02425 November 21, 2024 UHT/uht

## Exercise 11: The generator

Following section 11.2.3, consider the linear stochastic differential equation

$$dX_t = -X_t dt + \sqrt{2} dB_t, \quad X_0 = x$$

evolving on the interval  $X_t \in (-l, l)$  Let  $\tau = \inf\{t : |X_t| \ge l\}$  denote the first time of exit from the interval. We aim to find  $\mathbf{E}^{X_0 = x} \tau$ . Moreover, we want to find the probability of exiting to the right, i.e.  $\mathbb{P}^{X_0 = x}(X_\tau = 1)$ 

Question 1 Monte Carlo simulation: Estimate  $\mathbb{P}^{X_0=x}(X_{\tau}=l)$  and  $\mathbf{E}^{X_0=x}\tau$ , for x=l/2, by simulating N=1,000 realizations of  $X_t$  until  $\tau$ . Take l=1 and use a sufficiently fine time step. Repeat for l=2 and even larger values of l.

**Solution:** We start by setting up the model. In this solution, we only show results with one value of l, viz. 2, not to clutter the solution with too many plots.

```
require(SDEtools)
require(MASS)

f <- function(x) -x
g <- function(x) sqrt(2)

x0 <- 0.5
1 <- 2

## "Reasonable" time step
dt <- 1e-3</pre>
```

The following function simulates until the stopping time:

```
## Simulate with the Euler method until exit from domain
sim <- function(dummy)
{
    x <- x0
    t <- 0
    r <- 0
    while(abs(x)<1)
    {
        t <- t + dt
        x <- x + f(x)*dt + g(x)* rnorm(1,sd=sqrt(dt))
        r <- r + x^2 *dt
    }
    return(c(t=t,x=x,r=r))
}</pre>
```

We can now run a number of samples and estimate the probability of exit to the right as well as the time to exit:

```
## Obtain N samples
N <- 1000
res <- sapply(1:N,sim)
print(paste("Mean time to exit: ",mean(res[1,])))

## [1] "Mean time to exit: 4.56806199999995"

print(paste("Probability of exit to the right: ",mean(res[2,]>0)))

## [1] "Probability of exit to the right: 0.553"
```

Question 2 Finding  $\mathbb{P}^{X_0=x}(X_{\tau}=l)$  using a backward equation: Write a boundary value problem which governs  $h(x):=\mathbb{P}^{X_0=x}(X_{\tau}=l)$ . Solve the boundary value problem using whichever method you prefer. Plot the solution for the values of l you used in the previous and compare the results. *Hint:* Applicable methods are: Analytical solution, e.g. in terms of the scale function. Numerical solution using a built-in solver of boundary value problems (e.g. bvp4c in Matlab, pracma::bvp in R, scipy.solve\_bvp in python). Numerical solution using the generator obtained from fvade - in that case, use boundary condition 'e' to "extend" the generator and include the absorbing boundary points.

**Solution:** The BVP governing the probability of exit is

$$Lh = h'f + \frac{1}{2}g^2h'' = -xh'(x) + h'' = 0$$

with boundary conditions h(-l) = 0, h(l) = 1. Let us first determine the scale function s. Its derivative  $\phi = s'$  is given by the ODE

$$\phi'(x) = x\phi$$

so

$$\phi(x) = \phi(0)e^{x^2/2}$$

We can, arbitrarily, set  $\phi(0) = 1$  to get

$$s(x) = \int_0^x e^{y^2/2} \ dy.$$

For afficionados of special functions, this can be written in terms of the imaginary error function, erfi:

$$s(x) = \sqrt{2} \operatorname{erfi}(x/\sqrt{2})$$

although I am not sure if this is overly useful.

