# Udari Madhushani Sehwag

## RESEARCH INTEREST

My research vision is to embed AI agents with the ability to enhance their capabilities through collective intelligence, ultimately enabling them to seamlessly coexist with humans, augmenting their cognitive and physical capabilities. In my research work I primarily focus on developing socially intelligent and aligned AI agents.

**Key Topics**: Generative AI (LLMs - social intelligence, human behaviour proxy, collective alignment, governance), Multi-agent reinforcement learning (generalization, evolution of cooperation, communication), Game theory, Robotics, Bandit theory.

PhD thesis: Learning through social interactions and learning to socially interact in multi-agent learning

## **EDUCATION**

Degree	Institution	Years
Ph.D. (Artificial Intelligence)	Princeton University, USA	2017 - 2023
M.A. (Artificial Intelligence)	Princeton University, USA	2017 - 2019
B.Sc. (Robotics & Control Theory)	University of Peradeniya, Sri Lanka	2011 - 2015

## Honors

#### Graduate Honors (Princeton University)

• Harold W. Dodds Fellowship (prestigious honorific fellowship from Graduate School)	2021-22
• Britt and Eli Harari Fellowship	2020-21
• Larisse Rosentweig Klein Memorial Award	Fall 2019
Martin Summerfield Graduate Fellowship	2018-19
• Athena-Feron Prize for Mathematical Excellence	Fall 2018
• Elliotte Robinson Little '25 Student Aid Fund Fellowship	2017-18

### Other Awards

Presidential Award for Scientific Research (Sri Lanka)
 Best Undergraduate Project Award (IEEE Sri Lanka Section)
 December 2015

## EXPERIENCE

#### Visiting Postdoc

• Stanford University, California, USA

August 2023 - Present Focus: Alignment in foundation models, multi-step reasoning and self-improving in LLMs, Robotics

#### Research Scientist

JPMorgan AI Research, New York, USA
 Focus: Alignment in foundation models, multi-step reasoning and self-improving in LLMs, Mechanism design

#### Research Internships

Google Deepmind, London, UK
 *Mentors:* Daniel Hennes and Edgar Duenez-Guzman
 *Project:* Zero-shot Generalization in Mixed Motive Games

