

Back Propagation Learning :

- 1) A back-propagation neural net is a multilayer, feed-forward neural net consisting of an input layer, a hidden layer and an output layer.
- 2) The neurons present in the hidden and output layers have biases which are the connections from the units whose activation is always 1.
- 3) The bias terms also act as weights.
- 4) The architecture of a BPN, depicting only the dirⁿ of informⁿ flow for the feed-forward phase but during the back-propagation phase of learning, signals are sent in the reverse dirⁿ.
- 5) The inputs are sent to the BPN and the output obtained from the net could be either binary (0,1) or bipolar (-1,+1).
- 6) The activation funⁿ could be any funⁿ which increases monotonically and is also differentiable.

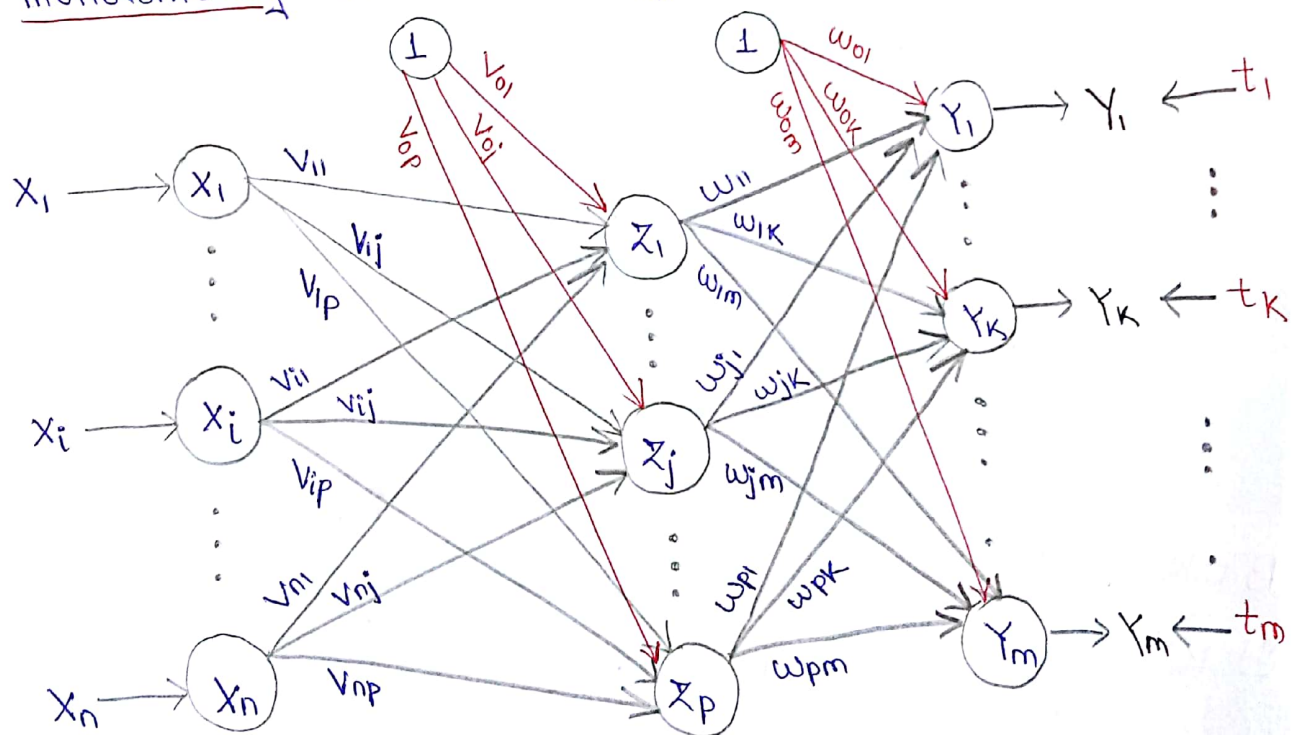


Fig : Architecture of a back-propagation n/w.

Training Algorithm

The error back-propagation learning Algorithm can be outlined in the following algorithm :

Step 0: Initialize weights and learning rate (take some ^{small} random values)

Step 1: Perform steps 2-9 when stopping condⁿ is false.

Step 2: Perform steps 3-8 for each training pair.

Feed-forward phase (Phase I):

Step 3: Each input unit receives input signal x_i and sends it to the hidden unit ($i = 1$ to n).

