# 第四章数据流挖掘(下)

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大数据分析与挖掘



# Today's Lecture

- More algorithms for streams:
  - 4.3 Filtering a data stream: Bloom filters
    - Select elements with property x from stream
  - 4.4 Counting distinct elements: Flajolet-Martin
    - Number of distinct elements in the last k elements of the stream
  - 4.5 Estimating moments: AMS method
    - Estimate std. dev. of last k elements
  - 4.7 Counting frequent items

# 4.3 流过滤

# Filtering Data Streams

# Filtering Data Streams

- Each element of data stream is a tuple
- Given a list of keys S
- Determine which tuples of stream are in S
- Obvious solution: Hash table
  - But suppose we do not have enough memory to store all of S in a hash table
    - E.g., we might be processing millions of filters on the same stream

## **Applications**

#### Example: Email spam filtering

- We know 1 billion "good" email addresses
- If an email comes from one of these, it is NOT spam

#### Publish-subscribe systems

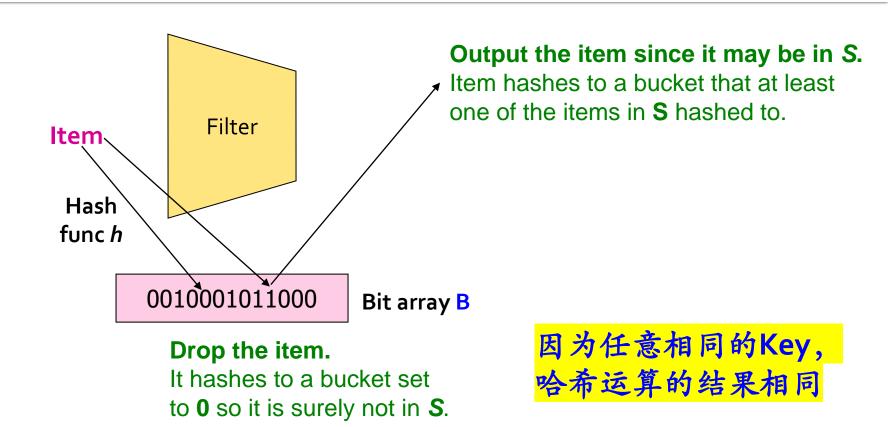
- You are collecting lots of messages (news articles)
- People express interest in certain sets of keywords
- Determine whether each message matches user's interest

### First Cut Solution (1)

#### Given a set of keys S that we want to filter

- Create a bit array B of n bits, initially all Os
- Choose a hash function h with range [0,n)
- Hash each member of s∈ S to one of n buckets, and set that bit to 1, i.e., B[h(s)]=1
- Hash each element a of the stream and output only those that hash to bit that was set to 1
  - Output a if B[h(a)] == 1

### First Cut Solution (2)



- Creates false positives but no false negatives
  - If the item is in S we surely output it, if not we may still output it

## First Cut Solution (3)

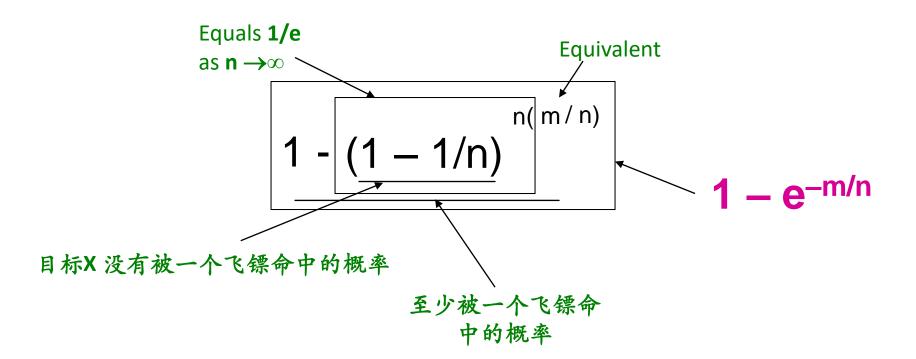
- |S| = 1 billion email addresses|B| = 1GB = 8 billion bits
- If the email address is in S, then it surely hashes to a bucket that has the big set to 1, so it always gets through (no false negatives)
- Approximately 1/8 of the bits are set to 1, so about 1/8<sup>th</sup> of the addresses not in S get through to the output (false positives)
  - Actually, less than 1/8<sup>th</sup>, because more than one address might hash to the same bit

