

## Exercise 13: Optimal control and fisheries management

Following the notes (section 13.8), we consider a population  $\{X_t : t \geq 0\}$  which is governed by the Itô sde

$$dX_t = X_t(1 - X_t) dt - U_t dt + \sigma X_t dB_t$$

Here,  $\{U_t : t \geq 0\}$  is a *catch rate*. The total profit arising from the harvesting is the random variable:

$$J = \int_0^T \sqrt{U_t} dt$$

Here,  $\sqrt{U_t}$  is the instantaneous income, which grows slower than the harvest  $U_t$  because the price will decrease with the supply. We allow only catches  $\{U_t\}$  such that  $X_t \geq 0$ .

**Question 1 Analytical steady-state solution:** Verify the solution in the notes. I.e., Show that a steady-state solution of the HJB equation is  $V(x, t) = V_0(x) - \gamma t$  with  $V_0(x) = \frac{1}{2} \log x + b$ ,  $\gamma = \frac{1}{2}(1 - \frac{1}{2}\sigma^2)$ , with the optimal control  $\mu^*(x) = x^2$ .

**Question 2 Simulation of the closed-loop system:** Simulate the system on the interval  $t \in [0, T]$ . Take  $\sigma = 1$ ,  $T = 10$ . Simulate also the system with constant harvest rate  $U_t = \frac{1}{2}X_t$ . Compare the two policies in terms of total payoff  $J$ ; how much better is the optimal strategy than the strategy with constant harvest rate? Why is it better?

**Question 3 Numerical solution of the HJB equation.:** Use the supplied code `HJB.R` to compute the value function and the optimal control from question 1; compare the numerical results with the analytical result. Take the domain to be  $[0, 5]$  and use reflection at both end points. Take  $\sigma = 0.5$ . *Note:* The formula (13.12) for the optimal control leads to numerical problems when  $V'_0$  is 0 or very small. A quick hack is to replace  $V'_0(x)$  in this formula with

$$\max\{V'_0(x), \bar{v}(x)\}$$

where  $\bar{v}(x)$  is  $\infty$  in the first grid cell and 0.01 in the remaining grid cells.

**Question 4 Extension to the Pella-Tomlinson model.:** Repeat the numerical analysis for the Pella-Tomlinson model

$$dX_t = X_t(1 - X_t^p) dt - U_t dt + \sigma X_t dB_t$$

for  $p = 0.5$  and  $p = 2$ . Show how the optimal policy depends on  $p$ .