

CMSC 471

ML: Decision Trees

Slides courtesy: Tim Finin



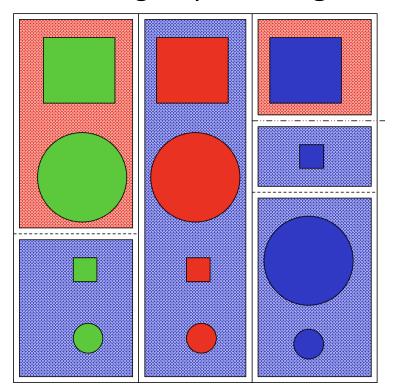
Decision Trees (DTs)

- A supervised learning method used for classification and regression
- Given a set of training tuples, learn model to predict one value from the others
 - Learned value typically a class (e.g., goodRisk)
- Resulting model is simple to understand, interpret, visualize, and apply



Learning a Concept

The red groups are **negative** examples, blue **positive**



Attributes

• Size: large, small

• Color: red, green, blue

• **Shape**: square, circle

Task

Classify new object with a size, color & shape as positive or negative



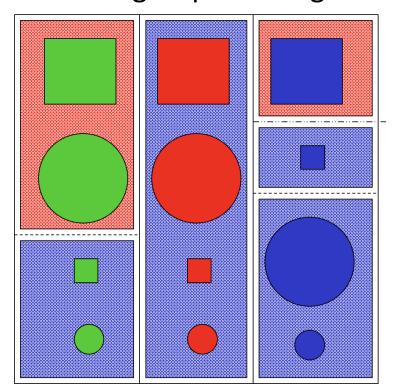
Training data

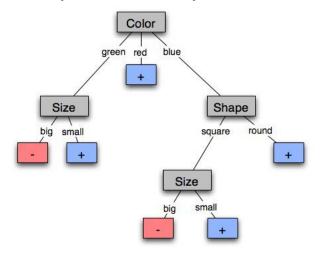
Size	Color	Shape	class	
Large	Green	Square	Negative	
Large	Green	Circle	Negative	
Small	Green	Square	Positive	
Small	Green	Circle	positive	
Large	Red	Square	Positive	
Large	Red	Circle	Positive	
Small	Red	Square	Positive	
Small	Red	Circle	Positive	
Large	Blue	Square	Negative	
Small	Blue	Square	Positive	
Large	Blue	Circle	Positive	
Small	Blue	Circle	Positive	



A decision tree-induced partition

The red groups are negative examples, blue positive



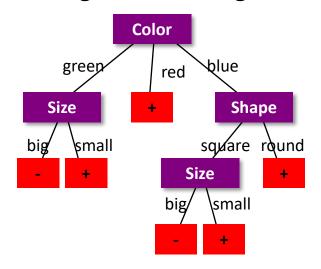


Negative things are big, green shapes and big, blue squares



Learning decision trees

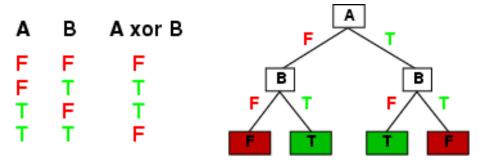
- Goal: Build decision tree to classify examples as positive or negative instances of concept using supervised learning from training data
- A **decision tree** is a tree where
- non-leaf nodes have an attribute (feature)
- leaf nodes have a classification(+ or -)
- each arc has a possible value of its attribute
- Generalization: allow for >2 classes
- —e.g., classify stocks as {sell, hold, buy}





Expressiveness of Decision Trees

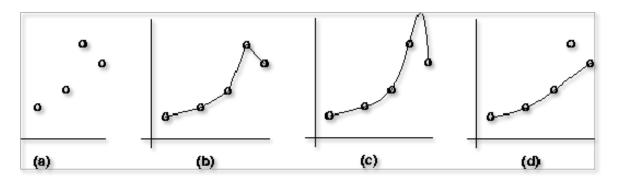
• Can express any function of input attributes, e.g., for Boolean functions, truth table row → path to leaf:



