Artificial Intelligence: Lab Assignment-7

Group Members-

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1 Question-1

```
Given data points- X = [-20], [-19], [-18], [-17], [20], [-10], [30] y = [10], [5], [-1], [5], [20], [-10], [30]
```

Train the neural network on 40 neurons and then predict the trained model on-

- 1. Range(-20 20)
- 2. Theta and Corresponding sin value

1.1 Code and Implementation

1.1.1 Neural Network

```
import numpy as np
import matplotlib.pyplot as plt

X = np.array(([-20], [-19], [-18], [-17], [20], [-10], [30]), dtype=float)
y = np.array(([10], [5], [-1], [5], [20], [-10], [30]), dtype=float)

# scale units
#X = X/np.amax(X, axis=0) # maximum of X array
#y = y/100

class Neural_Network(object):
    def __init__(self):
        #parameters
        self.inputSize = 1
        self.outputSize = 1
        self.hiddenSize = 40
        #weights
        self.W1 = np.random.randn(self.inputSize, self.hiddenSize)
```

```
# weight matrix from input to hidden layer
self.W2 = np.random.randn(self.hiddenSize, self.outputSize)
# weight matrix from hidden to output layer
```

1.2 Forward Propagation

```
def forward(self, X):
    #forward propagation through our network
    self.z = np.dot(X, self.W1)
    self.z2 = self.sigmoid(self.z) # activation function
    self.z3 = np.dot(self.z2, self.W2)
    #o = self.z3
    return self.z3

def sigmoid(self, s):
    # activation function
    #return 1/(1+np.exp(-s))
    return np.tanh(s)

def sigmoidPrime(self, s):
    #derivative of sigmoid
    #return s * (1 - s)
    return (1 - (np.tanh(s)**2))
```

1.3 Back Propagation

```
def backward(self, X, y, o):
    # backward propgate through the network
    self.o_error = y - o # error in output
    self.o_delta = self.o_error*self.sigmoidPrime(o)
    # applying derivative of sigmoid to error

self.z2_error = self.o_delta.dot(self.W2.T)
    # z2 error: how much our hidden layer weights contributed to output error
    self.z2_delta = self.z2_error*self.sigmoidPrime(self.z2)
    # applying derivative of sigmoid to z2 error

self.W1 += X.T.dot(self.z2_delta)
    # adjusting first set (input --> hidden) weights
    self.W2 += self.z2.T.dot(self.o_delta)
    # adjusting second set (hidden --> output) weights

def train (self, X, y):
```

1.4 Training the network

o = self.forward(X)self.backward(X, y, o)

```
 \begin{aligned} NN &= Neural\_Network() \\ for i in range(1000): \# trains the NN 1,000 times \\ print ("Input: \n" + str(X)) \end{aligned}
```

```
\begin{array}{lll} & print & ("Actual \ Output: \ \ \ '' + str(y)) \\ & print & ("Predicted \ Output: \ \ \ '' + str(NN.forward(X))) \\ & print & ("Loss: \ \ \ '' + str(np.mean(np.square(y - NN.forward(X))))) \\ & \# \ mean \ sum \ squared \ loss \\ & print & ("\ \ '') \\ & NN. \ train(X, y) \end{array}
```

1.5 Prediction on X and Y values-Decimal Values

```
result_array = np.array(([-20],[-19],[-18],[-17],[-16]
,[-15],[-14],[-13],[-12],[-11],[-10],
    [-9],[-8],[-7],[-6],[-5],[-4],[-3]
    ,[-2],[-1],[0],[1],[2],[3],[4],[5],[6],[7
    ,[8],[9],[10],[11],[12],[11],[12],[13]
    ,[14],[15],[16],[17],[18],[19],
    [20]),dtype=float)
    #X_final_pred = np.array((), dtype=float)
    print ("Predicted Output: \n" + str(NN.forward(result_array)))

plt.plot(result_array, NN.forward(result_array))

plt.ylabel('Input (X)')
    plt.ylabel('Prediction(Y_-)')
    plt.title('Prediction on given data')
    plt.grid(True)
    plt.savefig("test.png")
    plt.show()
```