# <u>Analysis:</u> Throwing Darts (1)

- 现在,我们来更精准的分析假阳性问题
- 想象一个投飞镖游戏,如果m个飞镖,n个概率相等的目标,一个目标被射中至少一个飞镖的概率是多少呢?
- 在上面的例子中:
  - 目标 = bits/buckets
  - 飞镖 = hash values of items

# <u>Analysis:</u> Throwing Darts (2)

- ■m个飞镖,n个目标
- ■1个目标至少被1个飞镖命中的概率:



# Analysis: Throwing Darts (3)

- Fraction of 1s in the array B =
   probability of false positive = 1 e<sup>-m/n</sup>
- Example: 10<sup>9</sup> darts, 8·10<sup>9</sup> targets
  - Fraction of 1s in  $B = 1 e^{-1/8} = 0.1175$ 
    - Compare with our earlier estimate: 1/8 = 0.125

### **Bloom Filter**

- Consider: |S| = m, |B| = n
- Use k independent hash functions  $h_1, ..., h_k$
- Initialization:
  - Set B to all 0s
  - Hash each element  $s \in S$  using each hash function  $h_i$ , set  $B[h_i(s)] = 1$  (for each i = 1,..., k) (note: we have a single array B!)
- Run-time:
  - When a stream element with key x arrives
    - If  $B[h_i(x)] = 1$  for all i = 1,..., k then declare that x is in S
      - That is, x hashes to a bucket set to 1 for every hash function h;(x)
    - Otherwise discard the element x

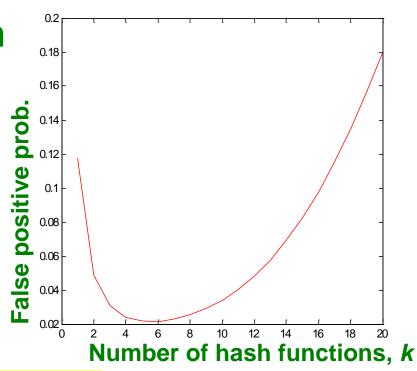
# **Bloom Filter -- Analysis**

- What fraction of the bit vector B are 1s?
  - Throwing k·m darts at n targets
  - So fraction of 1s is  $(1 e^{-km/n})$
- But we have k independent hash functions and we only let the element x through if all k hash element x to a bucket of value 1
- So, false positive probability = (1 − e<sup>-km/n</sup>)<sup>k</sup>

# Bloom Filter – Analysis (2)

- = m = 1 billion, n = 8 billion
  - k = 1:  $(1 e^{-1/8}) = 0.1175$
  - k = 2:  $(1 e^{-1/4})^2 = 0.0493$

What happens as we keep increasing k?



- "Optimal" value of k: n/m In(2)
  - In our case: Optimal k = 8 In(2) = 5.54 ≈ 6
    - Error at k = 6:  $(1 e^{-1/6})^2 = 0.0235$

### Bloom Filter: 总结

- Bloom filters guarantee no false negatives, and use limited memory
  - Great for pre-processing before more expensive checks
- Suitable for hardware implementation
  - Hash function computations can be parallelized
- Is it better to have 1 big B or k small Bs?
  - It is the same:  $(1 e^{-km/n})^k$  vs.  $(1 e^{-m/(n/k)})^k$
  - But keeping 1 big B is simpler

4.4 流中独立元素的数目统计

(2) Counting Distinct Elements

# Counting Distinct Elements

#### Problem:

- Data stream consists of a universe of elements chosen from a set of size N
- Maintain a count of the number of distinct elements seen so far
- Obvious approach:

Maintain the set of elements seen so far

 That is, keep a hash table of all the distinct elements seen so far

# Applications

- How many different words are found among the Web pages being crawled at a site?
  - Unusually low or high numbers could indicate artificial pages (spam?)
- How many different Web pages does each customer request in a week?
- How many distinct products have we sold in the last week?