May 2022 - Sep 2022

<ul> <li>Facebook AI Research, Menlo Park, California, USA         <i>Mentors:</i> Kalesha Bullard and Roberto Calandra         <i>Project:</i> Incentivizing Coordination in Multi-Agent Reinforcement Learnin</li> </ul>	May 2021 - August 2021
• Siemens, Princeton, New Jersey, USA	May 2020 - August 2020
Mentors: Biswadip Dey and Amit Chakraborty  Project: Using Hamiltonian Monte Carlo Sampling for Reinforcement Learni	ing Problems in High-dimension
Assistant in Research	
• Princeton University	September 2017 - May 2023
• Sri Lanka Technological Campus (SLTC), Sri Lanka	January 2016 - August 2017
Guest Lectures	
<ul> <li>MAE 545 Collective Intelligence: Dynamics and Control of Multi-Agent Sy (Princeton University)</li> </ul>	rstems Fall 2022
Assistant in Teaching	
<ul> <li>MAE 542 Advanced Dynamics (Princeton University)</li> <li>MAE 502/APC 506 Mathematical Methods of Engineering Analysis (Princeton MAE 345/MAE 549 Introduction to Robotics (Princeton University)</li> <li>EE 554 Microwave Techniques (University of Peradeniya), Sri Lanka</li> </ul>	Fall 2020 ceton University) Spring 2020 Fall 2019 October 2015 - December 2015
Outreach	
Mentoring Stanford University	
• Arjun Karanam (M.Sc. Computer Science)	2024-Present
University of California, Berkeley	
• Marwa Abdulhai (Ph.D. Electrical Engineering and Computer Sciences)	2024-Present
Princeton University	
• Justin Lidard (Ph.D. Mechanical Engineering)	2021-23
<ul> <li>Kathryn Wantlin (M.Sc. Computer Science)</li> <li>Sarah Dillender (B.S.E. Mechanical Engineering)</li> </ul>	2021-23 2020-21
<ul> <li>Thesis: Message passing structures for improved policy finding in decentra</li> <li>Gargi Sadalgekar, Samarie Wilson and Jacob Walrath (B.S.E. Mechanical Thesis: Decision making and task allocation in a multi-robot system.</li> </ul>	lized multi-agent Q-learning.
Peradeniya University, Sri Lanka	
• Lasitha Weerakon (Post graduate, Mechanical Engineering) Published in American Control Conference (ACC), 2018.	2016-17
• Isuru Basnayake (Post graduate, Mechanical Engineering)  Published in International Conference of Industrial and Information System	2016-17 ms, (ICIIS), 2017.
• Kusal Tennakoon (Post graduate, Mechanical Engineering) Published in International Conference of Industrial and Information System	2016-17 ms, (ICIIS), 2017.
Commitment to Diversity and Inclusion	
<ul> <li>Co-organized "Re-education Monthly Book Club" aimed towards improvin implicit biases (Princeton University)</li> </ul>	
<ul> <li>Co-organized the workshop "Diversity and Mentorship" at American Cont</li> <li>Co-organized the workshop "Inclusive Teaching" (Princeton University)</li> </ul>	rol Conference May 2021 Jan 2021
Leadership Roles	
<ul> <li>Committee member of Women in STEM Leadership Council (Princeton Use)</li> <li>Committee member of Graduate Women in Science &amp; Engineering (Prince)</li> <li>Future Digileaders Training (Stockholm, Sweden)</li> <li>Founder of EE Instructors Scholarship (Peradeniya University, Sri Lanka)</li> </ul>	~ /
Volunteer for	
World Maker Faire	September 2018

## ACADEMIC SERVICES

#### Program committee Member of

- Games Agents and Incentives Workshop (GAIW) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2023
- Adaptive and Learning Agents Workshop (ALA) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2023
- Adaptive and Learning Agents Workshop (ALA) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2022
- Cooperative AI Workshop at Conference on Neural Information Processing Systems (NeurIPS) 2021

### Co-organizer of

- Special issue on "Collective Artificial Intelligence" at Proceedings of National Academy of Science (PNAS) 2023
- Proceedings of National Academy of Science (PNAS) special issue symposium on "Collective Artificial Intelligence" 2022

#### Editor for

Journal: Proceedings of National Academy of Science (PNAS)

#### Reviewer for

Journal: Automatica, IEEE Transactions on Automatic Control, IEEE Control Systems Letters, Journal of Field Robotics

Conference: Conference on Neural Information Processing Systems, International Conference on Machine Learning, International Conference on Learning Representations, IEEE Conference on Decision and Control, American Control Conference, International Conference on Intelligent Robots and Systems, European Control Conference, International Conference of Industrial and Information Systems

#### Student Member of

IEEE (Institute of Electrical and Electronics Engineers), IEEE Young Professionals, IEEE Women in Engineering, APS (American Physical Society)

## Publications

#### **Technical Reports**

#### [T1] Melting Pot 2.0

John Agapiou, Alexander Vezhnevets, Duéñez-Guzmán, Jayd Matyas, Yiran Mao, Peter Sunehag, Raphael Köster, **Udari Madhushani**, Kavya Kopparapu, Ramona Comanescu, DJ Strouse, Michael B. Johanson, Sukhdeep Singh, Julia Haas, Igor Mordatch, Dean Mobbs, Joel Z Leibo ArXiv 2023

#### Peer-reviewed Journal Articles

#### [J4] Autocratic Learning and Unilateral Incentive Alignment in Two-player Stochastic Games

Alex McAvoy, **Udari Madhushani**, Christian Hilbe, Wolfram Barfuss, Krishnendu Chatterjee, Qi Su, Naomi Ehrich Leonard, Joshua B. Plotkin

