

# JIAJUN JIANG

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## 🎓 EDUCATION

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<b>Zhejiang University</b> <i>Master in Control Science and Engineering, GPA 84.2/100.</i>	09/2019 – 07/2022
<b>University of California, Davis</b> <i>Research Intern, Supervised by Prof. S.J. Ben Yoo.</i>	07/2018 – 09/2018
<b>University of California, Berkeley</b> <i>Visiting Student, Summer Session 2017.</i>	06/2017 – 08/2017
<b>Zhejiang University</b> <i>Bachelor in Automation + English Language and Literature, GPA: 86.6/100.</i>	09/2015 – 07/2019

## 🔧 EXPERIENCE

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<b>Autonomous Driving Lab</b> , Alibaba DAMO Academy, China <i>Algorithm Engineer</i> Localization Group. Supervised by: Dr. Sheng Yang Algorithms development for autonomous truck system in highway scenario. <ul style="list-style-type: none"><li>• Development of a trailer yaw estimation algorithm for the autonomous tractor-semitrailer system based on a one-dimensional histogram filter. The filter utilizes LiDAR pointcloud as observation and kinematic model as prediction.</li><li>• Online calibration parameter check algorithm between multiple LiDAR by checking both pointcloud and pose quality.</li><li>• Design and implement a lightweight storage method for long-distance pointcloud map, inspired by Universal Transverse Mercator projection and image compression algorithms.</li></ul>	07/2022 – present
<b>Autonomous Driving Lab</b> , Alibaba DAMO Academy, China <i>Internship</i> Localization Group. Supervised by: Dr. Mingyang Li Calibration method development of autonomous logistics robot on courier stations. <ul style="list-style-type: none"><li>• Develop a fast LiDAR-camera calibration check scheme using semantic segmentation of people.</li><li>• Design and implement a calibration process for LiDAR and camera systems at courier stations, utilizing a purpose-built calibration board.</li></ul>	04/2021 – 09/2021
<b>Intelligent Autonomous System Lab</b> , Zhejiang University, China <i>Master Student</i> Supervised by: Prof. Yu Zhang Development of a thermal SLAM system under challenging illumination conditions. <ul style="list-style-type: none"><li>• Purpose an SVD-based image processing method is proposed to improve image quality on low-contrast thermal images for SLAM by singular value reallocation.</li><li>• Develop a real-time optical flow network architecture on thermal images for data association.</li><li>• One of the contributors to the open-source <u>multi-spectral dataset</u>.</li></ul>	09/2019 – 06/2022
<b>Intelligent Autonomous System Lab</b> , Zhejiang University, China <i>Bachelor Thesis</i> Supervised by: Dr. Weichen Dai and Prof. Yu Zhang. Development of a calibration system for multi-spectral sensors. <ul style="list-style-type: none"><li>• Design and implement a special checkerboard for the calibration between the thermal camera and visible light camera.</li><li>• Develop a calibration method between LiDAR and visible light camera using calibration board with circular holes.</li></ul>	09/2018 – 05/2019

*Circuit Group Leader*

Circuit system development for humanoid kid-size soccer robots

- Design the schematic diagram and PCB board for servo signal transmission and foot sensor modules.
- Assemble and maintain the circuit system in daily routine and during the competition.

## PUBLICATIONS

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1. **J. Jiang**, X. Chen, W. Dai, Z. Gao and Y. Zhang, *Thermal-Inertial SLAM for the Environments With Challenging Illumination*, in IEEE Robotics and Automation Letters, vol. 7, no. 4, pp. 8767-8774, Oct. 2022
2. X. Chen, W. Dai, **J. Jiang**, B. He and Y. Zhang, *Thermal-Depth Odometry in Challenging Illumination Conditions*, in IEEE Robotics and Automation Letters, vol. 8, no. 7, pp. 3988-3995, Jul. 2023

## PATENTS

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1. Y. Zhang, W. Dai, **J. Jiang**. Map Segmentation Method And Device, Motion Estimation Method, And Device Terminal. US Patent, US20210312637A1.
2. Y. Zhang, Z. Gao, **J. Jiang**. Long-wave Infrared Image Denoising Method. Chinese Patent, CN115034992A.

## SKILLS

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- Programming Language: C/C++, Python,  $\text{\LaTeX}$ , Shell.
- Software: ROS, Git, MATLAB, Altium Designer, Keil

## HONORS AND AWARDS

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RoboCup World Humanoid KidSize League, 2nd Place	2019, Sydney, Australia
RoboCup German Open Humanoid KidSize League, 2nd Place	2019, Magdeburg, Germany
Scholarship for Outstanding Students (Top 10%)	2016,2017,2018, Hangzhou, China

## MISCELLANEOUS

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- HOMEPAGE: <https://www.elkula.com>
- GITHUB: <https://github.com/Elkulas>
- BILIBILI: <https://space.bilibili.com/8332491>
- LANGUAGES: Mandarin - Native speaker, English - Fluent (TOFEL 101 in 2018)
- HOBBIES: Saxophone, Bikepacking, Mountain Biking, Chinese Walnuts

## REFEREES

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### Academia:

- Dr. Yu Zhang, Associate Professor, Zhejiang University: [zhangyu80@zju.edu.cn](mailto:zhangyu80@zju.edu.cn)
- Dr. Weichen Dai, Associate Professor, Hangzhou Dianzi University: [weichendai@hdu.edu.cn](mailto:weichendai@hdu.edu.cn)

### Industry:

- Dr. Mingyang Li, Software Engineering Manager, AR Perception Team, Google: [mingyangli009@gmail.com](mailto:mingyangli009@gmail.com)
- Dr. Xiao Hu, Algorithm Expert, Autonomous Driving Lab, Alibaba Group: [hux062303@gmail.com](mailto:hux062303@gmail.com)