# **Using Small Storage**

- Real problem: What if we do not have space to maintain the set of elements seen so far?
- Estimate the count in an unbiased way
- Accept that the count may have a little error,
   but limit the probability that the error is large

# Flajolet-Martin Approach

- Pick a hash function h that maps each of the N elements to at least log, N bits
- For each stream element a, let r(a) be the number of trailing 0s in h(a)
  - r(a) = position of first 1 counting from the right
    - E.g., say h(a) = 12, then 12 is 1100 in binary, so r(a) = 2
- Record R = the maximum r(a) seen
  - $\mathbf{R} = \mathbf{max}_{\mathbf{a}} \mathbf{r(a)}$ , over all the items  $\mathbf{a}$  seen so far
- Estimated number of distinct elements = 2<sup>R</sup>

# Why It Works: Intuition

- Very very rough and heuristic intuition why Flajolet-Martin works:
  - 假设hash函数是纯随机的,等概率将a映射到N的值
  - 因此 h(a)就是编码为log2 N bits的序列
  - 末尾r个0的a占 2-r
    - 末尾1个0的a占 50% \*\*\*0
    - 末尾2个0的a占 25% \*\*00
    - 所以,看到末尾最长0的个数 *r=2* (\*100) ,可以估计大概有 4 个独立的元素②
  - So, it takes to hash about 2<sup>r</sup> items before we see one with zero-suffix of length r

# Why It Works: More formally

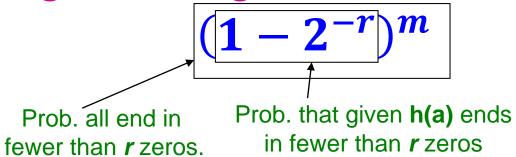
- Now we show why Flajolet-Martin works
- Formally, we will show that probability of finding a tail of r zeros:
  - Goes to 1 if m >> 2<sup>r</sup>如果m远大于2<sup>r</sup>则,发现r个 零的概率约接近1
  - Goes to 0 if  $m \ll 2^r$ 如果m远小于 $2^r$ 则,发现r个零的概率约接近0

其中,m是流中独立元素的数量

Thus,  $2^R$  will almost always be around m!

# Why It Works: More formally

- What is the probability that a given h(a) ends in at least r zeros is 2<sup>-r</sup>
  - h(a) hashes elements uniformly at random
  - Probability that a random number ends in at least r zeros is 2-r
- Then, the probability of NOT seeing a tail of length r among m elements:



# Why It Works: More formally

- Note:  $(1-2^{-r})^m = (1-2^{-r})^{2^r(m2^{-r})} \approx e^{-m2^{-r}}$
- Prob. of NOT finding a tail of length r is:
  - If  $m \ll 2^r$ , then prob. tends to 1
    - $(1-2^{-r})^m \approx e^{-m2^{-r}} = 1$  as  $m/2^r \rightarrow 0$
    - So, the probability of finding a tail of length r tends to 0
  - If *m* >> 2<sup>r</sup>, then prob. tends to 0
    - $(1-2^{-r})^m \approx e^{-m2^{-r}} = 0$  as  $m/2^r \to \infty$
    - So, the probability of finding a tail of length r tends to 1
- Thus, 2<sup>R</sup> will almost always be around m!