- There's a consistent decision tree for any training set with one path to leaf for each example, but it probably won't generalize to new examples
- Prefer more compact decision trees



Inductive learning and bias



- Suppose that we want to learn a function f(x) = y and we're given sample (x,y) pairs, as in figure (a)
- Can make several hypotheses about f, e.g.: (b), (c) & (d)
- Preference reveals learning technique bias, e.g.:
 - prefer piece-wise functions (b)
 - prefer a smooth function (c)
 - prefer a simple function and treat outliers as noise (d)



Preference bias: Occam's Razor

- William of Ockham (1285-1347)
 - "non sunt multiplicanda entia praeter necessitatem"
 - entities are not to be multiplied beyond necessity
- **Simplest** consistent explanation is the best
- Smaller decision trees correctly classifying training examples preferred over larger ones
- Finding the smallest decision tree is NP-hard, so we use algorithms that find reasonably small ones





R&N's restaurant domain

- Develop decision tree that customers make when deciding whether to wait for a table or leave
- Two classes: wait, leave
- Ten attributes: Alternative available? Bar in restaurant? Is it Friday? Are we hungry? How full is restaurant? How expensive? Is it raining? Do we have reservation? What type of restaurant is it? Estimated waiting time?
- Set of 12 training examples
- ~7000 possible cases

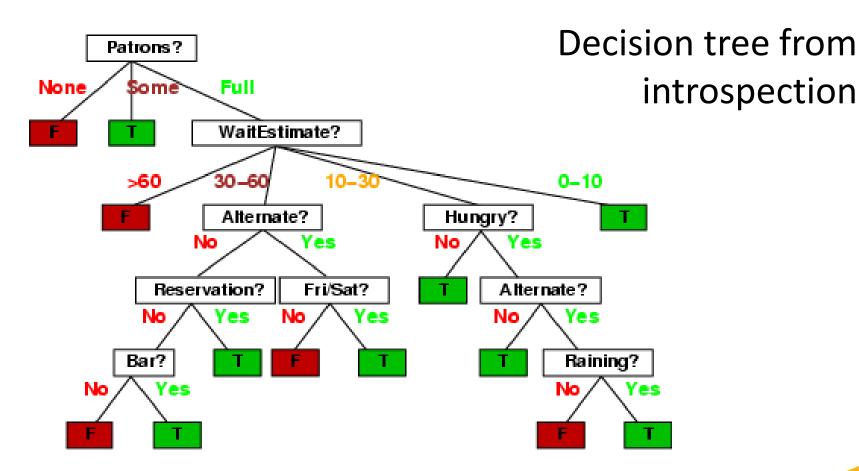


Attribute-based representations

Example	Attributes									Target	
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	Wait
X_1	Т	F	F	Т	Some	\$\$\$	F	Т	French	0–10	Т
X_2	Т	F	F	Т	Full	\$	F	F	Thai	30–60	F
X_3	F	Т	F	F	Some	\$	F	F	Burger	0–10	Т
X_4	Т	F	Т	Т	Full	\$	F	F	Thai	10–30	Т
X_5	Т	F	Т	F	Full	\$\$\$	F	Т	French	>60	F
X_6	F	Т	F	Т	Some	\$\$	Т	Т	Italian	0-10	Т
X_7	F	Т	F	F	None	\$	Т	F	Burger	0-10	F
X_8	F	F	F	Т	Some	\$\$	Т	Т	Thai	0–10	Т
X_9	F	Т	Т	F	Full	\$	Т	F	Burger	>60	F
X_{10}	Т	Т	Т	Т	Full	\$\$\$	F	Т	Italian	10-30	F
X_{11}	F	F	F	F	None	\$	F	F	Thai	0-10	F
X_{12}	Т	Т	Т	Τ	Full	\$	F	F	Burger	30–60	Т

- •Examples described by attribute values (Boolean, discrete, continuous), e.g., situations where will/won't wait for a table
- •Classification of examples is positive (T) or negative (F)
- Serves as a training set







Issues

20 Questions

- It's like <u>20 questions</u>
- We can generate many decision trees depending on what attributes we ask about and in what order
- How do we decide?
- What makes one decision tree better than another: number of nodes? number of leaves? maximum depth?



