# Weighted Projection Quantiles Algorithm

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Algorithm to calculate weighted projection quantile along the vector  $\mathbf{u} \in \mathcal{B}_p$ , given a set of observations  $\mathbf{X}_1, \mathbf{X}_2, ..., \mathbf{X}_n$ :

- 1. Compute  $Q_{proj}(\mathbf{u})$ , the projection quantile along  $\mathbf{u}$ 
  - Project each  $\mathbf{X}_i$  along  $\mathbf{u}$  to obtain  $X_{\mathbf{u}i} = \frac{\langle \mathbf{X}_i, \mathbf{u} \rangle}{\|\mathbf{u}\|}$ , for i = 1, 2, ..., n.
  - Find  $\alpha = \frac{1+\|\mathbf{u}\|}{2}$ -th quantile of  $X_{\mathbf{u}1}, ..., X_{\mathbf{u}n}$ , say  $q_{\mathbf{u}}$ ...
  - $Q_{proj}(\mathbf{u}) = q_{\mathbf{u}}\mathbf{e}_{\mathbf{u}}, \ \mathbf{e}_{\mathbf{u}} = \mathbf{u}/\|\mathbf{u}\|$  being the unit vector along  $\mathbf{u}$ .
- 2. Compute Weights corresponding to this projection quantile  $Q_{proj}(\mathbf{u})$ 
  - Compute global weights for the direction vector u by k-mean distance:
    - Compute k-mean distance corresponding to  $Q_{proj}(\mathbf{u})$  using  $\bar{d}_k = \frac{1}{n} \sum_{i=1}^n d_i \mathbb{I}_{\{d_i < d_{(k)}\}}$ , where  $d_i$  is the euclidean distance of  $\mathbf{X}_i$  from  $Q_{proj}(\mathbf{u})$  given by  $\|\mathbf{X}_i Q_{proj}(\mathbf{u})\|$ . k is a tuning parameter.
    - Compute the weights corresponding to **u**:

$$w_{\mathbf{u}} = \exp(-a.d_k)$$

where a is a tuning parameter.

- Compute weights for each sample point  $X_i$ ; i = 1, 2, ..., n:
  - Compute the orthogonal Norms by  $\|\mathbf{X}_{\mathbf{u}\perp i}\| = \|\mathbf{X}_i X_{\mathbf{u}i}\mathbf{e}_{\mathbf{u}}\|$ .
  - Compute weight of  $i^{th}$  sample:

$$w_{2i} = \exp\left[-b\frac{\|\mathbf{X}_{\mathbf{u}\perp i}\|}{\|\mathbf{X}_i\|}\right] \mathbb{I}_{\{\|\mathbf{X}_{\mathbf{u}\perp i}\|\leq \epsilon\}}$$

 $b, \epsilon$  being tuning parameters.

- 3. Compute the weighted projection quantile
  - Suppose there are m observations with non-zero weights  $w_{2i}$ , with indices  $i_1, i_2, ..., i_m$ . Define  $\tilde{X}_{\mathbf{u}i_j} = w_{\mathbf{u}}w_{2i_j}X_{\mathbf{u}i_j}$ .
  - Find  $\alpha = \frac{1+\|\mathbf{u}\|}{2}$ -th quantile of  $\tilde{X}_{\mathbf{u}i_1},...,\tilde{X}_{\mathbf{u}i_m}$ . Let it be  $\tilde{q}_{\mathbf{u}}$ .
  - Find the weighted projection quantile as  $\tilde{Q}_{proj}(\mathbf{u}) = \tilde{q}_{\mathbf{u}} \mathbf{e}_{\mathbf{u}}$ .