# Why It Doesn't Work

- E[2<sup>R</sup>] is actually infinite
  - Probability halves when  $R \rightarrow R+1$ , but value doubles
- Workaround involves using many hash functions h<sub>i</sub> and getting many samples of R<sub>i</sub>
- How are samples R<sub>i</sub> combined?
  - Average? What if one very large value  $2^{R_i}$ ?
  - Median? All estimates are a power of 2
  - Solution:
    - Partition your samples into small groups
    - Take the median of groups
    - Then take the average of the medians

# 4.5 矩估计

# **Estimating Moments**

矩 (moment) 是对变量分布和形态特点的一组度量, 将流中独立元素的计数问题推广到更一般的情况

### Generalization: Moments

 Suppose a stream has elements chosen from a set A of N values

全集A,有N个不同的值元素。现实中,即使全集中元素不是数值型,我们也可以将元素排序,并用整数i来标记每个元素

- Let m<sub>i</sub> be the number of times value i occurs in the stream (m<sub>i</sub>是元素i出现的次数)
- The k<sup>th</sup> moment (K 阶矩) is

$$\sum_{i \in A} (m_i)^k$$

# Special Cases

$$\sum_{i \in A} (m_i)^k$$

- Othmoment = number of distinct elements
  - The problem just considered 独立元素的数量
- 1<sup>st</sup> moment = count of the numbers of elements = length of the stream 所有元素数量,等价于流的总长度
  - Easy to compute
- 2nd moment = surprise number S =
   a measure of how uneven the distribution is
   奇异数,可以用于刻画流中元素的分布不均匀性

## **Example: Surprise Number**

- Stream of length 100
- 11 distinct values
- Item counts: 10, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9, 9
  Surprise S = 910
- Item counts: 90, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  Surprise S = 8,110

每个独立元素,出现次数越均匀,奇异数越 小,越不均匀,奇异数越大

### **AMS Method**

- AMS method works for all moments
- Gives an unbiased estimate (无偏估计)
- We will just concentrate on the 2<sup>nd</sup> moment S
- We pick and keep track of many variables X:
  - For each variable X we store X.el and X.val
    - X.el corresponds to the item i
    - X.val corresponds to the count of item i
  - Note this requires a count in main memory,
     so number of Xs is limited 不用记录流中每个元素
- Our goal is to compute  $S = \sum_i m_i^2$

### One Random Variable (X)

- How to set X.val and X.el?
  - Assume stream has length n (实际n不断增长,后面介绍处理方法)
  - Pick some random time *t* (*t<n*) to start, so that any time is equally likely (选择了一组t)
  - Let at time t the stream have item i. We set X.el = i
  - Then we maintain count c (X.val = c) of the number of is in the stream starting from the chosen time t

将每个t时刻的元素记为X.el,并从t到n,对X.el的 X.val进行计数

### One Random Variable (X)

• Then the estimate of the  $2^{nd}$  moment ( $\sum_i m_i^2$ ) is:

$$S = f(X) = n(2 \cdot c - 1)$$

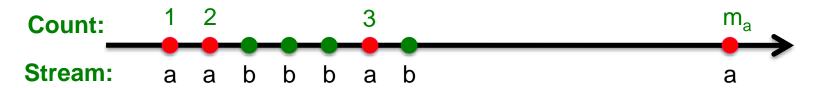
- Where, c = X.val
- Note, we will keep track of multiple Xs, (X<sub>1</sub>,

 $X_2,...X_k$ ), and our final estimate will be

$$S = 1/k \sum_{j=1}^{k} f(X_j)$$
 最终估值

K个变量的计数,是内存可以计算的,不是全部独立元素

# Expectation Analysis 期望



- 2<sup>nd</sup> moment is  $S = \sum_i m_i^2$
- c<sub>t</sub> ... number of times item at time t appears from time **t** onwards  $(c_1=m_a, c_2=m_a+1, c_3=m_b)$
- $E[f(X)] = \frac{1}{n} \sum_{t=1}^{n} n(2c_t 1)$  $= \frac{1}{n} \sum_{i} n \left( 1 + 3 + 5 + \dots + 2m_i - 1 \right)$