<u>ID3</u> / <u>C4.5</u> / J48 Algorithm

- Greedy algorithm for decision tree construction developed by <u>Ross Quinlan</u> circa 1987
- Top-down construction of tree by recursively selecting *best attribute* to use at current node
- Once attribute selected for current node, generate child nodes, one for each possible attribute value
- Partition examples using values of attribute, & assign these subsets of examples to the child nodes
- Repeat for each child node until examples associated with a node are all positive or negative



Choosing best attribute

 Key problem: choose attribute to split given set of examples

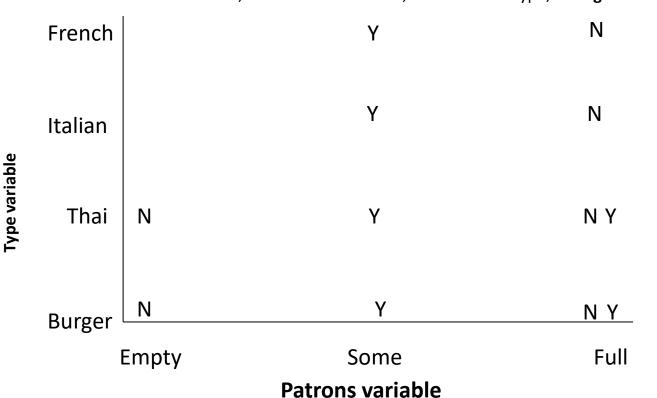


- Possibilities for choosing attribute:
- **-Random:** Select one at random
- **Least-values:** one with smallest # of possible values
- -Most-values: one with largest # of possible values
- -Max-gain: one with largest expected information gain
- -Gini impurity: one with smallest gini impurity value
- The last two measure the homogeneity of the target variable within the subsets
- The ID3 algorithm uses max-gain



Restaurant: type vs patrons?

Random: Patrons or Wait-time; Least-values: Patrons; Most-values: Type; Max-gain: ???

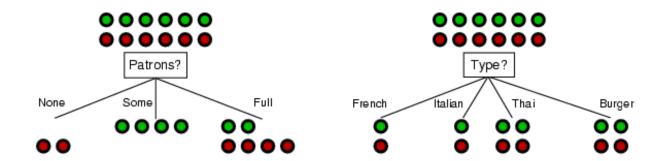




Choosing an attribute



Idea: good attribute splits examples into subsets that are (ideally) all positive or all negative



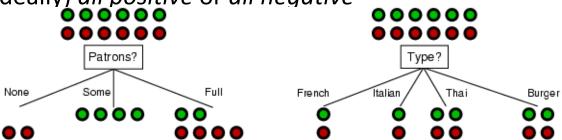
Which is better: *Patrons?* or *Type?*



Choosing an attribute



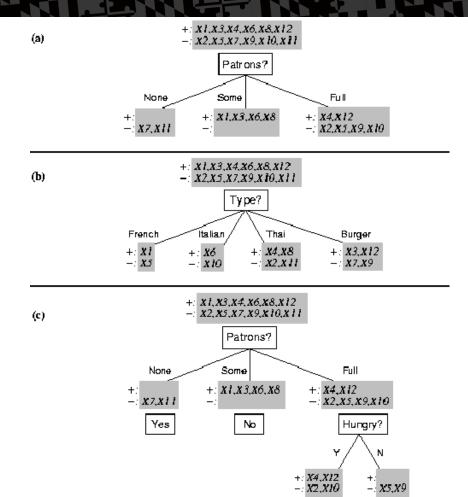
Idea: good attribute splits examples into subsets that are (ideally) all positive or all negative



