka Octo	ober 2015 - December 2015
OUTREACH	
Mentoring	
Stanford University	
• Arjun Karanam (M.Sc. Computer Science)	2024
University of California, Berkeley	
 Marwa Abdulhai (Ph.D. Electrical Engineering and Computer Sciences) Nivasini Ananthakrishnan (Ph.D. Electrical Engineering and Computer Sciences) 	2024 ces) 2024
University of Maryland, College Park	
 Yuancheng Xu (Ph.D. Applied Mathematics) Souradip Chakraborty (Ph.D. Computer Science) 	2024 2024
University College London, UK	
• Oliver Slumbers (Ph.D. Computer Science)	2024
Princeton University	
• Hui Yuan (Ph.D. Electrical and Computer Engineering)	2024
• Justin Lidard (Ph.D. Mechanical Engineering)	2021-23
 Kathryn Wantlin (M.Sc. Computer Science) Sarah Dillender (B.S.E. Mechanical Engineering) 	2021-22 2020-21
Thesis: Message passing structures for improved policy finding in decentralize	
• Gargi Sadalgekar, Samarie Wilson and Jacob Walrath (B.S.E. Mechanical Eng	
Thesis: Decision making and task allocation in a multi-robot system.	
Peradeniya University, Sri Lanka	
• Lasitha Weerakon (Post graduate, Mechanical Engineering)	2016-17
 Isuru Basnayake (Post graduate, Mechanical Engineering) Kusal Tennakoon (Post graduate, Mechanical Engineering) 	2016-17 2016-17
Commitment to Diversity and Inclusion	2010 11
• Co-organized "Re-education Monthly Book Club" aimed towards improving a	wareness of 2020-23
implicit biases (Princeton University)	
• Co-organized the workshop "Diversity and Mentorship" at American Control	
• Co-organized the workshop "Inclusive Teaching" (Princeton University)	Jan 2021
Leadership Roles	anna an
 Committee member of Women in STEM Leadership Council (Princeton University) Committee member of Graduate Women in Science & Engineering (Princeton 	* /
- Commission member of Graduate women in belence & Engineering (1 infector	2020-20

• Future Digileaders Training (Stockholm, Sweden)

• Founder of EE Instructors Scholarship (Peradeniya University, Sri Lanka)

November 2019

2016

Volunteer for

World Maker FaireAmerican Control Conference

September 2018

June 2018

ACADEMIC SERVICES

Program committee Member of

- Games Agents and Incentives Workshop (GAIW) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2023, 2024
- Adaptive and Learning Agents Workshop (ALA) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2022, 2023
- Cooperative AI Workshop at Conference on Neural Information Processing Systems (NeurIPS) 2021

Co-organizer of

- Special issue on "Collective Artificial Intelligence" at Proceedings of National Academy of Science (PNAS) 2023
- Proceedings of National Academy of Science (PNAS) special issue symposium on "Collective Artificial Intelligence" 2022

Editor for

Journal: Proceedings of National Academy of Science (PNAS) 2023, 2024

Reviewer for

Journal: Automatica, IEEE Transactions on Automatic Control, IEEE Control Systems Letters, Journal of Field Robotics

Conference: Conference on Neural Information Processing Systems, International Conference on Machine Learning, International Conference on Learning Representations, IEEE Conference on Decision and Control, American Control Conference, International Conference on Intelligent Robots and Systems, European Control Conference, International Conference of Industrial and Information Systems

Member of

IEEE (Institute of Electrical and Electronics Engineers), IEEE Young Professionals, IEEE Women in Engineering, APS (American Physical Society)

PUBLICATIONS

Technical Reports

[T1] Melting Pot 2.0

John Agapiou, Alexander Vezhnevets, Duéñez-Guzmán, Jayd Matyas, Yiran Mao, Peter Sunehag, Raphael Köster, **Udari Madhushani**, Kavya Kopparapu, Ramona Comanescu, DJ Strouse, Michael B. Johanson, Sukhdeep Singh, Julia Haas, Igor Mordatch, Dean Mobbs, Joel Z Leibo ArXiv 2023

Peer-reviewed Journal Articles

[J4] Autocratic Learning and Unilateral Incentive Alignment in Two-player Stochastic Games