(Proceedings of National Academy of Science - special issue on Collective Artificial Intelligence) 2024 (under review)

### [J3] Collective Cooperative Intelligence

Wolfram Barfuss, Jessica Flack, Chaitanya S. Gokhale, Lewis Hammond, Christian Hilbe, Joel Leibo, Tom Lenaerts, Naomi Leonard, Simon Levin, **Udari Madhushani**, Alex McAvoy, Janusz M. Meylahn, Fernando P. Santos

(Proceedings of National Academy of Science - special issue on Collective Artificial Intelligence) 2024 (conditionally accepted)

#### [J2] Heterogeneous Explore-Exploit Strategies on Multi-Star Networks

Udari Madhushani, Naomi Leonard

IEEE Control Systems Letters, 2021.

[J1] Semi-globally Exponential Trajectory Tracking for a Class of Spherical Robots Udari Madhushani, Sanjeeva Maithripala, Janaka Wijayakulasooriya, Jordan Berg Automatica, 2017.

#### Peer-reviewed Conference Articles

- [C15] AI Risk Management Should Understand and Account for Both Safety and Security Xiangyu Qi, ....., Udari Madhushani Sehwag, ....., Prateek Mittal (Under review at ICML 2024)
- [C14] O3D: Offline Data-Driven Discovery and Distillation for Sequential Decision Making with Large Language Models

Yuchen Xiao, Yanchao Sun, Mengda Xu, **Udari Madhushani**, Jared Vann, Deepeka Garg, Sumitra Ganesh (Under review at ICML 2024)

- [C13] On Using Hamiltonian Monte Carlo Sampling for Reinforcement Learning Udari Madhushani, Biswadip Dey, Naomi Leonard, Amit Chakraborty Conference on Decision and Control, (CDC) 2022. (Invited Paper)
- [C12] A Regret Minimization Approach to Multi-Agent Control Udaya Ghai, Udari Madhushani, Naomi Leonard, Elad Hazan International Conference on Machine Learning, (ICML) 2022.
- [C11] Provably Efficient Multi-Agent Reinforcement Learning with Fully Decentralized Communication Justin Lidard, Udari Madhushani, Naomi Leonard American Control Conference, (ACC) 2022.
- [C10] One More Step Towards Reality: Cooperative Bandits with Imperfect Communication Udari Madhushani, Abhimanyu Dubey, Naomi Leonard, Alex Pentland Conference on Neural Information Processing Systems, (NeurIPS) 2021.
- [C9] Multi-robot Learning and Coverage of Unkown Fields
  Maria Santos, Udari Madhushani, Alessia Benevento, Naomi Leonard
  IEEE International Symposium on Multi-Robot and Multi-Agent Systems, (MRS) 2021.
- [C8] Distributed Bandits: Probabilistic Communication on d-regular Graphs Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2021.
- [C7] A Dynamic Observation Strategy for Multi-agent Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2020.
- [C6] Heterogeneous Stochastic Interactions for Multiple Agents in a Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2019. (Invited Paper)
- [C5] Feedback Regularization and Geometric PID Control for Robust Stabilization of a Planar Three-link Hybrid Bipedal Walking Model Lasitha Weerakon, Udari Madhushani, Sanjeeva Mathripala, Jordan Berg American Control Conference, (ACC) 2018.
- [C4] Multi-armed Bandit Based Approach for Performance Enhancement of Window Intensity Test (WIT) Detector Kusal Tennakoon, Udari Madhushani, Sanjeeva Mathripala

International Conference of Industrial and Information Systems, (ICIIS) 2017.

[C3] Intrinsic PID Controller for a Segway Type Mobile Robot Isuru Basnayake, Udari Madhushani, Sanjeeva Mathripala International Conference of Industrial and Information Systems, (ICIIS) 2017. [C2] Feedback Regularization and Geometric PID Control for Trajectory Tracking of Mechanical Systems: Hoop Robots on an Inclined Plane

Udari Madhushani, Sanjeeva Mathripala, Jordan Berg American Control Conference, (ACC) 2017.

