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Support Vector Machine
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P28 Hard-Margin SVM - Model Defination
                                                                                                        SVM three features: Margin; Duality; kernel
                                                                                                                                                    Ohard-margin SUM Osaft-margin SVM 3 Kernel SVM
                                                                                                                         f(w) = sign(w^{T}x + b) Let distance (w, b, x_i) be the distance of x_i to hyperplane w^{T}x + b
                                                                                                                    distance (w.b.xi) = ITWII / wo xi tbl
                                                                                                                   Maximum internal classifier { û, } = ovgmax margin (w.b)
                                                                                                                                                                                                                                                        margin (w,b) = \min_{i=1,...N}^{min} distance(w,b,x_i) \Rightarrow The distance from the nearest point to the hyperplane among all points
                                                                                                                             S.t. y_{\cdot}(\omega X_{i}+b) > 0 \quad i=1 \cdots N
\Rightarrow \begin{cases} \hat{\alpha} \cdot \hat{\beta} = \underset{\omega,b}{\operatorname{org}} \underset{i}{\operatorname{min}} y_{i}(\omega X_{i}+b) \\ \text{S.t. } y_{\cdot}(\omega X_{i}+b) > 0 \Rightarrow \exists \gamma > 0 \text{ s.t. } \underset{\omega,b}{\operatorname{min}} y_{i}(\omega X_{i}+b) = \gamma \end{cases}
\Rightarrow \begin{cases} \hat{\alpha} \cdot \hat{\beta} = \underset{\omega,b}{\operatorname{org}} \underset{i}{\operatorname{min}} y_{i}(\omega X_{i}+b) = \gamma \\ \text{S.t. } y_{i}(\omega X_{i}+b) > 0 \Rightarrow \exists \gamma > 0 \text{ s.t. } \underset{\omega,b}{\operatorname{min}} y_{i}(\omega X_{i}+b) = \gamma \end{cases}
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P29 Model Solution, Duality Problem
                                                                                                                                              \mathcal{L}(\omega,b,\lambda) = \frac{1}{2}\omega^{2}\omega + \frac{1}{1-1}\lambda_{i}\left[1-y_{i}(\omega x_{i}+b)\right] \implies \begin{cases} \hat{\omega}, \hat{b} = \frac{m_{i}h}{\omega,b} \frac{max}{\Delta} \mathcal{L}(\omega,b,\lambda) \\ \text{s.t. } \lambda_{i} \neq 0 \end{cases}
                                                                                                                                                  #Lagrange Multiplier Method hides the y; (w x; +b)=1 condition in the filtering process of finding minimum
                                                                                                                                                      \Rightarrow \begin{cases} \text{If } 1-y; (\text{wilith}) > 0, & \max \{(w,b,\lambda) = \frac{1}{2}w^{T}w + 00 = 0 \} \\ \text{If } 1-y; (\text{wilith}) \leq 0, & \max \{(w,b,\lambda) = \frac{1}{2}w^{T}w + 00 = 0 \} \\ \text{win } \max \{(w,b,\lambda) = \min \{(\infty,\frac{1}{2}w^{T}w) = \min \{\frac{1}{2}w^{T}w + 1 \} \} \end{cases}
                                                                                                                                                    Duality Problem: Weak Duality; min max f > max min f
                                                                                                                                                                                                                                                   Strong Quality: minmax f = maxminf
                                                                                                                                                       \begin{cases} \hat{\lambda} = \max_{\lambda} \min_{\lambda} \lambda(w,b,\lambda) \\ s.t. \quad \lambda \geq 0 \quad i=1...N \\ \frac{\partial \lambda}{\partial b} = \frac{\kappa}{2} \lambda(y) = 0 \quad \text{if } \lambda \lambda(w,b,\lambda) \Rightarrow \text{ Find it with support vectors in the next section.} \end{cases}
                                                                                                                                                                                    \frac{\partial m}{\partial T} = M - \frac{1}{2} y(\hat{J}_1 X) = 0 \hat{W} = \frac{1}{2} y(\hat{J}_1 X) + (y(\hat{J}_1 Y))

\begin{array}{lll}
\sum_{\lambda \in \mathcal{A}} (\omega, \lambda, \lambda) &= \frac{1}{2} \left( \frac{1}{2} \lambda_{\lambda} J_{\lambda} X_{\lambda} \right)^{T} \left( \frac{1}{2} \lambda_{\lambda} J_{\lambda} X_{\lambda} \right) + \frac{1}{2} \lambda_{\lambda} - \frac{1}{2} \lambda_{\lambda} J_{\lambda} J_{\lambda} X_{\lambda} \right)^{T} X_{\lambda} \\
&= \frac{1}{2} \frac{1}{2} \frac{1}{2} \lambda_{\lambda} \lambda_{\lambda} J_{\lambda} J_{\lambda} J_{\lambda} X_{\lambda}^{T} X_{\lambda} + \frac{1}{2} \lambda_{\lambda} - \frac{1}{2} \frac{1}{2} \lambda_{\lambda} \lambda_{\lambda} J_{\lambda} J_{\lambda} J_{\lambda}^{T} X_{\lambda} \\