Alex McAvoy, **Udari Madhushani Sehwag**, Christian Hilbe, Wolfram Barfuss, Krishnendu Chatterjee, Qi Su, Naomi Ehrich Leonard, Joshua B. Plotkin

Proceedings of National Academy of Science - Special issue on Collective Artificial Intelligence (PNAS) 2024 (accepted for publication)

[J3] Collective Cooperative Intelligence

Wolfram Barfuss, Jessica Flack, Chaitanya S. Gokhale, Lewis Hammond, Christian Hilbe, Joel Leibo, Tom Lenaerts, Naomi Leonard, Simon Levin, **Udari Madhushani Sehwag**, Alex McAvoy, Janusz M. Meylahn, Fernando P. Santos

Proceedings of National Academy of Science - Special issue on Collective Artificial Intelligence (PNAS) 2024 (accepted for publication)

[J2] Heterogeneous Explore-Exploit Strategies on Multi-Star Networks Udari Madhushani, Naomi Leonard IEEE Control Systems Letters, 2021.

[J1] Semi-globally Exponential Trajectory Tracking for a Class of Spherical Robots Udari Madhushani, Sanjeeva Maithripala, Janaka Wijayakulasooriya, Jordan Berg Automatica, 2017.

Peer-reviewed Conference Articles

- [C15] SORRY-Bench: A Systematic Evaluation on Large Language Model Safety Refusal Behaviors Tinghao Xie, Xiangyu Qi, Yi Zeng, Yangsibo Huang, **Udari Madhushani Sehwag**, Boyi Wei, Luxi He, Kaixuan Huang, Dacheng Li, Ying Sheng, Bo Li, Danqi Chen, Kai Li, Peter Henderson, Prateek Mittal (Under review at NeurIPS 2024)
- [C14] O3D: Offline Data-Driven Discovery and Distillation for Sequential Decision Making with Large Language Models
 Yuchen Xiao, Yanchao Sun, Mengda Xu, Udari Madhushani Sehwag, Jared Vann, Deepeka Garg, Sumitra Ganesh
 Conference on Language Modeling COLM 2024.
- [C13] On Using Hamiltonian Monte Carlo Sampling for Reinforcement Learning Udari Madhushani, Biswadip Dey, Naomi Leonard, Amit Chakraborty Conference on Decision and Control, (CDC) 2022. (Invited Paper)
- [C12] A Regret Minimization Approach to Multi-Agent Control Udaya Ghai, Udari Madhushani, Naomi Leonard, Elad Hazan International Conference on Machine Learning, (ICML) 2022.
- [C11] Provably Efficient Multi-Agent Reinforcement Learning with Fully Decentralized Communication Justin Lidard, Udari Madhushani, Naomi Leonard American Control Conference, (ACC) 2022.
- [C10] One More Step Towards Reality: Cooperative Bandits with Imperfect Communication Udari Madhushani, Abhimanyu Dubey, Naomi Leonard, Alex Pentland Conference on Neural Information Processing Systems, (NeurIPS) 2021.
- [C9] Multi-robot Learning and Coverage of Unkown Fields Maria Santos, Udari Madhushani, Alessia Benevento, Naomi Leonard IEEE International Symposium on Multi-Robot and Multi-Agent Systems, (MRS) 2021.
- [C8] Distributed Bandits: Probabilistic Communication on d-regular Graphs Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2021.
- [C7] A Dynamic Observation Strategy for Multi-agent Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2020.
- [C6] Heterogeneous Stochastic Interactions for Multiple Agents in a Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2019. (Invited Paper)
- [C5] Feedback Regularization and Geometric PID Control for Robust Stabilization of a Planar Three-link Hybrid Bipedal Walking Model Lasitha Weerakon, Udari Madhushani, Sanjeeva Mathripala, Jordan Berg American Control Conference, (ACC) 2018.
- [C4] Multi-armed Bandit Based Approach for Performance Enhancement of Window Intensity Test (WIT)

 Detector

Kusal Tennakoon, **Udari Madhushani**, Sanjeeva Mathripala International Conference of Industrial and Information Systems, (**ICIIS**) 2017.