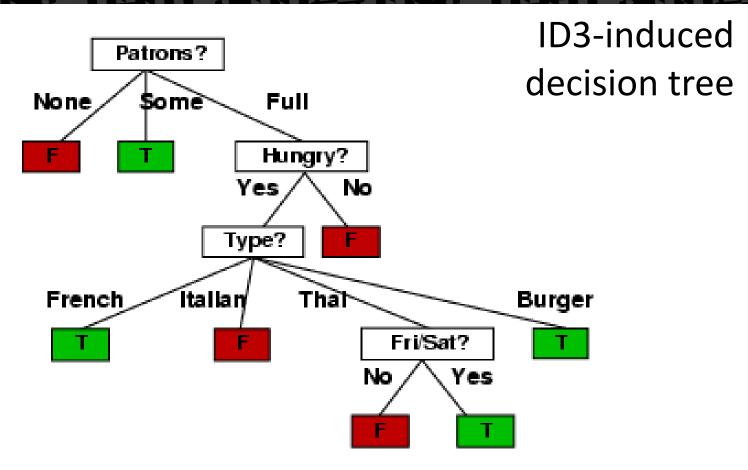
- **Patrons:** for six examples we know the answer and for six we can predict with prob. 0.67
- **Type:** our prediction is no better than chance (0.50)



Splitting examples by testing attributes

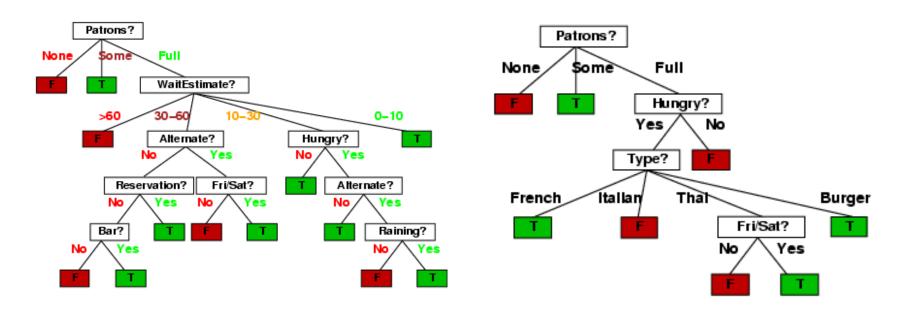








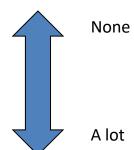
Compare the two Decision Trees





Information Entropy

- <u>Information entropy</u> ... tells how much information there is in an event. More uncertain an event is, more information it contains
- Receiving a message is an event
- How much information is in these messages
 - The sun rose today!
 - It's sunny today in Honolulu!
 - The coin toss is heads!
 - It's sunny today in Seattle!
 - Life discovered on Mars!



Information theory 101

- For n equally probable possible event or data values, each has probability 1/n
- Information of a message is -log(p) = log(n)
 e.g., with 16 messages, then log(16) = 4 and we need 4 bits to identify/send each message
- For **probability distribution P** $(p_1, p_2 ... p_n)$ for n messages, its information (aka H or <u>entropy</u>) is:

$$I(P) = -(p_1 * log(p_1) + p_2 * log(p_2) + ... + p_n * log(p_n))$$

Entropy of a distribution

$$I(P) = -(p_1 * log(p_1) + p_2 * log(p_2) + ... + p_n * log(p_n))$$

- Examples:
 - If P is (0.5, 0.5) then I(P) = 0.5*1 + 0.5*1 = 1
 - If P is (0.67, 0.33) then I(P) = -(2/3*log(2/3) + 1/3*log(1/3)) = 0.92
 - If P is (1, 0) then I(P) = 1*1 + 0*log(0) = 0
- More uniform probability distribution, greater its information: more information is conveyed by a message telling you which event actually occurred
- Entropy is the average number of bits/message needed to represent a stream of messages