&= \frac{1}{2} \lambda_{\lambda} - \frac{1}{2} \frac{1}{2} \frac{1}{2} \lambda_{\lambda} \lambda_{\lambda} J_{\lambda} J_{\lambda}^{T} J_{\lambda}^{T} X_{\lambda} \\
&= \frac{1}{2} \lambda_{\lambda} - \frac{1}{2} \frac{1}{2} \frac{1}{2} \lambda_{\lambda} \lambda_{\lambda} J_{\lambda}^{T} J_{\lambda}^{T} J_{\lambda}^{T} X_{\lambda} \\
&= \frac{1}{2} \lambda_{\lambda} - \frac{1}{2} \frac{1}{2} \frac{1}{2} \frac{1}{2} \lambda_{\lambda} \lambda_{\lambda} J_{\lambda}^{T} J_{\lambda}
P30 Model Solution, kKT Condition (Korush-kuhn-Tucker condition)
                                                                                                                                                                          K|\zeta| condition : \begin{cases} \frac{\partial L}{\partial b} = 0 & \frac{\partial L}{\partial w} = 0 \\ \lambda_1 \left( 1 - y_1(w\lambda_1 + b) \right) = 0 \longrightarrow \text{Complementory Slackness} \left( \frac{5}{2}\lambda_1 + \frac{1}{2}\lambda_2 \right) \\ \lambda_1 \geq 0, \ |-y_1(w\lambda_1 + b) \leq 0 \end{cases} Support Vectors : \lambda \neq 0; Non-support Vectors : \lambda = 0
                                                                                                                                                                         Find \hat{b}: \exists (x_k, y_k) \mid s.f. \vdash y_k(\vec{w}x_k+b) = 0 (i.e. support vectors)
                                                                                                                                                                                                                                         : yk(wxk+b)=1 => yk(wxk+b)=yk -yk=11 : wxk+b=yk
                                                                                                                                                                                                                                           \hat{x} = \sum_{k=1}^{N} \lambda_k \hat{y}_k \hat{y}_
    P3| Soft-margin SVM
                                                                                                                                                                                            Allow classiter to make mistakes: \hat{\omega}, \hat{b} = \frac{\partial g_{w,b}}{\partial w_{w,b}} \pm w^{T}w + loss
                                                                                                                                                                                               O Count : (ass = \frac{1}{14}] { y; (wx; tb)<1} But the function ist continuous
                                                                                                                                                                                             @Distance: If yi(wixi+b) >1, lossi=0; If yi(wixi+b)<1, lossi=1-yi(wixi+b)
                                                                                                                                                                                                             : (bs); = max { 0, 1-y; (w7x;+b)}
                                                                                                                                                                                                       Simplify to \Rightarrow g_i = 1 - y_i(w x_i + b), g_i \ge 0
\begin{cases} \hat{w}, \hat{b} = \underset{w,b}{\operatorname{arg min}} = w^T w + C \underset{i=1}{\underline{\forall}} g_i \\ \text{s.t.} \quad y_i(w^T x + b) \ge 1 - g_i, \quad g_i \ge 0 \end{cases}
   P32 Weak Duality
                                                                                                                                                                            Generalized constrained optimization problem : \int \min_{x} f(x)
                                                                                                                                                                                                                                                                                                                                                                                                                                                   st. mi(x) <0, nj(x) =0 i=1...M, j=1...N
                                                                                                                                                                         d(x,\lambda,\eta) = f(x) + \underset{i=1}{\overset{\text{def}}{\rightleftharpoons}} \lambda; m; (x) + \underset{i=1}{\overset{\text{def}}{\rightleftharpoons}} \eta; n; (x) \qquad \begin{cases} \min \max_{x \in X} \ \chi(x,\lambda,\eta) & \approx \text{ Unconstrained form of the original problem} \\ \text{s.t. } \lambda; \geqslant 0 \quad i=1\cdots M \end{cases} 
\text{In fact there are still constraints}
                                                                                                                                                                                   Duality Problem S Original Problem
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هرم، ۱۸۰۱ - این اوا ۱۱
                                                         # If mi(x)>0, coefficient is negative S.f. 2; 30 i=1...M In fact there are still constraints
