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P36 Background
                                                                                                                                                                                                                                                                     Non linear - Transformation
                                                                                                                                                                                          Nonlinear
                                                    Data : Linear divisible
                                                                                                                  Allow mistakes
                                                                                                                  Pocket Algorithm
                                                                                                                                                                                            p(x)+PLA
                                                                                                                                                                                                                                                               input space feature space
                                                                    Hard-Margin SVM
                                                                                                                                                                       Φ(x)+Hord-Maggin SVM (kernal SVM)
                                                                                                                 Soft-Margin SVM
                                                                                     (1,0,1) (0,1,1) (1,0,1)
                                                       XOR Problem: Linear indivisible
                                                                       品本的形
                                                        Problems caused by non-linearity: OHigh-dimensional transformation due to nonlinearity (Dimensional upgrading process \varphi(x))
                                                                                                                                                   ② Duality donates dot product \phi(x_i)^{\mathsf{T}} \phi(x_j)
                                                        ②: Havd - Margin SVM

\begin{cases}
\lambda = a g_{A}^{m/\lambda} \stackrel{!}{\rightarrow} \stackrel{!}{\rightarrow} \lambda_{i} \lambda_{j} y_{i} y_{j} (x_{i}^{T} x_{j}) - \stackrel{!}{\rightarrow} \lambda_{i} \\
S.f. \lambda_{i} \geqslant 0, i = 1 \cdots N \\
\stackrel{!}{\rightarrow} \lambda_{i} y_{i}^{T} = 0
\end{cases}

\phi(x_{i})^{T} \phi(x_{j})
                                                            .. Complete dimensional upgrading and dot product simultaneously by kernel fuction
                                                              k(x,x') = \phi(x)^{\mathsf{T}}\phi(x') = \langle \phi(x), \phi(x') \rangle
P37 Positive-Definite Kernel
                                                        kemel: k: \chi * \chi \mapsto \mathbb{R} \ \forall \chi, \chi' \in \chi(\chi) \text{ indicates space} Then k(\chi, \chi) is kernel function
                                                       Positive-definite Kernel D: k: X × X → R, ∀ x, x' ∈ χ, ∃ k(x,x'). If ∃ø! χ → R, Ø∈ H (Hilbert space)
                                                                                                              S.t. k(x,x') = \langle \phi(x)^T \phi(x') \rangle, then k(x,x') is positive-definite kernel function
                                                                                                         0:k:\chi\cdot\chi\mapsto\mathbb{R}, \forall x, x'\in\chi, \hat{\mathbf{A}}k(x,x'). If k(x,x') satisfies the following two properties:
                                                                                                                   Osymmetry opositive-definite Then K(XX) is called positive-definite function
                                                                (1) Symmetry \iff k(x, x') = k(x', x)
                                                                © positive-definite \iff Any n elements, x_1, x_2 \cdots x_n \in \mathcal{X}, the corresponding Gram matrix is positive semidefinite i.e. \forall y \in \mathcal{X}, y^T k y \geq 0 \Rightarrow Gram matrix: k = k(x_1, x_2, \dots x_n) \cdots k
                                                             i.e. \forall y \in \mathcal{X}, y \neq 0 # Grain matrix: k = k(x_1, x_1) \cdots k(x_1, x_N)
k(x_1, x_1) = \langle \phi(x), \phi(x') \rangle \iff \text{Grain matrix is positive semidefinite}
k(x_1, x_1) = k(x_1, x_1) \cdots k(x_N, x_N)
with
                                                               # Hilbert Pace is complete linear space unith infinite number of dimensions and inner product (为建放空间) ① ③ (③
                                                                  ① Closed under limit: \{k_n\} \in \mathcal{H} \underset{n \to \infty}{\lim} k_n = k \in \mathcal{H}
② \{symmetry\} \{s,g\} = sg,f\}
\{s,g\} = sg,
P38 Proof of Necessity
                                                                Known K(x,x') = \langle \phi(x), \phi(x') \rangle, proof Gram matrix is positive-definite, and K(x,x') is symmetry
                                                                                Symmetry: k(x,x') = \angle \phi(x), \phi(x') > k(x',x) = \angle \phi(x'), \phi(x) > k(x',x) = \angle \phi(x')
                                                                                                  . Inner product has symmetry \langle \phi(x), \phi(x') \rangle = \langle \phi(x'), \phi(x) \rangle
                                                                  Ann is positive-definite (1) Eigenvalue >0

3 V2 = R^ 2TA270 V

Proof. positive-definite: V2 = R^ 2T k2 = 2T k1 .....kin 2
                                                                                                         \therefore k(X,x') = k(x',x) = Satify symmetry
                                                                                                              層式= 2^{T} [\phi(X_i) ... \phi(X_N)]^{T} [\phi(X_i) ... \phi(X_N)] 2
                                                                                                                          = \| \lambda [\phi(x_1) \cdots \phi(x_N)] \|^2 > 0
= \| [\frac{1}{2} \lambda_1 \phi(x_1)] \|^2
P38,5 Widely Used Kemal Function
                                                                  Common Kernel Functions (1) Linear Kernal K(x,x') = <x,x'>
                                                                                                       ⑤ Polynomial (BIRTI) kernal k(x,x') = (\langle x,x'\rangle + 1)^r 
③ Gaussian Kernal k(x,x') = \exp\{\frac{-||X-X'||^2}{2\sigma^2}\}
                                                                      Distance in the Feature Space: ||\phi(x) - \phi(x)||^2 = \langle \phi(x), \phi(x) \rangle - 2 \langle \phi(x), \phi(x) \rangle + \langle \phi(x), \phi(x') \rangle
                                                                      = k(x,x) - \sum k(x,x') + k(x',x')
Angle in the Feature Space: \cos \theta = \frac{\langle \phi(x), \phi(x') \rangle}{\||\phi(x)|| \||\phi(x')||} = \frac{k(x,x')}{\int K(x,x) K(x',x')}
                                                                         kernel function binary classification
                                                                      Feature mapping Use each dimension of y as a coordinate
                                                                                             0_{D^0} X: C_t = \frac{1}{N} \sum_{i:[N+C_i]} \phi(x_i) (C is the mean value of the vectors after chimension upgrading)
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(DIf $\phi(x)$ is known than the solution can be solved directly