Step 4: Each hidden unit z_j ($j = 1$ to p) sums its weighted input signals to calculate net input:

$$Z_{inj} = V_{0j} + \sum_{i=1}^n x_i V_{ij}$$

Calculate output of the hidden unit by applying its activation funⁿs over Z_{inj} (binary or bipolar sigmoidal activation funⁿ):

$$z_j = f(Z_{inj})$$

and send the output signal from the hidden unit to the input of output layer units.

Step 5: For each output unit Y_k ($k = 1$ to m). Calculate the net input:

$$Y_{ink} = W_{0k} + \sum_{j=1}^p z_j W_{jk}$$

and apply the activation funⁿ to compute output signal.

$$Y_k = f(Y_{ink})$$

Back-propagation of error (Phase II):

Step 6: Each output unit Y_k ($k = 1$ to m) receives a target pattern corresponding to the input training pattern & computes the error correction term:

$$\delta_k = (t_k - Y_k) f'(Y_{ink})$$

[for binary sigmoidal — $f'(x) = \lambda f(x) [1 - f(x)]$]

On the basis of the calculated error correction term, update the change in weights & bias.

$$\Delta w_{jk} = \alpha \delta_k z_j \quad ; \quad \Delta w_{0k} = \alpha \delta_k$$

Also, send δ_k to the hidden layer backwards.

Step 7: Each hidden unit ($z_j, j = 1 \text{ to } p$) sum its delta slips from the o/p units.

$$\delta_{inj} = \sum_{k=1}^m \delta_k w_{jk}$$

The term δ_{inj} gets multiplied with the derivative of $f(z_{inj})$ to calculate the error term:

$$\delta_j = \delta_{inj} f'(z_{inj})$$

On the basis of the calculated δ_j , update the change in weights and bias:

$$\Delta v_{ij} = \alpha \delta_j x_i \quad ; \quad \Delta v_{oj} = \alpha \delta_j$$

Weight and bias updation (phase III)

Step 8: Each o/p unit ($y_k, k = 1 \text{ to } m$) updates the bias & weights:

$$w_{jk}(\text{new}) = w_{jk}(\text{old}) + \Delta w_{jk}$$

$$w_{ok}(\text{new}) = w_{ok}(\text{old}) + \Delta w_{ok}$$

Each hidden unit ($z_j, j = 1 \text{ to } p$) updates its bias & weights:

$$v_{ij}(\text{new}) = v_{ij}(\text{old}) + \Delta v_{ij}$$

$$v_{oj}(\text{new}) = v_{oj}(\text{old}) + \Delta v_{oj}$$

Step 9: check for the stopping condⁿ. The stopping condⁿ may be certain no. of epochs reached or when the actual o/p equals the target o/p.

Testing Algorithm of Back-Propagation Nlw:

The testing procedure of the BPN is as follows:

Step 0: Initialize the weights. The weights are taken from the training Algorithm.

Step 1: Perform steps 2-4 for each i/p vector.

Step 2: Set the activation of i/p unit for $x_i (i = 1 \text{ to } n)$.

Step 3: Calculate the net gip to hidden unit x and its oip.

for $j=1$ to p ,

$$Z_{inj} = V_{oj} + \sum_{i=1}^n x_i V_{ij}$$

$$Z_j = f(Z_{inj})$$

Step 4: Now compare the oip of the oip layer unit. for $k=1$ to m .

$$Y_{ink} = w_{ok} + \sum_{j=1}^p Z_j w_{jk}$$

$$Y_k = f(Y_{ink})$$

Use sigmoidal activation function for calculating the oip.

Flowchart of training Process:

The terminologies used in the flowchart and in the training algorithm are as follows:

x = input training vector $(x_1, x_2, \dots, x_i, \dots, x_n)$

t = target oip vector $(t_1, \dots, t_k, \dots, t_m)$

α = learning state parameter

x_i = input unit i . (Since the gip layer uses identity activation funⁿ, the gip and oip signals here are same.)

V_{oj} = bias on j^{th} hidden unit.

w_{ok} = bias on k^{th} oip unit.

Z_j = hidden unit j . The net gip to Z_j is

$$Z_{inj} = V_{oj} + \sum_{i=1}^n x_i V_{ij}$$

and the oip is:

$$Z_j = f(Z_{inj})$$

Y_k = oip unit k . The net gip to Y_k is

$$Y_{ink} = w_{ok} + \sum_{j=1}^p Z_j w_{jk}$$

and the oip is:

$$Y_k = f(Y_{ink})$$

δ_k = error correction weight adjustment for w_{jk} that is due to an error at output unit y_k , which is back-propagated to the hidden units that feed into unit y_k .