**Definition** Given a random vector  $\mathbf{X} \in \mathbb{R}^p$  that follows a multivariate distribution F, and a point  $\mathbf{p} \in \mathbb{R}^p$ , find  $\alpha_{\mathbf{p}}$  such that  $\|\mathbf{p}\|$  is the  $\alpha_{\mathbf{p}}$ -th quantile for the projection of  $\mathbf{X}$  on  $\mathbf{p}$ , say  $X_{\mathbf{p}}$ . Then the **Projection Quantile Depth** (PQD) at  $\mathbf{p}$  with respect to F is defined as

$$D(\mathbf{p}, F) = \exp(-\alpha_{\mathbf{p}})$$

Given data  $\mathbf{X}_1, \mathbf{X}_2, ..., \mathbf{X}_n$ , the PQD at a given  $\mathbf{p}$  can be estimated by finding the two nearest points on either side of  $\|\mathbf{p}\|$  along  $\mathbf{p}$ , say  $\mathbf{p}_1, \mathbf{p}_2$ , obtain their corresponding quantiles, say  $\alpha_1, \alpha_2$  respectively, then estimate  $\alpha_{\mathbf{p}}$  by a linear approximation:

$$\hat{\alpha}_{\mathbf{p}} = \frac{(\alpha_1 - \alpha_2)(\|\mathbf{p}\| - \|\mathbf{p}_1\|)}{\|\mathbf{p}_1\| - \|\mathbf{p}_2\|} + \alpha_1$$

and plugging it in the above definition.

#### Algorithm 1 Algorithm for PQD-based classification

- 1: **procedure** PQDCLASSIFIER(training data  $\mathbf{X}_i \in \mathbb{R}^{n_i \times p}$  with class labels i; i = 1, 2, ..., k, new data  $\mathbf{x}_{new} \in \mathbb{R}^p$ )
- 2: Set i = 1.
- 3: top:
- 4: Estimate from the sample the PQD of **p** with respect to the  $i^{th}$  population, say  $D(\mathbf{x}_{new}, \mathbf{X}_i)$ .
- 5: if i = k then Stop
- 6: **else**
- 7: Set  $i \leftarrow i + 1$ , **goto** top

8:

9: Find c that maximizes the PQD of  $\mathbf{x}_{new}$  w.r.t. all possible classes:

$$D(\mathbf{x}_{new}, \mathbf{X}_c) = \max\{D(\mathbf{x}_{new}, \mathbf{X}_i) : i = 1, 2, ..., k\}$$

10: Assign class c to new data  $\mathbf{x}_{new}$ .

**Note** One can define a weighted version of PQD by replacing  $X_{\mathbf{p}}$  by their weighted version  $\tilde{X}_{\mathbf{p}}$ . A weighted classification scheme follows similarly.

### Modifications

1.  $w_{2i} = \mathbb{I}_{\{\|X_{\mathbf{u}\perp i}\| \leq \epsilon\}}$  Wouldn't work. The objective function here is

$$\begin{split} \tilde{\Psi}_{\mathbf{u}}(q) &= & \mathbb{E}\left[\{|X_{\mathbf{u}} - q| + \alpha(X_{\mathbf{u}} - q)\}\mathbb{I}_{\{\|\mathbf{X}_{\mathbf{u}\perp}\| \leq \epsilon\}}\right] \\ &= & \mathbb{E}\left[|X_{\mathbf{u}} - q| + \alpha(X_{\mathbf{u}} - q)\right]P\left[\|\mathbf{X}_{\mathbf{u}\perp}\| \leq \epsilon\right] \\ &= & \Psi_{\mathbf{u}}(q)P\left[\|\mathbf{X}_{\mathbf{u}\perp}\| \leq \epsilon\right] \end{split}$$

because  $Cov(X_{\mathbf{u}}\mathbf{e}_{\mathbf{u}}, \mathbf{X}_{\mathbf{u}\perp}) = \mathbf{0}$ . Hence it gives out PQ as the minimizer.

## New notion of data depth

We define a data depth based on projection quantiles (which, of course, can be extended to the weighted versions), on the lines of Zuo's Projection Depth [ref?].