The following code illustrates multiple ways of computing the result. We first use the solver pracma::bvp for boundary value problems:

```
## Using pracma::bup
require(pracma)

## Loading required package: pracma

sol <- bvp(f=function(x)x,g=function(x)0*x,h=function(x)0*x,x=c(-1,1),y=c(0,1),n=200)</pre>
```

We next compute the scale function with numerical integration, and fixes the constant to match the boundary conditions.

```
## Compute the solution from the scale function, using numerical integration
phi <- function(x) exp(integrate(function(y)-2*f(y)/g(y)/g(y),lower=0,upper=x)$value)
phiv <- function(x) sapply(x,phi) # Vectorize
s <- function(x) integrate(phiv,lower=0,upper=x)$value
sv <- function(x) sapply(x,s) # Vectorize

sm <- s(-1) # Boundary points
sp <- s(+1)

ss <- function(x) (sv(x)-sm)/(sp-sm) # Scaled scale function (sic)</pre>
```

Finally, we discretize the equation using the fvade function:;

```
## Discretize the generator and find its null space
xi <- seq(-1,1,length=201)
xc <- xi[-1] - 0.5*diff(xi)
G <- fvade(f,function(x)0.5*g(x)*g(x),xi,'e')

## Loading required package: Matrix

##
## Attaching package: 'Matrix'

## The following objects are masked from 'package:pracma':
##
## expm, lu, tril, triu

sG <- Null(t(G))
coefs <- solve(sG[c(1,nrow(sG)),],c(0,1))
h <- sG %*% coefs</pre>
```

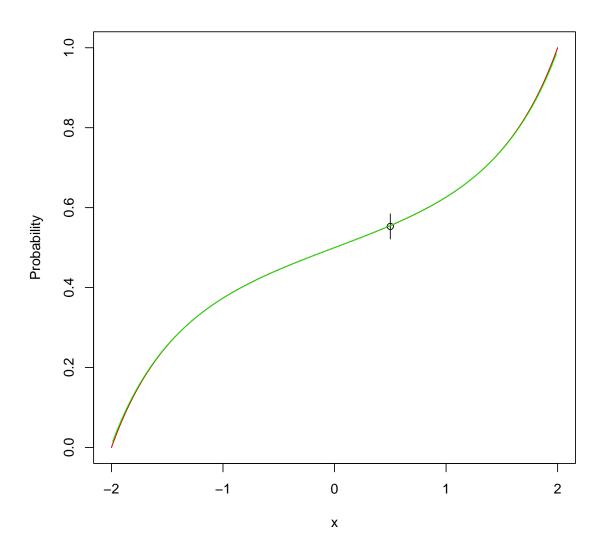
We can now plot the solutions to compare

```
## Plot bup::pracma solution
plot(sol$xs,sol$ys,type="l",xlab="x",ylab="Probability")

## Scale function by numerical integration
plot(ss,from=-1,to=1,col="red",add=TRUE)

## Monte carlo
points(x0,mean(res[2,]>0))
lines(c(x0,x0),mean(res[2,]>0)+c(-2,2)*sqrt(var(res[2,]>0)/ncol(res)))

## With the generator
lines(xc,h[2:(length(h)-1)],col="green")
```



We see that they all agree reasonably well.

For small values of l, the solution approaches a straight line connecting the two endpoints. As the

domain is increased, a plateau emerges around x=0 where h varies less and is roughly equal to 1/2; in stead, the variation in h concentrates at the boundaries. In this situation, the drift is likely to take the process to the equilibrium value of x=0 where it will remain a long time until a random fluctuation takes it to one of the boundaries. Only when the initial condition is near the boundary does it have an effect, namely through the event that the noise takes the particle to the boundary before it relaxes to the origin.

Question 3 Finding  $\mathbf{E}\tau$  using a backward equation: Write a boundary value problem which governs  $k(x) := \mathbf{E}^{X_0 = x}\tau$ . Solve the problem, plot the solution, and compare with the Monte Carlo solution as well as with the analytical result. *Hint:* The same methods apply. If using fvade, it is slightly easier to use absorbing boundary conditions ('a').