**Group times** by the value seen

Time t when the last *i* is seen (*c*,=1)

Time **t** when the penultimate i is seen ( $c_t$ =2)

Time **t** when the first *i* is seen ( $c_t = m_i$ )

 $m_i$  ... total count of item *i* in the stream

(we are assuming stream has length **n**)

# **Expectation Analysis**

- $E[f(X)] = \frac{1}{n} \sum_{i} n (1 + 3 + 5 + \dots + 2m_i 1)$ 
  - $\sharp \psi (1+3+5+\dots+2m_i-1) = \sum_{i=1}^{m_i} (2i-1) = \frac{m_i(1+2m_i-1)}{2} = m_i^2$
- Then  $E[f(X)] = \frac{1}{n} \sum_i n (m_i)^2$
- So,  $E[f(X)] = \sum_{i} (m_i)^2 = S$
- We have the second moment (in expectation)!

## **Higher-Order Moments**

- For estimating k<sup>th</sup> moment we essentially use the same algorithm but change the estimate:
  - For k=2 we used  $n(2\cdot c-1)$
  - For k=3 we use:  $n(3\cdot c^2 3c + 1)$  (where c=X.val)
- Why?
  - For k=2: Remember we had  $(1+3+5+\cdots+2m_i-1)$  and we showed terms **2c-1** (for **c=1,...,m**) sum to  $m^2$ 

    - So:  $2c 1 = c^2 (c 1)^2$
  - For k=3:  $c^3 (c-1)^3 = 3c^2 3c + 1$
- Generally: Estimate =  $n(c^k (c-1)^k)$

# **Combining Samples**

#### In practice:

- Compute f(X) = n(2c-1) for as many variables X as you can fit in memory
- Average them in groups
- Take median of averages

#### Problem: Streams never end

- We assumed there was a number n, the number of positions in the stream
- But real streams go on forever, so n is a variable – the number of inputs seen so far

## Streams Never End: Fixups

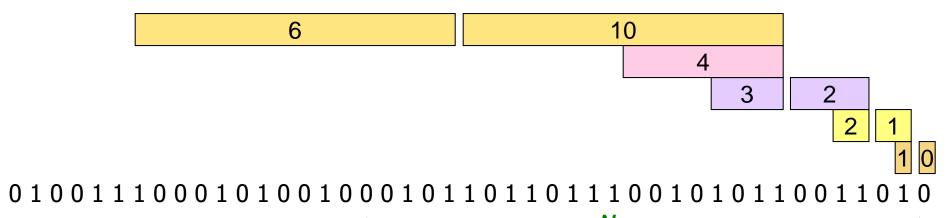
- (1) The variables X have n as a factor keep n separately; just hold the count in X
- (2) Suppose we can only store k counts.
  We must throw some Xs out as time goes on:
  - Objective: Each starting time t is selected with probability k/n
  - Solution: (fixed-size sampling!)
    - Choose the first k times for k variables
    - When the  $n^{th}$  element arrives (n > k), choose it with probability k/n
    - If you choose it, throw one of the previously stored variables X out, with equal probability

# 4.7 基于衰减窗口的计数问题

# **Counting Itemsets**

# **Counting Itemsets**

- New Problem: Given a stream, which items appear more than s times in the window?
- Possible solution: Think of the stream of baskets as one binary stream per item
  - 1 = item present; 0 = not present
  - Use DGIM to estimate counts of 1s for all items



### Extensions

- In principle, you could count frequent pairs or even larger sets the same way
  - One stream per itemset
- Drawbacks:
  - Only approximate
  - Number of itemsets is way too big

