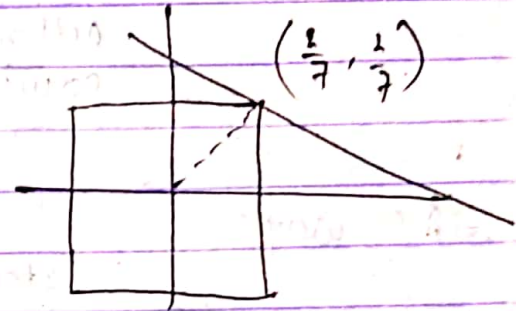
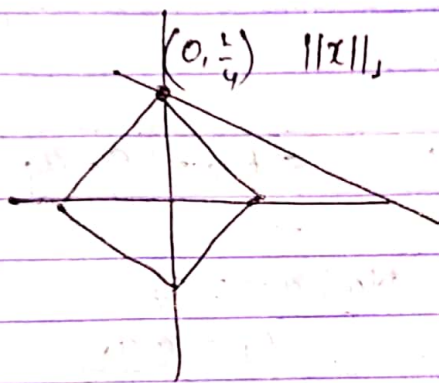
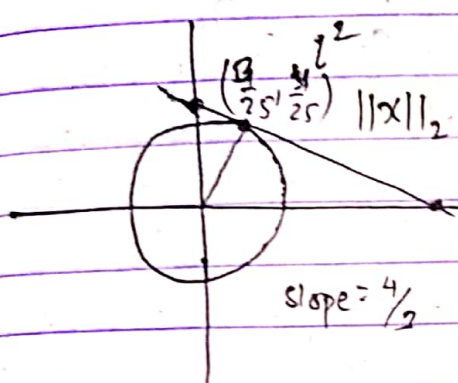


## Lec. 11 : Minimization and Gram-Schmidt

Minimize  $\|x\|_1$ ,  $\|x\|_2$  and  $\|x\|_\infty$  with respect to  
 $3x_1 + 4x_2 = 1$ .

The unit balls for different norms are



You expand/shrink unit balls to become tangent to the constraint line. We've encountered this in previous units.

Project: Visualization in 2d and 3d for different constraints.

## Gram-Schmidt:

① Usual way.

$$A = QR$$

↑

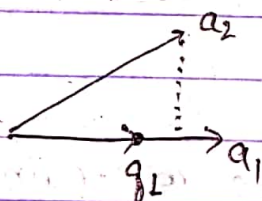
orthogonal  
columns

$$\Rightarrow R = Q^T A = Q^T A$$

$$\begin{bmatrix} q_1^T \\ \vdots \\ q_n^T \end{bmatrix} [a_1 \dots a_n]$$

$$\therefore R_{ij} = q_i^T a_j$$

18.06 way:



Step 1: Normalize  $a_1$

$$q_1 = \frac{a_1}{\|a_1\|}$$

Step 2: Subtract the component of  $a_2$  along  $q_1$  from  $a_2$  to obtain the component of  $a_2$  perpendicular to  $q_1$

$$\text{i.e. } A_2 = a_2 - (a_2^T q_1) q_1$$

$$\begin{aligned} x q_1 + \vec{e} &= \vec{a}_2 \\ x q_1^2 &= \vec{a}_2 \cdot \vec{q}_1 \\ \therefore x &= \frac{a_2^T q_1}{\|q_1\|} \end{aligned}$$

$$\therefore x = a_2^T q_1 \left[ \begin{array}{l} q_1 \text{ is unit} \\ \text{vector} \end{array} \right]$$

Step 3: Normalize  $A_2$

$$q_2 = \frac{A_2}{\|A_2\|}$$

For the vectors that follow,

$$A_k = a_k - \left[ (a_k^T q_1) q_1 + \dots + (a_k^T q_{k-1}) q_{k-1} \right]$$

$$q_k = \frac{A_k}{\|A_k\|}$$

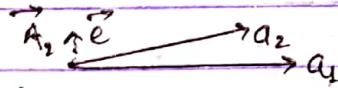


Rich:

Gram-Schmidt is applied in the usual order, at least in theory. So, we allow column exchanges in this method.

- Suppose  $a_1$  is of decent size

- $a_2$  could be close to  $a_1$



- $e$  is too small,  $q_2 = \frac{A_2}{\|A_2\|}$  could blow up because  $\|A_2\|$  is too small

So,

$$A_2 = a_2 - (a_2^T q_1) q_1$$

$$= a_3 - (a_3^T q_1) q_1$$

$$= a_n - (a_n^T q_1) q_1$$

Choose the  $A_2$  that is largest

we would have to compute these anyway.

Project: Implement in code.

### KRYLOV

$$Ax = b$$

long and sparse matrix

compute  $b, Ab, A^2b, \dots, A^{j-1}b$

= The combinations give Krylov's space  $K_j$

$x_j$  = Best vector [closest vector in Krylov's space]

What if these are nearly dependent?

→ orthogonalize [Arnold's method]

• Why is orthogonal (normal) basis great?

$$x = Qc = c_1 q_1 + c_2 q_2 + \dots + c_n q_n \quad \text{as} \quad \begin{bmatrix} Q \end{bmatrix} \begin{bmatrix} c \end{bmatrix}$$

$$c = Q^T x = Q^T x \quad \text{[for orthogonal basis]}$$

Arnoldi's algorithm;