**Definition** Given a random vector  $X \in \mathbb{R}^p$  that follows a multivariate distribution F, and a point  $x \in \mathbb{R}^p$ , define an outlyingness function

$$O(x, F) = \sup_{\|u\|=1} \left| F_u(x_u) - \frac{1}{2} \right|$$

where  $F_{\mathbf{u}}$  is the distribution function of  $X_{\mathbf{u}}$ , and  $x_u = \langle x, u \rangle / ||u||$ . Then we define the **Projection Quantile Depth** at x with respect to F as

$$PQD(x,F) = \frac{1}{1 + O(x,F)}$$

We now follow the order in Zuo's paper to obtain the properties of the PQD.

**(P1)** Affine invariance Say G is the cdf of AX + b. Then we have O(Ax + b, G) = O(x, F) because for all  $u \in \mathbb{R}^p$  we have

$$F(x) = G(Ax + b) \Rightarrow F_u(x_u) = G_{Au+b} ((Ax + b)_{Au+b})$$

where subscripting denotes projection.

(P2) Quasi-concavity for  $0 < \lambda < 1, z = \lambda x + (1 - \lambda)y$ ,

$$F_{u}(z_{u}) = F_{\mathbf{u}}(\lambda x_{u} + (1 - \lambda)y_{u})$$

$$\Rightarrow \left| F_{u}(z_{u}) - \frac{1}{2} \right| \leq \begin{cases} \left| \max\{F_{u}(x_{u}), F_{u}(y_{u})\} - \frac{1}{2} \right| & \text{if } F_{u}(z_{u}) < 1/2 \\ \left| \min\{F_{u}(x_{u}), F_{u}(y_{u})\} - \frac{1}{2} \right| & \text{otherwise} \end{cases}$$

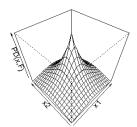
$$\leq \max\left\{ \left| F_{u}(x_{u}) - \frac{1}{2} \right|, \left| F_{u}(y_{u}) - \frac{1}{2} \right| \right\}$$

and we finally get  $PQD(z, F) \ge \max\{PQD(x, F), PQD(y, F)\}.$ 

- **(P3)** Vanishing at infinity For  $||x|| \to \infty$  we have  $F_u(x_u) \to 1$  hence  $PQD(x,F) \to 2/3$ . So we can define  $PQD^*(x,F) = PQD(x,F) 2/3$  to obtain P3.
- (P4) Maximized at center of symmetric F Halfspace symmetry of F w.r.t. center  $\theta$  implies (halfspace) symmetry of  $F_u$  around  $\theta_u$  for any  $u \in \mathbb{R}^p$ , so that  $F_u(\theta_u) = 1/2$  and subsequently PQD achieves its max value 1 at  $\theta$ .

#### **Projection Depth**

#### **Projection Quantile Depth**



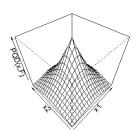


Figure 1: Projection Depth (left) and Projection Quantile Depth (right) for  $\mathcal{N}_2((0,0)',I_2)$ 

**Example 1** For  $X \sim \mathcal{N}_2((0,0)', I_2)$  we have  $X_u \sim N(0,1)$  for any  $u \in \mathbb{R}^p$ : ||u|| = 1. Due to the symmetry of the distribution function maximizing  $|F_u(x_u) - 1/2|$  is equivalent to maximizing  $F_u(x_u) = \Phi(x_u) = \Phi(\langle x, u \rangle)$ .

Converting u to polar coordinates we can maximize over the angle  $\theta$  that u makes with the X-axis, and can easily find that the above function maximizes at  $\theta = \tan^{-1}(x_2/x_1)$ , which is the direction for x itself. Thus for given x the sup is obtained at u = x, and we have

$$PQD(x,F) = \frac{1}{1 + \Phi(\|x\|) - 1/2} = \frac{2}{1 + 2\Phi(\|x\|)}$$
(1)

Fig. 1 shows a comparison of PQD with Zuo's PD for standard bivariate normal.

**Note** In place of standard bivariate normal, one can use any circularly symmetric F, i.e. a distribution that has the same marginal distribution  $F_0$  along all one-dimensional projections to come up with an exact formula for PQD(x, F). In that general scenario,  $\Phi(.)$  will be replaced by  $F_0(.)$  in (1).