

JIAJUN JIANG

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🎓 EDUCATION

Zhejiang University <i>Master in Control Science and Engineering, GPA 84.2/100.</i>	09/2019 – 07/2022
University of California, Davis <i>Research Intern, Supervised by Prof. S.J. Ben Yoo.</i>	07/2018 – 09/2018
University of California, Berkeley <i>Visiting Student, Summer Session 2017.</i>	06/2017 – 08/2017
Zhejiang University <i>Bachelor in Automation + English Language and Literature, GPA: 86.6/100.</i>	09/2015 – 07/2019

🔧 EXPERIENCE

Autonomous Driving Lab , Alibaba DAMO Academy, China <i>Localization Algorithm Engineer</i> Localization Group. Algorithms development for autonomous truck system in highway scenario. <ul style="list-style-type: none">• Development of a trailer yaw estimation algorithm for the autonomous tractor-semitrailer system based on a one-dimensional histogram filter. The filter utilizes LiDAR pointcloud as observation and kinematic model as prediction.• Online calibration parameter check algorithm between multiple LiDAR by checking both pointcloud and pose quality.• Design and implement a lightweight storage method for long-distance pointcloud map, inspired by Universal Transverse Mercator projection and image compression algorithms.	07/2022 – now
Autonomous Driving Lab , Alibaba DAMO Academy, China <i>Internship</i> Localization Group. Calibration method development of autonomous logistics robot on courier stations. <ul style="list-style-type: none">• Develop a fast LiDAR-camera calibration check scheme using semantic segmentation of people.• Design and implement a calibration process for LiDAR and cameras on courier stations with a designed calibration board.	04/2021 – 08/2021
Intelligent Autonomous System Lab , Zhejiang University, China <i>Master Student</i> Supervised by: Prof. Yu Zhang Development of a thermal SLAM system under challenging illumination conditions. <ul style="list-style-type: none">• An SVD-based image processing method is proposed to improve image quality on low-contrast thermal images for SLAM by singular value reallocation.• Develop a real-time optical flow network architecture on thermal images for data association.• One of the contributors to the open-source <u>multi-spectral dataset</u>.	09/2019 – 06/2022
Intelligent Autonomous System Lab , Zhejiang University, China <i>Bachelor Thesis</i> Supervised by: Prof. Yu Zhang. Development of a calibration system for multi-spectral sensors. <ul style="list-style-type: none">• Design and implement a special checkerboard for the calibration between the thermal camera and visible light camera.• Develop a calibration method between LiDAR and visible light camera using calibration board with ArUco marker.	09/2018 – 05/2019

PUBLICATIONS

1. **J. Jiang**, X. Chen, W. Dai, Z. Gao and Y. Zhang, *Thermal-Inertial SLAM for the Environments With Challenging Illumination*, in IEEE Robotics and Automation Letters, vol. 7, no. 4, pp. 8767-8774, Oct. 2022
2. X. Chen, W. Dai, **J. Jiang**, B. He and Y. Zhang, *Thermal-Depth Odometry in Challenging Illumination Conditions*, in IEEE Robotics and Automation Letters, vol. 8, no. 7, pp. 3988-3995, Jul. 2023

PATENTS

1. Y. Zhang, W. Dai, **J. Jiang**. Map Segmentation Method And Device, Motion Estimation Method, And Device Terminal. US Patent, US20210312637A1.
2. Y. Zhang, Z. Gao, **J. Jiang**. Long-wave Infrared Image Denoising Method. Chinese Patent, CN115034992A.

SKILLS

- C/C++, Python, MATLAB, ROS, OpenCV, PCL, GIT, Pytorch.

HONORS AND AWARDS

RoboCup World Humanoid KidSize League, 2nd Place	2019, Sydney, Australia
RoboCup German Open Humanoid KidSize League, 2nd Place	2019, Magdeburg, Germany
Scholarship for Outstanding Students (Top 10%)	2016,2017,2018, Hangzhou, China

MISCELLANEOUS

- HOMEPAGE: <https://www.elkula.com>
- GITHUB: <https://github.com/Elkulas>
- LANGUAGES: Mandarin - Native speaker, English - Fluent (TOFEL 101 in 2018)
- HOBBIES: Saxophone, Bikepacking, Mountain Biking, Chinese Walnuts