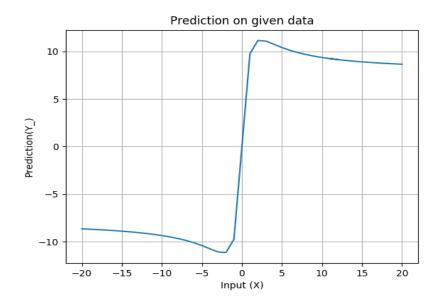


Figure 1: Decimal Value prediction

1.6 Prediction on Theta and Sin Values

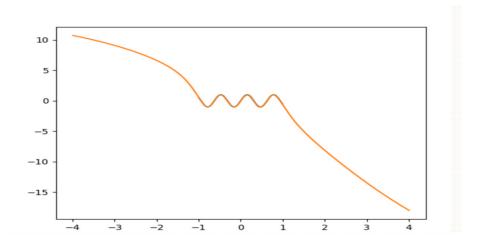


Figure 2: 100 iterations

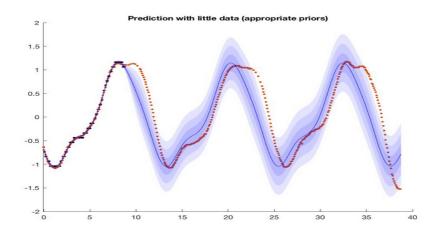


Figure 3: 1000 iterations

2 Neural Network Prediction on Climate Data

```
import pandas as pd
import numpy as np
import tensorflow as tf
from sklearn.metrics import explained_variance_score, \
           mean_absolute_error , \
           median_absolute_error
from sklearn.model_selection import train_test_split
df = pd.read_csv('end-part2_df.csv').set_index('date')
df.describe().T
df = df.drop(['mintempm', 'maxtempm'], axis=1)
y = df['meantempm']
X_{train}, X_{tmp}, y_{train}, y_{tmp} = train_{test_split}(X, y, test_{size} = 0.2, random_{test_split}(X, y, test_{test_split}(X, y, test_{t
X_{test}, X_{val}, y_{test}, y_{val} = train_{test_split}(X_{tmp}, y_{tmp}, test_{size} = 0.5, ration 1)
X_train.shape, X_test.shape, X_val.shape
print ("Training instances
                      Training features
                      format(X_train.shape[0],
                      X_{train.shape[1])
print ("Validation instances {},
                   Validation features {}"
                   . format (X_val.shape [0],
                   X_{\text{val}}. shape [1])
print ("Testing instances
                   \{\}, Testing features
                    {}".format(X_test.shape[0],
                   X_{\text{-}}test.shape[1]))
feature_cols = [tf.feature_column.numeric_column(col)
                                            for col in X. columns]
regressor = tf.estimator.
                                 DNNRegressor (feature_columns=feature_cols,
                                                                       hidden_units = [50, 50],
                                                                       model_dir='tf_wx_model')
def wx_input_fn(X, y=None, num_epochs=None,
                                           shuffle=True, batch_size=400):
           return tf.estimator.
           inputs.pandas_input_fn(x=X,
                                                                 num_epochs=num_epochs,
                                                                 shuffle=shuffle,
                                                                    batch_size=batch_size)
evaluations = []
STEPS = 400
```

```
for i in range (100):
    regressor.train(
    input_fn=wx_input_fn(X_train, y=y_train)
    , steps=STEPS)
    evaluation = regressor.evaluate(
    input_fn=wx_input_fn(X_val, y_val,
                       num_epochs=1,
                       shuffle=False),
                       steps=1)
    evaluations.append(regressor.
    evaluate (input\_fn=wx\_input\_fn (X\_val,
              y_val, num_epochs=1, shuffle=False)))
# manually set the parameters of the figure to and appropriate size
plt.rcParams['figure.figsize'] = [14, 10]
loss_values = [ev['loss'] for ev in evaluations]
training_steps = [ev['global_step'] for ev in evaluations]
plt.scatter(x=training_steps, y=loss_values)
plt.xlabel('Training steps (Epochs = steps / 2)')
plt.ylabel('Loss (SSE)')
plt.show()
```