### Exponentially Decaying Windows指数衰减窗口

- Exponentially decaying windows: A heuristic for selecting likely frequent item(sets)
  - What are "currently" most popular movies?
    - Instead of computing the raw count in last **N** elements
    - Compute a smooth aggregation over the whole stream
- If stream is  $a_1$ ,  $a_2$ ,... and we are taking the sum of the stream, take the answer at time t to be:

$$=\sum_{i=1}^{t}a_{i}(1-c)^{t-i}$$

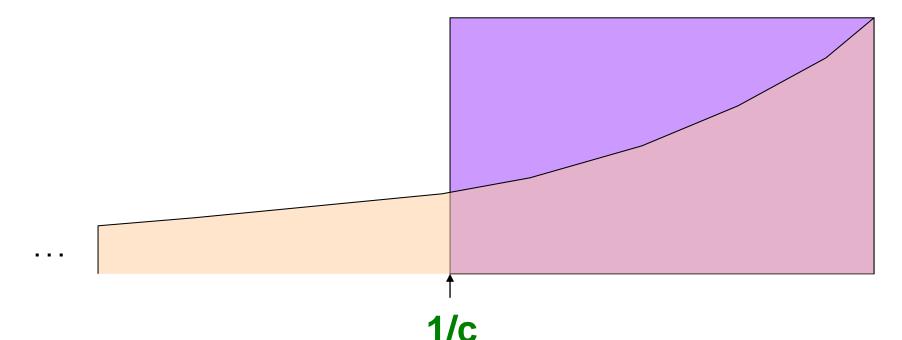
- c is a constant, presumably tiny, like 10<sup>-6</sup> or 10<sup>-9</sup>
- When new a<sub>t+1</sub> arrives:
   Multiply current sum by (1-c) and add a<sub>t+1</sub>

## **Example: Counting Items**

- If each a<sub>i</sub> is an "item" we can compute the characteristic function of each possible item x as an Exponentially Decaying Window
  - That is:  $\sum_{i=1}^{t} \delta_i \cdot (1-c)^{t-i}$  where  $\delta_i$ =1 if  $a_i$ =x, and 0 otherwise
  - Imagine that for each item x we have a binary stream (1 if x appears, 0 if x does not appear)
  - New item x arrives:
    - Multiply all counts by (1-c)
    - Add +1 to count for element x
- Call this sum the "weight" of item x

## **Sliding Versus Decaying Windows**

"权重的和"相同的情况下: 滑动窗口,1/c大小的窗口内,权重都为1 衰减窗口,参与计算的流元素更多,权重取决于出现时间



Important property: Sum over all weights  $\sum_{t} (1-c)^{t}$  is 1/[1-(1-c)] = 1/c

# Example: Counting Items

- What are "currently" most popular movies?
- Suppose we want to find movies of score > ½
  - Important property: Sum over all weights  $\sum_t (1-c)^t$  is 1/[1-(1-c)] = 1/c
- Thus:
  - There cannot be more than **2/c** movies with score of ½ or more 权重(得分)为1/2或更高的,不超过2/c
- So, 2/c is a limit on the number of movies being counted at any time

### **Extension to Itemsets**

- Count (some) itemsets in an E.D.W. (指数衰减窗口)
  - What are currently "hot" itemsets?
    - Problem: Too many itemsets to keep counts of all of them in memory
- When a basket B comes in:
  - Multiply all counts by (1-c)
  - For uncounted items in B, create new count
  - Add 1 to count of any item in B and to any itemset contained in B that is already being counted
  - Drop counts < ½</p>
  - Initiate new counts (next slide)

### **Initiation of New Counts**

- Start a count for an itemset S ⊆ B if every proper subset of S had a count prior to arrival of basket B
  - Intuitively: If all subsets of S are being counted this means they are "frequent/hot" and thus S has a potential to be "hot"

#### Example:

- Start counting S={i, j} iff both i and j were counted prior to seeing B
- Start counting S={i, j, k} iff {i, j}, {i, k}, and {j, k} were all counted prior to seeing B

# How many counts do we need?

- Counts for single items < (2/c)·(avg. number of items in a basket)
- Counts for larger itemsets = ??
- But we are conservative about starting counts of large sets
  - If we counted every set we saw, one basket of 20 items would initiate 1M counts