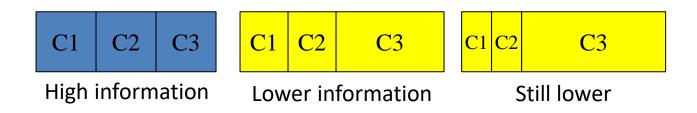
Information for classification

To divide T records is into disjoint "answer" classes $(C_1..C_k)$, the information needed to identify class of element of T is:

$$Info(T) = I(P)$$

where P is the probability distribution of partition $(C_1, C_2, ..., C_k)$:

Info(T) =
$$I(|C_1|/|T|, |C_2|/|T|, ..., |C_k|/|T|)$$

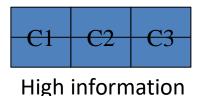




Information for classification II

If we further divide T w.r.t. attribute X into sets $\{T_1,T_2,...,T_n\}$, the information needed to identify class of an element of T is: the weighted average of information needed to identify class of an element of T_i , i.e., weighted average of Info (T_i) :

$$Info(X,T) = \sum |T_i|/|T| * Info(T_i)$$







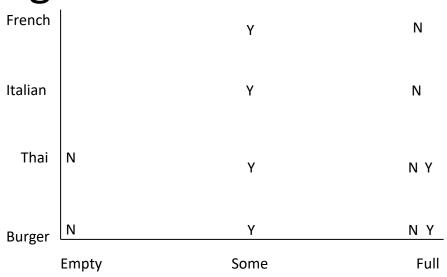
Information gain

- Gain(X,T) = Info(T) Info(X,T) is difference of
 - info needed to identify element of T and
 - info needed to identify element of T after value of attribute X known
- This is gain in information due to attribute X
- Used to rank attributes and build DT where each node uses attribute with greatest gain of those not yet considered in path from root
- goal: **create small DTs** to minimize questions

Computing Information Gain

Should we ask about restaurant type or how many patrons there are?

- $\bullet I(T) = ?$
- •I (Pat, T) = ?
- •I (Type, T) = ?



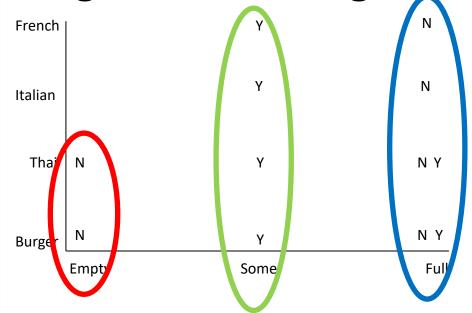
Gain (Patrons, T) = ?
Gain (Type, T) = ?

$$I(P) = -(p_1 * log(p_1) + p_2 * log(p_2) + ... + p_n * log(p_n))$$



Computing information gain

```
I(T) =
 -(.5 \log .5 + .5 \log .5)
 = .5 + .5 = 1
I (Pat, T) =
 2/12 (0) + 4/12 (0) +
 6/12 (- (4/6 log 4/6 +
         2/6 log 2/6))
 = 1/2 (2/3*.6 +
    1/3*1.6)
 = .47
I (Type, T) =
 2/12(1) + 2/12(1) +
 4/12(1) + 4/12(1) = 1
```