	count	mean	std	min	25%	50%	75%	max
meantempm	997.0	13.129388	10.971591	-17.0	5.0	15.0	22.00	32.00
maxtempm	997.0	19.509529	11.577275	-12.0	11.0	22.0	29.00	38.00
mintempm	997.0	6.438315	10.957267	-27.0	-2.0	7.0	16.00	26.00
meantempm_1	997.0	13.109328	10.984613	-17.0	5.0	15.0	22.00	32.00
meantempm_2	997.0	13.088265	11.001106	-17.0	5.0	14.0	22.00	32.00
meantempm_3	997.0	13.066199	11.017312	-17.0	5.0	14.0	22.00	32.00
meandewptm_1	997.0	6.440321	10.596265	-22.0	-2.0	7.0	16.00	24.00
meandewptm_2	997.0	6.420261	10.606550	-22.0	-2.0	7.0	16.00	24.00
meandewptm_3	997.0	6.393180	10.619083	-22.0	-2.0	7.0	16.00	24.00
neanpressurem_1	997.0	1016.139418	7.582453	989.0	1011.0	1016.0	1021.00	1040.00
meanpressurem_2	997.0	1016.142427	7.584185	989.0	1011.0	1016.0	1021.00	1040.00
meanpressurem_3	997.0	1016.151454	7.586988	989.0	1011.0	1016.0	1021.00	1040.00

Figure 4: Dataset

3 Hopfield Network

Out[3]:

```
clear all;
close all;
\% Patterns to store
% D, J, C, M
%---
%figure;
%imshow(reshape(-X(:,1),5,5)');
% Learn the weights according to Hebb's rule
[m,n] = size(X);
W = zeros(m,m);
for\ i\ =\ 1\!:\!n
    W = W + X(:, i) *X(:, i);
W(logical(eye(size(W)))) = 0;
W = W/n;
```

```
Index: 997 entries, 2015-01-04 to 2017-09-27
Data columns (total 39 columns):
meantempm
                     997
                         non-null
                                    int64
maxtempm
                     997
                         non-null
mintempm
                     997
                         non-null
                                   int64
meantempm
                         non-null
                                    float64
meantempm 2
                     997
                         non-null
                                    float64
meantempm_3
                     997
                         non-null
                                    float64
meandewptm 1
                     997
                         non-null
                                    float64
                     997
                                    float64
meandewptm
                         non-null
meandewptm 3
                     997
                         non-null
                                    float64
meanpressurem 1
                     997
                                    float64
                         non-null
                                    float64
meanpressurem
                     997
                         non-null
meanpressurem 3
                     997
                         non-null
                                    float64
maxhumidity_1
                                    float64
                     997
                         non-null
maxhumidity_
                     997
                         non-null
                                    float64
maxhumidity_
                         non-null
                                    float64
                     997
minhumidity_
                     997
                                    float64
                         non-null
minhumidity_
                     997
                         non-null
                                    float64
minhumidity
                     997
                         non-null
                                    float64
maxtempm_1
                     997 non-null float64
```

Figure 5: Dataframe

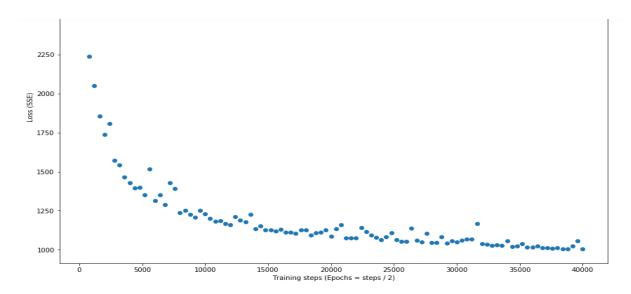


Figure 6: Loss vs Epochs

Figure 7: Prediction Output on climate data-

```
% Dynamical (Linear) System and fixed points
%—
x = X(:,1);
x(5) = -1 * x(5);
figure (1);
subplot(1,2,1);
imshow(reshape(-X(:,1),5,5));
subplot(1,2,2);
imshow(reshape(-x,5,5)');
y = x;
erry = 10;
while erry > 1
        yp = sign(W*y);
        erry = norm(yp-y);
        y = yp;
        figure (2);
        imshow(reshape(-y, 5, 5)');
        pause();
endwhile
\% Damaging 50 neurons!
%-
```

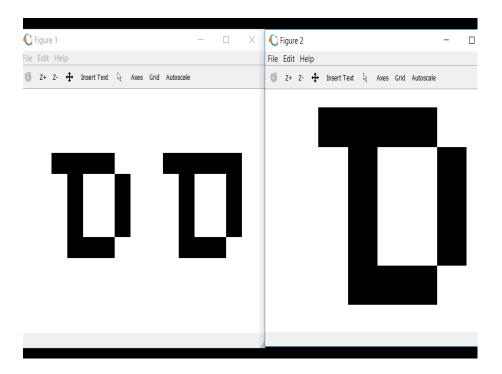


Figure 8: Hop Field Output