**Solution:** Now the boundary value problem is (compare the notes)

$$Lk + 1 = -xk'(x) + k'' + 1 = 0, \quad k(-l) = k(l) = 0.$$

The notes give an analytical solution in terms of an integral that must be evaluated numerically. Here, we solve it numerically as a BVP using pracma::bvp as well as the discretized generator:

```
sol <- bvp(f=function(x)x,g=function(x)0*x,h=function(x)0*x-1,x=c(-1,1),y=c(0,0),n=200)

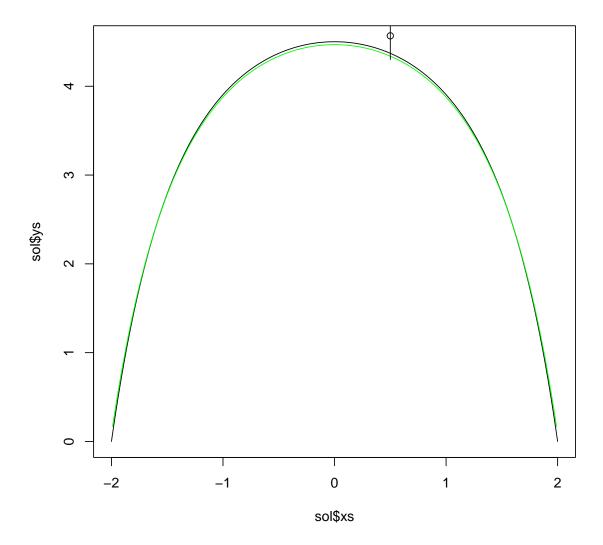
G <- fvade(f,function(x)0.5*g(x)*g(x),xi,'a')
k.fvade <- solve(G,rep(-1,nrow(G)))</pre>
```

We plot the solutions for comparison:

```
## Plot solution from pracma::bup
plot(sol$xs,sol$ys,col=1,type="1")

## Plot solution from generator
lines(xc,k.fvade,col="green")

## Add Monte Carlo; add confidence interval
points(x0,mean(res[1,]))
lines(rep(x0,2),mean(res[1,]) + c(2,-2)*sqrt(var(res[1,])/N))
```



Also here, when the domain is small so that the noise is dominating, we recover approximately the quadratic scaling from space to time which characterizes pure diffusion. When the noise level is low, we get a plateau around x = 0 where the time to absorption varies less with the initial condition; the reasoning is the same as in the previous question.

**Question 4** Finding the expected total pay-off: Find, as a function of x, the expected total pay-off

$$\mathbf{E}^{X_0=x} \int_0^\tau X_t^2 dt$$

Extend the Monte Carlo simulation to compute also this payoff and compare with the numerical solution.

**Solution:** In this case the boundary value problem is

$$(Lk)(x) + x^2 = 0, \quad k(-1) = k(1) = 0.$$

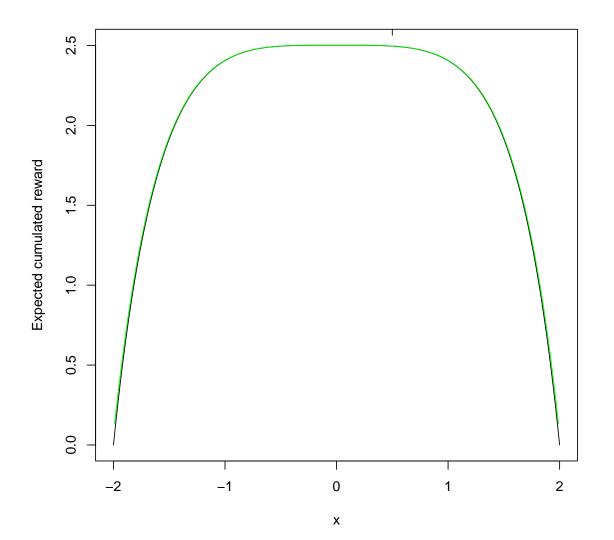
We solve as a BVP using pracma::bvp, the discretized generator, and with Monte Carlo:

```
## Compute solution with pracma::bup
sol <- bvp(f=function(x)x,g=function(x)0*x,h=function(x)-x^2,x=c(-1,1),y=c(0,0),n=200)
## Compute solution from generator
G <- fvade(f,function(x)0.5*g(x)*g(x),xi,'a')
k.fvade <- solve(G,-xc^2)</pre>
```