[C3] Intrinsic PID Controller for a Segway Type Mobile Robot Isuru Basnayake, Udari Madhushani, Sanjeeva Mathripala International Conference of Industrial and Information Systems, (ICIIS) 2017.

[C2] Feedback Regularization and Geometric PID Control for Trajectory Tracking of Mechanical Systems: Hoop Robots on an Inclined Plane

Udari Madhushani, Sanjeeva Mathripala, Jordan Berg American Control Conference, (ACC) 2017.

[C1] WIT: Window Intensity Test Detector and Descriptor

Udari Madhushani, Sanjeeva Mathripala, Janaka Wijayakulasooriya International Conference of Industrial and Information Systems, (ICHS) 2016.

Peer-reviewed Workshop Articles

[W10] A Heterogeneous Agent Model of Mortgage Servicing: An Income-based Relief Analysis Deepeka Garg, Benjamin Patrick Evans, Leo Ardon, Annapoorani Lakshmi Narayanan, Jared Vann, Udari Madhushani, Makada Henry-Nickie, Sumitra Ganesh AI in Finance for Social Impact (AIFinSI), AAAI Conference on Artificial Intelligence, (AAAI) 2024.

[W9] O3D: Offline Data-Driven Discovery and Distillation for Sequential Decision Making with Large Language Models

Yuchen Xiao, Yanchao Sun, Mengda Xu, **Udari Madhushani**, Jared Vann, Deepeka Garg, Sumitra Ganesh Foundation Models for Decision Making Workshop (**FMDM**), Conference on Neural Information Processing Systems, (**NeurIPS**) 2023.

- [W8] Heterogeneous Social Value Orientation Leads to Meaningful Diversity in Sequential Social Dilemmas Udari Madhushani, Kevin McKee, John Agapiou, Joel Z Leibo, Thomas Anthony, Richard Everett, Edward Hughes, Karl Tuyls, Edgar Duéñez-Guzmán Adaptive and Learning Agents Workshop (ALA), International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2023)
- [W7] Multi-robot Learning and Coverage of Unkown Fields
 Maria Santos, Udari Madhushani, Alessia Benevento, Naomi Leonard
 Autonomous Robots and Multirobot Systems (ARMS), International Conference on Autonomous Agents and
 Multiagent Systems (AAMAS) 2022.
- [W6] A Regret Minimization Approach to Multi-Agent Control Udaya Ghai, Udari Madhushani, Naomi Leonard, Elad Hazan Workshop on Gamification and Multiagent Solutions (GMS), International Conference on Learning Representations (ICLR) 2022. (Oral - Won the best poster award)
- [W5] Provably Efficient Decentralized Communication for Multi-Agent RL Justin Lidard, Udari Madhushani, Naomi Leonard Reinforcement Learning in Games (RLG), AAAI Conference on Artificial Intelligence (AAAI) 2022. (Oral)
- [W4] On Using Hamiltonian Monte Carlo Sampling for Reinforcement Learning Problems in High-dimension Udari Madhushani, Biswadip Dey, Naomi Leonard, Amit Chakraborty Deep Reinforcement Learning Workshop (Deep RL), Conference on Neural Information Processing Systems (NeurIPS) 2021.
- [W3] When to Call Your Neighbor? Strategic Communication in Cooperative Stochastic Bandits Udari Madhushani, Naomi Leonard Learning and Decision-Making with Strategic Feedback (StratML), Conference on Neural Information Processing Systems (NeurIPS) 2021.

[W2] It Doesn't Get Better and Here's Why: A Fundamental Drawback in Natural Extensions of UCB to Multi-agent Bandits

Udari Madhushani, Naomi Leonard

I can't Believe It's Not Better! Workshop (ICBINB), Conference on Neural Information Processing Systems (NeurIPS) 2020. (Spotlight)

[W1] Distributed Learning: Sequential Decision Making in Resource-Constrained Environments

Udari Madhushani, Naomi Leonard

Practical ML for Developing Countries Workshop (PML4DC), International Conference on Learning Representations, (ICLR) 2020. (Oral)

SKILLS

Computer Skills: Python, PyTorch, TensorFlow, JAX, Matlab, LATEX

Language Skills: Sinhala (Native), English (Fluent)