Udari Madhushani

Ph.D. Candidate Princeton University, Princeton, NJ 08544 **UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io UdariMadhu.github.io**

RESEARCH INTEREST

Reinforcement learning (sequential decision making in uncertain environments), contact processes (simple contagion in random graphs), evolving voter models (stochastic rewiring of interactions), robotics (path planing using geometric controls)

EDUCATION

Program	Institution	Years
Ph.D., Mechanical Engineering	Princeton University NJ, USA	2017 - Present
M.A., Mechanical Engineering	Princeton University NJ, USA	2017 - 2019
B.Sc. Eng (Hons), Electronic Engineering	University of Peradeniya Kandy, Sri Lanka	2011 - 2015

EXPERIENCE

Assistant in Research

• Princeton University	September 2017 - Present
• Sri Lanka Technological Campus, Sri Lanka	January 2016 - August 2017

Research Internships

• Siemens, Princeton, USA	May 2020 - August 2020
• Atrenta Lanka (Pvt.) Ltd., Sri Lanka	October 2014 - January 2015

Assistant in Teaching (Princeton University)

• MAE 542 Advanced Dynamics	Fall 2020
\bullet MAE 502/APC 506 Mathematical Methods of Engineering Analysis	Spring 2020
• MAE 345/MAE 549 Introduction to Robotics	Fall 2019

Mentoring (Princeton University)

• Sarah Dillender (B.S.E. Mechanical Engineering)	2020-21
• Jacob Walrath (B.S.E. Mechanical Engineering)	2020-21
• Samarie Wilson (B.S.E. Mechanical Engineering)	2020-21
• Gargi Sadalgekar (B.S.E. Mechanical Engineering)	2020-21

OUTREACH

Leadership Training

Future Digileaders (Stockholm, Sweden)

November 2019

Volunteer for

World Maker Faire
 American Control Conference
 June 2018

ACADEMIC SERVICE

Student Member of

IEEE (Institute of Electrical and Electronics Engineers), IEEE Young Professionals, IEEE Women in Engineering, APS (American Physical Society)

Reviewer for

Automatica, IEEE Transactions on Automatic Control, IEEE Control Systems Letters, Conference on Decision and Control, American Control Conference, European Control Conference, Journal of Field Robotics, IEEE Transactions on Communications

Honors

Graduate Honors (Princeton University)

• Britt and Eli Harari Fellowship	2020-21
• Larisse Rosentweig Klein Memorial Award	Fall 2019
Martin Summerfield Graduate Fellowship	2018-19
• Athena-Feron Prize for Mathematical Excellence	Fall 2018
Elliotte Robinson Little '25 Student Aid Fund Fellowship	2017-18

Awards

• Presidential Award for Scientific Research (Sri Lanka)

2019

• Best Undergraduate Project Award (IEEE Sri Lanka Section)

December 2015

Publications

Journal Papers

- Decentralized Stochastic Bandits with Probabilistic Communications Udari Madhushani, Naomi Leonard (In Preparation).
- Cooperative Bandits: A Class of Communication Protocols with Logarithmic Communication Cost **Udari Madhushani**, Naomi Leonard (In Preparation).
- Heterogeneous Explore-Exploit Strategies on Multi-Star Networks

Udari Madhushani, Naomi Leonard IEEE Control Systems Letters, (under review).

• Semi-globally Exponential Trajectory Tracking for a Class of Spherical Robots Udari Madhushani, Sanjeeva Maithripala, Janaka Wijayakulasooriya, Jordan Berg Automatica, 2017.

Conference Papers

- Broadcast when Exploring: Cost-effective Communication in Distributed Stochastic Bandits **Udari Madhushani**, Naomi Leonard (In Preparation).
- Hamiltonian Q-learning: Data Efficient RL Using Importance-sampling Udari Madhushani, Biswadip Dey, Naomi Leonard, Amit Chakraborty International Conference on Learning Representations, (ICLR) 2021 (Under Review).
- A Dynamic Observation Strategy for Multi-agent Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2020.
- Heterogeneous Stochastic Interactions for Multiple Agents in a Multi-armed Bandit Problem Udari Madhushani, Naomi Leonard European Control Conference, (ECC) 2019. (Invited Paper)

• Feedback Regularization and Geometric PID Control for Robust Stabilization of a Planar Three-link Hybrid Bipedal Walking Model

Lasitha Weerakon, **Udari Madhushani**, Sanjeeva Mathripala, Jordan Berg American Control Conference, **(ACC)** 2018.

• Multi-armed Bandit Based Approach for Performance Enhancement of Window Intensity Test (WIT) Detector

Kusal Tennakoon, **Udari Madhushani**, Sanjeeva Mathripala International Conference of Industrial and Information Systems, (**ICHS**) 2017.

• Intrinsic PID Controller for a Segway Type Mobile Robot

Isuru Basnayake, **Udari Madhushani**, Sanjeeva Mathripala International Conference of Industrial and Information Systems, (**ICHS**) 2017.

• Feedback Regularization and Geometric PID Control for Trajectory Tracking of Mechanical Systems: Hoop Robots on an Inclined Plane

Udari Madhushani, Sanjeeva Mathripala, Jordan Berg American Control Conference, (ACC) 2017.

WIT: Window Intensity Test Detector and Descriptor

Udari Madhushani, Sanjeeva Mathripala, Janaka Wijayakulasooriya International Conference of Industrial and Information Systems, (ICIIS) 2016.

Workshop Papers

• It Doesn't Get Better and Here's Why: A Fundamental Drawback in Natural Extensions of UCB to Multiagent Bandits

Udari Madhushani, Naomi Leonard

I can't Believe It's Not Better! Workshop (ICBINB), Conference on Neural Information Processing Systems, (NeurIPS) 2020. (Under Review)

Distributed Learning: Sequential Decision Making in Resource-Constrained Environments

Udari Madhushani, Naomi Leonard

Practical ML for Developing Countries Workshop (PML4DC), International Conference on Learning Representations, (ICLR) 2020. (Oral)

SKILLS

Computer Skills

Python, PyTorch, Matlab, \LaTeX

Language Skills

Sinhala (Mother Tounge), English (Fluent)