                                          Duality Problem < Original Problem
                                          max min L(x, x, y) < min max L(x, x, y)
                                          \overline{\mathcal{U}}: \underset{x}{\text{min}} \mathcal{L}(x,\lambda,\eta) \leq \mathcal{L}(x,\lambda,\eta) \leq \underset{\lambda,\eta}{\text{max}} \mathcal{L}(x,\lambda,\eta)
                                                  X is constant now, i.e. A(\lambda n) \leq B(x)
                                                    \therefore \max A(\lambda, \eta) \leq \min B(x)
P33 Duality Problem - Geometric Interpretation
                                          Simplified optimization problem: \int m \ln f(x) \ x \in \mathbb{R}^p \implies \int (\chi_{\lambda}) = f(x) + \lambda m(x), \lambda \neq 0
                                                                           S.f. m(x) ≤ 0
                                          P^* = minf(x), m(x) \le 0 (Original problem optimum solution) d^* = \max_{x} \min_{x} \int_{x} (x, x) (Duality problem optimum solution)
                                         G = \{ (m(x), f(x)) \mid x \in \mathcal{P} \} \quad \not\bowtie \quad m(x) = \alpha \quad f(x) = b
                                          P^* = \inf\{b \mid (a,b) \in G, a \leq 0\}  (inf is infimum (TARR))
                                          d = \max_{\alpha} \min_{\alpha} \{(\lambda_{\alpha}) \text{ Set } g(\lambda) = \min_{\alpha} \{b + \lambda_{\alpha}\}  d = \max_{\alpha} g(\lambda)
                                              ga) = inf{b+\ala,b)&a} i.e. the minimum of the intersection of the line b+\a=? and G
                                                d^* is the point that maximum g(\lambda) when \lambda (slope) changes, i.e. line O
                                                i of X \leq P^{*} When the part of the function G that intersects the b-axis is a convex function + slater condition
                                                                                                                    # Slater is a sufficient non-essential condition for strong duality
P34 Slater Condition
                                            Sminfal D= {domf ∩ dom ẩm; ∩an}
                                           St. mi(a) < 0, i=1 ·· M Domain of definition
                                                     N_{j}(X) = 0, j = 1 \dots N_{j}
                                             Slater condition:
                                              \exists \hat{x} \in \text{relint} \bigcirc \bigcirc The set is the inner part after removing the boundary \bigcirc \bigcirc \bigcirc \bigcirc \bigcirc
                                                                                                                                                                           Slope -\lambda \le 0 Unsatisfied
                                              S.t. \forall i=1...M, m_i(\hat{x})<0 \Longrightarrow The set G must have points at microso
                                             \bigcirc Most convex optimization problems scatisfy Slater \bigcirc Affine function no need to proof m_i(\widehat{x}) < 3
                                              # Affine function: The polynomial function with the highest order is 1 e.g. f(x) = Ax+b
                                                  Affine function with a constant term of zero is linear function e.g. f(x) = AX
                                              From D. if for is a convex function and minimo one affine functions, then it satisfies Slater .: Satisfy strong duality
P35 KKT (andition
                                                   [min f(x)
                                                         Passable condition: \begin{cases} m_i(x^*) \leq 0 \\ n_j(x^*) = 0 \end{cases} optimal solution optimal value \lambda^* \geq 0 \qquad \text{Set} \quad d^* = \lambda^*, \, \eta^* complementary slackness: \lambda_i m_i = 0 \qquad \qquad p^* = \chi^* gradient is 0: \frac{2J(x, \chi^*, \eta^*)}{2\chi}|_{x=\chi^*} = 0 Tt's also used in SVM: Support vectors with \chi \neq 0 f kKT by Strong Duality Support vectors with \chi \neq 0
                                                   Proof KKT by Strong Duality
                                                  d^* \stackrel{Q}{=} \stackrel{\text{max}}{\uparrow} g(\lambda, \eta) \stackrel{Q}{=} g(\lambda^*, \eta^*) = \stackrel{\text{min}}{\downarrow} L(\lambda, \lambda^*, \eta^*) \stackrel{Q}{=} L(\lambda^*, \lambda^*, \eta^*) \stackrel{Q}{=}
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d^{x} \stackrel{\text{iff}}{=} \chi^{x} \eta^{x} \mathcal{J}(\lambda, \eta) \stackrel{\text{iff}}{=} \mathcal{J}(\chi^{x}, \eta^{x}) = \lim_{X \to X} \mathcal{J}(\chi, \chi^{x}, \eta^{x}) \stackrel{\text{iff}}{=} \mathcal{J}(\chi^{x}, \chi^{x}, \eta^{x}) \stackrel{\text{iff}}{=} \mathcal{J}(\chi^{x}, \chi^{x}, \eta^{x}) \stackrel{\text{iff}}{=} \mathcal{J}(\chi^{x}, \chi^{x}, \eta^{x}) = 0
\lim_{X \to X} \mathcal{J}(\chi^{x}, \chi^{x}, \eta^{x}) = \lim_{X \to X} \mathcal{J}(\chi^{x}, \chi^{x}, \eta^{x}) \stackrel{\text{iff}}{=} \chi^{x} \eta^{x} \mathcal{J}(\chi, \chi^{x}, \eta^{x}) \stackrel{\text{if}}{=} \chi^{x} \eta^{x} \mathcal{J}(\chi, \chi^{x}, \chi^{x}, \eta^{x}) \stackrel{\text{if}}{=} \chi^{x} \eta^{x} \mathcal{J}(\chi, \chi^
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