δ_j = error correction weight adjustment for v_{ij} i.e. due to the back-propagation of error to the hidden unit z_j .

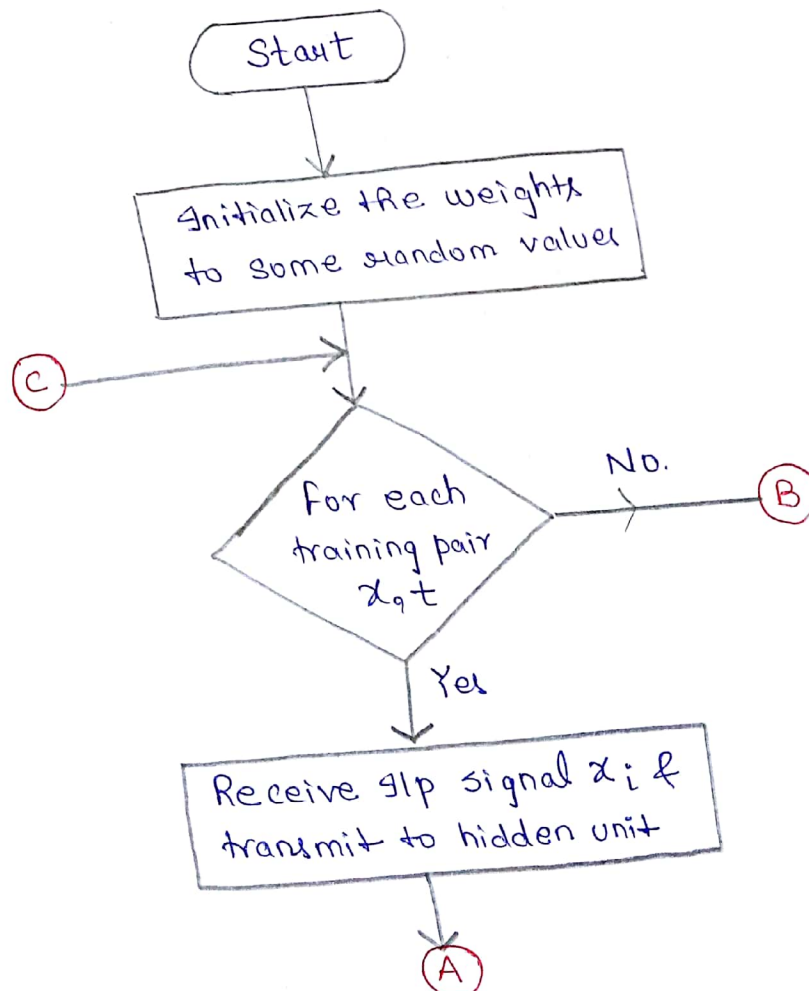
* Also, Note that the commonly used Activation functions are binary sigmoidal and bipolar sigmoidal activation functions.

* These functions are used in the BPN bcoz of the following characteristics:

- i) Continuity
- ii) differentiability
- iii) non decreasing monotony.

* The range of binary sigmoid is from 0 to 1, and for bipolar sigmoid it is from -1 to +1.

Flow chart



(A)

In hidden unit, calculate o/p,

$$Z_{inj} = V_{oj} + \sum_{i=1}^n x_i V_{ij}$$

$$x_i = f(Z_{inj}), \quad \begin{matrix} j=1 \text{ to } p \\ i=1 \text{ to } n \end{matrix}$$

Send Z_j to the o/p layer units

calculate o/p signal from o/p layer,

$$Y_{ink} = W_{ok} + \sum_{j=1}^p Z_j W_{jk}$$

$$Y_k = f(Y_{ink}) \quad k=1 \text{ to } m$$

Target pair t_k enters

Compute error correction factor

$$\delta_k = (t_k - Y_k) f'(Y_{ink})$$

(blw o/p and hidden)

Find weight & bias correction term

$$\Delta w_{jk} = \alpha \delta_k Z_j ; \Delta w_{ok} = \alpha \delta_k$$

Calculate error term δ_j
(blw hidden & i/p)

$$\delta_{inj} = \sum_{k=1}^m \delta_k W_{jk}$$

$$\delta_j = \delta_{inj} f'(Z_{inj})$$

Compute change in weights & bias based on

$$\delta_i, \Delta V_{ij} = \alpha \delta_j x_i, \Delta V_{oj} = \alpha \delta_j$$

(E)