## We plot the solutions:

```
plot(sol$xs,sol$ys,type="1",xlab="x",ylab="Expected cumulated reward")
lines(xc,k.fvade,col="green")

## Add Monte Carlo; add confidence interval
points(x0,mean(res[3,]))
lines(rep(x0,2),mean(res[3,]) + c(2,-2)*sqrt(var(res[3,])/N))
```



Again, we see the good agreement and the plateau around x = 0. In this case the plateau is more pronounced, because the running reward  $x^2$  vanishes at the equilibrium, so k''(0) = 0.

## Is the origin attainable under the CIR and GBM processes?

Question 5 The CIR process: Example 11.7.1 in the notes establishes a criterion under which the Cox-Ingersoll-Ross process may reach the origin. Fill in the details in the argument, thus verifying the criterion.

**Solution:** The scale function is given by  $s' = \phi$  where

$$\phi(x) = \exp\left(\int_{x_0}^x \frac{2\lambda(x-\xi)}{\gamma^2 x} dx\right)$$
.

We can compute this integral explicitly:

$$\phi(x) = \exp\left(\frac{2\lambda}{\gamma^2}(x - x_0) - \frac{2\lambda\xi}{\gamma^2}\log(x/x_0)\right)$$

or

$$\phi(x) = e^{2\lambda(x-x_0)/\gamma^2} (x_0/x)^{2\lambda\xi/\gamma^2}$$

Note that  $\phi(x)$  diverges as  $x \to 0$  but is continuous elsewhere. The question is if  $\phi$  is integrable over  $(0, x_0)$ . Since the first term, the exponential, is continuous at  $0, \phi$  will be integrable if and only if the latter term is integrable. This is the case if and only if

$$2\lambda\xi/\gamma^2<1.$$

(In that case, an antiderivative is, up to scale,  $x^{1-2\lambda\xi/\gamma^2}$  which is continuous at 0). In conclusion, the origin is attainable if and only if

$$2\lambda\xi < \gamma^2$$
 .

Note that this condition only involves the drift  $f(0) = \lambda \xi$  at the boundary, and the diffusivity near the boundary, i.e.  $D'(0) = \gamma^2/2$ .

We see that the boundary is attainable if the drift at the boundary weak, compared to the diffusivity gradient. This is natural, since it is the noise that must push the state on to the boundary and in doing so overcome the drift that pushes the state away.

Question 6 Geometric Brownian motion: Example 11.7.2 establishes a criterion for which geometric Brownian motion may converge to the origin. Fill in the details in the argument, thus verifying the criterion.

**Solution:** The scale function is given by  $s' = \phi$  where

$$\phi(x) = \exp\left(\int_{x_0}^x \frac{-2rx}{\sigma^2 x^2} \ dx\right) \quad .$$

We can compute this integral explicitly:

$$\phi(x) = \exp\left(\frac{2r}{\sigma^2}\log(x_0/x)\right) = (x_0/x)^{2r/\sigma^2}$$

So, (discarding the constants, because the scale function is only uniquely defined up to shift and scale)

$$s(x) = (x_0/x)^{2r/\sigma^2 - 1}$$

Here we assume  $2r/\sigma^2 \neq 1$ . We see that the scale function is continuous at 0 if and only if  $2r/\sigma^2 - 1 < 00$ . Hence the origin is attainable if and only if

$$2r < \sigma^2$$
.

The case  $2r/\sigma^2 = 1$  must be trated separately: Then, we find that the scale function is a log function which diverges at x = 0, so that the origin is not attainable.

In words, the origin is attainable if the drift is towards the origin, or if the drift is away from the origin but weaker than the noise. Keep this in mind next week when we talk about stability.