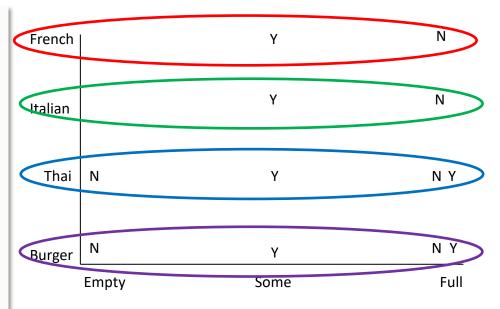
Gain (Patrons, T) = 1 - .47 = .53
Gain (Type, T) = 1 - 1 = 0

$$I(P) = -(p_1*log(p_1) + p_2*log(p_2) + ... + p_n*log(p_n))$$



Computing information gain

```
I(T) =
-(.5 \log .5 + .5 \log .5)
= .5 + .5 = 1
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    1/3*1.6)
 = .47
I (Type, T) =
 2/12 (1) + 2/12 (1) +
 4/12(1) + 4/12(1) = 1
```



Gain (Patrons, T) =
$$1 - .47 = .53$$

Gain (Type, T) = $1 - 1 = 0$

$$I(P) = -(p_1 * log(p_1) + p_2 * log(p_2) + .. + p_n * log(p_n))$$



How well does it work?

Case studies show that decision trees often at least as accurate as human experts

- Study for diagnosing breast cancer had humans correctly classifying examples 65% of the time; DT classified 72% correct
- British Petroleum designed DT for gas-oil separation for offshore oil platforms that replaced an earlier rule-based expert system
- Cessna designed an airplane flight controller using
 90,000 examples and 20 attributes per example



Extensions of ID3

- Using alternate selection metric gain ratios, ...
- Real-valued data
- Noisy data and overfitting
- Generation of rules
- Setting parameters
- Cross-validation for experimental validation of performance
- C4.5: extension of ID3 accounting for unavailable values, continuous attribute value ranges, pruning of decision trees, rule derivation, etc.



Real-valued data?

Many ML systems work only on nominal data

- Select thresholds defining intervals so each becomes a discrete value of attribute
- Use heuristics: e.g., always divide into quartiles
- Use domain knowledge: e.g., divide age into infant (0-2), toddler (3-5), school-aged (5-8)
- Or treat this as another learning problem
 - Try different ways to discretize continuous variable;
 see which yield better results w.r.t. some metric
 - E.g., try midpoint between every pair of values



Noisy data?

ML systems must deal with noise in training data

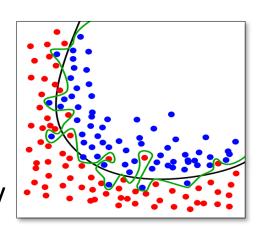
- Two examples have same attribute/value pairs, but different classifications
- Some attribute values wrong due to errors in the data acquisition or preprocessing phase
- Classification is wrong (e.g., + instead of -) because of some error
- Some attributes irrelevant to decision-making, e.g., color of a die is irrelevant to its outcome

Bias in the training data is a related problem



Overfitting 😊

- Overfitting occurs when a statistical model describes random error or noise instead of underlying relationship
- If hypothesis space has many dimensions (many attributes) we may find **meaningless regularity** in data irrelevant to true distinguishing features Students with an *m* in first name, born in July, & whose SSN digits sum to a prime number get better grades in AI
- If we have too little training data, even a reasonable hypothesis space can overfit





Avoiding Overfitting

- Remove obviously irrelevant features
- E.g., remove 'year observed', 'month observed', 'day observed', 'observer name' from feature vector
- Getting more training data
- Pruning lower nodes in a decision tree
- E.g., if gain of best attribute at a node is below a threshold, stop and make this node a leaf rather than generating children nodes



Summary: decision tree learning

- Widely used learning methods in practice for problems with relatively few features
- Strengths
 - Fast and simple to implement
 - Can convert result to a set of easily interpretable rules
 - Empirically valid in many commercial products
 - Handles noisy data
 - Easy for people to understand
- Weaknesses
 - Large decision trees may be hard to understand
 - Requires fixed-length feature vectors
 - Non-incremental (i.e., batch method)
 - Univariate splits/partitioning using only one attribute at a time so limits types of possible trees