PINNs for Navier Stokes equations

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1 Introduction

2 PINNs design for Navier Stokes



Introduction

PINNs design for Navier Stokes





• Incompressible General Form:

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \nu \frac{\partial^2 u_i}{\partial x_i \partial x_j} + f_i \tag{1}$$

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2D Steady Incompressible Navier-Stokes eqn. reduces to:

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(3)

$$u\frac{\partial v}{\partial x} + v\frac{\partial v}{\partial y} = -\frac{1}{\rho}\frac{\partial p}{\partial y} + \nu\left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2}\right) \tag{4}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \tag{5}$$

• **Nonlinearity:** The equations involve nonlinear terms $(u\frac{\partial u}{\partial x}, v\frac{\partial u}{\partial y})$, making them challenging to solve analytically or numerically.

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- Additional Transport equations (Ex: Energy conservation)



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Frame Title

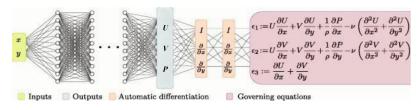


Figure: PINNs for NSE2d

Let, $Y_{pred}(\theta) = [U, V, P]_{pred}$, where θ represents the parameters of the network and $Y_{true} = [U, V, P]$ be the ground truth.

residual loss,
$$L_r = w_1 \epsilon_1 + w_2 \epsilon_2 + w_3 \epsilon_3$$
 (6)

Total Loss,
$$L = L_r + \beta L_b$$
 (7)

Optimization problem reads to,

$$\min_{\theta} L(Y_{pred}(\theta), Y_{true})$$



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Kovasznay flow

We will solve Kovasznay flow equation on $\Omega=[0,1]^2$. The governing eqns. are 3, 4 and 5 with Dirichlet Boundary Conditions $u(x,y)=0, (x,y)\in\partial\Omega$. The reference solution is $u=1-e^{\zeta x}cos(2\pi y),\ v=\frac{\zeta}{2\pi}e^{2\pi x}$ and $p=\frac{1}{2}(1-e^{1-e^{2\zeta x}}),$ where $\zeta=\frac{1}{2\nu}-\sqrt{\frac{1}{4\nu^2}+4\pi^2}$