[C1] WIT: Window Intensity Test Detector and Descriptor

Udari Madhushani, Sanjeeva Mathripala, Janaka Wijayakulasooriya International Conference of Industrial and Information Systems, (ICIIS) 2016.

### Peer-reviewed Workshop Articles

[W10] A Heterogeneous Agent Model of Mortgage Servicing: An Income-based Relief Analysis Deepeka Garg, Benjamin Patrick Evans, Leo Ardon, Annapoorani Lakshmi Narayanan, Jared Vann, Udari Madhushani, Makada Henry-Nickie, Sumitra Ganesh AI in Finance for Social Impact (AIFinSI) in AAAI Conference on Artificial Intelligence, (AAAI) 2024.

[W9] O3D: Offline Data-Driven Discovery and Distillation for Sequential Decision Making with Large Language Models

Yuchen Xiao, Yanchao Sun, Mengda Xu, **Udari Madhushani**, Jared Vann, Deepeka Garg, Sumitra Ganesh Foundation Models for Decision Making Workshop (**FMDM**), Conference on Neural Information Processing Systems, (**NeurIPS**) 2023.

- [W8] Heterogeneous Social Value Orientation Leads to Meaningful Diversity in Sequential Social Dilemmas Udari Madhushani, Kevin McKee, John Agapiou, Joel Z Leibo, Thomas Anthony, Richard Everett, Edward Hughes, Karl Tuyls, Edgar Duéñez-Guzmán Adaptive and Learning Agents Workshop (ALA) at International Conference on Autonomous Agents and Multi Agent Systems (AAMAS) 2023)
- [W7] Multi-robot Learning and Coverage of Unkown Fields
  Maria Santos, Udari Madhushani, Alessia Benevento, Naomi Leonard
  Autonomous Robots and Multirobot Systems (ARMS), International Conference on Autonomous Agents and
  Multiagent Systems (AAMAS) 2022.
- [W6] A Regret Minimization Approach to Multi-Agent Control Udaya Ghai, Udari Madhushani, Naomi Leonard, Elad Hazan Workshop on Gamification and Multiagent Solutions (GMS), International Conference on Learning Representations, (ICLR) 2022. (Oral - Won the best poster award)
- [W5] Provably Efficient Decentralized Communication for Multi-Agent RL Justin Lidard, Udari Madhushani, Naomi Leonard Reinforcement Learning in Games (RLG), AAAI Conference on Artificial Intelligence, (AAAI) 2022. (Oral)
- [W4] On Using Hamiltonian Monte Carlo Sampling for Reinforcement Learning Problems in High-dimension Udari Madhushani, Biswadip Dey, Naomi Leonard, Amit Chakraborty Deep Reinforcement Learning Workshop (Deep RL), Conference on Neural Information Processing Systems, (NeurIPS) 2021.
- [W3] When to Call Your Neighbor? Strategic Communication in Cooperative Stochastic Bandits Udari Madhushani, Naomi Leonard Learning and Decision-Making with Strategic Feedback (StratML), Conference on Neural Information Processing Systems, (NeurIPS) 2021.
- [W2] It Doesn't Get Better and Here's Why: A Fundamental Drawback in Natural Extensions of UCB to Multi-agent Bandits

Udari Madhushani, Naomi Leonard

I can't Believe It's Not Better! Workshop (ICBINB), Conference on Neural Information Processing Systems, (NeurIPS) 2020. (Spotlight)

## [W1] Distributed Learning: Sequential Decision Making in Resource-Constrained Environments

Udari Madhushani, Naomi Leonard

Practical ML for Developing Countries Workshop (PML4DC), International Conference on Learning Representations, (ICLR) 2020. (Oral)

# SKILLS

Computer Skills: Python, PyTorch, TensorFlow, JAX, Matlab, LATEX

Language Skills: Sinhala (Native), English (Fluent)